4 -12 -24 -36 Modern Mathematical Methods for Physicists and = $\begin{bmatrix} 0_n & 0_n \\ 0_n & 0_n \end{bmatrix}$ Engineers $n - 1_n$ $dx = \int_{a}^{b} f(x)^{*} \left| -i \frac{dg}{dx}(x) \right| dx$ C,D.Cantrell 物理学家和工程师用的现代数学方法 $\leq \left(\max_{i} \left| \frac{\partial y}{\partial x_{i}} \right| \right)^{2} \sum_{j=1}^{m} \sigma_{j}^{2}$ $\leq R^2 \sum_{j=1}^{m} \sigma_j^2 + 0 \qquad C = \begin{pmatrix} 1 & 5 & 9 \\ 2 & 6 & 10 \\ 3 & 7 & 11 \\ 4 & 8 & 12 \end{pmatrix}$ 18 19 15 $\sin(2k+1)x$ 20 / $= \frac{2k+1}{2}$ $\int_{-\infty}^{x} \cos(2k+1)u \, du$ **CAMBRIDGE** I Jm I Jm n 「x 号· (1) な な が で う cos(2k+1)u du -36

MODERN MATHEMATICAL METHODS FOR PHYSICISTS AND ENGINEERS

C. D. CANTRELL

CAMBRIDGE UNIVERSITY PRESS 光界例よれ版公司 书 名: Modern Mathe

ists and Engineers

朝内大街 137号 100010)

作 者: C. D. Cantrel

中 译 名: 物理学家和

出版者: 世界图书出版

印刷者: 北京世图印刷

发 行: 世界图书出版公

联系电话: 010-64015659, 640383-47

电子信箱: kjsk@vip.sina.com

开 本: 24 印 张: 33

出版年代: 2004年11月

书 号: 7-5062-6636-9/O · 485

版权登记: 图字:01-2004-5385

定 价: 116.00 元

世界图书出版公司北京公司已获得 Cambridge University Press 授权在中国大陆 独家重印发行。

PREFACE

The purpose of *Modern Mathematical Methods for Physicists and Engineers* is to help graduate and advanced undergraduate students of the physical sciences and engineering acquire a sufficient mathematical background to make intelligent use of modern computational and analytical methods. This book responds to my students' repeated requests for a mathematical methods text with a modern point of view and choice of topics.

For the past fifteen years I have taught graduate courses in computational and mathematical physics. Before introducing the course on which this book is based, I found it necessary, in courses ranging from numerical methods to the applications of group theory in physics, to summarize the rudiments of linear algebra and functional analysis before proceeding to the ostensible subjects of the course. The questions of the students who studied early drafts of this work have helped to shape the presentation. Some students working concurrently in nearby telecommunication, semiconductor, or aerospace, industries have contributed significantly to the substance of portions of the book.

The following is an example of the situations that motivated me to take the time to write a mathematical methods text that breaks significantly with the past: Every semester, students come to my office, puzzled over numerical models in which minor changes in the data produce drastic changes in the outputs. Unfortunately most of these students lack the mathematical background needed to conceptualize some of the most common problems of numerical computation. For an engineer, and for the increasingly large fraction of physics graduates who make careers in numerical modeling or electrical engineering, conceptual understanding of analytical and numerical models is an absolutely essential ingredient of successful designs. A computer can be a tool for understanding, and not merely a means for obtaining a numerical answer of unknown reliability and significance, only in the hands of those who understand the foundations and potential shortcomings of numerical methods. Yet the traditional mathematical methods taught to students in engineering and physics for most of the twentieth century do not provide a sufficient background even for introductory graduate texts on many important contemporary topics, of which numerical computation is only one.

What upper-level undergraduate and first-year graduate students in physics and engineering tend consistently to lack is an understanding of basic mathematical structures – groups, rings, fields, and vector spaces – and of mappings that preserve these structures. In times gone by, students learned mathematical structures though intensive practice with examples. However, in curricula that already are under fire for taking too many years, there simply is no time to learn the language of mathematics by example. Like adults who learn grammar in

order to accelerate the acquisition of a foreign language, contemporary students in physics or engineering can more easily acquire a durable understanding of applied and numerical mathematics if they have been exposed to the most essential formal mathematical structures.

The core of Modern Mathematical Methods for Physicists and Engineers is linear algebra and basic functional analysis. Computation is the subject of two of the first three chapters because computational examples and exercises occur throughout the book. Chapters on sets and groups, rings and fields provide necessary background for subsequent chapters on vector spaces, inner-product spaces, linear mappings, and matrix representations of finite groups. Group-throry concepts provide an approach to partial differential equations and special functions based on algebra instead of complex analysis. Throughout the book, abstraction is not an end in itself, but a means for students to remember concepts and use them intelligently.

The exercises range in difficulty from simple applications of the definitions in the text to problems that may challenge strong students. In both the text and the exercises, asterisks indicate material that is unusually difficult, and that may be omitted on a first reading.

The manuscript for this book was created in LaTeX on a Macintosh Power Book® using the program Textures®. The illustrations were created using Adobe Illustrator®.

I thank all those who have contributed to this book, especially my students. Special thanks are due to Professors William J. Pervin and Poras Balsara, and to Dawn Hollenbeck, for their valuable comments on portions of the manuscript.

MODERN MATHEMATICAL METHODS FOR PHYSICISTS AND ENGINEERS

The advent of powerful desktop computers has revolutionized scientific analysis and engineering design in fields as disparate as particle physics and telecommunications. *Modern Mathematical Methods for Physicists and Engineers* provides an up-to-date mathematical and computational education for students, researchers, and practicing engineers.

The author begins with a review of computation and then deals with a range of key concepts including sets, fields, matrix theory, and vector spaces. He then goes on to cover more advanced subjects such as linear mappings, group theory, and special functions. Throughout, he concentrates exclusively on the most important topics for the working physical scientist or engineer, with the aim of helping them to make intelligent use of the latest computational and analytical methods.

The book contains well over 400 homework problems and covers many topics not dealt with in other textbooks. It will be an ideal textbook for senior undergraduate and graduate students in the physical sciences and engineering, as well as a valuable reference for working engineers.

C. D. Cantrell received his Ph.D. from Princeton University in 1968. He taught at Swarthmore College from 1967 until 1973 and was a staff member at the Los Alamos National Laboratory from 1973 until 1979. Since then he has been at the University of Texas at Dallas, where he is Professor of Physics and Electrical Engineering, and Director of the Photonic Technology and Engineering Center. Professor Cantrell is a consultant for Alcatel USA and Ericsson and is a Fellow of the American Physical Society, the Optical Society of America, and the IEEE.

PUBLISHED BY THE PRESS SYNDICATE OF THE UNIVERSITY OF CAMBRIDGE The Pitt Building, Trumpington Street, Cambridge, United Kingdom

CAMBRIDGE UNIVERSITY PRESS

The Edinburgh Building, Cambridge CB2 2RU, UK 40 West 20th Street, New York, NY 10011-4211, USA 477 Williamstown Road, Port Melbourne, vic 3207, Australia Ruiz de Alarcón 13, 28014 Madrid, Spain Dock House, The Waterfront, Cape Town 8001, South Africa

© C. D. Cantrell 2000

This book is in copyright. Subject to statutory exception and to the provisions of relevant collective licensing agreements, no reproduction of any part may take place without the written permission of Cambridge University Press.

First published 2000 Reprinted 2002

Typeface Times Roman 10.5/13 pt. System LaTeX 2€ [TB]

A catalog record for this book is available from the British Library.

Library of Congress Cataloging in Publication Data

Cantrell, C. D. (Cyrus D.), 1940-

Modern mathematical methods for physicists and engineers / C. D.

Cantrell.

p. cm

Includes bibliographical references (p. -).

ISBN 0-521-59180-5 (hb). - ISBN 0-521-59827-3 (pbk.)

AND MAY NOT BE DISTRIBUTED AND SOLD ELSEWHERE.

1. Mathematics. I. Title.

QA37.2.C24 1999

510 - dc21

98-24761

CIP

ISBN 0 521 59180 5 hardback

ISBN 0 521 59827 3 paperback

This reprint edition is published with the permission of the Syndicate of the Press of the

University of Cambridge, Cambridge, England.

THIS EDITION IS LICENSED FOR DISTRIBUTION AND SALE IN THE PEOPLE'S REPUBLIC OF CHINA ONLY, EXCLUDING TAIWAN, HONG KONG AND MACAO

CONTENTS

Pref	ace			page xix
1	FOL	JNDA	TIONS OF COMPUTATION	1
	1.1	1		
	1.2	Repre	sentations of Numbers	2
		1.2.1	Integers	3
		1.2.2	Rational Numbers and Real Numbers	14
		1.2.3	Representations of Numbers as Text	17
		1.2.4	Exercises for Section 1.2	20
	1.3	Finite	Floating-point Representations	21
		1.3.1	Simple Cases	21
		1.3.2	Practical Floating-point Representations	25
			Approaching Zero or Infinity Gracefully	28
		1.3.4	Exercises for Section 1.3	30
	1.4	Floati	ng-point Computation	31
		1.4.1	Relative Error; Machine Epsilon	31
			Rounding	32
		1.4.3	Floating-point Addition and Subtraction	35
		1.4.4	Exercises for Section 1.4	36
	1.5	Propa	gation of Errors	37
		1.5.1	General Formulas	37
		1.5.2	Examples of Error Propagation	39
		1.5.3	Estimates of the Mean and Variance	41
		1.5.4	Exercises for Section 1.5	43
	1.6	Biblio	ography and Endnotes	45
		1.6.1	Bibliography	45
		1.6.2	Endnotes	46
2	SET	SAN	D MAPPINGS	47
	2.1	Introd	luction	47
	2.2	Basic	Definitions	49
		2.2.1	Sets	49
		2.2.2	Mappings	53
			Axiom of Choice	62
		2.2.4	Cartesian Products	62

viii CONTENTS

		2.2.5	Equivalence and Equivalence Classes	65
		2.2.6	Exercises for Section 2.2	67
	2.3	Union	, Intersection, and Complement	68
		2.3.1	Unions of Sets	68
		2.3.2	Intersections of Sets	69
		2.3.3	Relative Complement	70
			De Morgan's Laws	71
			Exercises for Section 2.3	71
	2.4	Infinit		72
			Basic Properties of Infinite Sets	72
		-837/450000	Induction and Recursion	73
			Countable Sets	76
			Countable Unions and Intersections	77
			Uncountable Sets	78
			Exercises for Section 2.4	80
	2.5		ed and Partially Ordered Sets	82
			Partial Orderings	82
			Orderings; Upper and Lower Bounds	83
			Maximal Chains	84
	200 000		Exercises for Section 2.5	84
	2.6	Biblio	graphy	85
3	EVA	LUAT	ION OF FUNCTIONS	86
3		LUAT	or ments at the second of the	86 86
3		Introd	or ments at the second of the	
3	3.1	Introd Sensit	uction	86
3	3.1	Introd Sensit 3.2.1	uction ivity and Condition Number	86 86
3	3.1	Introd Sensit 3.2.1 3.2.2	uction ivity and Condition Number Definitions	86 86 86
3	3.1	Introd Sensit 3.2.1 3.2.2 3.2.3	uction ivity and Condition Number Definitions Evaluation of Polynomials	86 86 86 87
3	3.1	Introd Sensit 3.2.1 3.2.2 3.2.3 3.2.4	uction ivity and Condition Number Definitions Evaluation of Polynomials Multiple Roots of Polynomials	86 86 86 87 89
3	3.1 3.2	Introd Sensit 3.2.1 3.2.2 3.2.3 3.2.4 Recurs	uction ivity and Condition Number Definitions Evaluation of Polynomials Multiple Roots of Polynomials Exercises for Section 3.2	86 86 86 87 89 91
3	3.1 3.2	Introd Sensit 3.2.1 3.2.2 3.2.3 3.2.4 Recurs 3.3.1	uction ivity and Condition Number Definitions Evaluation of Polynomials Multiple Roots of Polynomials Exercises for Section 3.2 sion and Iteration	86 86 87 89 91 92
3	3.1 3.2	Introd Sensit 3.2.1 3.2.2 3.2.3 3.2.4 Recurs 3.3.1 3.3.2	uction ivity and Condition Number Definitions Evaluation of Polynomials Multiple Roots of Polynomials Exercises for Section 3.2 sion and Iteration Finding Roots by Bisection	86 86 87 89 91 92 92
3	3.1 3.2	Introd Sensit 3.2.1 3.2.2 3.2.3 3.2.4 Recurs 3.3.1 3.3.2 3.3.3	uction ivity and Condition Number Definitions Evaluation of Polynomials Multiple Roots of Polynomials Exercises for Section 3.2 sion and Iteration Finding Roots by Bisection Newton-Raphson Method	86 86 87 89 91 92 92
3	3.1 3.2	Introd Sensit 3.2.1 3.2.2 3.2.3 3.2.4 Recurs 3.3.1 3.3.2 3.3.3 3.3.4	uction ivity and Condition Number Definitions Evaluation of Polynomials Multiple Roots of Polynomials Exercises for Section 3.2 sion and Iteration Finding Roots by Bisection Newton-Raphson Method Evaluation of Series	86 86 87 89 91 92 92 92
3	3.1 3.2 3.3	Introd Sensit 3.2.1 3.2.2 3.2.3 3.2.4 Recurs 3.3.1 3.3.2 3.3.3 3.3.4	uction ivity and Condition Number Definitions Evaluation of Polynomials Multiple Roots of Polynomials Exercises for Section 3.2 sion and Iteration Finding Roots by Bisection Newton-Raphson Method Evaluation of Series Exercises for Section 3.3 uction to Numerical Integration	86 86 87 89 91 92 92 92 95 97
3	3.1 3.2 3.3	Introd Sensit 3.2.1 3.2.2 3.2.3 3.2.4 Recurs 3.3.1 3.3.2 3.3.3 3.3.4 Introd	uction ivity and Condition Number Definitions Evaluation of Polynomials Multiple Roots of Polynomials Exercises for Section 3.2 sion and Iteration Finding Roots by Bisection Newton-Raphson Method Evaluation of Series Exercises for Section 3.3 uction to Numerical Integration Rectangle Rules	86 86 87 89 91 92 92 92 95 97
3	3.1 3.2 3.3	Introd Sensit 3.2.1 3.2.2 3.2.3 3.2.4 Recurs 3.3.1 3.3.2 3.3.3 3.3.4 Introd 3.4.1 3.4.2	uction ivity and Condition Number Definitions Evaluation of Polynomials Multiple Roots of Polynomials Exercises for Section 3.2 sion and Iteration Finding Roots by Bisection Newton-Raphson Method Evaluation of Series Exercises for Section 3.3 uction to Numerical Integration Rectangle Rules	86 86 87 89 91 92 92 92 95 97 99
3	3.1 3.2 3.3	Introd Sensit 3.2.1 3.2.2 3.2.3 3.2.4 Recurs 3.3.1 3.3.2 3.3.3 3.3.4 Introd 3.4.1 3.4.2 3.4.3	uction ivity and Condition Number Definitions Evaluation of Polynomials Multiple Roots of Polynomials Exercises for Section 3.2 sion and Iteration Finding Roots by Bisection Newton-Raphson Method Evaluation of Series Exercises for Section 3.3 uction to Numerical Integration Rectangle Rules Trapezoidal Rule	86 86 87 89 91 92 92 92 95 97 99
3	3.1 3.2 3.3	Introd Sensit 3.2.1 3.2.2 3.2.3 3.2.4 Recurs 3.3.1 3.3.2 3.3.3 3.3.4 Introd 3.4.1 3.4.2 3.4.3 3.4.4	uction ivity and Condition Number Definitions Evaluation of Polynomials Multiple Roots of Polynomials Exercises for Section 3.2 sion and Iteration Finding Roots by Bisection Newton-Raphson Method Evaluation of Series Exercises for Section 3.3 uction to Numerical Integration Rectangle Rules Trapezoidal Rule Local and Global Errors	86 86 87 89 91 92 92 92 95 97 99 101 102
3	3.1 3.2 3.3	Introd Sensit 3.2.1 3.2.2 3.2.3 3.2.4 Recurs 3.3.1 3.3.2 3.3.3 1ntrod 3.4.1 3.4.2 3.4.3 3.4.4 Solution	uction ivity and Condition Number Definitions Evaluation of Polynomials Multiple Roots of Polynomials Exercises for Section 3.2 sion and Iteration Finding Roots by Bisection Newton-Raphson Method Evaluation of Series Exercises for Section 3.3 uction to Numerical Integration Rectangle Rules Trapezoidal Rule Local and Global Errors Exercises for Section 3.4	86 86 87 89 91 92 92 92 95 97 99 101 102 102
3	3.1 3.2 3.3	Introd Sensit 3.2.1 3.2.2 3.2.3 3.2.4 Recurs 3.3.1 3.3.2 3.3.3 3.3.4 Introd 3.4.1 3.4.2 3.4.3 3.4.4 Solutio 3.5.1	uction ivity and Condition Number Definitions Evaluation of Polynomials Multiple Roots of Polynomials Exercises for Section 3.2 sion and Iteration Finding Roots by Bisection Newton-Raphson Method Evaluation of Series Exercises for Section 3.3 uction to Numerical Integration Rectangle Rules Trapezoidal Rule Local and Global Errors Exercises for Section 3.4 on of Differential Equations	86 86 87 89 91 92 92 92 95 97 99 101 102 102 105

CONTENTS

		3.5.4	Selected Finite-difference Methods	112
		3.5.5	Exercises for Section 3.5	118
	3.6	120		
4	GR	OUPS,	RINGS, AND FIELDS	121
	.4.1	Introd	uction	121
	4.2	Group	os	122
		4.2.1	Axioms	122
		4.2.2	Two-element Group	127
			Orbits and Cosets	130
			Cyclic Groups	136
		4.2.5	Dihedral Groups	141
			Cubic Groups	143
		4.2.7	Continuous Groups	143
		4.2.8	3 0	147
		4.2.9	Exercises for Section 4.2	149
	4.3	_	Homomorphisms	152
			Definitions and Basic Properties	152
			Normal Subgroups	158
			Direct Product Groups	162
		4.3.4		164
	4.4	*Symr	metric Groups	165
		(0.0) 0.00	Permutations	165
			Cayley's Theorem	167
		4.4.3	Cyclic Permutations	169
		4.4.4	Even and Odd Permutations	171
		4.4.5	Exercises for Section 4.4	173
	4.5		and Integral Domains	175
		4.5.1	Axioms and Examples	175
		4.5.2	1	179
			Rational Numbers	180
		4.5.4	*Ring Homomorphisms	181
		4.5.5	Exercises for Section 4.5	184
	4.6	Fields		184
		4.6.1	Axioms and Examples	184
		4.6.2	*Galois Fields	186
		4.6.3	Exercises for Section 4.6	189
	4.7	Biblio	graphy	189
5	VEC	CTOR	SPACES	191
	5.1	Introd	luction	191
	5.2	Basic	Definitions and Examples	193
		5.2.1	Axioms for a Vector Space	193
			Selected Pealizations of the Vector space Avions	104

		5.2.3	Vector Subspaces	201
		5.2.4	*Comments on Vector-space Axioms	205
		5.2.5	Exercises for Section 5.2	208
	5.3	Linear	Independence and Linear Dependence	211
		5.3.1	Definitions	211
		5.3.2	Basic Results on Linear Dependence	212
		5.3.3	Examples of Linear Independence	216
		5.3.4	Exercises for Section 5.3	219
	5.4	Bases	and Dimension	221
		5.4.1	Dimension of a Vector Space	221
		5.4.2	Selected Realizations of Vector-space Bases	225
		5.4.3	Vector-space Isomorphisms	228
		5.4.4	Gaussian Elimination and Linear Dependence	232
		5.4.5	Exercises for Section 5.4	237
	5.5		lementary Subspaces	239
		5.5.1	Vector Complements and Direct Sums	239
			Definition of Complementary Subspaces	240
		5.5.3	Dimensions of Complementary Subspaces	241
		5.5.4	Direct Sums of Vector Spaces	242
			Bases of Complementary Subspaces	243
			Examples of Direct Sums of Vector Spaces	244
			Exercises for Section 5.5	245
	5.6		ography and Endnotes	246
		5.6.1	Bibliography	246
		5.6.2	Endnotes	246
6	LIN	NEAR	MAPPINGS I	248
	6.1	Linea	r Mappings and their Matrices	248
		6.1.1	Basic Properties	248
		6.1.2	Matrix of a Linear Mapping	250
		6.1.3	Computation of Matrix Products	261
		6.1.4	Invariant Subspaces and Direct Sums	263
		6.1.5	Other Examples of Linear Mappings	265
		6.1.6	Exercises for Section 6.1	268
	6.2	Nons	ingular Linear Mappings	271
		6.2.1	Definitions and Basic Properties	271
		6.2.2	Change of Basis	275
		6.2.3	Permutation Matrices	277
		6.2.4	General Linear Group of a Vector Space	278
		6.2.5	Exercises for Section 6.2	278
	6.3	Singu	ılar Linear Mappings	281
		6.3.1	Singularity and Linear Dependence	281
		6.3.2	Visualization of Singular Linear Mappings	282

CONTENTS xi

		6.3.3	Null Space of a Linear Mapping	28.
		6.3.4	Other Examples of a Singular Linear Mappings	28
		6.3.5	Exercises for Section 6.3	28
	6.4	Introd	uction to Digital Filters	288
		6.4.1	Definitions	288
		6.4.2	Noise Amplification by Digital Filters	29
		6.4.3	Difference Operators	292
		6.4.4	Exercises for Section 6.4	298
	6.5	Trace	and Determinant	299
		6.5.1	Trace of a Linear Mapping	299
		6.5.2	Determinants	300
			Exercises for Section 6.5	309
	6.6		on of Linear Equations	310
			Basic Facts about Linear Equations	310
		6.6.2		312
			Computational Aspects of Gaussian Elimination	317
			LU and LDM T Decompositions	317
			Bases of the Range and Null Space	319
			Rank-nullity Theorem	32
		-	Exercises for Section 6.6	322
	6.7		lements of Null Space	324
			Quotient Space V/null [A]	324
		6.7.2		325
			Rank-nullity Theorem (Again)	327
			Right Inverses of a Linear Mapping	327
			Examples of Right Inverses	328
			Exercise for Section 6.7	330
	6.8	Biblio	graphy	330
7	LIN	IEAR	FUNCTIONALS	331
	7.1	Motiv	ation for Studying Functionals	331
	7.2	Dual S	Spaces	332
		7.2.1	Definitions	332
		7.2.2	Range and Null Space of a Linear Functional	334
		7.2.3	Exercises for Section 7.2	335
	7.3	Coord	linate Functionals	336
		7.3.1	Definitions	336
		7.3.2	Coordinate Functionals on \mathbb{F}^n	337
			Isomorphism of \mathcal{V}^* to \mathcal{V}	338
		7.3.4	Coordinate Functionals on Two-dimensional Euclidean Space	339
		7.3.5	Coordinate Functionals and the Reciprocal Lattice	341
		7.3.6	Isomorphism of V to V^{**}	345
		7.3.7	Exercises for Section 7.3	346

xii CONTENTS

	7.4	Annih	nilator of a Subspace	347
		7.4.1	Definitions	347
		7.4.2	Bases of the Annihilator	347
		7.4.3	Exercises for Section 7.4	348
	7.5	Other	Realizations of Dual Spaces	349
		7.5.1		349
		7.5.2	Dual of $\mathbb{F}^{\mathbb{Z}^+}$	349
		7.5.3	Boundary and Initial Conditions for Differential Equations	349
	7.6	Polyn	omial Interpolation	350
		7.6.1	Lagrangian Interpolation	350
		7.6.2	Exercises for Section 7.6	352
	7.7	Tenso	rs	352
		7.7.1	Definitions and Basic Properties	353
		7.7.2	Components of Second-rank Tensors	356
		7.7.3	the state of the second of the	358
		7.7.4	Tensors of Rank m	361
			Linear Mappings of Tensors	362
		7.7.6	Exercises for Section 7.7	365
8	INN	IER PI	RODUCTS AND NORMS	367
	8.1	Inner-	product Spaces	367
		8.1.1	Definitions	367
		8.1.2	Canonical Inner Products	369
		8.1.3	Metric Tensor	372
		8.1.4	Indefinite Inner Products	378
		8.1.5	Orthogonality	379
		8.1.6	Exercises for Section 8.1	383
	8.2	Geom	netry of Inner-product Spaces	384
		8.2.1	Pythagoras's Theorem	384
			Orthonormal Bases	392
			Orthogonal Polynomials	397
		8.2.4	Exercises for Section 8.2	403
	8.3	Projec	ction Methods	406
		8.3.1	Projection of a Vector onto a Subspace: Definition	406
		8.3.2	Orthogonal Projectors	407
			Orthogonal Complement	409
		8.3.4	Exercises for Section 8.3	416
	8.4	Least	-squares Approximations	417
		8.4.1	Motivation	417
		8.4.2		418
		8.4.3	Inequalities for Least-squares Approximations	419
		8.4.4	Approximation by Finite Fourier Sums	420
		8.4.5	Chebyshev Approximations	421

CONTENTS xiii

		8.4.6	Mapping a Function to its Fourier Coefficients	422
		8.4.7		423
	8.5	Discre	ete Fourier Transform	424
		8.5.1	Approximation of Fourier Coefficients	424
		8.5.2	Discrete Fourier Basis	425
		8.5.3	Periodic Extension	428
		8.5.4	Aliasing	430
		8.5.5	Sampling Theorem and Alias Mapping	433
		8.5.6	Exercise for Section 8.5	437
	8.6	Volum	ne of an m-Parallelepiped	437
			Parallelepipeds	437
		8.6.2	Recursive Definition of Volume	438
			Volume as a Determinant	438
			Determinant as a Volume Ratio	440
		8.6.5	Jacobian Determinant	441
			Exercise for Section 8.6	443
	8.7	Vecto	r and Matrix Norms	443
			Vector Norms	443
			Norm of a Linear Mapping	446
			Matrix Norms	450
			Norm of an Integral	453
			Exercises for Section 8.7	453
	8.8		Products and Linear Functionals	455
			Introduction	455
			Inner-product Mapping	456
			Inverse Inner-product Mapping	459
			Exercises for Section 8.8	464
	8.9	Biblio	ography and Endnotes	464
		8.9.1		465
		8.9.2	Endnotes	465
9	LIN	EAR	MAPPINGS II	466
	9.1	Dyad	ls	466
			Motivation	466
		9.1.2	Definition of a Dyad	466
		9.1.3	Dyadic Expansions	469
			Resolutions of the Identity Mapping	47
		9.1.5	Exercise for Section 9.1	473
	9.2	Trans	spose and Adjoint	473
			Transpose	473
			Adjoint	476
			Other Realizations of the Adjoint	480
			Properties of the Adjoint	483

XIV CONTENTS

		9.2.5	Hermitian and Self-adjoint Mappings	485
		9.2.6	Isometric and Unitary Mappings	487
		9.2.7	Exercises for Section 9.2	491
	9.3	Eigenva	llues and Eigenvectors	493
		9.3.1	Secular Equation	493
		9.3.2	Diagonalization of Hermitian Matrices	495
		9.3.3	Normal Linear Mappings	502
		9.3.4	Exercises for Section 9.3	504
	9.4	Singula	r-value Decomposition	507
		9.4.1		507
		9.4.2	Matrix Version of the Singular-value Decomposition	509
		9.4.3		511
		9.4.4		512
			Data Compression Using the SVD	514
			Exercises for Section 9.4	514
	9.5	Linear	Equations II	515
		9.5.1		515
			Diagonal Dominance	516
		9.5.3	Condition Number of the Linear-equation Problem	517
		9.5.4		520
	9.6		d Applications of Linear Equations	521
			The Linear Least-squares Problem	521
		9.6.2	Linear Difference Equations	523
		9.6.3		529
			Exercises for Section 9.6	530
	9.7	Bibliog	graphy	531
10	CON		ENCE IN NORMED VECTOR SPACES	532
	10.1		s and Norms	532
			Metric Spaces	532
			Normed Vector Spaces	534
			Examples of Metric and Normed Vector Spaces	536
			Open Sets	539
		10.1.5	Exercises for Section 10.1	541
	10.2			543
			Limit Points and Closed Sets	543
			Dense Sets and Separable Spaces	548
			Exercises for Section 10.2	552
	10.3		rgence of Sequences and Series	553
			Convergence of Sequences	553
			Numerical Sequences	558
			Numerical Series	560
		10.3.4	Exercises for Section 10.3	565

CONTENTS XY

	10.4	Strong	and Pointwise Convergence	566
		10.4.1	Strong Convergence	566
		10.4.2	Operators	570
		10.4.3	Sequences of Real-valued Functions	572
		10.4.4	Series of Real-valued Functions	575
		10.4.5	Exercises for Section 10.4	576
	10.5	Continu	uity	577
		10.5.1	Pointwise Continuity	577
		10.5.2	Uniform Continuity	580
	10.6	Best Ap	pproximations in the Maximum and Supremum	
		Norms		581
		10.6.1	Best Approximations in the Maximum Norm	583
			Best Approximations in the Supremum Norm	589
		10.6.3	Exercises for Section 10.6	592
	10.7	Hilbert	and Banach Spaces	594
			Survey of Complete Metric Vector Spaces	594
		10.7.2	Complete Orthonormal Sets	597
		10.7.3	Orthogonal Series	599
		10.7.4	Practical Aspects of Fourier Series	603
			Orthogonal-polynomial Expansions	610
		10.7.6	Exercises for Section 10.7	613
	10.8	Bibliog	graphy	615
11	GRO	UP RE	PRESENTATIONS	616
	11.1	Prelimi	inaries	616
		11.1.1	Background	616
		11.1.2	Symmetry-adapted Functions	618
		11.1.3	Partner Functions	619
		11.1.4	Exercises for Section 11.1	621
	11.2	Reduci	bility of Representations	621
		11.2.1	Invariant Subspaces and Irreducibility	622
		11.2.2	Schur's Lemma	623
		11.2.3	Eigenvectors of Invariant Operators	627
		11.2.4	Exercises for Section 11.2	629
	11.3	Unitari	ity and Orthogonality	630
		11.3.1	Consequences of the Rearrangement Theorem	630
		11.3.2	Unitary Representations	631
			Orthogonality Theorems	633
		11.3.4	Product Relation for Characters	638
		11.3.5	Reduction of Unitary Representations	640
		11.3.6	Construction of Character Tables	643
		11.3.7	Characters of Kronecker Products	644
		11.3.8	Exercises for Section 11.3	646

11.4	Two-din	nensional Rotation Group	641
	11.4.1	Representation Space for $SO(2)$	648
	11.4.2	Representations of $SO(2)$	649
	11.4.3	Completeness Relation for $\{e^{-im\theta}\}$	650
	11.4.4	Exercise for Section 11.4	652
11.5	Symmet	ry and the One-dimensional Wave Equation	652
	11.5.1	Boundary Conditions and Symmetry	652
	11.5.2	Wave Equation for a Vibrating String	653
	11.5.3	Boundary Conditions for the One-dimensional Wave	
		Equation	653
	11.5.4	Form Invariance of the Wave Equation	653
	11.5.5	Invariance of the Wave Equation Under Translations	656
	11.5.6	Invariance of the Wave Equation Under Lorentz	
		Transformations	656
	11.5.7	D'Alembert's Solution of the Wave Equation	657
	11.5.8	Solution for a String of Infinite Length	658
	11.5.9	Solution for a String of Finite Length	659
	11.5.10	Exercises for Section 11.5	661
11.6	Discrete	Translation Groups	662
	11.6.1	Motivation	662
	11.6.2	Invariance Under the Discrete Translation Group	662
	11.6.3	Discrete-shift-invariant Digital Filters	663
	11.6.4	Representations of the Discrete Translation Group	664
	11.6.5	Discrete-time Transfer Function	665
	11.6.6	Exercises for Section 11.6	668
11.7	Continu	ous Translation Groups	669
	11.7.1	Translation Group of the Real Line	669
	11.7.2	Irreducible Representations of $T(\mathbb{R})$	669
	11.7.3	$\{\psi_k\}$ as Momentum Eigenfunctions	671
	11.7.4	Representation of $T(\mathbb{E}^2)$ Carried by ψ_k	672
	11.7.5	Translation Group of Euclidean n-space	673
	11.7.6	Exercises for Section 11.7	676
11.8	Fourier '	Transforms	676
	11.8.1	Fourier Transform in One Dimension	676
	11.8.2	Completeness Relation for the $\{\psi_k\}$	677
	11.8.3	Fourier Transforms in n-dimensional Euclidean	
		Space	678
	11.8.4	Poisson Sum Formula	679
	11.8.5	Exercises for Section 11.8	679
11.9	Linear,	Shift-invariant Systems	680
	11.9.1	Continuous-time-shift Invariance	680
	11.9.2	Continuous-time Transfer Function	681
	1193	Exercises for Section 11 9	683