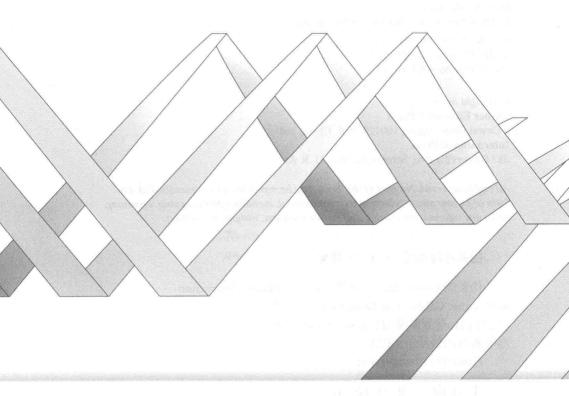
**SMM 13** Surveys of Modern Mathematics

# **Gauss-Manin Connection in Disguise:** Calabi-Yau Modular Forms

Hossein Movasati

伪装的 Gauss-Manin 联络



## Gauss-Manin Connection in Disguise:

Calabi-Yau Modular Forms

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WEIZHIANG DE Gauss-Manin LIANLUO

Hossein Movasati

With Appendices by Khosro M. Shokri and Carlos Matheus





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Centre for Mathematics and its Applications Mathematical Sciences Institute Australian National University Canberra, ACT 0200, Australia To my parents Rogayeh and Ali, and my family Sara and Omid

#### **Preface**

The guiding principle in this monograph is to develop a theory of (Calabi-Yau) modular forms parallel to the classical theory of (elliptic) modular forms. It is originated from many period manipulations of the B-model Calabi-Yau variety of mirror symmetry in Topological String Theory and the earlier works of the author in which the theory of (quasi) modular forms is introduced using a larger moduli space of elliptic curves, and the Ramanujan differential equations between Eisenstein series have been derived from the corresponding Gauss-Manin connection. We have in mind an audience with a basic knowledge of Complex Analysis, Differential Equations, Algebraic Topology and Algebraic Geometry. Although the text is purely mathematical and no background in String Theory is required, some of our computations are inspired by mirror symmetry, and so the reader who wishes to explore the motivations, must go to the original Physics literature. The text is mainly written for two primary target audiences: experts in classical modular and automorphic forms who wish to understand the q-expansions of physicists derived from Calabi-Yau threefolds, and mathematicians in enumerative Algebraic Geometry who want to understand how mirror symmetry counts rational curves in compact Calabi-Yau threefolds. Experts in modular forms are warned that they will not find so much Number Theory in the present text, as this new theory of modular forms lives its infancy, and yet many problems of complex analysis nature are open. We have still a long way to deal with more arithmetic oriented questions. For our purpose we have chosen a particular class of such a-expansions arising from the periods of a Calabi-Yau threefold called mirror quintic, and in general, periods which satisfy fourth-order differential equations. The applications of classical modular forms are huge and we are guided by the fact that this new type of modular forms might have similar applications in the near future, apart from counting rational curves and Gromov-Witten invariants. The main goal is to describe in detail many analogies and differences between classical modular forms and those treated here. The present text is a complement to the available books on the mathematical aspects of mirror symmetry such as "Mirror Symmetry and Algebraic Geometry" of D. A. Cox and S. Katz and "Mirror Symmetry" of C. Voisin. We hope that our text makes a part of mirror symmetry, which is relevant to Number Theory, more accessible to mathematicians.

viii

Hossein Movasati December 2016 Rio de Janeiro, RJ, Brazil

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## Frequently used notations

 $(\mathbb{C}^n,0)$ 

k, k̄ M <sup>tr</sup>	A field of characteristic zero and its algebraic closure. The transpose of a matrix $M$ . We also write $M = [M_{ij}]$ , where $M_{ij}$ is the $(i,j)$ entry of $M$ . The indices $i$ and $j$ always count the rows and columns, respectively. The dual of an $R$ -module $V$ , where $R$ is usually the ring $\mathbb Z$ or the field $k$ . We always write a basis of a free $R$ -module of rank $r$ as a $r \times 1$ matrix. For a basis $\delta$ of $V$ and $\alpha$ of $V^{\vee}$ we denote by
	$[\boldsymbol{\delta},\boldsymbol{\alpha}^{tr}] := [\alpha_j(\delta_i)]_{i,j}$
	the corresponding $r \times r$ matrix.
d	The differential operator or a natural number, being clear in the text which one we mean.
X	A mirror quintic Calabi-Yau threefold, mirror quintic for short, or an elliptic curve defined over the field k, being clear in the
	text which we mean, §3.1. We will also use $X$ as one of the Yamaguchi-Yau variables in §2.17. Another usage of $X$ is as a fundamental system of a linear differential equation, §7.4.
X(k)	The set of k-rational points of $X$ defined over the field k. In particular for $k \subset \mathbb{C}$ , $X(\mathbb{C})$ is the underlying complex manifold of $X$ . Sometimes, for simplicity we write $X = X(\mathbb{C})$ , being clear in the context that $X$ is a complex manifold.
$\omega, \eta$	A differential 3-form on $X$ . In many cases it is a holomorphic $(3,0)$ -form.
$H_3(X,\mathbb{Z})$	The third homology of $X = X(\mathbb{C})$ .
$\delta_i, i = 1, 2, 3, 4$	A symplectic basis of $H_3(X,\mathbb{Z})$ .
T	Moduli of enhanced mirror quintics over k, §2.3.
S	A moduli of mirror quintics over k, §3.2.
$\mathscr{O}_{T},\mathscr{O}_{S}$	The k-algebra of regular functions on T and S, $T = \operatorname{Spec}(\mathscr{O}_T)$ , etc.

A small neighborhood of 0 in  $\mathbb{C}^n$ .

 $\Phi, \Psi$ 

 $t_0, i = 0, \dots, 9$ Regular functions in T, §3.2, §3.6. Vector fields on T.  $\Omega_{T}^{i}$ The  $\mathcal{O}_{\mathsf{T}}$ -module of differential *i*-forms on  $\mathsf{T}$ .  $X \to T$ , X/TThe universal family of enhanced mirror quintics. A single variety is denoted by X, §3.6.  $X_t, t \in T$ A fiber of  $X \to T$ .  $H_{\mathrm{dR}}^*(X)$ Algebraic de Rham cohomology, §3.6.  $H_{\mathrm{dR}}^*(X/T)$ Relative algebraic de Rham cohomology, §3.6.  $F^*H^*_{\mathrm{dR}}(X)$ The pieces of Hodge filtration, §3.6.  $F^*H^*_{dR}(X/T)$ The pieces of Hodge filtration, §3.6. A basis of  $H_3(X)$  or  $H^3(X/T)$ , §2.3.  $\alpha_i, i = 1, ..., 4$ The intersection form in de Rham cohomology and singular ho- $\langle \cdot, \cdot \rangle$ mology, §3.4, §4.1.  $\delta^{\mathsf{pd}} \in H^3_{\mathsf{dR}}(X)$ The Poincaré dual of  $\delta \in H_3(X,\mathbb{Z})$ , §4.1.

$$\Phi := \begin{pmatrix} 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 \\ 0 & -1 & 0 & 0 \\ -1 & 0 & 0 & 0 \end{pmatrix}, \quad \Psi := \begin{pmatrix} 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ -1 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 \end{pmatrix} \tag{0.1}$$

G,g An algebraic group and its element, §3.10. Lie(G), g The Lie algebra of G and its element, §3.10.  $g_i, i = 1, ..., 6$ A parametrization of  $g \in G$ , §3.10. Gauss-Manin connection, §3.3, §3.8. A The Gauss-Manin connection matrix, §3.3, §3.8. Y Yukawa coupling, §2.3.  $E_k$ Eisenstein series of weight k, §2.5 The derivation  $z \frac{\partial}{\partial z}$ , §2.7, or a special period matrix, §4.12.  $M_0, M_1$ Monodromy matrices, §2.7. Γ The monodromy group, §2.7  $\mathbb{H}$ Upper half plane or the monodromy covering, §4.6. τ The canonical coordinate of the upper half plane or a special period matrix, §4.2.  $\tau_i$ , i = 0, 1, 2, 3Meromorphic functions on  $\mathbb{H}$ , §2.10, §10.2.  $\theta_i$ , i = 0, 1, 2, 3Meromorphic functions on  $\mathbb{H}$ , §4.12, §10.2.  $\mathsf{F}_g^{\mathrm{alg}},\mathsf{F}_g^{\mathrm{non}},\mathsf{F}_g^{\mathrm{hol}}$ Genus g topological string partition functions, §2.13. A fourth-order linear differential equations, §2.15. Holomorphic and logarithmic solutions of L = 0, §2.7, §7.1.  $\psi_0, \psi_1$ Particular solutions of L=0 and their derivatives, §2.7, §7.4. We  $x_{ij}$ denote by  $X := [x_{ij}]$  the corresponding matrix. General solutions of L = 0 and their derivatives, §4.15.  $y_{ij}$ A linear system attached to L = 0, §7.3. A $a_i(z)$ Coefficients of L, §2.15. Expressions in terms of the solutions of L, §2.15.  $X, U, V_1, V_2, V_3$ Yamaguchi-Yau variables, §2.17, §6.1, §8.4.

P	Period map or period matrix, §4.1.
П	Generalized period domain, §4.4.
F G F	Intersection matrices \$7.4

Intersection matrices, §7.4. F, G, E

The Euler number of the underlying Calabi-Yau threefolds of L=X

0, §7.3.

 $h^{21}$ The (2,1) Hodge number of the underlying Calabi-Yau threefolds of L=0. The text mainly deals with  $h^{21}=1$ .

## Online supplemental items

Many arguments and proofs of the present text rely on heavy computer computations. For this purpose, we have used Singular, [GPS01], a computer programming language for polynomial computations. Throughout the text I have used notations in the form [Supp Item x], where x=1, 2, 3, etc. Each of these notations refers to a supplemental item, such as computer data or code, etc., that can be accessed online from my web page:

http://w3.impa.br/~hossein/singular/GMCD-MQCY3-SuppItems.html

The web page serves as a hot-linked index to all of this book's online supplemental items. These supplemental items are mainly for two purposes. First, they are mainly for the reader who does not want to program by her or himself and wants to check the statements using our computer codes. Second, we only present a small amount of computer data in the text, and the reader can use the supplemental item in order to access to more data, for instance more coefficients of a q-expansion of a series. We have also written a library in Singular [Supp Item 1] which has been useful for our computations.

## **Contents**

1	Intro	oduction	1
	1.1	What is Gauss-Manin connection in disguise?	3
	1.2	Why mirror quintic Calabi-Yau threefold?	4
	1.3	How to read the text?	5
	1.4	Why differential Calabi-Yau modular form?	5
2	Sum	mary of results and computations	7
	2.1	Mirror quintic Calabi-Yau threefolds	7
	2.2	Ramanujan differential equation	8
	2.3	Modular vector fields	9
	2.4	Geometric differential Calabi-Yau modular forms	11
	2.5	Eisenstein series	12
	2.6	Elliptic integrals and modular forms	14
	2.7	Periods and differential Calabi-Yau modular forms, I	15
	2.8	Integrality of Fourier coefficients	17
	2.9	Quasi- or differential modular forms	18
	2.10	Functional equations	19
	2.11	Conifold singularity	21
		The Lie algebra $\mathfrak{sl}_2$	22
	2.13	BCOV holomorphic anomaly equation, I	23
		Gromov-Witten invariants	24
	2.15	Periods and differential Calabi-Yau modular forms, II	25
	2.16	BCOV holomorphic anomaly equation, II	28
	2.17	The polynomial structure of partition functions	29
	2.18	Future developments	30
2	N/L - 3	-1! -6 d	31
3		uli of enhanced mirror quintics	
	3.1	What is mirror quintic?	
	3.2	Moduli space, I	
	3.3	Gauss-Manin connection, I	
	3.4	Intersection form and Hodge filtration	34

xii Contents

	3.5	A vector field on S	35
	3.6	Moduli space, II	35
	3.7	The Picard-Fuchs equation	36
	3.8	Gauss-Manin connection, II	37
	3.9	Proof of Theorem 2	39
		Algebraic group	39
		Another vector field	41
		Weights	42
		A Lie algebra	43
4	Торо	ology and periods	45
	4.1	Period map	45
	4.2	τ-locus	46
	4.3	Positivity conditions	48
	4.4	Generalized period domain	49
	4.5	The algebraic group and $\tau$ -locus	50
	4.6	Monodromy covering	51
	4.7	A particular solution	52
	4.8	Action of the monodromy	52
	4.9	The solution in terms of periods	54
	4.10	Computing periods	55
	4.11	Algebraically independent periods	57
	4.12	θ-locus	58
	4.13	The algebraic group and the $\theta$ -locus	60
	4.14	Comparing $\tau$ and $\theta$ -loci	61
	4.15	All solutions of $R_0$ , $\check{R}_0$	62
		Around the elliptic point	62
	4.17	Halphen property	63
		Differential Calabi-Yau modular forms around the conifold	64
	4.19	Logarithmic mirror map around the conifold	65
		Holomorphic mirror map	67
5	Forn	nal power series solutions	69
	5.1	Singularities of modular differential equations	69
	5.2	q-expansion around maximal unipotent cusp	70
	5.3	Another q-expansion	71
	5.4	q-expansion around conifold	72
	5.5	New coordinates	73
	5.6	Holomorphic foliations	74
6	Торо	ological string partition functions	75
	6.1	Yamaguchi-Yau's elements	75
	6.2	Proof of Theorem 8	76
	6.3	Genus 1 topological partition function	77
	6.4	Holomorphic anomaly equation	78

Contents	xiii

	6.5	Proof of Proposition 1	80
	6.6	The ambiguity of $F_g^{alg}$	81
	6.7	Topological partition functions $F_g^{alg}$ , $g = 2, 3 \dots$	82
	6.8	Topological partition functions for elliptic curves	82
7	Holo	omorphic differential Calabi-Yau modular forms	85
	7.1	Fourth-order differential equations	85
	7.2	Hypergeometric differential equations	86
	7.3	Picard-Fuchs equations	87
	7.4	Intersection form	89
	7.5	Maximal unipotent monodromy	91
	7.6	The field of differential Calabi-Yau modular forms	92
	7.7	The derivation	94
	7.8	Yukawa coupling	94
	7.9	q-expansion	95
0	TA.T	La	97
8		-holomorphic differential Calabi-Yau modular forms	97
	8.1		-
	8.3	Anti-holomorphic derivation	
	8.4	Yamaguchi-Yau elements	
	8.5	Hypergeometric cases	
	0.5	Hypergeometric cases	105
9	BCC	OV holomorphic anomaly equation	105
	9.1	Genus 1 topological partition function	
	9.2	The covariant derivative	
	9.3	Holomorphic anomaly equation	108
	9.4	Master anomaly equation	108
	9.5	Algebraic anomaly equation	109
	9.6	Proof of Theorem 9	110
	9.7	A kind of Gauss-Manin connection	111
	9.8	Seven vector fields	
	9.9	Comparison of algebraic and holomorphic anomaly equations	
	9.10		
	9.11	Structure of the ambiguity	116
10	0.1	11.87	110
10		abi-Yau modular forms	
		Classical modular forms	
		A general setting	
	10.3	The algebra of Calabi-Yau modular forms	121
11	Prol	blems	125
		Vanishing of periods	
		Hecke operators	
		Maximal Hodge structure	
		Monodromy	
			/

xiv Contents

	11.5 Torelli problem       129         11.6 Monstrous moonshine conjecture       130         11.7 Integrality of instanton numbers       131         11.8 Some product formulas       132         11.9 A new mirror map       133         11.10Yet another coordinate       135         11.11Gap condition       136         11.12Algebraic gap condition       137         11.13Arithmetic modularity       140
A	Second-order linear differential equations
1.8	A.1 Holomorphic and non-holomorphic quasi-modular forms
	A.2 Full quasi-modular forms
B	Metric
	B.1 Poincaré metric
	B.2 Kähler metric for moduli of mirror quintics
C	Integrality properties
	Integrality properties HOSSEIN MOVASATI, KHOSRO M. SHOKRI
	C.1 Introduction
	C.2 Dwork map
	C.3 Dwork lemma and theorem on hypergeometric functions 156
	C.4 Consequences of Dwork's theorem
	C.5 Proof of Theorem 13, Part 1
	C.6 A problem in computational commutative algebra
	C.7 The case $n = 2$
	C.8 The symmetry
	C.9 Proof of Theorem 13, Part 2
	C.10 Computational evidence for Conjecture 1
	C.11 Proof of Corollary 1
D	Kontsevich's formula
	Kontsevich's formula  Carlos Matheus
	D.1 Examples of variations of Hodge structures of weight <i>k</i> 164
	D.2 Lyapunov exponents
	D.3 Kontsevich's formula in the classical setting
	D.4 Kontsevich's formula in Calabi-Yau 3-folds setting
	D.5 Simplicity of Lyapunov exponents of mirror quintics 173
	References