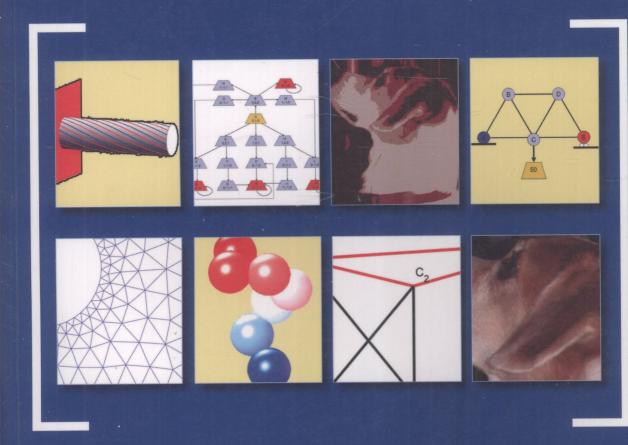
Scientific Computing WITH CASE STUDIES



Dianne P. O'Leary

Scientific Computing WITH CASE STUDIES

Dianne P. O'Leary

University of Maryland College Park, Maryland





sian.

Society for Industrial and Applied Mathematics
Philadelphia

Copyright © 2009 by the Society for Industrial and Applied Mathematics and the Mathematical Programming Society

10987654321

All rights reserved. Printed in the United States of America. No part of this book may be reproduced, stored, or transmitted in any manner without the written permission of the publisher. For information, write to the Society for Industrial and Applied Mathematics, 3600 Market Street, 6th Floor, Philadelphia, PA, 19104-2688 USA.

Trademarked names may be used in this book without the inclusion of a trademark symbol. These names are used in an editorial context only; no infringement of trademark is intended.

MATLAB is a registered trademark of The MathWorks, Inc. For MATLAB product information, please contact The MathWorks, Inc., 3 Apple Hill Drive, Natick, MA 01760-2098 USA, 508-647-7000, Fax: 508-647-7101, info@mathworks.com, www.mathworks.com.

Mathematica is a registered trademark of Wolfram Research, Inc.

Maple is a registered trademark of Waterloo Maple, Inc.

The images in Figure 1.1 were taken from http://nightglow.gsfc.nasa.gov/eric_journal_files/sydney_bridge.jpg and http://www.cpsc.gov/cpscpub/prerel/prhtml07/07267a.jpg

Figure 26.1 (http://www.myrmecos.net/insects/Tribolium1.html) is owned by Alex Wild.

Figures 11.1 and 11.2 were taken by Timothy O'Leary.

Library of Congress Cataloging-in-Publication Data

O'Leary, Dianne P.

Scientific computing with case studies / Dianne P. O'Leary.

p. cm.

Includes bibliographical references and index.

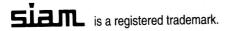
ISBN 978-0-898716-66-5

1. Mathematical models--Data processing--Case studies. I. Title.

QA401.Q44 2008

510.285--dc22

2008031493



To Gene H. Golub, my first research mentor.

To my parents, Raymond and Anne Prost.

To my husband, Timothy.

To my children, Theresa, Thomas, and Brendan.

With love.

□

Preface

A master carpenter does not need to know how her hammer was designed or what Newton's laws say about the force that the hammer applies. But she does need to know how to use the hammer, when to use a ball-peen hammer instead, and what to do when things go wrong, for example, when a nail bends as it is driven.

We take the same viewpoint in this book. Although there are fascinating stories to tell in the details of how basic numerical algorithms are designed and how they operate, we view them as tools in our virtual toolbox, discussing the innards just enough to be able to master their uses. Instead we focus on how to choose the most appropriate algorithm, how to make use of it, how to evaluate the results, and what to do when things go wrong.

This viewpoint frees us to explore many diverse applications of our tools, and through such case studies we practice the analysis and experimentation that are the mainstays of computational science.

The reader should have background knowledge equivalent to a first course in scientific computing or numerical analysis. Excellent textbooks for learning this information include those by Michael Heath [71], Cleve Moler [108], and Charles Van Loan [148].

Examples and illustrations use the MATLAB® programming language. Standard MATLAB functions provide us with our basic numerical algorithms, and the graphics interface is quite useful. For some problems, we make use of some of the MATLAB toolboxes, in particular, the Optimization Toolbox. If you do not have access to MATLAB, the basic numerical algorithms can also be obtained from NETLIB and other sources noted in the text. Sample programs for each case study are available at the website

www.cs.umd.edu/users/oleary/SCCS/

No single book can give a computational scientist all of the background needed for a career. In fact, computational science is primarily a collaborative enterprise, since it is rare that a single individual has all of the computational and scientific background necessary to complete a project. My hope is that this particular slice of knowledge will prove useful in your work and will lead you to further study, exciting applications, and productive collaborations.

I'm grateful to my many mentors, collaborators, and students, who through their probing questions forced me to seek deeper understanding and clearer explanations. May you too be blessed with good colleagues.

xiv Preface

Notes to Students

This book is written as a textbook for a second course in scientific computing, so it assumes that you have had a semester (or equivalent) of background using a standard textbook such as that by Heath [71], Moler [108], Van Loan [148], or equivalent. The Basics box at the beginning of each unit tells you what part of this material you might want to review in preparation for the unit. The Mastery box is a checklist of points to master in working through the unit.

The basic premise behind this book is that people learn by doing. Therefore, the book is best read with a pencil, paper, and MATLAB window close at hand. Challenges are sprinkled throughout the text, and they are meant be worked as they are encountered, or at least before the end of the chapter. Answers are provided for most challenges at

```
www.cs.umd.edu/users/oleary/SCCS/
```

There you can see examples of how someone else worked through the challenges. Mastery will be best if the answers are used to verify and refine your own approach to the problem. Merely reading the answer, though tempting, is (unfortunately) no substitute for trying to work the challenge on your own.

Pointers give important information and references to additional literature and software. I hope the content of this book leads you to want to learn more about scientific computing.

Notes to Instructors

The material in this book has been used for a semester and a half in a graduate level course in the applied mathematics program at the University of Maryland.

- I lecture from the introductory material in each unit, with material from the Case Studies used to occasionally provide extra information and motivation. Students can become quite passionate about some of the Case Studies, especially the more visual ones such as the image deblurring problem (Chapter 6), the data clustering problem (Chapter 11), and the epidemiology models (Chapter 19 and 21).
- For quizzes and exams, I derive problems from the Mastery points at the beginning of each unit.
- If possible, I like to allow "laboratory time" in class for students to work on some of the Challenges. The opportunity to see how other people solve problems is helpful even to the best students. This is especially true if, as at the University of Maryland, the students in this course come from backgrounds in mathematics, computer science, and engineering. This provides a remarkably diverse set of viewpoints on the material and enriches the dialog.
- Many of the Case Studies were originally homeworks.
- For a term project, I often ask students to develop a Case Study, using the tools
 presented in the course to solve a problem in their application area. Such projects can
 then be adapted for use in later terms. My students Nargess Memarsadeghi, David
 A. Schug, and Yalin E. Sagduyu developed particularly interesting case studies, and
 adapted versions of them are included here.

Preface xv

• There are not many unsolved exercises in this book. In the age of the Internet, there are very few textbook problems for which solutions cannot be found somewhere, and providing solutions here at least puts all students on equal footing. Some unsolved exercises and Case Studies are available on the book's website, and I would be grateful for your contribution of additional ones to post there.

There is a great deal of flexibility in choice and ordering of units, except that the optimization unit should be covered before nonlinear equations, and dense matrix computations should be discussed before optimization. The first six units form the syllabus for a one semester course at Maryland, while the final one is combined with a textbook in numerical solution of partial differential equations for the second semester.

Acknowledgments

I am grateful for the help of many, including the following:

 Computing in Science and Engineering, published by the American Institute of Physics and the IEEE Computer Society, for permission to include chapters derived from the case studies published there: Chapters

```
1 (Vol. 8, No. 5, 2006, pp. 86–90),
3 (Vol. 8, No. 3, 2006, pp. 86–89),
4 (Vol. 7, No. 6, 2006, pp. 78–80),
6 (Vol. 5, No. 3, 2003, pp. 82–85),
7 (Vol. 8, No. 2, 2006, pp. 66-70),
8 (Vol. 5, No. 6, 2003, pp. 60–63),
11 (Vol. 5, No. 5, 2003, pp. 54–57),
12 (Vol. 6, No. 5, 2004; pp. 60–62),
13 (Vol. 6, No. 3, 2004, pp. 66–69),
14 (Vol. 7, No. 1, 2005, pp. 56–59),
15 (Vol. 7, No. 2, 2005, pp. 60–62),
17 (Vol. 9, No. 1, 2007, pp. 72–76),
18 (Vol. 6, No. 6, 2004; pp. 58–62),
19 (Vol. 6, No. 1, 2004, pp. 68-70),
21 (Vol. 6, No. 2, 2004, pp. 50-53),
22 (Vol. 5, No. 4, 2003, pp. 68–71),
23 (Vol. 7, No. 3, 2005, pp. 20–23),
26 (Vol. 9, No. 2, 2007, pp. 96–99),
27 (Vol. 7, No. 5, 2005, pp. 62-67),
28 (Vol. 8, No. 4, 2006, pp. 74–78),
29 (Vol. 6, No. 4, 2004, pp. 74–76),
30 (Vol. 7, No. 6, 2005, pp. 74–77),
31 (Vol. 7, No. 4, 2005, pp. 68–70),
32 (Vol. 8, No. 5, 2006, pp. 86-90).
```

- Jennifer Stout, Lead Editor of Computing in Science and Engineering, who patiently
 edited the case studies.
- Mei Huang, for her work on Chapter 18.

XVi Preface

• Jin Hyuk Jung, who as a teaching assistant wrote supplementary lecture notes from which some of the figures were taken, particularly those in Chapters 5, 9, and 24.

- Nargess Memarsadeghi, David Schug, and Yalin Sagduyu, whose term projects were so interesting that they led to case studies included here.
- Staff in the Technical Support Department at The MathWorks, for discussions about the sources of overhead in MATLAB interpreted and compiled instructions.
- James G. Nagy, a master teacher, who inspired the case studies and coauthored the first one.
- The National Science Foundation and the National Institute of Standards and Technology, for supporting my research into many of the problems discussed in the case studies.
- Timothy O'Leary for the photo of Charlie in Chapter 11.
- Students in the University of Maryland courses Scientific Computing I and II: (especially Samuel Lamphier) for their patience and debugging as the notes were developed.
- G. W. Stewart, for his example of clearly written textbooks and for the privilege of being his colleague at Maryland.
- Howard Elman, David Gilsinn, Vadim Kavalerov, Tamara Kolda, Samuel Lamphier, K.J.R. Liu, Brendan O'Leary, Bert Rust, Simon P. Schurr, Elisa Sotelino, G. W. Stewart, and Layne T. Watson for helpful comments.

The images in Figure 1.1 were taken from http://nightglow.gsfc.nasa.gov/eric_journal_files/sydney_bridge.jpgandhttp://www.cpsc.gov/cpscpub/prerel/prhtml07/07267a.jpg,and that in Figure 26.1 (http://www.myrmecos.net/insects/Tribolium1.html) is owned by Alex Wild.

Contents

Pro	Preface		
I	Prelin	ninaries: Mathematical Modeling, Errors, Hardware, and Software	1
1	Errors and Arithmetic		
	1.1	Sources of Error	5
	1.2	Computational Science and Scientific Computing	7
	1.3	Computer Arithmetic	8
	1.4	How Errors Propagate	14
	1.5	Mini Case Study: Avoiding Catastrophic Cancellation	15
	1.6	How Errors Are Measured	17
	1.7	Conditioning and Stability	20
2	Sensitivity Analysis: When a Little Means a Lot		23
	2.1	Sensitivity Is Measured by Derivatives	23
	2.2	Condition Numbers Give Bounds on Sensitivity	24
	2.3	Monte Carlo Experiments Can Estimate Sensitivity	27
	2.4	Confidence Intervals Give Insight into Sensitivity	28
3	Com	puter Memory and Arithmetic:	31
	A Lo	ook Under the Hood	
	3.1	A Motivating Example	31
	3.2	Memory Management	32
	3.3	Determining Hardware Parameters	34
	3.4	Speed of Computer Arithmetic	36
4	Design of Computer Programs:		39
		ring Your Legacy	
	4.1	Documentation	39
	4.2	Software Design	41
	4.3	Validation and Debugging	42
	4.4	Efficiency	43

viii Contents

II	Dense	Matrix Computations	45
5	Mati	rix Factorizations	49
	5.1	Basic Tools for Matrix Manipulation: The BLAS	50
	5.2	The LU and Cholesky Decompositions	52
	5.3	The QR Decomposition	57
		5.3.1 QR Decomposition by Givens Rotations	58
		5.3.2 QR by Gram–Schmidt Orthogonalization	60
		5.3.3 Computing and Using the QR Decomposition	62
		5.3.4 Mini Case Study: Least Squares Data Fitting	65
	5.4	The Rank-Revealing QR Decomposition (RR-QR)	67
	5.5	Eigendecomposition	68
		5.5.1 Computing the Eigendecomposition	68
		5.5.2 Mini Case Study: Stability Analysis of a Linear Control System	71
		5.5.3 Other Uses for Eigendecompositions	72
	5.6	The Singular Value Decomposition (SVD)	73
		5.6.1 Computing and Using the SVD	73
		5.6.2 Mini Case Study: Solving Ill-Conditioned and Rank-Deficient	
		Least Squares Problems	74
	5.7	Some Matrix Tasks to Avoid	76
	5.8	Summary	78
6 7	(coar	e Study: Image Deblurring: I Can See Clearly Now authored by James G. Nagy) e Study: Updating and Downdating Matrix Factorizations: mange in Plans	81 87
8	Case	e Study: The Direction-of-Arrival Problem	97
Ш	Optin	nization and Data Fitting	105
9	Num	nerical Methods for Unconstrained Optimization	109
	9.1	Fundamentals for Unconstrained Optimization	109
		9.1.1 How Do We Recognize a Solution?	
		9.1.2 Geometric Conditions for Optimality	
		9.1.3 The Basic Minimization Algorithm	
	9.2	The Model Method: Newton	
	7.2	9.2.1 How Well Does Newton's Method Work?	
		9.2.2 Making Newton's Method Safe: Modified Newton Methods	
	9.3	Descent Directions and Backtracking Linesearches	
	9.3	Trust Regions	
	9.4	Alternatives to Newton's Method	
	9.3	9.5.1 Methods that Require Only First Derivatives	
		9.5.1 Methods that Require Only First Derivatives	
	0.7	9.5.3 Methods that Require No Derivatives	
	9.6	Summary	131

Contents ix

10	Numerical Methods for Constrained Optimization	135
	10.1 Fundamentals for Constrained Optimization	135
	10.1.1 Optimality Conditions for Linear Constraints	
	10.1.2 Optimality Conditions for the General Case	
	10.2 Solving Problems with Bound Constraints	
	10.3 Solving Problems with Linear Equality Constraints: Feasible Directions	
	10.4 Barrier and Penalty Methods for General Constraints	
	10.5 Interior-Point Methods	
	10.6 Summary	
	10.0 Sullillary	147
11	Case Study: Classified Information:	149
	The Data Clustering Problem	
	(coauthored by Nargess Memarsadeghi)	
12	Case Study: Achieving a Common Viewpoint:	157
	Yaw, Pitch, and Roll	
	(coauthored by David A. Schug)	
13	Case Study: Fitting Exponentials: An Interest in Rates	163
14	Case Study: Blind Deconvolution: Errors, Errors Everywhere	169
15	Cose Study, Plind Decenvelation, A Metter of Norm	175
15	Case Study: Blind Deconvolution: A Matter of Norm	175
IV	Monte Carlo Computations	183
16	Monte Carlo Principles	187
	16.1 Random Numbers and Their Generation	188
	16.2 Properties of Probability Distributions	
	16.3 The World Is Normal	
	16.4 Pseudorandom Numbers and Their Generation	
	16.5 Mini Case Study: Testing Random Numbers	
		173
17	Case Study: Monte Carlo Minimization and Counting:	195
	One, Two, Too Many	
	(coauthored by Isabel Beichl and Francis Sullivan)	
18	Case Study: Multidimensional Integration:	203
	Partition and Conquer	
19	Case Study: Models of Infection: Person to Person	213
V	Ordinary Differential Equations	221
20	Solution of Ordinary Differential Equations	225
	20.1 Initial Value Problems for Ordinary Differential Equations	
	20.1.1 Standard Form	
	20.1.1 Standard Form	
	20.1.2 Solution Families and Stability	228

Contents

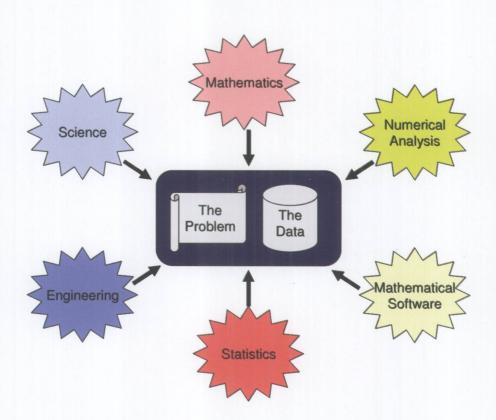
	20.2	Methods for Solving IVPs for ODEs	. 232
		20.2.1 Euler's Method, Stability, and Error	. 232
		20.2.2 Predictor-Corrector Methods	. 237
		20.2.3 The Adams Family	. 239
		20.2.4 Some Ingredients in Building a Practical ODE Solver	
		20.2.5 Solving Stiff Problems	
		20.2.6 An Alternative to Adams Formulas: Runge–Kutta	
	20.3	Hamiltonian Systems	
	20.4	Differential-Algebraic Equations	
		20.4.1 Some Basics	
		20.4.2 Numerical Methods for DAEs	
	20.5	Boundary Value Problems for ODEs	
	20.5	20.5.1 Shooting Methods	
		20.5.2 Finite Difference Methods	
	20.6	Summary	
	20.0	Summary	. 230
21	Case	Study: More Models of Infection: It's Epidemic	259
22	Case	Study: Robot Control: Swinging Like a Pendulum	265
	(coau	thored by Yalin E. Sagduyu)	
23	Case	Study: Finite Differences and Finite Elements	273
	Getti	ng to Know You	
VI	Nonlin	near Equations and Continuation Methods	281
24	Nonli	inear Systems	285
	24.1	The Problem	. 285
	24.2	Nonlinear Least Squares Problems	
	24.3	Newton-like Methods	
		24.3.1 Newton's Method for Nonlinear Equations	
		24.3.2 Alternatives to Newton's Method	
	24.4	Continuation Methods	
		24.4.1 The Theory behind Continuation Methods	
		24.4.2 Following the Solution Path	
25	Casa	Study: Variable-Geometry Trusses	297
25	Casc	Study. Variable-Ocolletty Trusses	2)1
26	Case	Study: Beetles, Cannibalism, and Chaos	301
VII	Sparse	e Matrix Computations,	
		Application to Partial Differential Equations	307
27	Solvi	ng Sparse Linear Systems	311
	Takir	ng the Direct Approach	
	27.1	Storing and Factoring Sparse Matrices	
	27.2	What Matrix Patterns Preserve Sparsity?	. 313
	27.2	Representing Sparsity Structure	214

Contents

	27.4	Some Reordering Strategies for Sparse Symmetric Matrices	
	27.5	Reordering Strategies for Nonsymmetric Matrices	321
28	Iterat	tive Methods for Linear Systems	323
	28.1	Stationary Iterative Methods (SIMs)	
	28.2	From SIMs to Krylov Subspace Methods	326
	28.3	Preconditioning CG	328
	28.4	Krylov Methods for Symmetric Indefinite Matrices and for Normal	
		Equations	330
	28.5	Krylov Methods for Nonsymmetric Matrices	
	28.6	Computing Eigendecompositions and SVDs with Krylov Methods	333
29	Case	Study: Elastoplastic Torsion: Twist and Stress	335
30		Study: Fast Solvers and Sylvester Equations Sides Now	341
31	Case	Study: Eigenvalues: Valuable Principles	347
32	Multi	grid Methods: Managing Massive Meshes	353
Bibli	ograpł	ny	361
Index	ĸ		373

Unit I

Preliminaries: Mathematical Modeling, Errors, Hardware and Software





The topic of this book is efficient and accurate computation with mathematical models. In this unit, we discuss the basic facts that we need to know about error, software, and computers.

We begin our study with some basics. First in Chapter 1 we consider how errors are introduced in scientific computing and how to measure them. We apply these principles in Chapter 2, studying how small changes in our data can affect our answers. In Chapter 3, we see how computer memory is organized and how that impacts the efficiency of our algorithms. Then in Chapter 4, we study the principles behind writing and documenting our algorithms.

BASICS: To understand this unit, the following background is helpful:

- MATLAB programming [78].
- Gauss elimination; see a linear algebra textbook or a beginning book on numerical analysis or scientific computing [148].

MASTERY: After you have worked through this unit, you should be able to do the following:

- Identify the sources of error in scientific computing.
- Represent an integer in a fixed-point number system and a real number in a floating-point number system.
- Use the parameter ϵ_m (machine epsilon) to determine the error introduced in floating-point representation.
- Measure relative and absolute errors and determine how they are magnified during computation.
- Write algorithms that compute values such as the sum of a series, avoiding unnecessary inaccuracies.
- Determine ways to avoid catastrophic cancellation in designing algorithms.
- Use forward and backward error analysis to assess the quality of a computed solution to a problem.
- Determine whether a problem is well-conditioned or ill-conditioned.
- Discuss the importance of stability in an algorithm.
- Measure the sensitivity of a problem using derivatives, condition numbers, Monte Carlo experiments, and confidence intervals.
- Distinguish between a row-oriented matrix algorithm and a column-oriented matrix algorithm, and be able to write them for simple tasks.
- Explain how matrices are stored in main memory and moved to cache, and perform counts of page moves.
- Count the number of multiplications in a given MATLAB algorithm.
- Explain what the BLAS are and why they are useful.
- Document computer programs effectively.
- Understand the principles of modular design.
- Write a program to validate a function that you have written.