

ELECTROMAGNETICS AND OPTICS

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Published by

World Scientific Publishing Co. Pte. Ltd. P O Box 128, Farrer Road, Singapore 9128

USA office: Suite 1B, 1060 Main Street, River Edge, NJ 07661 UK office: 73 Lynton Mead, Totteridge, London N20 8DH

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ISBN 981-02-0848-0 981-02-0849-9 (pbk)

Printed in Singapore by Utopia Press.

ELECTROMAGNETICS AND OPTICS

To our wives:

Zaharoula

Ariadne

Christine

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Preface

Εἴτε φῶς εἴτ' ἀἡρ ἐστί τὸ μεταξὺ τοῦ ορωμένου καὶ τοῦ ὅμματος, η διὰ τοὐτου κίνησίς ἐστίν η ποιοῦσα τὸ ορᾶν.¹
Αριστοτέλης

Modern communication systems encompass information-carrying and information processing devices. The need for ever higher capacity has gradually linked progress in communications with light signals traveling through low-loss fibres and optical devices. Multichannel fibre links of enormous capacity are currently in use in developed parts of the world. Moreover, the scientists' dream of optical supercomputers that will be able to perform numbercrunching at the speed of light, has renewed interest in optics as well as in electromagnetics, since light is a high-frequency electromagnetic radiation.

Although both electromagnetics and optics are based on Maxwell's equations, their common origin is only superficially realised by students of applied physics or electrical engineering. Deeper physical insight might be achieved by treating electromagnetics and optics in parallel and from common ground, thus enlightening the natural link between them.

By presenting principles, theory and phenomena of electromagnetics and optics, this book contributes to the task of bridging the two disciplines. Implicit in our effort is the general communication problem.

Wavefunctions and rays used by electromagnetics and optics, respectively, to represent the information-carrying signal are associated with solutions of

Aristotle, De Anima, 438^b3-5

Whether light or air is the medium between the visible object and the eye, the motion through this medium is what produces vision.

the wave and ray equations. Waveguides and resonators used in optical applications are analysed from the standpoint of both field theory and ray theory, the dual approach aimed at revealing to the reader the interrelations between electromagnetics and optics.

The book covers five subjects in fourteen chapters. The subjects covered are light/matter interactions, guidance, resonance, processing and applications. An outline of the contents of each chapter follows.

Starting from Maxwell's equations, the wave equation is formulated in Chapter 1. Solutions are given for isotropic and anisotropic media. Reflection/refraction of a uniform plane wave at a dielectric boundary, the Brewster angle and the critical angle are treated next. Chapter 1 is concluded with a discussion concerning the concept of coherent radiation and the uncertainty principle, chiefly for use in subsequent chapters.

principle, chiefly for use in subsequent chapters.

The asymptotic solution of the wave equation in the high-frequency limit leads to geometrical optics, which is examined in Chapter 2. The Huygens principle and the concept of optical path length are used to formulate the eikonal and ray equations. The laws of geometrical optics are derived next by using Fermat's principle. Variational principles and quantum considerations in optics are finally discussed.

The laws of geometrical optics lead to ray theory, which is presented in Chapter 3. Several forms of light/matter interactions, such as reflection, refraction, diffraction and scattering in the optical band, are treated. Ray tracing by the ABCD transition matrix as well as rays in layered and inhomogeneous media are examined. A hybrid wave/ray approach is used on some occasions.

Guidance of light by dielectric waveguides is treated in Chapters 4 and 5. Step-index, graded-index and weakly guiding structures are analysed, appropriate wavefunctions are determined and rays are traced. Brief discussions of coupling and dispersion are also included.

Chapter 6 deals with resonance. Oscillating waveforms in microwave resonators are determined in rectangular, cylindrical and spherical cavities bounded by metallic walls. Interest is next focussed on optical resonators. Repetitive ray paths are determined through the ABCD matrix method. The Fabry-Perot etalon is treated next. Finally, an introduction to paraxial resonator theory is presented with reference to geometrical and perturbational stability of optical cavities.

The Gaussian beam is introduced in Chapter 7. Starting from the scalar wave equation for the beam, the corresponding waveforms are determined. Trans-

PREFACE ix

formation and propagation of the Gaussian beam are also examined.

Problems related with the laser are examined in Chapter 8. The basic equation of the laser is determined and the broadening mechanism is discussed. Oscillation of the laser and the gain saturation are also treated.

Chapter 9 deals with Fourier optics. Considering light as a scalar disturbance, the features of light propagation and the associated filtering process are thoroughly investigated. The transmittance function of a discontinuity surface is introduced next; basic reflection/refraction phenomena with regard to the thin lens are treated, thus establishing a link between Fourier and Gaussian optics.

The results of Fourier optics are also compared with the results of the scalar theory of diffraction, which is developed in Chapter 10. Kirchhoff's diffraction theory is presented there and the Fresnel/Fraunhofer approximations are analysed. Several representative applications are included in Chapter 10.

The scalar diffraction theory is used in Chapter 11 to explain the process of holographic wavefront reconstruction. Properties of the reconstructed images and beams are investigated. A qualitative description of various kinds of holograms concludes chapter 11.

Elements of optical radiation are presented in Chapter 12. Radiometric and photometric quantities are defined and discussed. Thermal radiation and the field of light are also examined there.

Chapter 13 deals with optical techniques and components applied to remote sensing. Photographic imaging by aerial cameras and the operation of radiometers are discussed in the first part of the chapter, which refers to passive remote sensing. Optical data processing is discussed next, chiefly as a prerequisite for the ensuing description of the optical processor used by synthetic aperture radars.

Finally, chapter 14 examines the fundamental principles of the non-linear optics. Classical atomic models are described and the coupled wave equations are treated. A generalisation of the laws of optics is thus obtained.

Considering that the contemporary problems (dielectric waveguides, holography, lasers etc.) of the electrical engineer require a more advanced background, we feel that the proposed book will help senior-level students and engineers not only to understand the various physical problems but also to cope with applications.

We are deeply indebted to all those who have assisted in the realisation of this book. Many thanks are due to Prof. J.A. Tsoukalas for his valuable

suggestions and discussions. We are also grateful to our colleagues Dr. T. Tsiboukis, Dr. S. Panas, Dr. C. Antonopoulos, Dr. P. Hagouel, Dr. G. Sergiadis and Dr. M. Zervas for the valuable discussions and their comments. In addition, thanks are due to Dipl. Eng. E. Kriezis for his meticulous checks of several parts of the manuscript. We further thank the unknown reviewers engaged by the publishers. Finally, we gratefully acknowledge the work of Mrs. J. Hassekidou-Maragou and Miss V. Altintzi in preparing the drawings of the book.

Thessaloniki, 1991

E.E. Kriezis D.P. Chrissoulidis A.G. Papagiannakis

Contents

Preface Contents		vi x	
1	REVIE	EW OF THE EQUATIONS OF ELECTROMAGNETIC FIELD	1
	1.1	Poynting's Vector - Intensity of Light, 1	
	1.2	Wave Equation in Isotropic Media, 3	
	1.3	Wave Propagation in Anisotropic Media, 8	
	1.4	Reflection and Refraction at a Dielectric Boundary, 19	
	1.5	Brewster's Angle - Critical Angle, 24	
	1.6	Coherent Radiation, 27	
	1.7	Uncertainty Principle, 29	
2	GEOM	METRICAL OPTICS	33
	2.1	Introduction, 33	
	2.2	Eikonal Equation and Ray Equation, 35	
	2.3	Applications of Ray Equation, 42	
		2.3.1 Rays in a Spherically Inhomogeneous Medium, 42	
		2.3.2 Rays in a Cylindrically Inhomogeneous Medium, 45	
	2.4	Fermat's Principle, 48	
	2.5	Boundary Conditions, 51	
	2.6	Variational Principles in Optics, 54	
	2.7	Quantum Considerations in Optics, 59	
	2.8	Exercises, 64	
3	RAY 7	THEORY	67
	3.1	Introduction, 67	
	3.2	Mirror Reflection, 68	
	3.3	Prism/Lens Refraction, 77	
	3.4	Ray Tracing by the ABCD Matrix, 85	
	3.5	Rays in Non-Uniform Media, 93	
	3.6	Rays in Layered Structures, 100	
	3.7	Reflection/Refraction Gratings, 107	
	3.8	Simple Scattering Processes, 113	
	3.9	Exercises, 117	

4	PLAN	AR DIELECTRIC WAVEGUIDES	119
	4.1	Introduction, 119	
	4.2	Dielectric Film, 123	
		4.2.1 TM-Modes, 124	
		4.2.2 TE-Modes, 127	
		4.2.3 Weakly Guiding Film, 130	
	4.3	Dielectric Slab, 132	
		4.3.1 Total Internal Reflection, 132	
		4.3.2 TE-Modes, 137	
		4.3.3 TM-Modes, 141	
		4.3.4 Weakly Guiding Slab, 142	
	4.4	Coupled Slab Waveguides, 146	
	4.5	Rectangular Dielectric Waveguide, 151	
	4.6	Graded-Index Slab, 155	
	4.7	Rays in Dielectric Slabs, 158	
	4.8	Exercises, 161	
5	FIBR	ES	163
	5.1	Introduction, 163	
	5.2	Step-Index Fibre, 166	
	5.3	Graded-Index Fibre, 178	
	5.4	Rays in Fibres, 183	
	5.5	Pulse Distortion in Single-Mode Fibres, 192	
	5.6	Mode Conversion/Coupling, 196	
	5.7	Exercises, 201	
6	RESONATORS 2		
	6.1	Introduction, 203	
	6.2	Oscillating Waveforms in Microwave Resonators, 203	
		6.2.1 The Rectangular Cavity, 205	
		6.2.2 The Cylindrical Cavity, 208	
		6.2.3 The Spherical Cavity, 212	
		6.2.4 Resonant Mode Density, 217	
	6.3	Repetitive Ray Paths in Optical Resonators, 219	
		6.3.1 Mode Spectrum of Two-Mirror Optical Cavity, 223	
		6.3.2 ABCD Matrix of Stable Optical Resonator, 224	
	6.4	The Fabry-Perot Etalon, 227	
	6.5	Paraxial Resonator Theory, 232	
		6.5.1 Geometrical Stability, 232	
		6.5.2 Perturbational Stability, 234	
		6.5.3 Stable and Unstable Optical Resonators, 236	
		6.5.4 Mode Volume, 239	
	6.6	Exercises 240	

CONTENTS xiii

7	GAUS	SSIAN BEAM	241
	7.1	Introduction, 241	
	7.2	Scalar Wave Equation, 241	
	7.3	Gaussian Beam, 245	
	7.4	Higher-Order Beam Modes, 254	
	7.5	Transformation of Gaussian Beam and q-Parameter, 255	
	7.6 7.7	ABCD Matrix for the Gaussian Beam, 259	
	7.7	Propagation of the Gaussian Beam, 264 Exercises, 270	
8	LASE	R	271
	8.1	Introduction, 271	
	8.2	Spontaneous and Stimulated Emission. Absorption, 272	
	8.3	The Concept of Laser. Basic Equation of Laser, 276	
	8.4	Lineshape Broadening, 279	
		8.4.1 Doppler Broadening, 280	
		8.4.2 Homogeneous Radiative Lifetime Broadening, 282	
	0.5	8.4.3 Collision Broadening, 285	
	8.5 8.6	Laser Modes, 286 The Electron Oscillator Model of the Atomic Transition, 289	
	8.7	The Laser Oscillation Condition, 291	
	8.8	Gain Saturation, 296	
	8.9	Exercises, 306	
9	FOUR	RIER OPTICS	309
	9.1	Introduction, 309	
	9.2	Light: Vector or Scalar Disturbance?, 309	
	9.3	Propagation of the Light Disturbance, 310	
		9.3.1 Spatial Frequencies of a Wave Disturbance, 311	
		9.3.2 Propagation of the Angular Spectrum, 3139.3.3 The Propagation as a Spatial Filter, 316	
		9.3.4 Let's go Afar, 319	
		9.3.5 Let's go Even Farther, 326	
	9.4	Transmittance function of a Discontinuity Surface, 327	
	9.5	Refraction, 329	
	9.6	Reflection, 333	
	9.7	The Thin Lens, 336	
	9.8	Exercises, 337	
10	SCAL	AR THEORY OF DIFFRACTION	341
	10.1	Introduction, 341	
	10.2	Formulation of the Problem - Kirchhoff's Boundary Conditions,	342

11

10.3	Fresnel - Kirchhoff Diffraction, 347	
10.4	The Rayleigh - Sommerfeld Diffraction Equation, 349	
10.5	Fresnel Diffraction, 352	
10.6	Fraunhofer Diffraction, 357	
10.7	Comparison of Fourier Optics and STD, 359	
10.8	Diffraction of a Plane Wave, 363	
10.9	Fraunhofer Diffraction by a Rectangular Aperture, 365	
10.10	Fraunhofer Diffraction by a Circular Aperture, 366	
10.11	Fraunhofer Diffraction by Grating of Harmonic Amplitude	
	Variation, 368	
10.12	Fraunhofer Diffraction by Grating of Harmonic Phase	
	Variation, 370	
10.13	Fresnel Diffraction by a Rectangular Aperture, 373	
10.14	Diffraction by an Infinite Slit, 376	
10.15	Fresnel Zones - Vibration Curve, 380	
10.16	Fresnel Zone Plate, 383	
10.17	Exercises, 386	
OPTIO	CAL HOLOGRAPHY	389
11.1	Introduction, 389	
11.2	A Qualitative Description of Holography, 390	
11.3	About Coherence, 391	
11.4	Interference of two Wave Disturbances, 394	
11.5	The Recording Medium, 396	
11.5	11.5.1 The Photographic Film, 397	
	11.5.2 The Hurter-Driffield Curve, 397	
	11.5.3 The Transmittance vs. Exposure Curve, 398	
11.6	Hologram Construction, 399	
11.7	Wavefront Reconstruction, 402	
11.7	11.7.1 The Transmitted Disturbance, 402	
	11.7.2 The Choice of the Reference Waves, 404	
	11.7.3 The Third Diffraction Term, 405	
	11.7.4 The Fourth Diffraction Term, 406	
11.8	Properties of the Reconstructed Waves, 407	
11.9	Hologram Types, 418	
11.7	11.9.1 Fresnel Hologram, 418	
	11.9.2 Fourier Transform Hologram, 418	
	11.9.3 Lensless Fourier Transform Hologram, 419	
	11.9.4 Image Hologram, 420	
	11.9.5 Computer Holograms, 420	
	11.9.6 Other Types of Holograms, 421	
11.10	Volume Holograms, 421	
11.11	Applications of Holography, 426	

CONTENTS xv

	11.12	11.11.1 Three-Dimensional Characteristics, 426 11.11.2 Spherical Reference Waves, 427 11.11.3 High Density, 427 11.11.4 High Speed, 427 11.11.5 Coherence and Interference, 427 11.11.6 Phase Inversion, 429 11.11.7 Accuracy, 429 Exercises, 429	
12	OPTIO	CAL RADIATION	431
	12.1 12.2	Introduction, 431 Radiometric Quantities, 432 12.2.1 Spectral Distribution of Radiation, 439	
	12.3 12.4	Photometric Quantities, 442 Thermal Radiation, 446	
		12.4.1 The Wien Displacement Law, 44712.4.2 The Planck Radiation Law, 449	
	12.5	The Field of Light, 454	
13	OPTIO	CAL TECHNIQUES IN REMOTE SENSING	459
	13.1	Introduction, 459	
	13.2 13.3	Photographic Imaging, 461 Electro-Optical Sensors, 471	
	13.4	Optical Data Processing, 476	
	13.5	Application to SAR signals, 487	
14	NON-I	LINEAR OPTICS	497
	14.1	Introduction, 497	
	14.2	The General Model of the Anharmonic Oscillator, 498	
	14.3	Maxwell's Equations, 503	
	14.4	Second Harmonic Generation, 505	
	14.5	Self-Focusing, 508	
	14.6	Stimulated Raman Scattering, 513	
	14.7	Brillouin Scattering, 516	
AI	PPEND	IXES	
A	THE	FOURIER TRANSFORM	523
	A .1	The One-Dimensional Fourier Transform, 523	
	A.2	The Two-Dimensional Fourier Transform, 526	
	A.3	The Three-Dimensional Fourier Transform, 529	
	A.4	The Hankel and Fourier-Bessel Transforms, 530	

	A.5 A.6	The Angular Spectrum of a Disturbance, 534 Fourier Transform Properties, 536	
В	THE	SCALAR GREEN'S FUNCTION	539
	B.1	Green's Function for the Scalar Helmholtz Equation, 539 B.1.1 Posing the Problem, 539 B.1.2 Definition of Green's Function, 540 B.1.3 A Fundamental Property of Green's Function, 543 B.1.4 Computation of Green's Function, 544	
	B.2 B.3	The Radiation Condition and the Free Space Green's Function, Green's Function in Two Dimensions, 548	544
C	ELEC	CTROMAGNETIC FIELD AND QUANTUM CONSIDERATION	551
Re	ference	es	557
Su	Subject Index		

Chapter 1

Review of the Equations of Electromagnetic Field

1.1 Poynting's Vector - Intensity of Light

It is well known that light is an electromagnetic phenomenon which conforms to *Maxwell's equations*. The possibility of linking light to electromagnetism has been considered by several predecessors of Maxwell. Maxwell's equations, in differential form, are as follows:

$$\nabla \times \vec{\varepsilon} = -\frac{\partial \vec{B}}{\partial t} \tag{1.1}$$

$$\nabla \times \vec{\mathcal{H}} = \frac{\partial \vec{\mathcal{D}}}{\partial t} + \vec{\mathcal{J}}$$
 (1.2)

$$\nabla \cdot \vec{\mathcal{B}} = 0 \tag{1.3}$$

$$\nabla \cdot \vec{\mathcal{D}} = \varrho \tag{1.4}$$

The polarisation \vec{P} and magnetisation \vec{M} are introduced through the well-known constitutive relations:

$$\vec{\mathcal{D}} = \varepsilon_0 \vec{\varepsilon} + \vec{\mathcal{P}} \tag{1.5}$$

$$\vec{\mathcal{B}} = \mu_0 (\vec{\mathcal{H}} + \vec{\mathcal{M}}) \tag{1.6}$$

The surface power density is represented by the Poynting vector:

$$\vec{\mathcal{I}} = \vec{\varepsilon} \times \vec{\mathcal{H}} \tag{1.7}$$

If harmonic time variation is assumed, the *electric field intensity* $\vec{\epsilon}$ and the *magnetic field intensity* $\vec{\mathcal{H}}$ are expressed as follows:

$$\vec{\varepsilon} = \text{Re}\left\{\vec{E}e^{j\omega t}\right\} = \frac{1}{2}\left(\vec{E}e^{j\omega t} + \vec{E}^*e^{-j\omega t}\right)$$
(1.8)

$$\vec{\mathcal{H}} = \text{Re}\left\{\vec{H}e^{j\omega t}\right\} = \frac{1}{2}\left[\vec{H}e^{j\omega t} + \vec{H}^*e^{-j\omega t}\right]$$
 (1.9)

with F^* as the complex conjugate of F. By using the expressions of Eqs.(1.8 & 1.9) for $\vec{\epsilon}$ and $\vec{\mathcal{H}}$, Eq.(1.7) is written as follows:

$$\vec{\mathcal{I}} = \frac{1}{4} \left[\vec{E} \times \vec{H}^* + \vec{E}^* \times \vec{H} \right] + \frac{1}{4} \left[\vec{E} \times \vec{H} e^{2j\omega t} + \vec{E}^* \times \vec{H}^* e^{-2j\omega t} \right]$$
(1.10)

If the relations $\operatorname{Re}\left\{\vec{E}\times\vec{H}^{*}\right\} = \left(\vec{E}\times\vec{H}^{*} + (\vec{E}\times\vec{H}^{*})^{*}\right)/2$, $\left(\vec{E}\times\vec{H}^{*}\right)^{*} = \vec{E}^{*}\times\vec{H}$ and $\left(\vec{E}\times\vec{H}e^{2j\omega t}\right)^{*} = \vec{E}^{*}\times\vec{H}^{*}e^{-2j\omega t}$ are used, Eq.(1.10) can be shortened as follows:

$$\vec{\mathcal{G}} = \frac{1}{2} \operatorname{Re} \left\{ \vec{E} \times \vec{H}^* \right\} + \frac{1}{2} \operatorname{Re} \left\{ \vec{E} \times \vec{H} e^{2j\omega t} \right\}$$
 (1.11)

It should be noted that only the second term in the right-hand side of Eq.(1.11) is time-dependent, its frequency being double that of $\vec{\varepsilon}$ and $\vec{\mathcal{H}}$. The vector

$$\vec{S}_{c} = \frac{1}{2} \vec{E} \times \vec{H}^{*} \tag{1.12}$$

is defined as the *complex Poynting vector*. Maxwell's equations, as adapted to harmonic time variation, will next be used to determine \vec{S}_c . Eqs.(1.1 & 1.2) are written as follows:

$$\nabla \times \vec{E} = -j\omega \mu \vec{H} \tag{1.13}$$

$$\nabla \times \vec{\mathbf{H}} = \mathbf{j}\omega \vec{\mathbf{D}} + \vec{\mathbf{J}} \tag{1.14}$$

with $\vec{f} = \text{Re}\{\vec{J}e^{j\omega t}\}$. The following relation can easily be proved from Eqs.(1.13 & 1.14):

$$-\vec{\mathbf{H}}^{*} \cdot \nabla \times \vec{\mathbf{E}} + \vec{\mathbf{E}} \cdot \nabla \times \vec{\mathbf{H}}^{*} = \vec{\mathbf{E}} \cdot \vec{\mathbf{J}}^{*} + j\omega (\vec{\mathbf{B}} \cdot \vec{\mathbf{H}}^{*} - \vec{\mathbf{E}} \cdot \vec{\mathbf{D}}^{*})$$
(1.15)

The vector identity $\nabla \cdot (\vec{A} \times \vec{B}) = \vec{B} \cdot \nabla \times \vec{A} - \vec{A} \cdot \nabla \times \vec{B}$ indicates that Eq.(1.15) may be transformed into the following:

$$-\nabla \cdot \left(\vec{E} \times \vec{H}^{*}\right) = \vec{E} \cdot \vec{J}^{*} + j\omega \left(\vec{B} \cdot \vec{H}^{*} - \vec{E} \cdot \vec{D}^{*}\right)$$
(1.16)

By using Eqs.(1.5, 1.6 & 1.12) and integrating Eq.(1.16) throughout a given volume V, yields:

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