# Methods for Special Functions

Amparo Gil Javier Segura Nico M. Temme

sian.

## Numerical Methods for Special Functions

## **Amparo Gil**

Universidad de Cantabria Santander, Cantabria, Spain

## **Javier Segura**

Universidad de Cantabria Santander, Cantabria, Spain

### Nico M. Temme

Centrum voor Wiskunde en Informatica Amsterdam, The Netherlands Copyright © 2007 by the Society for Industrial and Applied Mathematics.

10987654321

All rights reserved. Printed in the United States of America. No part of this book may be reproduced, stored, or transmitted in any manner without the written permission of the publisher. For information, write to the Society for Industrial and Applied Mathematics, 3600 University City Science Center, Philadelphia, PA 19104-2688.

Trademarked names may be used in this book without the inclusion of a trademark symbol. These names are used in an editorial context only; no infringement of trademark is intended.

Maple is a registered trademark of Waterloo Maple, Inc.

Mathematica is a registered trademark of Wolfram Research, Inc.

MATLAB is a registered trademark of The MathWorks, Inc. For MATLAB product information, please contact The MathWorks, Inc., 3 Apple Hill Drive, Natick, MA 01760-2098 USA, 508-647-7000, Fax: 508-647-7101, info@mathworks.com, www.mathworks.com.

### Library of Congress Cataloging-in-Publication Data

Gil, Amparo.

Numerical methods for special functions / Amparo Gil, Javier Segura, Nico M. Temme.

p. cm.

Includes bibliographical references and index.

ISBN 978-0-898716-34-4 (alk. paper)

- 1. Functions, Special—Data processing. 2. Numerical analysis. 3. Asymptotic expansions.
- 4. Apporximation theory. I. Segura, Javier. II. Temme, N. M. III. Title.

QA351.G455 2007 518'.6-dc22



## Numerical Methods for Special Functions

To our sons Alonso and Javier (A.G. & J.S.)

To my grandsons Ambrus and Fabian (N.M.T.)



## **Preface**

Probably, the most extended (pseudo)definition of the set of functions known as "special functions" refers to those mathematical functions which are widely used in scientific and technical applications, and of which many useful properties are known. These functions are typically used in two related contexts:

- as a way of obtaining simple closed formulas and other analytical properties of solutions of problems from pure and applied mathematics, statistics, physics, and engineering;
- 2. as a way of understanding the nature of the solutions of these problems, and for obtaining numerical results from the representations of the functions.

Our book is intended to provide assistance when a researcher or a student needs to get the numbers from analytical formulas containing special functions. This book should be useful for those who need to compute a function by their own means, or for those who want to know more about the numerical methods behind the available algorithms. Our main purpose is to provide a guide of available methods for computations and when to use them. Also, because of the large variety of numerical methods that are available for computing special functions, we expect that a broader "numerical audience" will be interested in many of the topics discussed (particularly in the first part of the book). Several levels of reading are possible in this book and most of the chapters start with basic principles. Examples are given to illustrate the use of the methods, pseudoalgorithms are given to describe technical details, and published algorithms for computing a selection of functions are described as practical illustrations for the basic methods of this book.

The presentation of the topics is organized in four parts: Basic Methods, Further Tools and Methods, Related Topics and Examples, and Software. The first part (Basic Methods) describes a set of methods which, in our experience, are the most popular and important ones for computing special functions. This includes convergent and divergent series, Chebyshev expansions, linear recurrence relations, and quadrature methods. These basic chapters are mostly self-contained and start from first principles. We expect that many of the contents are appropriate for advanced numerical analysis courses (parts of the chapters are in fact based on classroom notes); however, because the main focus is on special functions, detailed examples of application are also provided.

The second part of the book (Further Tools and Methods) contains a set of important methods for computing special functions which, however, are probably not so well known as the basic methods (at least for readers who are not very familiar with special functions).

xiv Preface

Certainly, this does not mean that these tools are less effective than the selected basic methods; for example, the performance of uniform asymptotic expansions is quite impressive in many instances. The chapters in this second part are: Continued Fractions, Computation of the Zeros of Special Functions, Uniform Asymptotic Expansions, and Other Methods (Padé approximations, sequence transformations, best rational approximations, Taylor's method for ordinary differential equations, and further quadrature methods including the Clenshaw–Curtis and Filon methods).

The third part (Related Topics and Examples) describes some methods that are specific to certain functions. A first chapter is devoted to the (asymptotic) numerical inversion of a class of distribution functions with details for gamma and beta distributions (a topic which researchers in statistics, probability, and econometrics may find useful). A second chapter (Further Examples) describes varied topics such as the Euler summation formula (and applications), the computation of symmetric elliptic integrals (Carlson's method), and the numerical inversion of Laplace transforms.

We thank NIST for the permission to quote part of a section in the DLMF project (from the chapter "Numerical Methods") on solving ordinary differential equations by using Taylor series (our §9.5), and Frank Olver for his assistance in writing this part. We thank the SIAM editorial staff, in particular Louis Primus, for their patience and splendid cooperation.

Finally, the fourth part illustrates the use of the methods by providing descriptions of specific algorithms for computing selected functions: Airy functions, Legendre functions, and parabolic cylinder functions, among others. The corresponding Fortran 90 routines can be downloaded from

### http://functions.unican.es.

The web page will hold successive actualizations and extensions of the available software. We would like to thank Dr. Van Snyder for his extensive and useful comments, and Dr. Ernst Joachim Weniger for providing us with notes, and further useful information, on Padé approximations and sequence transformations. Finally, we thank the Spanish Ministry of Education and Science for financial support (projects MTM2004-01367, MTM2006-09050).

## **Contents**

Preface					
1	Intro	duction		1	
I	Basic I	Methods		13	
2	Conv	ergent and	Divergent Series	15	
	2.1	Introduct	ion	15	
		2.1.1	Power series: First steps	15	
		2.1.2	Further practical aspects	17	
	2.2	Different	ial equations and Frobenius series solutions	18	
		2.2.1	Singular points	19	
		2.2.2	The solution near a regular point	20	
		2.2.3	Power series expansions around a regular singular point .	22	
		2.2.4	The Liouville transformation	25	
	2.3	Hypergeo	ometric series	26	
		2.3.1	The Gauss hypergeometric function	28	
		2.3.2	Other power series for the Gauss hypergeometric function	30	
		2.3.3	Removable singularities	33	
	2.4	Asympto	totic expansions		
		2.4.1	Watson's lemma	36	
		2.4.2	Estimating the remainders of asymptotic expansions	38	
		2.4.3	Exponentially improved asymptotic expansions	39	
		2.4.4	Alternatives of asymptotic expansions	40	
3	Chebyshev Expansions				
	3.1	Introduct	ion	51	
	3.2	Basic res	ults on interpolation	52	
		3.2.1	The Runge phenomenon and the Chebyshev nodes	54	
	3.3	Chebysh	ev polynomials: Basic properties	56	
		3.3.1	Properties of the Chebyshev polynomials $T_n(x)$	56	
		3.3.2	Chebyshev polynomials of the second, third, and fourth		
			kinds	60	

viii Contents

	3.4	Chebyshev	interpolation	62
		3.4.1	Computing the Chebyshev interpolation polynomial	64
	3.5	Expansions	in terms of Chebyshev polynomials	66
		3.5.1	Convergence properties of Chebyshev expansions	68
	3.6	Computing	the coefficients of a Chebyshev expansion	69
		3.6.1	Clenshaw's method for solutions of linear differential	
			equations with polynomial coefficients	70
	3.7	Evaluation of	of a Chebyshev sum	75
	.,	3.7.1	Clenshaw's method for the evaluation of a Chebyshev sum	75
	3.8		ion of power series	80
	3.9		Computation of Airy functions of real variable	80
	3.10		expansions with coefficients in terms of special functions.	83
4	Linea	r Recurrence	Relations and Associated Continued Fractions	87
	4.1		1	87
	4.2		f three-term recurrence relations	88
		4.2.1	Minimal solutions	89
	4.3		eorem	92
	112	4.3.1	Scaled recurrence relations	94
	4.4	210(B)(C) (C)	lutions of TTRRs and continued fractions	95
	4.5		ble recurrence relations	96
	4.5	4.5.1	The confluent hypergeometric family	96
		4.5.2	The Gauss hypergeometric family	
	4.6		the minimal solution of a TTRR	105
	4.0	4.6.1	Miller's algorithm when a function value is known	105
		4.6.2	Miller's algorithm with a normalizing sum	107
		4.6.3	"Anti-Miller" algorithm	
	4.7		eous linear difference equations	
	4.7	4.7.1	Inhomogeneous first order difference equations.	112
		4.7.1	Examples	112
		472	Inhomogeneous second order difference equations	
		4.7.2		
	4.0			110
	4.8	4.7.3 Olver's method		110
		4.8.1	A canonical example: Modified Bessel function	
		4.8.2	Other examples: Hypergeometric recursions	
		4.8.3	A first order inhomogeneous equation	
		4.8.4	A warning	122
5		lrature Metho		123
	5.1		n	
	5.2		otes quadrature: The trapezoidal and Simpson's rule	
		5.2.1	The compound trapezoidal rule	
		5.2.2	The recurrent trapezoidal rule	
		5.2.3	Euler's summation formula and the trapezoidal rule	
	5.3	Gauss quac	Irature	132

Contents ix

		5.3.1	Basics of the theory of orthogonal polynomials and Gauss	
			quadrature	
		5.3.2	The Golub–Welsch algorithm	
		5.3.3	Example: The Airy function in the complex plane	
		5.3.4	Further practical aspects of Gauss quadrature	
	5.4	The trape	ezoidal rule on $\mathbb R$	
		5.4.1	Contour integral formulas for the truncation errors	148
		5.4.2	Transforming the variable of integration	153
	5.5	Contour	integrals and the saddle point method	157
		5.5.1	The saddle point method	158
		5.5.2	Other integration contours	163
		5.5.3	Integrating along the saddle point contours and examples	165
II	Furthe	er Tools and	d Methods	171
6	Nume	erical Asne	cts of Continued Fractions	173
•	6.1	-	tion	
	6.2		ns and notation	
	6.3		nce transformations and contractions	
	6.4	-	forms of continued fractions	
	0.1	6.4.1	Stieltjes fractions	
		6.4.2	Jacobi fractions	
		6.4.3	Relation with Padé approximants	
	6.5		ence of continued fractions	
	6.6		al evaluation of continued fractions	
	0.0	6.6.1	Steed's algorithm	
		6.6.2	The modified Lentz algorithm	
	6.7		functions and continued fractions	
	0.7	6.7.1	Incomplete gamma function	
		6.7.1		
			Gauss hypergeometric functions	
7	-		the Zeros of Special Functions	191
	7.1		tion	
	7.2		assical methods	
		7.2.1	The bisection method	
		7.2.2	The fixed point method and the Newton-Raphson method	
		7.2.3	Complex zeros	197
	7.3	Local str	ategies: Asymptotic and other approximations	197
		7.3.1	Asymptotic approximations for large zeros	199
		7.3.2	Other approximations	202
	7.4	Global st	rategies I: Matrix methods	205
		7.4.1	The eigenvalue problem for orthogonal polynomials	206
		7.4.2	The eigenvalue problem for minimal solutions of TTRRs	207
	7.5		rategies II: Global fixed point methods	
		7.5.1	Zeros of Bessel functions	213

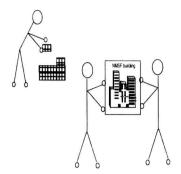
x Contents

		7.5.2	The general case	219
	7.6	Asymptot	tic methods: Further examples	224
		7.6.1	Airy functions	224
		7.6.2	Scorer functions	227
		7.6.3	The error functions	229
		7.6.4	The parabolic cylinder function	233
		7.6.5	Bessel functions	233
		7.6.6	Orthogonal polynomials	
8	Unifo	rm Asympi	totic Expansions	237
J	8.1	Asympto	tic expansions for the incomplete gamma functions	237
	8.2	Uniform	asymptotic expansions	239
	8.3	Uniform	asymptotic expansions for the incomplete gamma functions .	240
	0.0	8.3.1	The uniform expansion	242
		8.3.2	Expansions for the coefficients	244
		8.3.3	Numerical algorithm for small values of $\eta$	245
		8.3.4	A simpler uniform expansion	247
	8.4		e expansions for Bessel functions	249
	0.4	8.4.1	The Airy-type asymptotic expansions	250
		8.4.2	Representations of $a_s(\zeta)$ , $b_s(\zeta)$ , $c_s(\zeta)$ , $d_s(\zeta)$	253
		8.4.3	Properties of the functions $A_{\nu}$ , $B_{\nu}$ , $C_{\nu}$ , $D_{\nu}$	254
		8.4.4	Expansions for $a_s(\zeta)$ , $b_s(\zeta)$ , $c_s(\zeta)$ , $d_s(\zeta)$	256
		8.4.5	Evaluation of the functions $A_{\nu}(\zeta)$ , $B_{\nu}(\zeta)$ by iteration	258
	8.5		e asymptotic expansions obtained from integrals	263
	0.5	8.5.1	Airy-type asymptotic expansions	264
		8.5.2	How to compute the coefficients $\alpha_n$ , $\beta_n$	267
		8.5.3	Application to parabolic cylinder functions $\dots$	270
		0.5.5	Application to parabolic cylinder ranedolls 1 1 1 1 1 1 1	
9	Othe	r Methods		275
	9.1	Introduc		
	9.2	Padé app	proximations	276
		9.2.1	Padé approximants and continued fractions	
		9.2.2	How to compute the Padé approximants	278
		9.2.3	Padé approximants to the exponential function	. 280
		9.2.4	Analytic forms of Padé approximations	
	9.3	Sequenc	e transformations	
		9.3.1	The principles of sequence transformations	. 286
		9.3.2	Examples of sequence transformations	. 287
		9.3.3	The transformation of power series	. 288
		9.3.4	Numerical examples	. 288
	9.4	Best rati	onal approximations	
	9.5	Numeric	cal solution of ordinary differential equations: Taylor	
		expansio	on method	. 291
		9.5.1	Taylor-series method: Initial value problems	. 292
		9.5.2	Taylor-series method: Boundary value problem	. 293
	0.6		andrature methods	. 294

Contents xi

		9.6.1	Romberg quadrature	
		9.6.2	Fejér and Clenshaw-Curtis quadratures	296
		9.6.3	Other Gaussian quadratures	298
		9.6.4	Oscillatory integrals	301
Ш	Related	l Topics and	d Examples	307
10	Invers		nulative Distribution Functions	309
	10.1		on	
	10.2		ic inversion of the complementary error function	
	10.3	, ,	ic inversion of incomplete gamma functions	
		10.3.1	The asymptotic inversion method	
		10.3.2	Determination of the coefficients $\varepsilon_i$	
		10.3.3	Expansions of the coefficients $\varepsilon_i$	
	0.421.121	10.3.4	Numerical examples	
	10.4	Generaliz		
	10.5		ic inversion of the incomplete beta function	
		10.5.1	The nearly symmetric case	
		10.5.2	The general error function case	
		10.5.3	The incomplete gamma function case	
	10.6	10.5.4	Numerical aspects	
	10.6	High orde	er Newton-like methods	321
11		er Example		331
	11.1	Introducti		
	11.2		summation formula	
	11.3		nations of Stirling numbers	
		11.3.1	Definitions	
		11.3.2	Asymptotics for Stirling numbers of the second kind.	
		11.3.3	Stirling numbers of the first kind	
	11.4		c elliptic integrals	
		11.4.1	The standard forms in terms of symmetric integrals	
		11.4.2	An algorithm	
	115	11.4.3	Other elliptic integrals	
	11.5		Il inversion of Laplace transforms	
		11.5.1	Complex Gauss quadrature	
		11.5.2 11.5.3	Deforming the contour	
		11.3.3	Using Padé approximations	552
IV	Softwa	re		353
12	Assoc	iated Algor	ithms	355
	12.1	Introducti		355
		12.1.1	Frrors and stability: Basic terminology	356

	12.1.2	Design and testing of software for computing functions:			
		General philosophy	357		
	12.1.3	Scaling the functions	358		
12.2	Airy and	Scorer functions of complex arguments	359		
	12.2.1	Purpose	359		
	12.2.2	Algorithms	359		
12.3	Associate	d Legendre functions of integer and half-integer degrees			
	12.3.1	Purpose	363		
	12.3.2	Algorithms			
12.4	Bessel fu	nctions	369		
	12.4.1	Modified Bessel functions of integer and half-integer			
		orders	370		
	12.4.2	Modified Bessel functions of purely imaginary orders			
12.5	Parabolic	cylinder functions			
	12.5.1	Purpose			
	12.5.2	Algorithm	378		
12.6	Zeros of	Bessel functions	385		
	12.6.1	Purpose	385		
	12.6.2	Algorithm	385		
List of Algo	orithms		387		
Bibliograpl	hy		389		
Indov	adev 4				



### Chapter 1

## Introduction

This book deals with numerical methods for computing special functions. This means that we describe numerical methods for computing quantities for which no general definition seems to be available. What makes a function used in applications or in pure mathematics a "special function"? This is perhaps a matter of taste. There is, however, a general practical consensus regarding which functions are special: a special function should be useful for applications and should satisfy certain special properties which allow analytical treatment.

Several centuries ago the astronomers used the trigonometric functions as their basic tools in mathematics. In recent centuries the development of wave theory introduced many other functions of higher level, and many of these functions became the classical functions with which many problems from physics and other applied sciences could be described. In pure mathematics special functions arose that played a role in number theory. Also later, some of the functions that became important in statistics and probability theory were new or related to the classical functions, in particular the gamma and beta distribution functions.

There are many books now that give collections of special functions and/or describe their properties. A classical reference is the *Handbook of Mathematical Functions*, edited by Milton Abramowitz and Irene Stegun. The first edition appeared in 1964 and very soon a complete revision of this important reference, with many new chapters, will be published, together with a free accessible web version. Although the *Handbook* has introductory matter on computing and approximating elementary and special functions, complete algorithms or software are not given in either version of this reference work.

When the *Handbook* was published in 1964, a great number of algorithms and methods for computing special functions were already known, but in later years many new ideas were developed and became available in the form of mathematical software for computing special functions. Software libraries were constructed and several books appeared with collections of software, some of them claiming to cover all the functions considered in the *Handbook*.

In the present book we are not so formidably optimistic that we claim to describe computational methods or algorithms for all functions described in the old or new version of the *Handbook*. However, we describe methods which, according to our own experience, appear most frequently in the computation of special functions; this is so particularly in the first part of the book, devoted to power series, Chebyshev expansions, recurrence relations

and continued fractions, and quadrature of integrals, but many other topics are also described in the book. Some methods are illustrated with explicit software examples in the last part of the book.

Airy functions are a good example of functions for which different techniques (convergent and divergent series, Chebyshev expansions, quadrature) can be of interest for computing the functions, depending on the range of the variable. Next we consider this set of functions, solutions of the second order differential equation y'' - xy = 0, as an example for introducing basic concepts to be described later to a greater extent. It should come as no surprise that we first discuss the solution of the differential equation using power series.

### Convergent power series and differential equations

In many books of mathematical methods for physicists or engineers the words "special functions" appear for the first time when solving certain differential equations (for instance, when solving the Schrödinger equation by separation of variables) and, particularly, when trying to solve the equations by power series. Equations such as the Hermite or Bessel equations appear, which can be solved by using convergent power series.

The fact that we can find a convergent series for a specific solution of a second order ordinary differential equation may seem to indicate that the computation of such a function is of no concern. However, this is not true from a numerical point of view, even when the series does converge for any real or complex value of the argument. It could only be true if we had at our disposal a computer equipped with infinite precision arithmetic, that was infinitely fast, and that was without limitations in the numbers which can be stored. Because this ideal machine does not exist, the use of series will be limited by these three factors (as any other method).

Take, for instance, the elementary example y'' - y = 0, with  $y_1(z) = e^z$  and  $y_2(z) = e^{-z}$  as two independent solutions. Maclaurin series for  $y_1$  and  $y_2$  are convergent for all z. However, when  $\Re z > 0$  the range of accurate computation of  $y_2(z)$  should be restricted to small |z|, because for large |z|, the first terms of the series are much larger in modulus than the whole sum, leading to numerical cancellation and severe loss of significant digits. Also, the series for  $y_1(z)$  is dangerous for large z because many terms need to be added. Maclaurin series should not be used very far from z = 0.

For not-so-elementary functions, the same types of limitations occur when using series (Chapter 2). Take for instance the very important case of the Airy functions, which are solutions of the second order ordinary differential equation

$$y''(z) - zy(z) = 0. (1.1)$$

We can try power series to find the general solution. Substituting  $y(z) = \sum_{n=0}^{\infty} a_n z^n$  we readily see that  $a_{2+3n} = 0$ ,  $n \in \mathbb{N}$ , and that two linearly independent solutions are

$$y_1(z) = \sum_{k=0}^{\infty} 3^k \left(\frac{1}{3}\right)_k \frac{z^{3k}}{(3k)!}, \quad y_2(z) = \sum_{k=0}^{\infty} 3^k \left(\frac{2}{3}\right)_k \frac{z^{3k+1}}{(3k+1)!},$$
 (1.2)

where  $(\alpha)_0 = 1$ ,  $(\alpha)_k = \alpha(\alpha + 1) \cdots (\alpha + k - 1)$ ,  $k \ge 1$ . Elementary methods (the ratio test) can be used to prove that both series are convergent for any complex value of z.

At this moment, let us restrict the problem to real positive z = x. We observe that both  $y_1(x)$  and  $y_2(x)$  are positive and increasing for x > 0; all the terms of the series are positive and no cancellations occur. Now, because all the solutions of the differential equation can be written as  $y(x) = \alpha y_1(x) + \beta y_2(x)$ , and both  $y_1(x)$  and  $y_2(x)$  tend to  $+\infty$  as  $x \to \infty$ , the equation necessarily has a solution f(x), called a *recessive solution*, such that  $f(x)/y(x) \to 0$  for any other solution y(x) not proportional to f(x).

Indeed, as  $x \to +\infty$ , either  $y_1(x)/y_2(x) \to 0$ , giving that  $y_1(x)$  is recessive, or  $y_2(x)/y_1(x) \to 0$ , giving that  $y_2(x)$  is recessive, or  $y_1(x)/y_2(x) \to C \neq 0$ , giving that  $y_1(x) - Cy_2(x)$  is recessive. The last possibility is what happens for the recessive solutions of (1.1), with  $C = 3^{1/3}\Gamma(2/3)/\Gamma(1/3)$ . Again, for an algorithm the Maclaurin series can only be considered for not too large x, particularly for computing the recessive solution (such as for  $e^{-x}$  in the former example).

Later we will see that the recessive solution is a multiple of Ai(z), which is exponentially small at  $+\infty$ , and both  $y_1(z)$  and  $y_2(z)$  given in (1.2) are exponentially large. Hence, the solutions  $y_1(z)$  and  $y_2(z)$  cannot be used to compute all solutions of (1.1) for all values of z, in particular when z is large, because this may introduce large errors. We say that  $y_1(z)$  and  $y_2(z)$  do not constitute a numerically satisfactory pair of solutions of (1.1) at  $+\infty$ , because the recessive solution cannot be computed by these two for large positive z. The same situation occurs when considering differential equations for other special functions. For a graph of the Airy function Ai(x), see Figure 1.1.

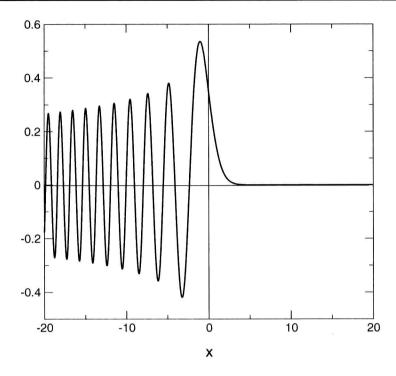
Obviously, one should never compute an exponentially decreasing function for large values of the variable as a linear combination of two increasing functions for values of the argument for which the computed value is much smaller than the increasing functions. Subtracting two large quantities for obtaining a small quantity is a numerical disaster. For the recessive Airy function Ai(x) we have Ai(1) = 0.135..., and the loss of significant digits becomes noticeable when we use the functions of (1.2) when  $x \ge 1$ . Therefore, if we need to compute the recessive solution, we must consider an independent method of computation for this function.

In addition, one needs to pay attention to different ranges of the variable in order to select a numerical satisfactory pair. For instance, going back to the elementary case, y'' - y = 0, the solutions  $y_1(z) = e^z$  and  $y_2(z) = e^{-z}$ , which constitute a numerically satisfactory pair when  $\Re z \gg 0$ , but this pair is not a satisfactory pair near z = 0. Near the origin, it is better to include  $y_3(z) = \sinh z = (y_1(z) - y_2(z))/2$  as a solution when |z| is small; a companion solution could be  $y_4(z) = \cosh z$ . Of course,  $y_3(z)$  and  $y_4(z)$  do not constitute a numerically satisfactory pair when  $|\Re z|$  is large.

### Liouville-Green approximation and dominant asymptotic behavior

More information on the behavior of the solutions of a linear second order differential equation can be obtained by transforming the equation. It is a straightforward matter to check (see also §2.2.4) that, if y(z) is a solution of (1.1), then the function  $Y(z) = z^{1/4}y(z)$  satisfies the equation

$$\ddot{Y}(\zeta) + \left(-1 + \frac{5}{36\zeta^2}\right)Y(\zeta) = 0$$
 (1.3)



**Figure 1.1.** The Airy function Ai(x) is oscillating for x < 0 and exponentially small for  $x \to +\infty$ .

in the variable  $\zeta=\frac{2}{3}z^{3/2}$ . Looking at (1.3), we can expect that for large  $\zeta$  the term  $5/(36\zeta^2)$  will be negligible and that the solutions will behave exponentially,  $Y(\zeta)\sim\exp(\pm\zeta)$ . Undoing the changes, we expect that the recessive solution of (1.1) behaves as  $z^{-1/4}\exp(-\frac{2}{3}z^{3/2})$ . A more detailed analysis [168, Chap. 6] shows that this approximation (the Liouville–Green approximation) makes sense. Therefore, we are certain that a recessive solution exists which decreases exponentially.

### Condition of solution of ordinary differential equations

It is not a surprise that the recessive solutions of the defining differential equations are usually the most important in applications; indeed, physical quantities are by nature finite quantities and functions representing these quantities should be bounded. From a numerical point of view, as explained, a special treatment for these functions is needed.

Anyway, isn't the Airy function a solution of a second order differential equation? Isn't it true that most students who have received a course on numerical analysis are familiar with methods for solving second order differential equations? Isn't it true that numerical methods for second order differential equations apply to any solution of the equation? So, can we rely blindly on, let's say, Runge–Kutta? Or do we need more analysis? The answer is, obviously, yes, analysis is necessary and one needs to know if the desired solution is recessive.