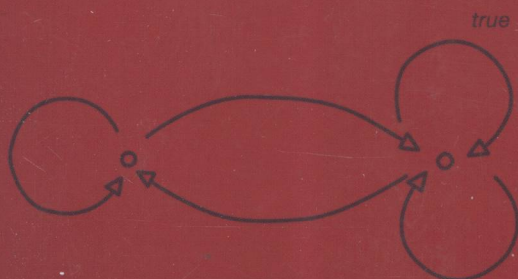
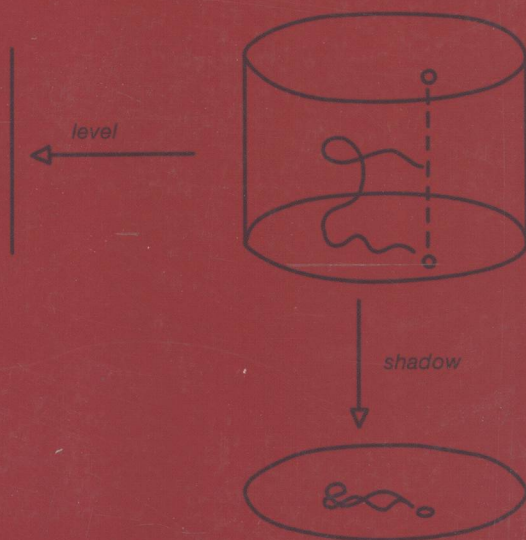


Conceptual Mathematics

A first introduction to categories

Second Edition

F. William Lawvere
Stephen H. Schanuel



CAMBRIDGE

0154-1
L425
E.2

Conceptual Mathematics, 2nd Edition

A first introduction to categories

F. WILLIAM LAWVERE

SUNY at Buffalo

STEPHEN H. SCHANUEL

SUNY at Buffalo



E2009003295



CAMBRIDGE
UNIVERSITY PRESS

CAMBRIDGE UNIVERSITY PRESS

Cambridge, New York, Melbourne, Madrid, Cape Town, Singapore, São Paulo, Delhi

Cambridge University Press

The Edinburgh Building, Cambridge CB2 8RU, UK

www.cambridge.org

Information on this title: www.cambridge.org/9780521894852

This edition © Cambridge University Press 2009

This publication is in copyright. Subject to statutory exception and to the provisions of relevant collective licensing agreements, no reproduction of any part may take place without the written permission of Cambridge University Press.

First published 1997

Second edition 2009

Printed in the United Kingdom

A catalog record for this publication is available from the British Library.

Library of Congress Cataloging in Publication Data

Lawvere, F.W.

Conceptual mathematics : a first introduction to categories / F. William

Lawvere, Stephen H. Schanuel. – 2nd ed.

p. cm.

Includes index.

ISBN 978-0-521-71916-2 (pbk.) – ISBN 978-0-521-89485-2 (hardback)

1. Categories (Mathematics) I. Schanuel, S. H. (Stephen Hoel), 1933– II. Title.

QA169.L355 2008

512'.62–dc22 2007043671

ISBN 978-0-521-89485-2 hardback

ISBN 978-0-521-71916-2 paperback

Cambridge University Press has no responsibility for the persistence or accuracy of URLs for external or third-party Internet Websites referred to in this publication and does not guarantee that any content on such websites is, or will remain, accurate or appropriate.

to Fatima

Preface

Since its first introduction over 60 years ago, the concept of category has been increasingly employed in all branches of mathematics, especially in studies where the relationship between different branches is of importance. The categorical ideas arose originally from the study of a relationship between geometry and algebra; the fundamental simplicity of these ideas soon made possible their broader application.

The categorical concepts are latent in elementary mathematics; making them more explicit helps us to go beyond elementary algebra into more advanced mathematical sciences. Before the appearance of the first edition of this book, their simplicity was accessible only through graduate-level textbooks, because the available examples involved topics such as modules and topological spaces.

Our solution to that dilemma was to develop from the basics the concepts of directed graph and of discrete dynamical system, which are mathematical structures of wide importance that are nevertheless accessible to any interested high-school student. As the book progresses, the relationships between those structures exemplify the elementary ideas of category. Rather remarkably, even some detailed features of graphs and of discrete dynamical systems turn out to be shared by other categories that are more continuous, e.g. those whose maps are described by partial differential equations.

Many readers of the first edition have expressed their wish for more detailed indication of the links between the elementary categorical material and more advanced applications. This second edition addresses that request by providing two new articles and four appendices. A new article introduces the notion of connected component, which is fundamental to the qualitative leaps studied in elementary graph theory and in advanced topology; the introduction of this notion forces the recognition of the role of functors.

The appendices use examples from the text to sketch the role of adjoint functors in guiding mathematical constructions. Although these condensed appendices cannot substitute for a more detailed study of advanced topics, they will enable the student, armed with what has been learned from the text, to approach such study with greater understanding.

Buffalo, January 8, 2009

F. William Lawvere
Stephen H. Schanuel

Organisation of the book

The reader needs to be aware that this book has two very different kinds of ‘chapters’:

The **Articles** form the backbone of the book; they roughly correspond to the written material given to our students the first time we taught the course.

The **Sessions**, reflecting the informal classroom discussions, provide additional examples and exercises. Students who had difficulties with some of the exercises in the Articles could often solve them after the ensuing Sessions. We have tried in the Sessions to preserve the atmosphere (and even the names of the students) of that first class. The more experienced reader could gain an overview by reading only the Articles, but would miss out on many illuminating examples and perspectives.

Session 1 is introductory. Exceptionally, Session 10 is intended to give the reader a taste of more sophisticated applications; mastery of it is not essential for the rest of the book.

Each Article is further discussed and elaborated in the specific subsequent Sessions indicated below:

Article I	Sessions 2 and 3
Article II	Sessions 4 through 9
Article III	Sessions 11 through 17
Article IV	Sessions 19 through 29
Article V	Sessions 30 and 31
Article VI	Sessions 32 and 33
Article VII	Sessions 34 and 35

The **Appendices**, written in a less leisurely manner, are intended to provide a rapid summary of some of the main possible links of the basic material of the course with various more advanced developments of modern mathematics.

Acknowledgements

First Edition

This book would not have come about without the invaluable assistance of many people:

Emilio Faro, whose idea it was to include the dialogues with the students in his masterful record of the lectures, his transcriptions of which grew into the Sessions; Danilo Lawvere, whose imaginative and efficient work played a key role in bringing this book to its current form;

our students (some of whom still make their appearance in the book), whose efforts and questions contributed to shaping it;

John Thorpe, who accepted our proposal that a foundation for discrete mathematics *and* continuous mathematics could constitute an appropriate course for beginners.

Special thanks go to Alberto Peruzzi, who provided invaluable expert criticism and much encouragement. Many helpful comments were contributed by John Bell, David Benson, Andreas Blass, Aurelio Carboni, John Corcoran, Bill Faris, Emilio Faro, Elaine Landry, Fred Linton, Saunders Mac Lane, Kazem Mahdavi, Mara Mondolfo, Koji Nakatogawa, Ivonne Pallares, Norm Severo, and Don Schack, as well as by many other friends and colleagues. We are grateful also to Cambridge University Press, in particular to Roger Astley and Maureen Storey, for all their work in producing this book.

Above all, we can never adequately acknowledge the ever-encouraging generous and graceful spirit of Fatima Fenaroli, who conceived the idea that this book should exist, and whose many creative contributions have been irreplaceable in the process of perfecting it.

Thank you all,

Buffalo, New York
2009

F. William Lawvere
Stephen H. Schanuel

Second Edition

Thanks to the readers who encouraged us to expand to this second edition, and thanks to Roger Astley and his group at Cambridge University Press for their help in bringing it about.

2009

F. William Lawvere
Stephen H. Schanuel

Contents

	Preface	xiii
	Organisation of the book	xv
	Acknowledgements	xvii
	<i>Preview</i>	
Session 1	Galileo and multiplication of objects	3
	1 Introduction	3
	2 Galileo and the flight of a bird	3
	3 Other examples of multiplication of objects	7
	<i>Part I The category of sets</i>	
Article I	Sets, maps, composition	13
	1 Guide	20
Summary:	Definition of category	21
Session 2	Sets, maps, and composition	22
	1 Review of Article I	22
	2 An example of different rules for a map	27
	3 External diagrams	28
	4 Problems on the number of maps from one set to another	29
Session 3	Composing maps and counting maps	31
	<i>Part II The algebra of composition</i>	
Article II	Isomorphisms	39
	1 Isomorphisms	39
	2 General division problems: Determination and choice	45
	3 Retractions, sections, and idempotents	49
	4 Isomorphisms and automorphisms	54
	5 Guide	58
Summary:	Special properties a map may have	59

Session 4	Division of maps: Isomorphisms	60
	1 Division of maps versus division of numbers	60
	2 Inverses versus reciprocals	61
	3 Isomorphisms as ‘divisors’	63
	4 A small zoo of isomorphisms in other categories	64
Session 5	Division of maps: Sections and retractions	68
	1 Determination problems	68
	2 A special case: Constant maps	70
	3 Choice problems	71
	4 Two special cases of division: Sections and retractions	72
	5 Stacking or sorting	74
	6 Stacking in a Chinese restaurant	76
Session 6	Two general aspects or uses of maps	81
	1 Sorting of the domain by a property	81
	2 Naming or sampling of the codomain	82
	3 Philosophical explanation of the two aspects	84
Session 7	Isomorphisms and coordinates	86
	1 One use of isomorphisms: Coordinate systems	86
	2 Two abuses of isomorphisms	89
Session 8	Pictures of a map making its features evident	91
Session 9	Retracts and idempotents	99
	1 Retracts and comparisons	99
	2 Idempotents as records of retracts	100
	3 A puzzle	102
	4 Three kinds of retract problems	103
	5 Comparing infinite sets	106
Quiz		108
How to solve the quiz problems		109
Composition of opposed maps		114
Summary/quiz on pairs of ‘opposed’ maps		116
Summary: On the equation $p \circ j = 1_A$		117
Review of ‘I-words’		118
Test 1		119
Session 10	Brouwer’s theorems	120
	1 Balls, spheres, fixed points, and retractions	120
	2 Digression on the contrapositive rule	124
	3 Brouwer’s proof	124

4	Relation between fixed point and retraction theorems	126
5	How to understand a proof: The objectification and ‘mapification’ of concepts	127
6	The eye of the storm	130
7	Using maps to formulate guesses	131

Part III Categories of structured sets

Article III	Examples of categories	135
1	The category $\mathcal{S}^{\circlearrowright}$ of endomaps of sets	136
2	Typical applications of $\mathcal{S}^{\circlearrowright}$	137
3	Two subcategories of $\mathcal{S}^{\circlearrowright}$	138
4	Categories of endomaps	138
5	Irreflexive graphs	141
6	Endomaps as special graphs	143
7	The simpler category \mathcal{S}^{\downarrow} : Objects are just maps of sets	144
8	Reflexive graphs	145
9	Summary of the examples and their general significance	146
10	Retractions and injectivity	146
11	Types of structure	149
12	Guide	151
 Session 11	 Ascending to categories of richer structures	 152
1	A category of richer structures: Endomaps of sets	152
2	Two subcategories: Idempotents and automorphisms	155
3	The category of graphs	156
 Session 12	 Categories of diagrams	 161
1	Dynamical systems or automata	161
2	Family trees	162
3	Dynamical systems revisited	163
 Session 13	 Monoids	 166
 Session 14	 Maps preserve positive properties	 170
1	Positive properties versus negative properties	173
 Session 15	 Objectification of properties in dynamical systems	 175
1	Structure-preserving maps from a cycle to another endomap	175
2	Naming elements that have a given period by maps	176
3	Naming arbitrary elements	177
4	The philosophical role of N	180
5	Presentations of dynamical systems	182

Session 16	Idempotents, involutions, and graphs	187
	1 Solving exercises on idempotents and involutions	187
	2 Solving exercises on maps of graphs	189
Session 17	Some uses of graphs	196
	1 Paths	196
	2 Graphs as diagram shapes	200
	3 Commuting diagrams	201
	4 Is a diagram a map?	203
Test 2		204
Session 18	Review of Test 2	205
	<i>Part IV Elementary universal mapping properties</i>	
Article IV	Universal mapping properties	213
	1 Terminal objects	213
	2 Separating	215
	3 Initial object	215
	4 Products	216
	5 Commutative, associative, and identity laws for multiplication of objects	220
	6 Sums	222
	7 Distributive laws	222
	8 Guide	223
Session 19	Terminal objects	225
Session 20	Points of an object	230
Session 21	Products in categories	236
Session 22	Universal mapping properties and incidence relations	245
	1 A special property of the category of sets	245
	2 A similar property in the category of endomaps of sets	246
	3 Incidence relations	249
	4 Basic figure-types, singular figures, and incidence, in the category of graphs	250
Session 23	More on universal mapping properties	254
	1 A category of pairs of maps	255
	2 How to calculate products	256

Session 24	Uniqueness of products and definition of sum	261
	1 The terminal object as an identity for multiplication	261
	2 The uniqueness theorem for products	263
	3 Sum of two objects in a category	265
Session 25	Labelings and products of graphs	269
	1 Detecting the structure of a graph by means of labelings	270
	2 Calculating the graphs $A \times Y$	273
	3 The distributive law	275
Session 26	Distributive categories and linear categories	276
	1 The standard map	
	$A \times B_1 + A \times B_2 \longrightarrow A \times (B_1 + B_2)$	276
	2 Matrix multiplication in linear categories	279
	3 Sum of maps in a linear category	279
	4 The associative law for sums and products	281
Session 27	Examples of universal constructions	284
	1 Universal constructions	284
	2 Can objects have negatives?	287
	3 Idempotent objects	289
	4 Solving equations and picturing maps	292
Session 28	The category of pointed sets	295
	1 An example of a non-distributive category	295
Test 3		299
Test 4		300
Test 5		301
Session 29	Binary operations and diagonal arguments	302
	1 Binary operations and actions	302
	2 Cantor's diagonal argument	303

Part V Higher universal mapping properties

Article V	Map objects	313
	1 Definition of map object	313
	2 Distributivity	315
	3 Map objects and the Diagonal Argument	316
	4 Universal properties and 'observables'	316
	5 Guide	319
Session 30	Exponentiation	320
	1 Map objects, or function spaces	320

	2 A fundamental example of the transformation of map objects	323
	3 Laws of exponents	324
	4 The distributive law in cartesian closed categories	327
Session 31	Map object versus product	328
	1 Definition of map object versus definition of product	329
	2 Calculating map objects	331
Article VI	The contravariant parts functor	335
	1 Parts and stable conditions	335
	2 Inverse Images and Truth	336
Session 32	Subobject, logic, and truth	339
	1 Subobjects	339
	2 Truth	342
	3 The truth value object	344
Session 33	Parts of an object: Toposes	348
	1 Parts and inclusions	348
	2 Toposes and logic	352
Article VII	The Connected Components Functor	358
	1 Connectedness versus discreteness	358
	2 The points functor parallel to the components functor	359
	3 The topos of right actions of a monoid	360
Session 34	Group theory and the number of types of connected objects	362
Session 35	Constants, codiscrete objects, and many connected objects	366
	1 Constants and codiscrete objects	366
	2 Monoids with at least two constants	367
Appendices		368
Appendix I	Geometry of figures and algebra of functions	369
	1 Functors	369
	2 Geometry of figures and algebra of functions as categories themselves	370
Appendix II	Adjoint functors with examples from graphs and dynamical systems	372
Appendix III	The emergence of category theory within mathematics	378
Appendix IV	Annotated Bibliography	381
Index		385

Preview

SESSION 1

Galileo and multiplication of objects

1. Introduction

Our goal in this book is to explore the consequences of a new and fundamental insight about the nature of mathematics which has led to better methods for understanding and using mathematical concepts. While the insight and methods are simple, they are not as familiar as they should be; they will require some effort to master, but you will be rewarded with a clarity of understanding that will be helpful in unravelling the mathematical aspect of any subject matter.

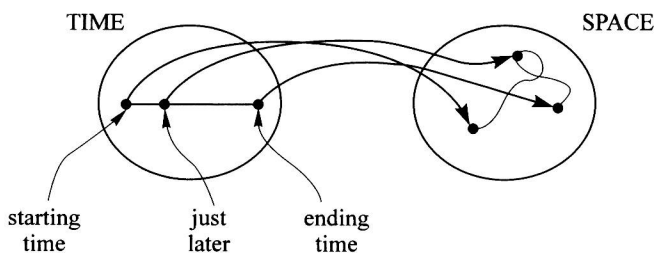
The basic notion which underlies all the others is that of a *category*, a ‘mathematical universe’. There are many categories, each appropriate to a particular subject matter, and there are ways to pass from one category to another. We will begin with an informal introduction to the notion and with some examples. The ingredients will be objects, maps, and composition of maps, as we will see.

While this idea, that mathematics involves different categories and their relationships, has been implicit for centuries, it was not until 1945 that Eilenberg and Mac Lane gave *explicit* definitions of the basic notions in their ground-breaking paper ‘A general theory of natural equivalences’, synthesizing many decades of analysis of the workings of mathematics and the relationships of its parts.

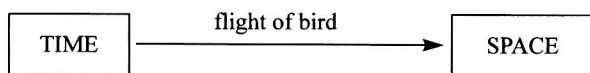
2. Galileo and the flight of a bird

Let’s begin with Galileo, four centuries ago, puzzling over the problem of motion. He wished to understand the precise motion of a thrown rock, or of a water jet from a fountain. Everyone has observed the graceful parabolic arcs these follow; but the motion of a rock means more than its track. The motion involves, for each instant, the position of the rock at that instant; to record it requires a motion picture rather than a time exposure. We say the motion is a ‘map’ (or ‘function’) from time to space.

The flight of a bird as a map from time to space



Schematically:

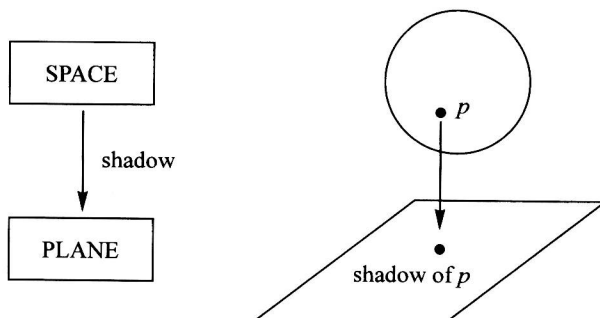


You have no doubt heard the legend; Galileo dropped a heavy weight and a light weight from the leaning tower of Pisa, surprising the onlookers when the weights hit the ground simultaneously. The study of vertical motion, of objects thrown straight up, thrown straight down, or simply dropped, seems too special to shed much light on general motion; the track of a dropped rock is straight, as any child knows. However, the motion of a dropped rock is not quite so simple; it accelerates as it falls, so that the last few feet of its fall takes less time than the first few. Why had Galileo decided to concentrate his attention on this special question of vertical motion? The answer lies in a simple equation:

$$\text{SPACE} = \text{PLANE} \times \text{LINE}$$

but it requires some explanation!

Two new maps enter the picture. Imagine the sun directly overhead, and for each point in space you'll get a shadow point on the horizontal plane:



This is one of our two maps: the 'shadow' map from space to the plane. The second map we need is best imagined by thinking of a vertical line, perhaps a pole stuck into the ground. For each point in space there is a corresponding point on the line, the one at the same level as our point in space. Let's call this map 'level':