

Jorge I. Auñón V. Chandrasekar

Introduction to

PROBABILITY

and

RANDOM PROCESSES

Jorge Auñón
Texas Tech University

V. Chandrasekar
Colorado State University

The McGraw-Hill Companies, Inc.

New York St. Louis San Francisco Auckland Bogotá Caracas Lisbon London Madrid Mexico City Milan Montreal New Delhi San Juan Singapore Sydney Tokyo Toronto

McGraw-Hill

HIII
A Division of The McGraw Hill Companies

Introduction to Probability and Random Processes

Copyright © 1997 by The McGraw-Hill Companies, Inc. All rights reserved. Printed in the United States of America. Except as permitted under the United States Copyright Act of 1976, no part of this publication may be reproduced or distributed in any form or by any means, or stored in a data base or retrieval system, without the prior written permission of the publisher.

This book is printed on acid-free paper.

1234567890 DOC DOC 9009876

ISBN 0-07-001563-5

This book was set in Palatino.

The editors were Lynn Cox and Terri Wicks.

The production supervisor was Louis Swaim.

The cover was designed by Nicole Leong.

R. R. Donnelley & Sons Company was printer and binder.

Library of Congress Cataloging-in-Publication Data

Auñón, Jorge.

Introduction to probability and random processes / Jorge Auñón,

V. Chandrasekar.

p. cm.

Includes index.

ISBN 0-07-001563-5

1. Probabilities. 2. Stochastic processes. I. Chandrasekar, V.

II. Title.

OA273.A86 1996

519.2—dc21

96-44042

CIP

Communications and Signal Processing

Senior Consulting Editor

Stephen W. Director, University of Michigan, Ann Arbor

Auñón/Chandrasekar: Introduction to Probability and Random Processes

Antoniou: Digital Filters: Analysis and Design

Candy: Signal Processing: The Model-Based Approach
Candy: Signal Processing: The Modern Approach

Carlson: Communications Systems: An Introduction to Signals and Noise in Electrical

Communication

Cherin: An Introduction to Optical Fibers
Collin: Antennas and Radiowave Propagation
Collin: Foundations for Microwave Engineering

Cooper and McGillem: Modern Communications and Spread Spectrum

Davenport: Probability and Random Processes: An Introduction for Applied Scientists and

Engineers

Drake: Fundamentals of Applied Probability Theory

Huelsman and Allen: Introduction to the Theory and Design of Active Filters

Jong: Method of Discrete Signal and System Analysis

Keiser: Local Area Networks

Keiser: Optical Fiber Communications

Kershenbaum: Telecommunications Network Design Algorithms

Kraus: Antennas

Kuc: Introduction to Digital Signal Processing

Mitra: Digital Signal Processing: A Computer-Based Approach
Papoulis: Probability, Random Variables, and Stochastic Processes

Papoulis: Signal Analysis

Papoulis: The Fourier Integral and Its Applications

Peebles: Probability, Random Variables, and Random Signal Principles

Proakis: Digital Communications

Schwartz: Information Transmission, Modulation, and Noise

Schwartz and Shaw: Signal Processing Siebert: Circuits, Signals, and Systems Smith: Modern Communication Circuits

Taub and Schilling: Principles of Communication Systems

Taylor: Principles of Signals and Systems

Also Available from McGraw-Hill

Schaum's Outline Series in Electronics & Electrical Engineering

Most outlines include basic theory, definitions, and hundreds of example problems solved in step-by-step detail, and supplementary problems with answers.

Related titles on the current list include:

Analog & Digital Communications
Basic Circuit Analysis
Basic Electrical Engineering
Basic Electricity
Basic Mathematics for Electricity & Electronics
Digital Principles
Electric Circuits
Electric Machines & Electromechanics
Electric Power Systems
Electronic Communication
Electronic Devices & Circuits
Feedback & Control Systems
Introduction to Digital Systems

Schaum's Electronic Tutors

Microprocessor Fundamentals

Signals & Systems

A Schaum's Outline plus the power of Mathcad® software. Use your computer to learn the theory and solve problems—every number, formula, and graph can be changed and calculated on screen.

Related titles on the current list include:

Electric Circuits
Feedback & Control Systems
Electromagnetics
College Physics

Available at most college bookstores, or for a complete list of titles and prices, write to: The McGraw-Hill Companies
Schaum's
11 West 19th Street
New York, New York 10011-4285
(212-337-4097)

To my mother and father Haydée Prieto and Fernando Auñón

To my beloved wife Margaret

To my daughters Christine, Melissa, Serena, and Maria

J.A.

I dedicate this book to my "GURUS" (all my teachers).

V.C.

Preface

This book presents an introduction to the topics of statistics, random variables, and random processes. It is intended for junior and senior engineering students, and offers a unique, practical approach to the subject. With a carefully selected blend of both theoretical and real-data examples, it connects the classroom to real-world problem solving, and uses the computer to explore the subtleties of probability theory and its applications. The book includes a large number of computer examples using both Mathcad¹ and MATLAB.² It also contains traditional end-of-chapter problems. Rather than

¹Mathcad is a registered trademark of MathSoft, Inc., 101 Main Street, Massachusetts, 02142. WWW:http://www.mathsoft.com. Printed by permission of MathSoft, Inc.

²MATLAB is a registered trademark of the MathWorks, Inc., 24 Prime Park Way, Natick, MA 01760-1500, Phone: 508-647-7000, WWW: http://www.mathworks.com.

xiv Preface

emphasizing programming sophistication, the book shows how the computer can be used as a live interface to visualize problem solving. The use of Mathcad and MATLAB demonstrate a natural progression through the solution of a problem. Students are able to change parameters in equations, or change entire equations and have results immediately available for their use. The computer examples available with each chapter are not designed as Mathcad or MATLAB tutorials. They are written in a fairly simplistic manner in order that students will be able to modify them to solve classroom type problems.

Chapters 1 and 2 present a general introduction to probability theory and to the basic statistical properties of a random variable. Chapter 3 departs from traditional textbooks by introducing students to the computer generation of gaussian-distributed random variables. The run test and the chi-square test are explained to test the equivalence of a probability density function of experimental data to a theoretical density function. Both Mathcad and MATLAB computer examples are presented at the end of the chapter.

Chapter 4 introduces the concept of random processes and the autocorrelation function. The coverage includes estimating the autocorrelation function of records of limited duration. Following the book's central pedagogical strategy, this section begins with an explanation of theory and a working, theoretical example. Then, in order to make the transition between a theoretical result and its practical use, real time-limited data is presented and analyzed.

Chapter 5 introduces students to the concept of the spectral density of a random process, and explores a number of techniques for the estimation of spectral density. First, the spectral density is estimated as the Fourier transform of the autocorrelation function. The autocorrelation function of a time-limited record is estimated using the FFT, and then the Fourier transform of the autocorrelation is found. The chapter also explores a second technique, the periodogram. In this technique, the data is divided into overlapping segments; the computation of the Fourier transform of each segment; and the average of all segments obtained. The model-based approach is the third technique explored. It exposes students to the theory that a random process may be described as an autoregressive process. The order of the model and coefficients of the model are found, and the estimate of the spectral density is calculated. A large collection of Mathcad and MATLAB computer examples are presented at the end of the chapter.

Chapter 6 introduces the analysis of linear systems when their inputs are random processes. It also considers the special case of matched filters. Chapter 7 presents a wide variety of useful applications, ranging from biomedical systems to radar systems. Finally, the Appendix provides a concise yet complete presentation of the fast Fourier transform (FFT).

Preface xv

In closing, we would like to thank the reviewers who aided in the development of the book: Dr. Ronald A. Iltis, University of California at Santa Barbara; Dr. V. Krishnan, University of Massachusetts at Lowell; Dr. Steven A. Tretter, University of Maryland; and, Jitendra K. Tugnait, Auburn University. We would also like to thank our editor, Lynn B. Cox, and editing supervisor, Terri Wicks.

Jorge I. Auñón V. Chandrasekar

About the Authors

Jorge I. Auñón is Dean of Engineering and a Professor of Electrical Engineering at Texas Tech University. He received his D.Sc. from The George Washington University in 1972. From 1973 until 1988, he taught electrical engineering at Purdue University. At Colorado State University, he served as Head of Electrical Engineering, and in 1995 he moved to Texas Tech University. Dr. Auñón is a Fellow of the IEEE and a Fulbright Scholar.

V. Chandrasekar received his Ph.D from Colorado State University, where he is currently an Associate Professor of Electrical Engineering. His main research interests are signal processing, radar systems, remote sensing polarimetry and neural networks. He has published over 120 papers on these topics. Dr. Chandrasekar has received several awards for his outstanding commitment to teaching and research. In 1996, he was a visiting professor at the National Research Council (CNR) of Italy.

McGraw-Hill Series in Electrical and Computer Engineering

Senior Consulting Editor

Stephen W. Director, University of Michigan, Ann Arbor

Circuits and Systems
Communications and Signal Processing
Computer Engineering
Control Theory
Electromagnetics
Electronics and VLSI Circuits
Introductory
Power and Energy
Radar and Antennas

Previous Consulting Editors

Ronald N. Bracewell, Colin Cherry, James F. Gibbons, Willis W. Harman, Hubert Heffner, Edward W. Herold, John G. Linvill, Simon Ramo, Ronald A. Rohrer, Anthony E. Siegman, Charles Susskind, Frederick E. Terman, John G. Truxal, Ernst Weber, and John R. Whinnery

Contents

	Prerace	X111
Chapter 1	Introduction to Probability	1
1.0	Basic Concepts of Probability	
1.1	Definitions	1 4 6
1.2	Elementary Set Theory	6
1.3	Axiomatic Approach to the Theory of Probability	10
1.4	Discrete and Continuous Sample Spaces	11
1.5	Conditional Probability and Bayes' Theorem	12
1.6	Independence of Events	18
1.7	Bernoulli Trials	21
1.8	Chapter Summary	27
1.9	Problems	28
1.10	Computer Examples	33
Chapter 2	Random Variables	40
2.0	Introduction	40
2.1	Concept of a Random Variable	40
2.2	Cumulative Distribution Function	41
2.3	Probability Density Function	47

x Contents

2.4	Basic Statistical Properties of a Random Variable and	50
2.5	Expected Values	
2.5	Moments	52
2.6	Examples of Different Distributions	56
2.7	Moment-Generating Functions and Characteristic Function	
2.8	Transformation of a Random Variable	71
2.9	Conditional Probability Density	81
2.10	Chapter Summary	85
2.11	Problems	87
2.12	Computer Examples	93
Chapter 3	Multiple Random Variables	105
3.0	Introduction	105
3.1	Joint Cumulative Distribution Function of two Random Variables	106
3.2	Joint Probability Density Function of two Random Variables	108
3.3	Statistical Properties of Jointly Distributed Random Variables: Joint Moments	112
3.4	Jointly Distributed Gaussian Random Variables	118
3.5	Functions of Gaussian Jointly Distributed Random	119
0.4	variables	
3.6	Conditional Probability Density	121
3.7	Probability Density Function of Sum of two Random Variables	124
3.8	Expected Value of Sums of Random Variables	136
3.9	Variance of Sum of Random Variables	136
3.10	Brief Introduction to Central Limit Theorem	138
3.11	Estimate of Population Mean, Expected Value, and Variance of Estimate	141
3.12	Estimate of Population Variance	145
3.13	Computer Generation of Uniform Random Variables	147
3.14	Computer Generation of Gaussian Distributed Random	148
	Variables using the Central Limit Theorem	140
3.15	Testing the Equivalence of a Probability Density Function	1/0
	of Experimental Data to a Theoretical Density Function	140
3.16	Chapter Summary	157
3.17	Problems	
3.18	Computer Examples	159 163
Chapter 4	Multiple Random Variables	200
4.0	Random Processes: Basic Definitions	203
4.1		203
4.1 4.2	Basic Properties of Random Processes Autocorrelation Function	207
4.3	The Cross-Correlation Function	212
ユ・ン	AIR CIOSTCOHEIAHOH PHICHON	')') 🗔

Contents xi

4.4	Estimate of Autocorrelation Function of Sample Records of Limited Duration	228
4.5	Chapter Summary	232
4.6	Problems	235
4.7	Computer Examples	241
Chapter 5	Spectral Density	268
5.0	Introduction	268
5.1	Basic Definition of the Spectral Density of a Random Process	269
5.2	Properties	272
5.3	White Noise	274
5.4	Time Domain and Frequency Domain Correspondence	277
5.5	Estimate of the Autocorrelation Function of a Discrete Function of Time using Frequency Domain Techniques	277
5.6	Estimation of the Spectral Density of Records of Limited Duration	282
5.7	Cross-Spectral Density	307
5.8	Estimation of Cross-Spectral Density of Records of Limited Duration	311
5.9	Coherence	315
5.10	Chapter Summary	321
5.11	Problems	324
5.12	Computer Examples	327
Chapter 6	Linear Systems	439
6.0	Introduction	439
6.1	Properties	441
6.2	Random Inputs	441
6.3	Estimate of the Response of Linear Systems using Frequency Domain Techniques	448
6.4	Matched Filter	453
6.5	Chapter Summary	462
6.6	Problems	463
6.7	Computer Examples	469
Chapter 7	Applications	492
7.0	Introduction	492
7.1	Radar Systems	493
7.2	Communication Systems	497
7.3	Solid-State Electronics	503
7.4	Computer Engineering	504
<i>7.</i> 5	Biomedical Systems	507

xii Contents

Appendix	Introduction of the Fast Fourier Transform	513
A.1	Introduction	513
A.2	Relationship Between the Continuous Fourier	514
	Transform (CFT) and the Discrete Fourier Transform (DF	T)
A.3	The Inverse Discrete Fourier Transform (IDFT)	518
A.4	The FFT Algorithm, Computational Speed, and Effects of Zero Padding	518
A.5	Practical Aspects of the Use of the FFT Algorithm	525
	Bibliography	529
	Index	531

Introduction to Probability

1.0 BASIC CONCEPTS OF PROBABILITY

The term probability is intimately involved with the term uncertainty. We say that it is improbable that there is life on the moon, that there is a 25 percent chance of rain tomorrow afternoon, etc. Practically, we are often confronted with situations where the exact truth is not known. We take chances and assume that a particular situation is likely to occur. Weather is a good example; the accurate prediction of the path of a hurricane has enabled many cities to adequately prepare for inclement weather. A tornado, however, is much more unpredictable, often having disastrous consequences. We are faced in everyday life with statements that have associated with them the word probable. For example, the probability of rolling a 1 using a fair die is 1/6; the probability of drawing a king of hearts out of a complete deck of cards is 1/52; etc. The first statement, addressing the probability of a 1's occurring when we toss a die, makes use of a number of assumptions. For example, it is assumed that the die is "fair"; we are also not counting other probable occurrences such as the loss of the die when it is tossed. It is usually assumed that when we toss a die, each side is equally likely to appear. One way of obtaining the number 1/6 is to toss the die many times and simply count

the number of times in which a 1 appears. This concept leads to the well-known ratio

Number of favorable occurrences Number of times the die was tossed

By evaluating this number we are actually evaluating the probability of a 1's occurring. This basic (and historic) definition of probability assumes that all possible outcomes, such as the occurrence of a specific face in the tossing of a die, are equally probable. Using this ratio, we conclude that every probability *P* is a number between 0 and 1:

$$0 \le P \le 1$$

Note that for P to be equal to 1, the numerator and denominator of the above ratio must equal each other. In such a case, when the probability of the event equals 1, we have a certain event. The relative frequency approach is essentially a counting approach. Basically, we are going to perform the experiment many times and then count the number of times that the particular event we are interested in occurs. For example, consider again the experiment of tossing a die. There are a number of possible events associated with this experiment. Let us mention just a few:

A 6 comes up.
An even number comes up.
A number less than 4 comes up.
A number between 1 and 6 (inclusive) comes up.

The fourth event is an interesting one, since there is nothing random associated with its outcome. Whenever we toss a die, the number will be between 1 and 6 (inclusive). This is what we call a certain event. Note that a certain event is not a random event, since we know ahead of time that it will occur. Therefore, the probability associated with this event is 1.

For any of the other events, the discrete probability associated with each may or may not be easy to calculate. The relative frequency approach provides us with a way to arrive at the probability associated with specific events. As mentioned earlier, this approach is essentially a counting approach. Suppose that we are interested in the probability that a 6 comes up when we toss a die. We perform the following experiment: We toss the die 1000 times and count each time that a 6 comes up. Then we approximate the probability associated with the event "a 6 comes up" as follows:

$$P(6) \approx \frac{\text{number of times a 6 appears}}{\text{total number of tosses}} = \frac{N_6}{N_{\text{trials}}}$$
 (1.1)