Photoelectric Sensors and Controls

SELECTION AND APPLICATION

Scott M. Juds

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Preface

Light sensing as a means of industrial control has been available for many decades. The technology incorporated into photoelectric controls and sensors since the early 1970s has revolutionized the market with significant advances in the state of the art in electronics, optics, and packaging. These advances have enabled photoelectric controls and sensors to overcome most of the barriers to their practical application.

The scope of technologies encompassed by these products generally extends into one or more areas in which the user has little background or training. This book is designed to provide the background and reference information necessary for making informed selection decisions. It is designed to improve the success in application of these devices by maintenance personnel, electricians, designers, and engineers. Material in this text is targeted at system designers, who must make the initial selection, and at maintenance personnel, who make sure installed systems keep working.

The book covers the basic fundamentals of optics and also gives an in-depth practical analysis of the major sensor configurations. Electrical control interfaces, control logic functions and specifications are described. Environmental issues, often a "gotcha" and important for system reliability, are discussed.

Finally, application issues and specific examples are discussed to help the reader understand the possibilities, practical limitations, and pitfalls. I thoroughly recommend experimentation as you read to help solidify concepts. Confucius put it this way: "I hear and I forget, I see and I remember, I do and I understand."

The text was specifically designed to be useful to readers with minimal experience in enclosures, optics, electronics, or industrial controls. Many drawings and graphs are used to simplify explanations and impart a solid practical understanding.

Prefere vi

ding Photoelectric Sensors and Controls you will be prepar 3 with the insight and knowledge to tackle even the toughe optical sensing and control problems.

ald like to extend special thanks and appreciation to T v physic Rocky Kyle for his technical review and for the photoelectric optics expertise he was willing to share over the years; to elec ical engineer and photoelectric expert Paul Mathews. who re swed the manuscript while sailing his boat to exotic the South Pacific; to artist John Jolley for his acplaces curacy and aesthetic interpretation of my stick figures; and to secret: y Jeri Barnhart for her assistance with the intricacies of our witten language, compilations, and correspondence.

Scott M. Juds

Contents

PRE	FACE		v
СНА	PTER 1	PHOTOELECTRIC CONTROLS AND SENSORS: INTRODUCTION	1
1.1	Introd	uction	1
		oles of Operation	2
	1.2.1	•	
		photoelectrics	2
	1.2.2	•	_
		photoelectrics	6
1.3	Princip	oal Optical Modes of Operation	8
	1.3.1	Thru-beam sensing	8
		Reflex sensing	9
		Proximity sensing	10
1.4	Photoe	lectric Trends	11
	1.4.1	Circuit technology	12
	1.4.2	Interference testing	13
		Interfacing	13
	1.4.4	Optics	16
	1.4.5	Packaging	16
СНА	PTER 2	OPTICAL FUNDAMENTALS	18
2.1	Produc	eing the Beam	18
1	2.1.1	Photoelements	20
	2.1.2	Lenses	21
	2.1.3	Beam patterns	24
2.2	Reflect		28
j.	2.2.1	Diffuse reflection	29
-	2.2.2	Specular reflection	30

viii			Contents
	2.2.3	Mixed diffuse and specular	
		reflection	31
	2.2.4		32
2.3	Transm		40
	2.3.1	Refraction	40
	2.3.2	Scattering and absorption Polarization	43
			49
2.4	The Sp		53
	2.4.1	Source and detector spectra	54
	2.4.2	Filters and dyes Fluorescence	5 7
	2.4.3	Fluorescence	69
2.5			61
	2.5.1	Total internal reflection Glass versus plastic fibers	61
	2.5.2	Glass versus plastic fibers	63
		Spectral attenuation	66
	2.5.4	End termination	69
2.6	Excess		69
		Definition	69
	2.6.2	Sensor characteristics	72
	2.6.3	Environmental effects Sensor and target variation	74
			75
2.7	Contras	st Ratio	77
	2.7.1	Low-contrast targets Low-contrast sensor techniques Contrast and target size	77
	2.7.2	Low-contrast sensor techniques	78
	2.7.3	Contrast and target size	82
	2.7.4	Color contrast	83
СНА	PTER 3	PHOTOELECTRIC OPTICAL	
		CONFIGURATIONS	87
3.1		Proximity Sensing	87
		Long-range proximity sensors	. 88
	3.1.2	Short-range proximity sensors	191
	3.1.3	Fixed-focus proximity sensors Variable proximity sensors	94
			96
	3.1.5	Ultraviolet fluorescent proximity	
		sensors	100
		Registration mark detection	101
3.2		Sensing	103
	3.2.1	Standard reflex sensors Visible beam sensors	104
			109
	3, 2, 3	Polarized reflex sensors	110

Ćon	itents		i
3.3	Thru-	Beam Sensing	11
	3.3.1	Standard thru-beam sensors	11
	3.3.2	Edge guide control	124
	3.3.3	Data transmission	12
3.4	Fiber	Optics	12'
	3.4.1	Thru-beam sensors	128
	3.4.2	Proximity sensors	13
	3.4.3	Reflex sensors	134
	3.4.4	Fiber cable construction	138
	3.4.5	Fiber cable tips	139
3.5	Scanne	ers	141
	3.5.1	Diameter scanners	142
	3.5.2	Safety light curtains	147
	3.5.3	Multiplexed remote sensor	
		scanners	150
	3.5.4	Other scanners	150
СНА	APTER 4	PHOTOELECTRIC OUTPUT INTERFACE	156
4.1	Electro	omechanical Relays	155
•••		Construction	156
			157
	4.1.3	Contact styles Contact materials	159
	4.1.4		160
		Rated life	164
4.2		State Relays	166
		Construction	169
	4.2.2		171
			171
	4 2 4	Inverse-parallel SCRs Bridged transistors	175
	4.2.5	Bilateral FETs	176
4.3		stor Interfaces	178
		Construction	178
	4.3.2		180
		PNP source transistors	
	4.3.4	Optically isolated circuits	183
4.4		ire Controls	183
4.4	4.4.1		183
	4.4.2		184
4.5		Interfaces	186
1.0			189
	4.5.1	· · · · · · · · · · · · · · · · · · ·	189
	1.0.4	Output circuits	190

×			Contents
СНА	PTER _. 5	PHOTOELECTRIC LOGIC	193
5.1	Timing	Logic	193
		Time delay logic	194
	5.1.2	One-shot circuits	196
	5.1.3	Underspeed/overspeed	199
5.2	Countir	ng Logic	200
	5.2.1	Latch	200
	5.2.2	Preset counter	201
	5.2.3.	Totalizing counter	202
	5.2.4	Shift register	202
5.3	Output	Device Logic	204
	5.3.1	Parallel OR	205
	5.3.2	Series AND	209
5.4	Photode	etector Logic	213
	5.4.1	Parallel OR	214
•		Sum/difference	216
	5.4.3	Series AND	217
	5.4.4	Fiber optic logic	218
	5.4.5		222
CHA	PTER 6	TESTING STANDARDS	227
6.1	Optical	Standards	227
			228
	6.1.2	Sunlight immunity Fluorescent light immunity	230
	6.1.3	Excess gain specifications	231
	6.1.4	Field of view and sensing	
		zone specification	233
6.2	Electric	al Standards	240
	6.2.1	Conducted noise immunity	240
	6.2.2	Radio-frequency noise	
		immunity	243
	6.2.3	Transient voltage spike	
		immunity	244
	6.2.4	Output ratings	244.
	6.2.5	No false pulse	248
	6.2.6	Safety	249
6.3	Mechani	cal/Environmental Standards	250
		Enclosures	250
	6.3.2	Temperature	255
	6.3.3	Humidity	256
	6.3.4	Shock	256
	6.3.5	Vibration	258

Contents	xi

CHA	APTER 7	SELECTION QUESTIONS	261
7.1		Requires Detection?	262
	7.1.1		262
		Reflectivity/transmissivity	262
7.2		Is It Located?	265
		Distance	265
		Local environment	269
7 0		Mounting location	270
7.3		ast Does It Move?	272
		Object transition time	272
		Sensor response time	274
7.4		Repeatability hat Will the Photoelectric	275
1.4	Interfa		975
		Load interface	275 275
		Power supply interface	275 276
7.5		uch Do Installation and	210
1.5		nance Count?	977
	7.5.1	Mounting	277 277
	7.5.2		282
	7.5.3	Alignment and adjustment	284
	7.5.4	Upkeep	286
	,,,,,	opheep	200
СНА	PTER 8	APPLICATION EXAMPLES	289
8.1	Materia	l and Process Control	290
	8.1.1	Broken yarn detection	290
	8.1.2	Broken thread detection	291
	8.1.3	Broken wire detection	292
	8.1.4	Web loop control	293
	8.1.5	"Rate of feed" tension control	294
	8.1.6	Web material centering	. 295
	8.1.7	Web edge control	296
	8.1.8	Web break detection: clear	
		plastic	297
	8.1.9	Web break detection: paper	298
		Web splice detection	299
	8.1.11	Web flaw detection	300
	8.1.12	Roll wind length control	301
	8.1.13	Roll end detection	302
	8.1.14	Trim length control	303
	8.1.15	Filter paper length control	304
	8.1.16	Cutoff saw control	305

xii			Contents
	8.1.17	Hypodermic needle quality	
		control	306
	8.1.18		
		detection	307
	8.1.19	Oven belt control	308
	8.1.20		309
	8.1.21	-	310
	8.1.22		311
	8.1.23	Liquid level control	312
	8.1.24	- • • · · · · · · · · · · · · · · · · ·	313
	8.1.25		314
	8.1.26		315
	8.1.27	· · · · · · · · · · · · · · · · · · ·	316
	8.1.28	8 1	317
	8.1.29	• •	. 318
	8.1.30	Integrated circuit lead	
		inspection	319
8.2	Packag		320
	8.2.1	Label on glass bottle	
		detection	320
	8.2.2	Cap and bottle presence	
		detection	321
	8.2.3	Cap orientation detection	322
	8.2.4	Bottle fill level and cap	
		detection	323
	8.2.5	Reversed cap detection	324
	8.2.6	Liquid level detection	325
	8.2.7	Liquid fill level detection	326
	8.2.8	Wine bottle missing cork	
		inspection	327
	8.2.9	Container spacing adjustment	328
	8.2.10	Fallen bottle control	329
	8.2.11		330
	8.2.12	G	331
	8.2.13	6	332
	8.2.14	Tube orientation	√ 333
	8.2.15	_	334
	8.2.16	Shiny container detection	335
	8.2.17	Indexing: shrink wrap	336
	8.2.18	Glue bead control	337

Contents		×iii	
8.3	Materia	ıl Handling	338
	8.3.1	Conveyor jam detection	338
	8.3.2	Container size sorting: two	
		sensors	339
	8.3.3	Container size sorting: one	
		sensor	340
	8.3.4	Container sorting by retro	
		tape	341
	8.3.5	Shift register delayed	0.40
		ejection	342 343
	8.3.6	Carton counting	343 344
	8.3.7		344
	8.3.8	- _ - _ -	345
	8.3.9	Stack height control	347
	8.3.11	<u> </u>	348
8.4			349
0.4	8.4.1	Bent/broken drill bit	040
	0.4.1	detection	349
	8.4.2		350
	8.4.3		
		fiber optics	351
	8.4.4	Mechanical thread detection	352
		Part detection: chute	353
		Small parts detection	354
	8.4.7	Part detection: robotic	355
	8.4.8	Die casting machine protection	356
	8.4.9	Part detection: assembly	357
	8.4.10	Part orientation	358
	8.4.11	Control of sequential	
		operations	359
8.5	People	and Vehicle Detection	360
	8.5.1		360
	8.5.2	Vehicle over-height detection	361
	8.5.3		
		window	362
	8.5.4	Customer detection: bank	
		teller window	363
	8.5.5	Long-range perimeter security	364
	8.5.6	Automatic carwash control	365

xiv	Contents
8.5.7 Automatic door control	366
8.5.8 Automatic door control	367
8.5.9 Collision avoidance	368
8.5.10 Photoelectric race track finishes	369
APPENDIX A CONVERSION AND CONSTANTS	371
APPENDIX B TEST STANDARDS AND BIBLIOGRAPHY	373
APPENDIX C RESISTANCE TO CHEMICAL ATTACK	377
REFERENCES	379
INDEX	381

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1

Photoelectric Sensors and Controls: Introduction

History, a distillation of rumour.

Thomas Carlyle
The French Revolution

In this chapter we provide a description of photoelectric controls and sensors, what they are, principles of operation, basic terminology, a look backward, and a look forward. Much of the information here will already be familiar to many readers. However, the foundation for material in other chapters will be laid here and may be useful to a complete understanding of later chapters.

1.1 INTRODUCTION

The number and variety of light-operated or light-controlled devices and equipment produced is tremendous. Photoelectric controls and sensors are only a small part of this vast product spectrum. Dusk lamp controls, television brightness compensation for ambient light, photo interrupters for paper and ribbon cartridge empty signals on printers, cassette auto-reverse sensors, automobile ignition electronic cams, television and stereo remote controls, door annunciators in small shops, smoke detectors, CRT light pens, the optical mouse for personal computers, shaft encoders, elevator door safety guards, invisible perimeter security sensors, and garage and toll gate automobile detection are a few of the many light-sensitive controls and sensors with which we interact in everyday life. Many of these are very specific in form to a particular market or need. As such, they will not be discussed here directly, although the principles of operation are

2 Chapter 1

likely to apply. Hidden within industry are countless other varieties of optically based sensors, controls, array scanners, bar code scanners, measurement scanners, range finders, and machine vision systems. In the larger sense, all of the aforementioned devices could be considered photoelectric controls and sensors. However, in this book, a more categorical definition will be used with particular attention to industrial sensors and controls.

The term "sensor" will be used to refer to a device that provides a simple signal-level output that is determined by the light level it receives. The term "control" will be used to refer to a device that, in addition to sensing, provides a control output capable of switching power to actuators that alter the flow of materials or other process events. Both sensors and controls are concerned with only a single sense point. The term "scanner" will be reserved for devices that have built-in physical or electronically synthesized scanning motion in order to gather information from more than a single sense point. A scanner may be a self-contained unit or an ensemble of sensors connected to a scan controller. Single-point sensors and controls are often erroneously referred to as scanners despite their inability, physically or electronically, to move the sense point in space. Although fixed-beam sensors and controls are not scanners, they can provide that function when the scanning motion is provided external to the sensor by the object's motion through the sensor's beam. In this book, these definitions are used consistently to avoid confusion.

1.2 PRINCIPLES OF OPERATION

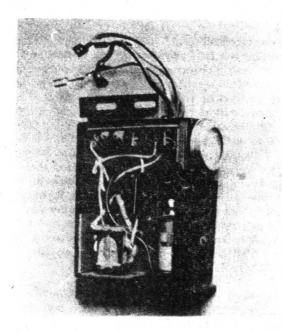
An industrial photoelectric sensor is a device composed of a light transmitter and light receiver. Light is directed toward the object by the transmitter. The receiver is pointed toward the same object and detects the presence or absence of reflected light originating from the transmitter. Detection of the light generates an output signal for use by an actuator, controller, or computer. The output signal can be analog or digital and is often internally modified with timing logic, scaling, or offset adjustments prior to output.

1.2.1 Conventional Unmodulated Photoelectrics

The light beam in early photoelectrics was generated by a constant-intensity (unmodulated) incandescent filament bulb much

like those used for automotive taillights. The light detector was generally a cadmium sulfide cell that allowed current to flow and energize a relay when lit, and blocked current flow, deenergizing the relay when dark. A cadmium sulfide cell is a photoresistive detector. Its ability to conduct or resist the flow of current is controlled by the intensity of light incident on its surface. Early photoelectrics were generally called "electric eyes" and eyen today are frequently referred to as "eves." Figure 1.1a shows an early electric eve, and Fig. 1.1b shows schematically how it functioned. In operation, this device projected light toward a reflector that would return it back to the electric eve's cadmium sulfide cell. If enough light fell on the cell, sufficient current would be conducted through the cell to activate the relay. It was generally necessary to shield the detector from other light sources and to use a powerful filament light source to achieve any sensitivity without false triggering. An object breaking the beam would then cause the darkened cadmium sulfide cell to switch off the relay.

In the late 1960s, the light-emitting diode (LED) was developed and provided an alternative light source to the incandescent light bulb. LEDs are a common sight today as numerical displays in clocks and stereos, illuminators in toy games, and indicator lamps on security system controls and floppy disk drives. A solid-state LED, sketched in Fig. 1.2, is constructed without the two most serious life-limiting design problems found in incandescent bulbs. Incandescent bulb tungsten filaments operate at about 4000°F. This high operating temperature creates great thermal stress. causing deterioration of the filament structure over time. The high operating temperature limits the useful life of these bulbs to about 2000 to 5000 hours. Further, the filament is a coil spring structure stretched between two posts. This delicate structure is stressed heavily by shock and vibration common to industrial production environments. The already short bulb life is significantly reduced by shock and vibration. In contrast, the LED has a bond wire that is encapsulated and is able to withstand extremely high shock and vibration stress. The LED operates at nearly ambient temperature and does not encounter great thermal stress. The typical rated life of an LED is in excess of 100,000 hours, which is more than 10 years of 24-hour days. This does not guarantee that all LEDs will last 10 years and then die. It means that the field failure rate will be on the order of 2 to 5% of that experienced with incandescent bulbs. This is a feature of significant value when the cost of maintenance and production downtime are considered.



(a)

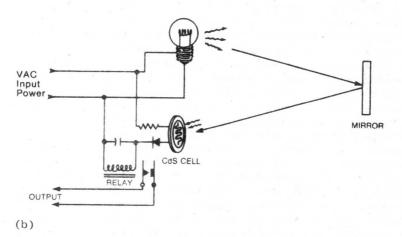


Figure 1.1 (a) Early electric eye with its cover removed; (b) schematic diagram of its function.