A BRIDGE BETWEEN CONTROL SCIENCE AND TECHNOLOGY

General Editors

J. GERTLER and L. KEVICZKY

Volume 3

LARGE-SCALE SYSTEMS, DECISION-MAKING, MATHEMATICS OF CONTROL

LARGE-SCALE SYSTEMS, DECISION-MAKING, MATHEMATICS OF CONTROL

Edited by

A. TITLI

Institut National des Sciences Appliques de Toulouse, France

M. G. SINGH UMIST, Manchester, UK

M. PACHTER

National Research Institute of Mathematical Sciences, Pretoria, South Africa M. L. J. HAUTUS

University of Technology, Eindhoven, The Netherlands

P. V. KOKOTOVIC

University of Illinois, Urbana, Illinois, USA

H. E. RAUCH

Lockheed, California, USA

Published for the

INTERNATIONAL FEDERATION OF AUTOMATIC CONTROL

by

PERGAMON PRESS

OXFORD · NEW YORK · TORONTO · SYDNEY · PARIS · FRANKFURT

U.K.

Pergamon Press Ltd., Headington Hill Hall, Oxford OX3 0BW, England

U.S.A.

Pergamon Press Inc., Maxwell House, Fairview Park, Elmsford, New York 10523, U.S.A.

CANADA

Pergamon Press Canada Ltd., Suite 104, 150 Consumers Road, Willowdale, Ontario M21 1P9,

Canada

AUSTRALIA

Pergamon Press (Aust.) Ptv. Ltd., P.O. Box 544, Potts Point, N.S.W. 2011, Australia

FRANCE

Pergamon Press SARL, 24 rue des Ecoles, 75240 Paris, Cedex 05, France

FEDERAL REPUBLIC OF GERMANY

Pergamon Press GmbH, Hammerweg 6, D-6242 Kronberg-Taunus,

Federal Republic of Germany

Copyright © 1985 IFAC

All Rights Reserved. No part of this publication may be reproduced, stored in a retrieval system or transmitted in any form or by any means: electronic, electrostatic, magnetic tape, mechanical, photocopying, recording or otherwise, without permission in writing from the copyright holders. First edition 1985

Library of Congress Cataloging in Publication Data

International Federation of Automatic Control. World Congress (9th: 1984: Budapest, Hungary) A bridge between control science and technology. (IFAC proceedings series; 1985, nos. 1-6) Contents: v. 1. Analysis and synthesis of control Contents: v. 1. Analysis and synthesis or control systems / edited by W. R. Perkins, A. G. J. MacFarlane, G. G. Leininger — v. 2. Identification, adaptive, and stochastic control / edited by L. Ljung, K. J. Astrom — v. 3. Large-scale systems, decision-making, mathematics of control / edited by A. Titli ... [et al.] — [etc.] 1. Automatic control — Congresses. 2. Systems engineering — Congresses. I. Gertler, Janos. II. Keviczky, László. III. Title. IV. Series. T[212.2.158 1984 629.8

British Library Cataloguing in Publication Data

International Federation of Automatic Control. World Congress (9th: 1984: Budapest) A bridge between control science and technology : proceedings of the Ninth Triennial World Congress of the International Federation of Automatic Control, Budapest, Hungary, 2-6 July 1984. -(IFAC proceedings series; 1985, no. 1-6) 1. Systems engineering 1. Title II. Series TA168 620.7ISBN 0-08-031669-7 ISBN 0--08-031666-2 (set)

These proceedings were reproduced by means of the photo-offset process using the manuscripts supplied by the authors of the different papers. The manuscripts have been typed using different typewriters and typefaces. The lay-out, sigures and tables of some papers did not agree completely with the standard requirements; consequently the reproduction does not display complete uniformity. To ensure rapid publication this discrepancy could not be changed; nor could the English be checked completely. Therefore, the readers are asked to excuse any deficiencies of this publication which may be due to the above mentioned reasons.

The Editors

1984

- No. 1 ALONSO-CONCHEIRO: Real-Time Digital Control Applications
- No. 2 ZWICKY: Control in Power Electronics & Electrical Drives (1983)
- No. 3 KLAMT & LAUBER: Control in Transportation Systems
- No. 4 RIJNSDORP, PLOMP & MÖLLER: Training for Tomorrow: Educational Aspects of Computerised Automation
- No. 5 WESTERLUND: Automation in Mining, Mineral & Metal Processing (1983)
- No. 6 SANCHEZ: Fuzzy Information, Knowledge Representation & Decision Analysis
- No. 7 BASAR & PAU: Dynamic Modelling & Control of National Economies (1983)
- No. 8 Van CAUWENBERGHE: Instrumentation & Automation in the Paper, Rubber, Plastics & Polymerisation Industries (1983)
- No. 9 PONOMARYOV: Artificial Intelligence
- No. 10 STRASZAK: Large Scale Systems: Theory & Applications (1983)

1985

- No. 1 *PERKINS, MACFARLANE & LEININGER: Analysis and Synthesis of Control Systems
- No. 2 *LJUNG & ASTROM: Identification, Adaptive and Stochastic Control
- No. 3 *TITLI, SINGH, PACHTER, HAUTUS, KOKOTOVIC & RAUCH: Large-scale Systems, Decision-making, Mathematics of Control
- No. 4 *NISENFELD, LEFKOWITZ, PAI & DY LIACCO: Process Industries, Power Systems
- No. 5 *REMBOLD, KEMPF, TOWILL, JOHANNSEN, PAUL, HARRISON, EHRENBERGER, TABAK, LESKIEWICZ, FENTON & DEBRA: Manufacturing, Man-Machine Systems, Computers, Components, Traffic Control, Space Applications
- No. 6 *VOSSIUS, WEED, RESWICK, COBELLI, HAIMES, TAKAMATSU, KAYA, NAJIM,
 MARTENSSON, CHESTNUT & LARSEN: Biomedical Applications, Water Resources,
 Environment, Energy Systems, Development, Social Effects, SWIIS, Education
 (*Ninth Triennial World Congress)
- No. 7 BILLINGS & YOUNG: Identification and System Parameter Estimation (1985)

NOTICE TO READERS

If your library is not already a standing/continuation order customer or subscriber to this series, may we recommend that you place a standing/continuation or subscription order to receive immediately upon publication all new volumes. Should you find that these volumes no longer serve your needs your order can be cancelled at any time without notice.

Copies of all previously published volumes are available. A fully descriptive catalogue will be gladly sent on request.

ROBERT MAXWELL Publisher at Pergamon Press

IFAC Related Titles

BROADBENT & MASUBUCHI: Multilingual Glossary of Automatic Control Technology
EYKHOFF: Trends and Progress in System Identification
ISERMANN: System Identification Tutorials (Automatica Special Issue)

A BRIDGE BETWEEN CONTROL SCIENCE AND TECHNOLOGY

NINTH TRIENNIAL WORLD CONGRESS OF IFAC

Sponsored by

International Association for Mathematics and Computer Simulation (IMACS)

International Federation of Automatic Control (IFAC)

International Federation for Information Processing (IFIP)

International Federation of Operational Research Societies (IFORS)

International Measurement Confederation (IMEKO)

United Nations Educational, Scientific and Cultural Organization (UNESCO)

United Nations Industrial Development Organization (UNIDO)

Supported by

Federation of Technical and Scientific Societies (MTESZ)

Hosted by

Hungarian Academy of Sciences in collaboration with the Hungarian National Committee of IFAC

Organized by

National Organizing Committee

International Programme Committee

H. Akashi, Japan (Vice-Chairman)

O. Aven, USSR

A. van Cauwenberghe, Belgium

J. B. Cruz, USA

A. R. Curran, USA

D. B. DeBra, USA

R. W. Gellie, Australia

J. Gertler, Hungary (Chairman)

G. Guardabassi, Italy

R. Isermann, Federal Republic of Germany (Vice-Chairman)

S. Kahne, USA

L. Keviczky, Hungary

H. Kwakernaak, Netherlands

P. M. Larsen, Denmark

I. Lefkowitz, USA

H. J. Leśkiewicz, Poland

U. Luoto, Finland

M. Najim, Morocco

G. J. Ölsder, Netherlands

L. F. Pau, France

P. Rabischong, France

B. Tamm, USSR

H. J. Warnecke, Federal Republic of Germany

A. Work, USSR

National Organizing Committee

P. Bakonyi

Cs. Bányász

M. Fekete V. Géczy

G. Hencsey (Vice-Chairman)

L. Helm

R. Kálmán (Chairman)

L. Keviczky

E. Knuth (Vice-Chairman)

J. Marton

Petróczy

E. Sós (Secretary-General)

PREFACE

The triennial World Congresses have always been the main events of the International Federation of Automatic Control. While symposia and workshops concentrate on specific technical areas, IFAC Congresses present a broad view on the state of the art and development trends in the entire field of automatic control and systems engineering, embracing both theory and applications. This tradition, established with the first IFAC Congress in Moscow in 1960, has been maintained and further advanced during the two decades that followed, a period marked by congresses in Basle, London, Warsaw, Paris, Boston, Helsinki and Kyoto. A look at the subjects covered at those congresses gives a good indication of the tremendous evolution our profession has gone through, from theory, components and industrial applications at the beginning to a multitude of new areas, ranging from mathematics of control, systems engineering and computers through applications in manufacturing, space and biomedical engineering and including such fields as economic and management systems, social effects of automation and developing countries.

The intention of the planners and organizers of the 1984 Budapest Congress was to keep these traditions and alloy them with some innovations in the technical programme. The broad approach to the entirety of the profession has been maintained, as well as Plenary Papers, Paper Sessions, Case Studies and Discussion Sessions as the main components of the technical programme. At the same time, the Paper Sessions were given more structure and the Technical Committees of IFAC a greater role in their organization. Discussion Sessions received more emphasis and new Industrial Problem Sessions were introduced into the programme.

Six subjects were selected for Plenary Lectures, each representing an area of major interest and present thrust in automatic control. Outstanding experts were invited to present broad and synthetizing views on each subject. These six lectures were meant to be the main focal points of the technical programme, an objective completely fulfilled by each of them. The six Plenaries, together with their authors, are as follows:

```
Development of systems science: Past, present and future. (J. Zaborszky)
Control theory in the 80s: Trends in feedback design (P.V. Kokotovic)
Incentives and control in economic organizations (R. Radner)
Process control and information systems (G. Färber)
Flexible manufacturing systems in Japan (H. Yoshikawa)
Control in and for biosystems (V.A. Viktorov, V.N. Novoseltsev, V.I. Shumakov)
```

The technical papers were arranged into 37 Congress Colloquia, each Colloquium dealing with a particular area or aspect of automatic control and systems engineering. The titles of the Colloquia were proposed by the Technical Committees of IFAC and their programme was shaped by separate Colloquium International Programme Committees set up by the Technical Committees. These Colloquium IPCs invited papers, reviewed the contributed ones and decided upon their acceptance and they arranged the accepted papers into Paper Sessions, within the general framework determined by the Congress IPC. The more than 150 activists working in the Colloquium IPCs and, especially, the chairmen of these committees, made a most substantial contribution to the Congress programme.

The 37 Colloquium titles are listed below, each with the primary organizer Technical Committee and the name of the IPC Chairman:

```
Control of power stations and systems (Applications, T.E. Dy Liacco)
Automatic control for the utilization of energy and materials (Applications, M.A. Pai)
Industrial process control (Applications, E.A. Nisenfeld)
Neur -control of motor functions (Biomed., G. Vossius)
Control of artificial organs (Biomed., H.R. Weed)
Control of assistive devices for paralyzed parients (Biomed., J. Reswick)
Control in endocrine-metabolic systems (Biomed., C. Cobelli)
Programmable and intelligent components and instruments in automatic control
  (Components, H.J. Leskiewicz)
Tools for software system design and integration (Computers, M.H. Paul)
Communications for real-time computer control (Computers, T.J. Harrison)
Safety of real-time computer systems (Computers, W.F. Enrenberger)
Microcomputer-based control (Computers, D. Tabak)
System approach to development (Developing Countries, M. Najim)
Modelling, economic analysis and strategic planning of energy systems
  (Economic and Management Systems, Y. Kaya)
Trends in automatic control education (Education, M.P. Larsen)
Flexible automation in manufacturing (Manufact., U. Rembold)
Robotics (Manufact., K.G. Kempf)
```

viii Preface

Computer aided engineering in manufacturing (Manufact., D.R. Towill) Mathematical systems theory (Math. of Control, M.L.J. Hautus) Control applications of non-linear programming (Math. of Control, H.E. Rauch) Team and game theory (Math. of Control, M. Pachter) Asymptotic analysis and singular perturbation (Math. of Control, P.V. Kokotovic) Social aspects of CAD/CAM and robotics (Social Effects, L. Martensson) Large-scale systems: theory, methodology and non-standard applications (Systems Eng., A. Titli) Computer aided system analysis and design (Systems Eng., G.G. Leininger) Industrial systems engineering (Systems Eng., I. Lefkowitz) Man-machine systems (Systems Eng., G. Johannsen) Application of large-scale techniques to human decision making and management (Systems Eng., M.G. Singh) Transportation systems (Systems Eng., R.E. Fenton) Process design and control for preventing environmental pollution (Systems Eng., T. Takamatsu) Water resources systems (Systems Eng., Y.Y. Haimes) Supplemental ways of improving international stability (Systems Eng., H. Chestnut) Space applications (Space, D.B. DeBra) Modelling and identification (Theory, L. Ljung) Synthesis of control systems (Theory, A.G.J. MacFarlane) Structural properties and analysis of control systems (Theory, W.R. Perkins) Adaptive and stochastic control (Theory, K.J. Astrom)

A total of more than a thousand draft papers were submitted by authors from 37 countries, of which 569 were accepted and 544 were actually received in final form and presented at the Congress.

Responding to a general demand for extended discussion opportunities. 38 Panel Discussion Sessions were organized, much more than at any previous congress. A significant portion of these Panel Discussions dealt with not strictly technical subjects, such as "The impact of culture on automation", "Management and education for world complexity" or "Computer aided design in control education". A special series of 11 Industrial Problem Sessions was devoted to problems like "Mill-wide control in the paper and pulp industry", "Production management of small orders in steel mills" or "How to interface human factors in automation projects".

Seven Case Studies were also presented, five of them reporting on results of the Hungarian hosts in education, nuclear power plant control, computer controlled manufacturing and computer application in agriculture and health-care.

The six volumes of the Proceedings contain the complete technical material of the Congress. The 544 technical papers are published in their original colloquium arrangement, related subject areas combined in each volume. The Colloquium IPC Chairmen have served as Editors of the respective volume and the full Colloquium IPCs are listed as well. Each volume letts with one of the six Plenary Lectures, the one most closely related to the rest of the volume. Summary reports on 32 of the Discussion Sessions, including a full account on the Industrial Problem Sessions, are also published, together with the entire material of the Case Studies. These reports are also distributed among the six volumes, according to their subject areas. The discussions that followed the presentation of papers in the technical sessions are not included, because this eventual and uneven material did not seem to justify the substantial effort and publications delay its editing would have implied.

We do hope that the publication of this material will render a useful service to the world-wide community of control and systems engineers and will further the realization of the Congress objective of broadening the bridge between Control Science and Technology.

Janos Gertler Chairman, Congress IPC

CONTENTS OF VOLUMES 1-6

VOLUME 1

PLENARY PAPER

Development of Systems Science - Past, Present, and Future $J.\ Zaborezky$	
COLLOQUIUM ON STRUCTURAL PROPERTIES AND ANALYSIS OF CONTROL SYSTEMS	
Structural Properties, Robustness, and Sensitivity	
Minimax Frequency Domain Optimization of Multivariable Linear Feedback Systems H. Kwakernaak	1
Robustness with Simultaneous Pole and Zero Movement across the $j_{\omega-axis}$ I. Postlethwaite and Yung Kuan Foo	2
Computation of Loss Function Derivatives with Respect to Feedback Coefficients and Control System Applications Sun Zeng-Qi and B. Qvarnström	3
Trajectory Properties and Cost Invariance in Discrete Linear Quadratic Problems M.M. Konstantinov, P.Hr. Petkov and N.D. Christov	3
Singular Optimal Control and the Identically Non-regular Problem in the Calculus of Variations	
P.K.A. Menon, H.J. Kelley and E.M. Cliff	4.
Presitivity Analysis of Time Optimal Control Systems 4. Becker and P.M. Frank	4
Structural Properties of Nonlinear Systems	
ested E-Decompositions of Complex Systems M.E. Sezer and D.D. Šiljak	55
on the Equivalence Problem of Control Systems and Control Systems with Time-lags in the Theory of Stabilization in Yong-Qing	
	61
ounded Real Lemma and Stability of the Time Lag Nonlinear Control Systems i Xunjing	6 -

T. Ushio and K. Hirai	~
Stability Analysis of Limit Cycles in Nonlinear Feedback Systems Using Describing Functions: Improved Results R.K. Miller, A.N. Michel and G.S. Krens	7
Vibrational Stabilizability of Nonlinear Systems R. Bellman, J. Bentsman and S.M. Meerkov	8
Structural Properties of Linear Systems	
Finite Effect Sequences - A Control Oriented System Description J. Ackermonn	9
On the Singularity of Reduced Order Models F.F. Shoji, K. Abe and H. Takeda	9
Structural Features and Discretization of Polynomial Systems K. Dobrovodský	10
Graph-theoretic Characterization of Structural Properties by Means of Paths and Cycle Families K.J. Reinschke	10
Eigenvalue Inclusion Regions and their Use in the Analysis of Linear and Nonlinear Multivariable Feedback Systems R.W. Daniel and B. Kouvaritakis	11:
Decoupling of Nonsquare Systems - a Necessary and Sufficient Condition in Terms of Infinite Zeros N. Suda and K. Umahashi	12.
Structural Features of Multivariable Systems 1	
Design of Internally Proper and Stable Control Systems V. Kudera	12'
On Grassmann Invariants and Almost Zeros of Linear Systems N. Karcanias and C. Giannakopoulos	13:
Realization of Disturbance Resistance of a Generalized State Space System by State Feedback $\it K.K.~\it Xu$	139
The Generalized Hessenberg Representation and Pole-Zero Structure D.K. Lindner and W.R. Perkins	145
Aspects of a Unifying Approach for the Design of Linear Systems A.C. Antoulas	151
Structural Controllability Analysis for Linear Systems in Linearly Parameterized Descriptor Form S. Hosoe, Y. Hayakawa and T. Aoki	
Structural Features of Multivariable Systems — II	155
Quasi-Jacobi Matrices, RC Networks and Alzerman's Conjecture J.I. Rêgo, E. Kasskurewics and L. Hsu	161
On the Development of Equiobservable Forms with Application to Adaptive	101
H. Ohta, M.M. Gupta and P.N. Nikiforuk Pransfer Matrix Approach to the Disturbance Decoupling Problem	165
fultivariable Partial Realization and the Aspect of Uniqueness	171
in I-O Property of Control Systems with Migmatched South Control	175
. Yamanaka and E. Shimemura	181

Decoupling and Stability: Structural Analysis

Decoupling of 2-D Systems by Dynamic State Feedback Controllers B.G. Mertsios	185
Stabilities of 2-D Linear Discrete-time Systems J.E. Kurek	191
Asymptotic Stability and the Lyapunov Equation for Two-dimensional Discrete Systems P. Agathoklis, E.I. Jury and M. Mansour	197
On Necessary and Sufficient Conditions for Absolute Stability of Discrete-time Systems Lj. Grujić, Z. Bučevac and Z. Ribar	201
An Analytic Stability Test for Linear Multivariable Feedback Systems with a Time Delay N. Östurk and A. Uras	207
Stability Analysis of Linear Periodic Systems via the Lyapunov Equation S. Bittanti, P. Bolsern and P. Colaneri	213
COLLOQUIUM ON SYNTHESIS OF CONTROL SYSTEMS	
Linear Multivariable Systems — I	
Regulation and Optimal Error Reduction in Linear Multivariable Systems 22. Wang and J.B. Pearson	219
Feedback Synthesis with Two Degrees of Freedom: (G_iB_iP) Controller $P.J.$ Anteaklis and M.K. Sain	223
Jordan Form Assignment by State Feedback S. Kubik and M. Schlegel	229
The Strong Functional Observers $J.E.$ Kurek	235
The Economical Output Feedback Stabilization Problem of Linear Multivariable Systems Hu Yang-zeng and Jiang Wei-sum	239
Decoupling and Pole-zero Placement in Singular Systems M.A. Christodoulou and P.N. Paraskevopoulos	245
Linear Multivariable Systems — II	
Robust Controllers for Uncertain Linear Multivariable Systems M. Vidyasagar and H. Kimura	251
Efficient Algorithm for Spectral Factorization J. Ježek and V. Kučera	257
Structural Synthesis of Multivariable Controllers D.Y. Ohm, J.W. Howse and S.P. Bhattacharyya	263
Parametric Optimization Problem for Control Systems with Time-delay H. Górecki and L. Popek	269
A Unified Approach for Designing Robust Linear Feedback Controllers $J.\ Lunze$	275
Synthesis of the Movement Automatic Control Laws by Exact Analytic Methods R.A. Nelepin	281
Optimal Control Systems — 1	
Frequency Shaped Linear Optimal Control with Transfer Function Riccati Equations J.B. Moone, B.D.O. Anderson and D.L. Minners	
J.B. Moore, B.D.O. Anderson and D.L. Mingori	287
Design of Suboptimal Controllers for Nonlinear Systems G.N. Saridis and J. Balaram	293

Siscress lime spoisse control of System / 1995 1996 1996	
M. Araki, T. Fujinaka and B. Kondo	299
Delayed Feedback Optimal Controller J. Kim and D.H. Chuung	305
Optimal Control of Managulation Robins L.D. Akulenko, fill Principle Control of the Control of	31.
On LQ Optimum Control of ARMAX Processes V. Peterka	317
Opcimal Control Systems te	
Robustness and Optimality: A Dual Performance Index M.J. Grimble and M.A. Johnson	323
Numerical Computation of Optimal Controls in the Presence of State dependent Time Lags H.G. Book and v. Schlöder	329
Synthesis of Near-optimal Controllers	323
B.2. Baharov, L. Baharova and L. Gunchev	335
Intermittent Closed-loop Policy for Optimal Regulation of Complex Continuous Systems	
B. Lang and N.E. Cheickh Obeid	341
Synthesis of Near Time-optimal Control of Optiliative Flants with Fime-delay $Ch.Iv.$ Damyanov, T.Ph. Proychev and L.At. Gunchev	347
Automatic Near Time-optimal Control of Plants with Two Controlling Elements or Parameters $L.At.\ Gunchev$	353
Distributed Discrete and Multi-disarnsional Systems	
A Method for Computing and Implementing Distributed Controls through Mobile	
Control Signals A.G. Butkovskiy, V.A. Kubyshkin, A.G. Smirnov, Ye.S. Tverdokhlebov and E.P. Chubarov	359
On the Synthesis of the Optimal Discrete Control System for Continuous-time Object	
N.A. Kuznetsov, F.N. Grigor'ev and A.P. Serebrovskiy	365
Dynamic Deadbeat Controller Synthesis for Discrete-time Systems with Input Disturbance K. Moriwaki and H. Akashi	
	371
Model Matching of 2-D Multi-input Multi-Qutput Systems M. Šebek	377
Minimal Order State Observer for Two-dimensional Systems S. Kawaj \dot{r}	383
Dead-beat Servo Problem for n-D Multi-input-output Linear Systems T . $Kaczorek$	389
Nonlinear and Robust Systems	
A New Approach to Binearize Nonlinear Systems: the Pseudo-linearization. Comparison with Crassical Methods	
C. Champetier, . Reboulet and P. Mouyon	393
Model Matching of Nonlinear Systems T. Okutan' and K. Furuta	399
Soft Control of a Flow Process with Lyapunov's Second Method	405
A Multiple Shooting Method for Numerical Computation of Open and Closed Loop Controls in Nonline ar Systems TI. Bock and . Krämer-Eis	4.7
· · · · · · · · · · · · · · · · · · ·	411

1 i

Study of Singular Control Problem by a Differential Form Theory - n-Dimensional Nonlinear Control System with n Controls Appearing Linearly	
T. Takagi and T. Katayama	417
A Bilinear Observer Approach to a Class of Nonlineal State Reconstruction Problems H. Sira-Ramires	423
Applications and Design Techniques	
On Synthesis of Robust Servo Systems T. Yoshikawa, T. Sugis and H. Hanafusa	429
Structural Constrained Controllers for Linear Discrete Dynamic Systems $J.C.$ Geromel and E.P. Melo	435
On the Synthesis of Modal Control J.F. Magni	441
Control of a Nuclear Power Plant Boiler using Prediction Techniques A.R. March	447
A Direct Method for Optimal Control Synthesis of Manipulator Point-to-point	•
Notion P. Marinov and P. Kiriasov	453
The Concepts of Inverse Problems in Dynamics and Synthesis of Algorithms to Control the Motion of Manipulator Robots P.D. Krut'ko, N.A. Lakota and E.P. Popov	400
Tion Man No., Min. Danova and B.F. Fopou	457
COLLOQUIUM ON COMPUTER AIDED SUSTEM ANALYSIS AND PROCESS	
COLLOQUIUM ON COMPUTER AIDED SYSTEM ANALYSIS AND DESIGN Computer Aided Design Software Packages	
Computer Aided Control and Real Time Control Program Organizing System	
"CACOS" K. Furuta and O. Yamano	
A Computer Aided Design Package for the Total Synthesis Problem	465
R.M. Schafer and M.K. Sain	471
An Interactive Frogram Package for Linear System Reduction L. Fortuna and A. Gallo	477
The Identification Package SATER A.J.W. van den Boom and R. Bollen	483
I.PD.E.M A Statistical Dynamic Identification Package by a Single Output Difference Equation Model Applied to Industrial Processes on Micro-computers	
L. Caralp, G. Pefaye, G. Durou and P. Jouve	489
BIMAS - A Basic Mathematical Package for Computer-aided Systems Analysis and Design	
A. Varga and V. Sima	495
Computer Aided Design of Sampled Data Systems	
An Interactive Simulation System for Analysis and Synthesis of Digital Control Systems	
M. Tanuma, Y. Morooka and T. Takano	501
Limit Cycles in Nonlinear Sampled Data Systems O.F. McNamara and D.P. Atherton	. 507
Computer Aided Design Methods for Control	
Gains, Phases and Angles A.G.J. MacFarlane and Y.S. Hung	513
The Approximation of Prescribed Magnitude and Phase Characteristics F. Gausch	
An Algorithm to Calculate Numerators of Higher Kinds	519
	525

1

Time Domain Synthesis of Compensators for Nonlinear Feedback Systems J.O. Gray and D. Valsamis	531
An Interactive Multicriteria Optimization Approach for Linear Control System Design A. Ollero and R. Marín	539
Test of Structural Properties of State-space Models through Algebraic Computation Y. Lecourtier, E. Walter and A. Raksanyi	545
Computer Aided Design Applications	
CAD of pH-control Systems O.L.R. Jacobs and W.A. Badran	551
Dynamic Analysis and Computer-aided Design of Robot Manipulators H. Asada	557
An Automatic Modelling System used in Computer Aided Design of Industrial Robets A. Davidoviciu, A. Modanga and G. Draganoiu	563
Computer Aided Design of Hydraulic and Electrohydraulic Drive Installations ${\it Fl.\ Ionescu}$	569
PANEL DISCUSSIONS	
The Role of Theory in Control Synthesis Chairman: A.G.J. MacFarlane (GB)	577
Control Methods in Robotics Chairman: G.N. Saridis (USA)	579
Author Index .	

Subject Index

VOLUME 2

PLENARY PAPER

Control Theory in the 80s: Trends in Feedback Design	
P.V. Kokotovic	583
COLLOQUIUM ON MODELLING AND IDENTIFICATION	
Identification Theory	
Perspectives on System Identification A.P. Sage	597
On the Generic Consistency of Instrumental Variable Estimates T. Söderström and P. Stoica	603
Strong Consistency of ML Estimators using Partial Fraction and Elementary Subsystem Representation of Multivariable Systems L. Keviczky, J. Bokor and S. Veres	609
A Generalized Diagram for Various Parameter Estimation Methods; the Coherence in Pseudo-linear Regression Schemes	
A.J.W. van den Boom and P. Eykhoff	615
A New Stable Identification Scheme and its Error Estimation for Nonlinear Systems without Inputs Gy. Sonnevend	621
	621
Measurement Errors in System Identification and the Practical Universality of Low-order LS and AR Models A. Niederlinski	627
Identification Methods	
Optimality in Discrete Adaptive Systems Ya. Z. Tsypkin	633
Optimality in Discrete Adaptive Systems Ya.Z. Tsypkin On the Identification of Linear Time-invariant Systems using Finite Plant	633
Optimality in Discrete Adaptive Systems Ya. 2. Tsypkin	633 637
Optimality in Discrete Adaptive Systems Ya.Z. Tsypkin On the Identification of Linear Time-invariant Systems using Finite Plant Records E.J. Davison, R.H. Kwong and Ying-Li Zhang Identification of Jump Component Parameters in Discrete Stationary Noise Processes	637
Optimality in Discrete Adaptive Systems Ya. Z. Tsypkin On the Identification of Linear Time-invariant Systems using Finite Plant Records E. J. Davison, R. H. Kwong and Ying-Li Zhang Identification of Jump Component Parameters in Discrete Stationary Noise Processes K. M. Hangos	
Optimality in Discrete Adaptive Systems Ya.Z. Tsypkin On the Identification of Linear Time-invariant Systems using Finite Plant Records E.J. Davison, R.H. Kwong and Ying-Li Zhang Identification of Jump Component Parameters in Discrete Stationary Noise Processes	637 643
Optimality in Discrete Adaptive Systems Ya.Z. Tsypkin On the Identification of Linear Time-invariant Systems using Finite Plant Records E.J. Davison, R.H. Kwong and Ying-Li Zhang Identification of Jump Component Parameters in Discrete Stationary Noise Processes K.M. Hangos A Method for Spatial Domain Identification of Distributed Parameter Systems under Noisy Observations Y. Sunahara, Sh. Aihara and F. Kojima	637
Optimality in Discrete Adaptive Systems Ya. Z. Tsypkin On the Identification of Linear Time-invariant Systems using Finite Plant Records E. J. Davison, R. H. Kwong and Ying-Li Zhang Identification of Jump Component Parameters in Discrete Stationary Noise Processes K. M. Hangos A Method for Spatial Domain Identification of Distributed Parameter Systems under Noisy Observations	637 643
Optimality in Discrete Adaptive Systems Ya.2. Tsypkin On the Identification of Linear Time-invariant Systems using Finite Plant Records E.J. Davison, R.H. Kwong and Ying-Li Zhang Identification of Jump Component Parameters in Discrete Stationary Noise Processes K.M. Hangos A Method for Spatial Domain Identification of Distributed Parameter Systems under Noisy Observations Y. Sunahara, Sh. Aihara and F. Kojima The Application of Block Pulse Operator in Identification of Distributed Parameter Systems	637 643 649
Optimality in Discrete Adaptive Systems Ya.Z. Tsypkin On the Identification of Linear Time-invariant Systems using Finite Plant Records E.J. Davison, R.H. Kwong and Ying-Li 2hang Identification of Jump Component Parameters in Discrete Stationary Noise Processes K.M. Hangos A Method for Spatial Domain Identification of Distributed Parameter Systems under Noisy Observations Y. Sunahara, Sh. Aihara and F. Kojima The Application of Block Pulse Operator in Identification of Distributed Parameter Systems Wang Shienyu and Jiang Wie-sun Identification of Systems Described by Hyperbolic Partial Differential Equations	637 643 649
Optimality in Discrete Adaptive Systems Ya.Z. Tsypkin On the Identification of Linear Time-invariant Systems using Finite Plant Records E.J. Davison, R.H. Kwong and Ying-Li Zhang Identification of Jump Component Parameters in Discrete Stationary Noise Processes K.M. Hangos A Method for Spatial Domain Identification of Distributed Parameter Systems under Noisy Observations Y. Sunahara, Sh. Aihara and F. Kojima The Application of Block Pulse Operator in Identification of Distributed Parameter Systems Wang Shienyu and Jiang Wie-sun Identification of Systems Described by Hyperbolic Partial Differential Equations Ou-Yang Liang	637 643 649

ARMA Modelling using Circular Lattice Filter H. Sakaî, H. Tokumaru and A. Futamura	611
Error Propagation Properties of Recursive Least Squares Adaptation Algorithms $S.\ Ljung$ and $L.\ Ljung$	677
Continuous-time Recursive Maximum Likelihood Method, A New Approach to Ljung's Scheme .	
L. Gerencelr, L. Gyöngy and Gy. Michaletsky	683
Tracking of Slowly Varying Parameters by Directional Porgetting R. Kulhavý and M. Kárný	687
Approaches to Robust Real-time Identification of Multivariable Stochastic Systems	
B. Kovačević and S. Stanković	
Model Structures	
Naive Approximate Realizations of Noisy Data A. Hajdasineki, P. Van den Hof and A. Damen	699
Identification of Economically Parametrized Systems S. Dasgupta, B.D.O. Anderson and R.J. Kays	705
Noise Order Determination under Unknown Process Based on Covariance of Composite Noise and Output H. Gotanda, S. Sagara and K. Wada	711
Structural Identifiability of Linear, Bilinear, Polynomial and Rational Systems	711
S. Vajda	717
Identification of Input-Output Bilinear Systems U. Kotta and U. Nurges	723
Parameter Estimation in Large Scale Interconnected Systems G.P. Rao, K. Diekmann and H. Unbehauen	729
Experiment Design	
Aspects of Input Signal Design for Order and Parameter Estimation in Linear Dynamical Systems A. Królikowski and P. Eykhoff	735
Optimal Input Design for Autoregressive Model Discrimination with Output Amplitude Constraints K. Uosaki, I. Tanaka and H. Sugiyama	741
Optimum Experiment Design for Parameter Identification in Distributed Systems: Energy and New Results E. Rafaj toutos	
Identification of Parametric and Nonparametric Models for MIMO Closed Loop Systems by the Correlation Method G. Bretthauer, T. Gamaleja and HH. Wilfert	747
Development and Testing of Methods of Parameter Estimation of Dynamic Systems in Consideration of Restrictions A. Seifert and J. Wernstedt	753
On Partial Properties of M-Sequence H. Kashiwagi and H. Harada	759 765
COLLOQUIUM ON ADAPTIVE AND STOCHASTIC CONTROL	
Estimation and Filtering	
Conditionally Optimal Estimation in Systems with Randomly Varying Structure V.S. Pugachev	773
Optimal Filtering of Nonstabilizable Systems having Singular State Transition	
C.E. de Souza, G.C. Goodwin and Siew Wah Chan	

The Finite Dimensional Filtering Problem for a Class of Nonlinear Discrete-time Systems	Fig. 1
J. Levine and G. Pignie	785
A Simplified Convergence Analysis for the Parallel Identifier with an BEM B.K. Altay and $\ddot{O}.H.$ Oral	791
State Estimation for Partially Observed Evolution Systems with State Dependent Noise S. Cherkaoui and M.E. Achhab	795
Conditionally Optimal Estimation Systems for Markov Diffusion Processes M.L. Dashevskii and I.D. Siluyanova	801
Recent Advances in Nonlinear Estimation	0.00
A Linear Method for the Design of Optimal Nonlinear Filters for Non-Gaussian Processes	•
R.J.P. de Figueiredo	807
On Asymptotic Approximations for some Nonlinear Filtering Problems $S.I.$ Marcus and $E.K.$ Westwood	811
Nonlinear Filtering in Riemannian Manifolds S.K. Ng and P.E. Caines	817
Estimation and Stochastic Control	
Recursive Identification and Adaptive Control of Discrete Objects V.N. Fomin	823
On the Improvement of the Adaptation Transients: An Adaptive Sampling Approach M. de la Sen	829
Simultaneous Detection and Estimation for Diffusion Process Signals $J.S.$ Baras	835
Dual Control for Identification and Guidance K. Birmiwal and Y. Bar-Shalom	841
Analysis of Bilinear Systems Subjected to White Gaussian Input S. Yasui	847
Recursive Prediction Error Methods in Open-loop Estimation and Adaptive Control $J.B.$ Moore and $R.K.$ Boel	851
Model Reference Adaptive Control	
Some Design Guidelines for Discrete-time Adaptive Controllers C.E. Rohre, M. Athans, L. Valavani and G. Stein	857
Direct Model Reference Adaptive Control for Linear Multivariable Systems $J.M.\ Dion\ and\ H.\ Lamare$	863
Some New Adaptive Algorithms for a Class of Model Reference Control Systems M.M. Gupta, P.N. Nikiforuk and Y. Yamamoto	871
A Discrete Time Multivariable Model Reference Adaptive Control Algorithm with Application to a Real Plant	
S. Fujii, N. Mizuno and Y. Nomura A New Direction of the Example of the Structure Structure	877
J. Chandrasekhar and M.P.R. Vittal Rao	883
Model Reference Fuzzy Adaptive Control Wei-min Cheng, Huang Shen-yue and Ho Hua-kon	- *: 8 6 9
Self-tuning with ARMA Models	\vec{I}
Decoupling Pole Placement Self-tuning Controller for a Class of Multivariable	
P.E. McDermott and D.A. Mellichamp	893
vevelopment of Model and a Method of Analysis for a Dual-rate Sampled Self-tuning Regulator . Kanniah, O.P. Malik and G.S. Hope	
- · · · · · · · · · · · · · · · · · · ·	899

Multi-loop Self-tuning Control: Cascade Systems P.J. Gawthrop	905
Extended Horizon Adaptive Control B.E. Ydstie	911
Some Practical Aspects of Adaptive Regulators of Arbitrary Order S.S. Stanković and M.S. Radenković	917
Self Tuning Control of Plants with Abrupt Changes J. Holst and N.K. Poulsen	923
LQ Self-tuning Control	
Adaptive Linear Quadratic Control for Stochastic Discrete Time Systems H.F. Chen and P.E. Caines	929
Multistep Horizon Self-tuning Controllers: the MUSMAR Approach E. Mosca, G. Zappa and C. Manfredi	935
Implicit and Explicit LQG Self-tuning Controllers M.J. Grimble	941
On Implicit Modelling Theory and its Application to Adaptive Control G. Bartolini, G. Casalino, F. Davoli, R. Minciardi and G. Zappa	949
A Globally Convergent Recursive Adaptive LQG Regulator J.B. Moore	955
Simple LQ Self-tuning Controllers J. Böhm, A. Halousková, M. Kárný and V. Peterka	961
Robustness Issues	
Robust Control of Systems Modeled as Markov Chains R.A. Milito and J.B. Cruz, Jr.	967
Input/Output Properties of Adaptive Control Systems: Robustness and Reduced Order Design $R.L.\ Kosut$	973
Practical Requirements and Theoretical Results in Robust Adaptive Control R. Ortega, M.M'Saad and C. Canudas	979
Robust Controller Design using Parameter Space C.B. Soh and C.S. Berger	987
Adaptive Control of Systems Subject to Large Parameter Changes T. Hägglund	993
Adaptive Control of Abruptly Changing Systems M. Millnert	999
New Algorithms and Computational Methods	
A Parallel Architecture for Kalman Filter Measurement Update J.M. Jover and T. Kailath	1005
Explicit Minimization Methods for Tuning of Nonlinear Regulators 5. Trulsson	1011
Adaptive Observer with Exponential Rate of Convergence for Multi-input Multi-output Systems A. Inoue, 2. Iwai, M. Ishitobi and H. Tokumaru	
Stochastic Approximation Algorithm with Gradient Averaging and On-line Stepsize Rules	1017
A. Ruszczyński and W. Syski	1023
torization Techniques in Discrete Time Adaptive Control	1029
engence of Mixed Type (Stochastic-determin [®] stic) Recursive Estimation as As Durancsér, 2s. Liposey and 2s. Vágó	
	1035