VOLUME TWO

SECOND EDITION

UNIVERSITY PHYSICS

ARFKEN GRIFFING

KELLY PRIEST

VOLUME

UNIVERSITY

TWO

PHYSICS

Second Edition

GEORGE B. ARFKEN

DAVID F. GRIFFING

DONALD C. KELLY

JOSEPH PRIEST

Miami University, Oxford, Ohio



Harcourt Brace Jovanovich, Publishers

and its subsidiary, Academic Press San Diego New York Chicago Austin Washington, D.C. London Sydney Tokyo Toronto Cover Credit: Visual Horizons/FPG International

Copyright © 1989, 1984 by Harcourt Brace Jovanovich, Inc.

All rights reserved. No part of this publication may be reproduced or transmitted in any form or by any means, electronic or mechanical, including photocopy, recording, or any information storage and retrieval system, without permission in writing from the publisher.

Requests for permission to make copies of any part of the work should be mailed to: Permissions, Harcourt Brace Jovanovich, Publishers, Orlando, Florida 32887.

Illustration Credits:

Fig. 23-1 The Granger Collection, New York; 25-15 Courtesy of Dr. T. T. Tsong, Pennsylvania State University; 26-13 Courtesy of Central Scientific Company; 29-3 Fundamental Photographs, New York; 29-20 From Marion, J. B. (1981). Physics in the Modern World (2nd ed.). Orlando, FL: Academic Press. Used with permission; 30-14 Courtesy of Central Scientific Company; 33-6 Photo by Jeff Sabo/Audio Visual Service, Miami University, Oxford; 35-20 Courtesy of Polaroid Corporation; 36-2 Fundamental Photographs, New York; 36-20(a) Photo by Jeff Sabo/Audio Visual Service, Miami University, Oxford; 37-1 Fundamental Photographs, New York; 37-3 Courtesy of Joseph Priest: 37-10 Fundamental Photographs, New York; 37-15 Photo by Jeff Sabo/Audio Visual Service, Miami University, Oxford; 38-1 From Rinard, Philip M. (1976). American Journal of Physics, 44, 70. Used with permission of the author; 38-9 From Cajent, M., Francon, M., & Thrien, I. (1962). Atlas of Optical Phenomena. Heidelberg, West Germany: Springer-Verlag. Used with permission of the publisher; 38-17 Courtesy of Donald C. Kelly; 39-1 AIP Neils Bohr Library; 39-13 Courtesy of Donald C. Kelly; 41-1 AIP Neils Bohr Library; 41-12 AIP Neils Bohr Library; 41-22 AIP Neils Bohr Library; 41-23 AIP Neils Bohr Library.

ISBN: 0-15-592975-5

Library of Congress Catalog Card Number: 88-80643

Printed in the United States of America

PREFACE

In this second edition of *University Physics* we present students with an authoritative and easy-to-use text. Among the features that we deem important for a beginning physics textbook are:

- a sound pedagogical presentation
- the systematic development of problem-solving skills
- a special sensitivity to students and their goals

A SOUND PEDAGOGICAL PRESENTATION

We present the most important physical principles in the least intimidating way. The unity of physics and the universal character of its principles are emphasized. Basic concepts are illustrated with numerous examples, many drawn from such diverse areas as astrophysics, sports, and the environment.

A SYSTEMATIC DEVELOPMENT OF PROBLEM-SOLVING SKILLS

A step-by-step Problem-Solving Guide is introduced in Chapter 3 and extended in Chapters 6 and 28. Students are shown how to approach and solve problems in a systematic fashion. The Guide is illustrated with numerous examples.

The text of each chapter concludes with a challenging Worked Problem, typical of those found in the end-of-chapter problem sets. Each chapter presents a set of Exercises and Problems that allow students to test their grasp of the principles. Single-concept Exercises reinforce ideas developed in the current chapter. The Exercises are followed by a set of substantive Problems that often illustrate the "vertical" structure of physics and require students to draw on concepts learned in earlier chapters. In this edition, we have provided a wide range of problems, with many problems at the challenging end of the spectrum. Instructors can readily match the abilities of their students to the problems.

A SPECIAL SENSITIVITY TO STUDENTS

Our goal is to create a learning environment that inspires student confidence. We are patient with students. For example, we have considered students who are taking calculus concurrently. The first five chapters avoid calculus and allow

students to develop problem-solving skills and build confidence before being confronted by calculus-based problems.

Also, the liberal use of examples and illustrations, and our Problem Solving Guide, help to produce the sensitive atmosphere for which we strive.

PATHWAYS THROUGH THIS TEXT

There are many ways to structure physics courses, and this text can be used in a variety of ways to meet that diversity. Here at Miami University we use the text in two slightly different sequences. In class sections open only to entering freshmen, the first semester covers Newtonian Mechanics (Chapters 1–13) and Special Relativity (Chapters 39–40). The special relativity is interwoven with Newtonian mechanics. The second semester is devoted to Electromagnetism (Chapters 23–35). Many of the students continue with a third semester that covers Materials and Fluid Mechanics (Chapters 14–15), Waves (Chapters 16–17), Thermal Physics (Chapters 18–22), Optics (Chapters 36–38), and selections from Contemporary Physics (Chapters 41–42).

In the other sequence here, upperclass students form a more heterogeneous audience. The first semester covers Newtonian mechanics, materials, and waves. Special relativity is omitted. The second semester covers electromagnetism and optics.

SUPPLEMENTS

We provide an Instructor's Answer Book, a Student's Solutions Manual containing solutions or hints to approximately twenty percent of the Exercises and Problems, and a set of transparencies. Instructional software is available for IBM compatibles and Apple II series microcomputers. A Study Guide written by T. William Houk, James E. Poth, and John W. Snider offers additional insights and opportunities for students to sharpen their problem-solving skills.

ACKNOWLEDGMENTS

We are indebted to many reviewers, students, and colleagues for their helpful criticisms during the development of this text. Special thanks go to Bill Adams, Baylor University; Larry Banks, Southwest Missouri State University; James T. Cushing, University of Notre Dame; Patrick Hamill, San Jose State University; Joseph H. Hamilton, Vanderbilt University; James Monroe, Penn State University-Beaver; R. D. Purrington, Tulane University; Eric Sheldon, University of Lowell; K. L. Schick, Union College; and Ken-Hsi Wang, Baylor University. Finally, to Jeff Holtmeier, Debbie Hardin, Chris Nelson, Kim Svetich, Merilyn Britt, Stacy Simpson, and Lynne Bush of Harcourt Brace Jovanovich go our collective thanks for their encouragements, proddings, and zealous attention to detail.

George B. Arfken

David F. Griffing

Donald C. Kelly

Joseph Priest

CONTENTS

This book is available in two versions: a two-volume set (Volume One: Chapters 1-22; Volume Two: Chapters 23-42) and a combined volume (Chapters 1-42). The complete Table of Contents is provided for both versions.

Preface v	3.4 The Second Condition of Equilibrium 47
	3.5 Center of Gravity 51
CHAPTER 1 General Introduction	Exercises 56
	Problems 59
1.1 The Development of Physics 2	
1.2 Science and Measurement 2	CHAPTER 4 Motion in One Dimension
1.3 Time 3	μοδέ
1.4 Length 6	4.1 Frames of Reference 5 65
1.5 Mass 8	4.2 Average Velocity 65
1.6 Dimensions and Units 9	4.3 Instantaneous Velocity 68
1.7 Physics and Mathematics 11	4.4 Acceleration 71
Exercises 13	4.5 The Program of Particle Kinematics 73
Problems 13	4.6 Linear Motion with Constant Acceleration 74
	Exercises 79
CHAPTER 2 Vector Algebra	Problems 81
2.1 Scalars and Vectors 162.2 Addition and Subtraction of Vectors 16	CHAPTER 5 Motion in a Plane
2.3 Components 全 20	het the
2.4 The Scalar Product 124	5.1 Projectile Motion in a Plane 84
2.5 The Vector Product 4 26	5.2 Acceleration in Circular Motion 90
Exercises 30	5.3 Relative Motion: Two Frames of
Problems 30	Reference 93
Trobonio	Exercises 99
	Problems 100
CHAPTER 3 Equilibrium of Rigid Bodies	
	CHAPTER 6 Newton's Laws
3.1 Force 34	
3.2 The First Condition of Equilibrium 36	6.1 Introduction to Newton's Laws 104
3.3 Torque かんと43	6.2 Newton's First Law 105

6.3 Newton's Second Law 107 CHAPTER 10 Rotational Motion	viii	Contents		
10.1 Rotational Kinematics 206	6.3	Newton's Second Law 107	CHAF	PTER 10 Rotational Motion
10.2 Rotational Kinetic Energy 211	6.4	Newton's Third Law 109		
10.3 Calculation of the Moment of Inertia 223	6.5	Newton's Law of Universal	10.1	Rotational Kinematics 206
Exercises 125		Gravitation 111	10.2	Rotational Kinetic Energy 211
## Problems 126	6.6	Mechanical Force Laws 119	10.3	Calculation of the Moment of Inertia 223
Problems 126		Exercises 125		Exercises 216
CHAPTER 11 Conservation of Angular		Problems 126		Problems 217
Momentum 11.1 Angular Momentum of a Particle 2.21	СНА	APTER 7 Work, Energy, and Power		
Momentum 179 The Law of Conservation of Linear Momentum 181 Momentum 182 Momentum 184 Momentum 185 Momentum 186 Momentum 181 Momentum 182 Momentum 183 Momentum 184 Momentum 185 Momentum 186 Momentum 186 Momentum 186 Momentum 186 Momentum 186 Momentum 186 Momentum 187 Momentum 188 Momentum 188 Momentum 189 Momentum 180 Momentum 180 Momentum 181 Mo			CHAF	PTER 11 Conservation of Angular
7.2 Work Done by a Variable Force 134 7.3 Kinetic Energy and the Work-Energy Principle 140 7.4 Power 143 7.5 Simple Machines 145 Exercises 149 Problems 151 CHAPTER 8 Conservation of Energy 8.1 Energy and Energy Conservation 158 8.2 Potential Energy 158 8.3 The Law of Conservation of Energy 161 8.4 Force from Potential Energy 166 8.5 Energy Graphs 168 Exercises 172 Problems 175 Exercises 172 Problems 175 CHAPTER 13 Oscillatory Motion 247 Exercises 250 Problems 251 The Law of Conservation of Linear Momentum 179 9.2 The Law of Conservation of Linear Momentum 181 13.1 Simple Harmonic Motion 264 3.2 Applications of Simple Harmonic Motion 264 3.3 Damped Motion 264 3.4 Damped Motion 265 3.5 Applications of Simple Harmonic Motion 267 3.6 Applications of Simple Harmonic Motion 268 3.7 Variable Mass Systems 3.8 Damped Motion 278 3.9 Exercises 3.9 Exercises 3.9 Exercises 3.10 Damped Motion 3.1	7.1	Work Done by a Constant Force 132		
Principle 140 11.2 Angular Momentum of a System of Particles 226	7.2	Work Done by a Variable Force 134		
Particles 226 Particles 226	7.3	· .	11.1	Angular Momentum of a Particle 221
7.5 Simple Machines 145 11.3 Combined Spin and Orbital Angular Momentum 229 Exercises 149 Exercises 234 Problems 151 Exercises 234 Problems 236 CHAPTER 8 Conservation of Energy Exercises 234 Problems 236 CHAPTER 12 Rotational Dynamics R.1 Energy and Energy Conservation of Energy 158 161 8.2 Potential Energy 158 161 8.3 The Law of Conservation of Energy 166 12.1 Dynamics of Rigid Body Motion 240 8.4 Force from Potential Energy 166 12.2 Precession 242 8.5 Energy Graphs 168 12.3 Work, Energy, and Power in Rotation 247 Exercises 172 12.4 Combined Translation and Rotation 247 Exercises 250 Problems 251 CHAPTER 13 Oscillatory Motion 9.1 Linear Momentum 179 179 9.2 The Law of Conservation of Linear Momentum 181 13.1 Simple Harmonic Motion 256 13.2 Applications of Simple Harmonic Motion 264 9.4 Center of Mass 190 13.3 Damped Motion 268 9.5 Variable Mass Systems 195 13.4 Driven Oscillator: Resonance 273 Exercises 278		Principle 140	11.2	
Exercises 149 Exercises 234 Problems 151 Exercises 234 Problems 236	7.4	Power · 143		
Exercises 149 Exercises 234 Problems 236	7. <i>5</i>	Simple Machines 145	11.3	
### Problems 131 Problems 236		Exercises 149		
### CHAPTER 8 Conservation of Energy ### 8.1 Energy and Energy Conservation 158 ### 8.3 The Law of Conservation of Energy 166 ### 8.4 Force from Potential Energy 166 ### 8.5 Energy Graphs 168 ### Exercises 172 ### Problems 175 ### CHAPTER 9 Conservation of Linear ### Momentum ### CHAPTER 13 Oscillatory Motion ### 9.2 The Law of Conservation of Linear Momentum 181 ### 9.3 Two-Particle Collisions 184 ### 9.4 Center of Mass 190 ### Problems 195 ### Problems 231 ### Problems 231 ### Problems 231 ### Problems 231 ### CHAPTER 12 Rotational Dynamics ### 12.1 Dynamics of Rigid Body Motion 240 ### 12.2 Precession 242 ### 12.3 Work, Energy, and Power in Rotation 247 ### Exercises 250 ### Problems 251 ### CHAPTER 13 Oscillatory Motion ### 256 ### 3.1 Simple Harmonic Motion 256 ### 3.2 Applications of Simple Harmonic Motion 264 ### 3.3 Damped Motion 268 ### 3.3 Damped Motion 268 ### 3.4 Driven Oscillator: Resonance 273 ### Exercises 199 ### Problems 251		Problems 151		
8.1 Energy and Energy Conservation 158 8.2 Potential Energy 158 8.3 The Law of Conservation of Energy 166 8.4 Force from Potential Energy 166 8.5 Energy Graphs 168 Exercises 172 Problems 175 CHAPTER 12 Rotational Dynamics 12.1 Dynamics of Rigid Body Motion 240 12.2 Precession 242 12.3 Work, Energy, and Power in Rotation 245 Exercises 250 Problems 251 CHAPTER 9 Conservation of Linear Momentum CHAPTER 13 Oscillatory Motion 9.1 Linear Momentum 179 9.2 The Law of Conservation of Linear Momentum 181 9.3 Two-Particle Collisions 184 9.4 Center of Mass 190 9.5 Variable Mass Systems 195 Exercises 199 Particle Condition 158 Exercises 199 Particle Condition 268 13.1 Simple Harmonic Motion 256 13.2 Applications of Simple Harmonic Motion 268 13.3 Damped Motion 268 13.4 Driven Oscillator: Resonance 273 Exercises 278				Problems 236
8.2 Potential Energy 158 8.3 The Law of Conservation of Energy 161 8.4 Force from Potential Energy 166 8.5 Energy Graphs 168 Exercises 172 Problems 175 CHAPTER 9 Conservation of Linear Momentum CHAPTER 13 Oscillatory Motion 9.1 Linear Momentum 179 9.2 The Law of Conservation of Linear Momentum 181 9.3 Two-Particle Collisions 184 9.4 Center of Mass 190 9.5 Variable Mass Systems 195 Exercises 199 Revolution of Energy 161 12.1 Dynamics of Rigid Body Motion 242 12.2 Precession 242 12.3 Work, Energy, and Power in Rotation 245 Exercises 250 Problems 251 CHAPTER 13 Oscillatory Motion 13.1 Simple Harmonic Motion 256 13.2 Applications of Simple Harmonic Motion 264 9.4 Center of Mass 190 13.3 Damped Motion 268 9.5 Variable Mass Systems 195 Exercises 199 Exercises 278	CHA	APTER 8 Conservation of Energy		
8.2 Potential Energy 158 8.3 The Law of Conservation of Energy 161 8.4 Force from Potential Energy 166 8.5 Energy Graphs 168 Exercises 172 Problems 175 CHAPTER 9 Conservation of Linear Momentum 179 9.2 The Law of Conservation of Linear Momentum 181 9.3 Two-Particle Collisions 184 9.4 Center of Mass 190 9.5 Variable Mass Systems 195 Exercises 199 Problems 195 Exercises 199 12.1 Dynamics of Rigid Body Motion 240 12.2 Precession 242 12.3 Work, Energy, and Power in Rotation 245 12.4 Combined Translation and Rotation 247 Exercises 250 Problems 251 CHAPTER 13 Oscillatory Motion 13.1 Simple Harmonic Motion 256 13.2 Applications of Simple Harmonic Motion 264 13.3 Damped Motion 264 13.4 Driven Oscillator: Resonance 273 Exercises 278	8.1	Energy and Energy Conservation 158	CHAF	PTER 12 Rotational Dynamics
8.4 Force from Potential Energy 166 8.5 Energy Graphs 168 Exercises 172 Problems 175 CHAPTER 9 Conservation of Linear Momentum CHAPTER 13 Oscillatory Motion 9.1 Linear Momentum 179 9.2 The Law of Conservation of Linear Momentum 181 9.3 Two-Particle Collisions 184 9.4 Center of Mass 190 9.5 Variable Mass Systems 195 Exercises 199 Exercises 199 Exercises 250 Problems 251 CHAPTER 13 Oscillatory Motion 13.1 Simple Harmonic Motion 256 Motion 264 13.2 Applications of Simple Harmonic Motion 268 13.3 Damped Motion 268 13.4 Driven Oscillator: Resonance 273 Exercises 199 Exercises 278	8.2	Potential Energy 158		
8.5 Energy Graphs 168 Exercises 172 Problems 175 CHAPTER 9 Conservation of Linear Momentum CHAPTER 13 Oscillatory Motion 9.1 Linear Momentum 179 9.2 The Law of Conservation of Linear Momentum 181 9.3 Two-Particle Collisions 184 9.4 Center of Mass 190 9.5 Variable Mass Systems 195 Exercises 199 Exercises 199 Exercises 250 Problems 251 CHAPTER 13 Oscillatory Motion 13.1 Simple Harmonic Motion 256 Motion 264 9.4 Driven Oscillator: Resonance 273 Exercises 199 Exercises 278	8.3	The Law of Conservation of Energy 161	12.1	Dynamics of Rigid Body Motion 240
Exercises 172 Problems 175 Exercises 250 Problems 251 CHAPTER 9 Conservation of Linear Momentum CHAPTER 13 Oscillatory Motion 9.1 Linear Momentum 179 9.2 The Law of Conservation of Linear Momentum 181 9.3 Two-Particle Collisions 184 9.4 Center of Mass 190 9.5 Variable Mass Systems 195 Exercises 199 Exercises 250 Problems 251 CHAPTER 13 Oscillatory Motion 13.1 Simple Harmonic Motion 256 Motion 264 13.2 Applications of Simple Harmonic Motion 264 9.4 Center of Mass 190 13.3 Damped Motion 268 9.5 Variable Mass Systems 195 Exercises 199 Exercises 278	8.4	Force from Potential Energy 166	12.2	Precession 242
Exercises 172 Problems 175 Exercises 250 Problems 251 CHAPTER 9 Conservation of Linear Momentum CHAPTER 13 Oscillatory Motion 9.1 Linear Momentum 179 9.2 The Law of Conservation of Linear Momentum 181 9.3 Two-Particle Collisions 184 9.4 Center of Mass 190 9.5 Variable Mass Systems 195 Exercises 199 Exercises 250 Problems 251 CHAPTER 13 Oscillatory Motion 13.1 Simple Harmonic Motion 256 Motion 264 13.2 Applications of Simple Harmonic Motion 264 9.4 Center of Mass 190 13.3 Damped Motion 268 9.5 Variable Mass Systems 195 Exercises 199 Exercises 278	8.5	0.	12.3	Work, Energy, and Power in Rotation 245
Problems 175 Exercises 250 Problems 251 CHAPTER 9 Conservation of Linear Momentum CHAPTER 13 Oscillatory Motion 9.1 Linear Momentum 179 9.2 The Law of Conservation of Linear Momentum 181 13.1 Simple Harmonic Motion 256 Momentum 181 13.2 Applications of Simple Harmonic Motion 264 9.4 Center of Mass 190 13.3 Damped Motion 268 9.5 Variable Mass Systems 195 Exercises 199 Exercises 278 Particular 201		•	12.4	Combined Translation and Rotation 247
CHAPTER 9 Conservation of Linear Momentum CHAPTER 13 Oscillatory Motion 9.1 Linear Momentum 179 9.2 The Law of Conservation of Linear Momentum 181 9.3 Two-Particle Collisions 184 9.4 Center of Mass 190 9.5 Variable Mass Systems 195 Exercises 199 Problems 251 CHAPTER 13 Oscillatory Motion 256 13.1 Simple Harmonic Motion 256 Motion 264 9.3 Damped Motion 268 9.4 Driven Oscillator: Resonance 273 Exercises 278				Exercises 250
Momentum 9.1 Linear Momentum 179 9.2 The Law of Conservation of Linear Momentum 181 9.3 Two-Particle Collisions 184 9.4 Center of Mass 190 9.5 Variable Mass Systems 195 Exercises 199 Particle Collisions 201 Exercises 278 CHAPTER 13 Oscillatory Motion 256 13.1 Simple Harmonic Motion 256 Motion 264 13.2 Applications of Simple Harmonic Motion 264 13.3 Damped Motion 268 13.4 Driven Oscillator: Resonance 273 Exercises 278		2.0		Problems 251
9.1 Linear Momentum 179 9.2 The Law of Conservation of Linear Momentum 181 9.3 Two-Particle Collisions 184 9.4 Center of Mass 190 9.5 Variable Mass Systems 195 Exercises 199 Particular Momentum 179 CHAPTER 13 Oscillatory Motion 256 13.1 Simple Harmonic Motion 256 Motion 264 13.2 Applications of Simple Harmonic Motion 264 13.3 Damped Motion 268 13.4 Driven Oscillator: Resonance 273 Exercises 278	СНА	PTER 9 Conservation of Linear		
9.1 Linear Momentum 179 9.2 The Law of Conservation of Linear Momentum 181 9.3 Two-Particle Collisions 184 9.4 Center of Mass 190 9.5 Variable Mass Systems 195 Exercises 199 Particle Momentum 179 13.1 Simple Harmonic Motion 256 Motion 264 13.2 Applications of Simple Harmonic Motion 264 9.4 Driven Oscillator: Resonance 273 Exercises 278	 	Momentum		
9.2The Law of Conservation of Linear Momentum13.1Simple Harmonic Motion2569.3Two-Particle Collisions184Applications of Simple Harmonic Motion9.4Center of Mass19013.3Damped Motion2689.5Variable Mass Systems19513.4Driven Oscillator: Resonance273Exercises199Exercises278	0.1		CHAP	TER 13 Oscillatory Motion
Momentum 181 9.3 Two-Particle Collisions 184 9.4 Center of Mass 190 9.5 Variable Mass Systems 195 Exercises 199 Particle Collisions 184 13.2 Applications of Simple Harmonic Motion 264 9.4 Driven Oscillator: Resonance 273 Exercises 278				
9.3 Two-Particle Collisions 184 Motion 264 9.4 Center of Mass 190 13.3 Damped Motion 268 9.5 Variable Mass Systems 195 13.4 Driven Oscillator: Resonance 273 Exercises 199 Exercises 278	9.2			Simple Harmonic Motion 256
9.4 Center of Mass 190 13.3 Damped Motion 268 9.5 Variable Mass Systems 195 13.4 Driven Oscillator: Resonance 273 Exercises 199 Exercises 278	0.0		13.2	
9.5 Variable Mass Systems 195 Exercises 199 Exercises 278 Problems 201				
Exercises 199 Exercises 278				•
Dualdon 201	9.5	•	13.4	Driven Oscillator: Resonance 273
Problems 201 Problems 279				Exercises 278
		Problems 201		Problems 279

CHA	PTER 14 Mechanical Properties of	CHAPTER 18 The First Law of
	Matter	Thermodynamics
14.1	States of Matter 282	18.1 Introduction to Thermodynamics 370
14.2	Stress and Strain 282	18.2 Temperature 370
14.3	Hooke's Law and Elastic Moduli 285	18.3 Heat 375
	Exercises 293	18.4 Thermodynamic Work 378
	Problems 295	18.5 Internal Energy 381
		18.6 The First Law of Thermodynamics 382
		18.7 Applications of the First Law 384
CHA	PTER 15 Fluid Mechanics	Exercises 388
		Problems 390
15.1	Fluid Statics 299	
15.2	Fluid Dynamics 304	CHAPTER 19 Thermal Properties of
15.3	Viscosity 311	Matter
15.4	Turbulence 316	40.4 ml ln
	Exercises 320	19.1 Thermal Expansion 393
	Problems 321	19.2 The Ideal Gas 395
		19.3 P-V-T Surfaces 400
		19.4 Change of Phase 403
CHAI	PTER 16 Wave Kinematics	Exercises 409
		Problems 411
16.1	Wave Characteristics 326	0//40750.00
16.2	Sinusoidal Waves 329	CHAPTER 20 Heat Transfer
16.3	The Principle of Superposition for	20.1
	Waves 333	20.1 Introduction to Heat Transfer 414
16.4	The Doppler Effect 335	20.2 Conduction 414
	Exercises 342	20.3 Convection 419
	Problems 344	20.4 Thermal Radiation 423
	•	Exercises 426
		Problems 427
CHAF	PTER 17 Mechanical Waves	CUARTER 21 TO A
		CHAPTER 21 The Second Law of
17.1	Waves on a String 347	Thermodynamics
17.2	Mechanical Waves: A Sampling 349	21.1 Introduction to the Second Law of
17.3	Energy Flow and Wave Intensity 355	Thermodynamics 431
17.4	Standing Waves and Boundary Conditions 360	21.2 Heat Engines and Thermodynamic Efficiency 432
	Exercises 366	21.3 The Carnot Cycle 435
	Problems 367	21.4 The Second Law of Thermodynamics 437

<u>x</u>	Contents		
21.5	The Kelvin Temperature Scale 440	25.4	The Derivative Relation Between
21.6	Entropy 441		E and V 521
	Exercises 448	25.5	Electrostatic Potential Energy 524
	Problems 449		Exercises 531
			Problems 533
CHA	PTER 22 Kinetic Theory		
		CHAI	PTER 26 Capacitors and Capacitance
22.1	The Atomic Model of Matter 453		1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
22.2	Mean Free Path 454	26.1	Introduction to Capacitors and
22.3	The Ideal Gas: Kinetic Interpretation	20.0	Capacitance 537
22.4	of Temperature 456	26.2	Capacitors in Series and in Parallel 540
22.4	The Distribution of Molecular Speeds 462	26.3	Energy Stored in an Electric Field 543
	Exercises 465	26.4 26.5	Effect of an Insulator on Capacitance 546 Polarization 550
	Problems 466	20.5	Exercises 552
			Problems 554
CHAI	PTER 23 Electric Charge		
	PTER 23 Electric Charge		
23.1	Electric Charge 469	CHAI	PTER 27 Electric Current
23.2	Coulomb's Law 471	27.1	Introduction to Electric Current 559
23.3	Superposition 472	27.2	Introduction to Electric Current 559 Electrical Resistance and Ohm's Law 563
	Exercises 479	27.3	Electrical Conductivity and Electrical
	Problems 480	27.5	Resistivity 563
		27.4	Dynamic Resistance 567
СНДЕ	PTER 24 Electric Field	27.5	Electric Power 569
	TEN 24 Electric Field		Exercises 572
24.1	Electric Field 485		Problems 573
24.2	Electric Flux 491		
24.3	Gauss' Law 494	CLIAI	
24.4	Motion of a Charged Particle in an	CHA!	PTER 28 Direct Current Circuits
	Electric Field 500	28.1	Sources of Electric Energy 577
	Exercises 503	28.2	11 M: 1 - 1
	Problems 505	28.3	Kirchhoft's Voltage Rule 579 Kirchhoff's Current Rule 582
		28.4	Applying Kirchhoff's Rules to
CHAF	PTER 25 Electric Potential	20.7	DC Circuits 583
-		28.5	The RC Circuit 589

28.6

Exercises

Problems

Current and Voltage Measurements

597

599

593

25.1

25.2

25.3

Potential Difference

Equipotential Surfaces

Electric Potential

510

518

513

Contents

CHAPTER 29	Magnetic Field	CHAPTER 33 Magnetic Properties of Matter
29.3 Motion Magneti	on of Magnetic Field 607 of a Charged Particle in a c Field 611 c Dipole in a Magnetic Field 619 624	33.1 Magnetic Classification of Materials 687 33.2 Diamagnetism 690 33.3 Paramagnetism 692 33.4 Ferromagnetism 694 Exercises 698 Problems 699 CHAPTER 34 Alternating Currents
CHAPTER 30	Magnetic Field of Electric	34.1 AC Generators 702 34.2 RMS Values 702
	Current	34.3 The RC Circuit 706
	of Biot and Savart 629	34.4 The RL Circuit 712
30.2 Ampère'		34.5 The RLC Circuit 714
30.3 The Mag	gnetic Force Between Parallel 640	34.6 Impedance Matching 719
Exercises	643	34.7 Transformers 721
Problems		Exercises 726
11000113	015	Problems 728
		CHAPTER 35 Maxwell's Equations and
CHAPTER 31	Electromagnetic Induction	Electromagnetic Waves
31.1 Motiona	l emf 649	35.1 Maxwell's Equations 731
31.2 Faraday's	s Law of Induction 651	35.2 Electromagnetic Waves 734
31.3 Lenz's La	aw 654	35.3 Energy Transfer via Electromagnetic Waves 742
• •	ion of Faraday's Law 656	35.4 Polarization 744
Exercises	663	Exercises 750
Problems	665	Problems 751
		CHAPTER 36 Geometric Optics
CHAPTER 32	Inductors and Inductance	Grina 1211 00 Geometric Optics
		36.1 Introduction to Geometric Optics 754
	and Inductance 669	36.2 Reflection and Refraction 754
	spects of Inductors 672	<i>36.3</i> Mirrors <i>760</i>
	tored in a Magnetic Field 677	36.4 Lenses 767
	ons in LC and LCR Circuits 678	36.5 Optical Systems 771
Exercises	681	Exercises 777
Problems	683	Problems 778

CHAF	PTER 37 Physical Optics: Interference	40.3 Relativistic Energy 856
37.1	Interference 783	40.4 Relativistic Energy and Momentum Conservation 860
37.2	Coherence 789	40.5 Mass Energy Transformations 862
37.3	Thin-Film Interference 792	Exercises 865
37.4	Optical Interferometers 797	Problems 866
	Exercises 801	
	Problems 802	CHAPTER 41 Quantum Physics
CHAF	PTER 38 Physical Optics: Diffraction	41.1 The Origins of Quantum Physics 869
		41.2 Rutherford and the Nuclear Atom 876
38.1	Diffraction 806	41.3 Bohr and the Hydrogen Atom 878
<i>38.2</i> <i>38.3</i>	Single-Slit Diffraction Pattern 808 Diffraction and Angular Resolution 812	41.4 De Broglie and the Wave-Particle Duality 883
38.4	Diffraction Gratings 815	41.5 Schrödinger's Equation and
38.5	Holography 821	Probability Waves 885
	Exercises 825	41.6 Quantum Optics and Lasers 887
	Problems 826	41.7 Superconductivity and Squids 893
		Exercises 903
CHAP	PTER 39 Special Relativity	Problems 904
39.1	Einstein's Postulates of Special Relativity 829	CHAPTER 42 Nuclear Structure and
39.2	The Relativity of Simultaneity 830	Nuclear Technology
39.3	The Lorentz Transformation Equations 832	42.1 The Neutron-Proton Model of the Nucleus 907
39.4	The Einstein Velocity Addition	42.2 Nuclear Stability 912
00.5	Formula 838	42.3 Radioactive Dating 922
39.5	Time Dilation and the Twin Effect 841	42.4 Neutron Activation Analysis 926
39.6	The Lorentz-FitzGerald Length Contraction 844	42.5 Nuclear Energy 929
	Exercises 848	Exercises 935
	Problems 848	Problems 936
	1100lems 040	
CHAI	PTER 40 Relativistic Dynamics	Answers, Volume One A-1
40.1	Relativistic Mechanics 851	Answers, Volume Two A-9
40.2	Relativistic Linear Momentum and Force 851	Index I-1

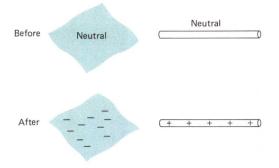


FIGURE 23.2

Separation of electric charge when a glass rod is rubbed with a silk cloth.

Conservation of Electric Charge

The concept that a net electric charge can never be created or destroyed goes back at least to Benjamin Franklin. When a glass rod is rubbed with silk, electrons are transferred from the glass to the silk, giving the silk a negative charge and leaving the glass rod with an equal positive charge. This transfer of electrons is illustrated in Figure 23.2. No change in the total charge of glass-plus-silk occurs. Conservation of charge has been tested repeatedly in the realm of high-energy physics and has been found to hold without exception. The principle of conservation of electric charge can be stated as follows:

The net electric charge remains constant in all processes.

The next two examples illustrate the conservation of electric charge in nuclear processes.

EXAMPLE 1

Uranium 238 Alpha Decay

The radioactive uranium 238 nucleus $^{238}_{92}$ U disintegrates by emitting an alpha particle (helium nucleus). This nuclear reaction may be written as

$$^{238}_{92}U \rightarrow ^{4}_{2}He + ^{234}_{90}Th$$

The superscripts give the combined number of neutrons and protons in each nucleus. The subscripts give the number of protons in each nucleus and therefore measure the positive nuclear charge. There are 92 protons in the uranium nucleus. The decay products contain a total of 92 protons, 2 in helium and 90 in thorium. The balancing of the subscripts, 92 for both sides, describes the exact conservation of electric charge in this nuclear reaction.

In Example 1, electric charge in the form of protons is simply rearranged. Sometimes electric charges are created. When this occurs, positive and negative charges are created in equal amounts, keeping the net charge unchanged.

EXAMPLE 2

Carbon 14 Beta Decay

Carbon 14 $\binom{14}{6}$ C) has six protons in its nucleus and is formed in our atmosphere by cosmic ray bombardment of nitrogen. Carbon 14 is unstable and transforms into nitrogen 14 by emitting an electron and an antineutrino (zero mass, zero charge).

$$^{14}_{6}\text{C} \rightarrow ^{14}_{7}\text{N} + _{-1}e + \bar{v}$$

In this process one of the 8 neutrons in the carbon 14 nucleus is transformed into three particles: a positively charged proton, a negatively charged electron, and a neutral antineutrino. The proton, the electron, and the antineutrino are *created* in the reaction. Although both positive and negative charges are created, the net charge remains the same (+6 before = -1 + 7 = +6 after).

23.2 COULOMB'S LAW

A quantitative breakthrough in electrostatics occurred in 1785 when the French scientist Charles Augustin de Coulomb measured the force between two small electrically charged spheres. Coulomb found that the force between the charged spheres was inversely proportional to the square of the distance between them and directly proportional to the product of their charges:

$$F \propto \frac{q_1 q_2}{r^2}$$

This proportionality is converted into an equation by introducing a proportionality constant. The result is known as **Coulomb's law of electrostatic** force and may be written as

$$F = k_e \frac{q_1 q_2}{r^2} \tag{23.1}$$

The SI unit of charge is the coulomb (symbol C). The operational definition of the coulomb, based on magnetic effects of electric currents, is presented in Chapter 30. The proportionality constant k_e is

$$k_e = 8.98755 \times 10^9 \,\mathrm{N \cdot m^2/C^2}$$
 (23.2)

Like all forces, the electrostatic force obeys Newton's third law. That is, Equation 23.1 describes the magnitude of the equal but oppositely directed forces that the charges q_1 and q_2 exert on each other (Figure 23.3). The Coulomb force is repulsive for like charges and attractive for unlike charges.

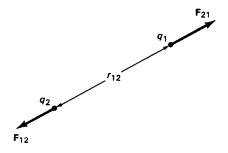


FIGURE 23.3

 F_{12} is the force exerted by q_1 on q_2 and F_{21} is the equal but oppositely directed force exerted by q_2 on q_1 . If q_1 and q_2 have the same sign, the forces are repulsive, as shown here. If q_1 and q_2 have opposite signs, the forces are attractive.

EXAMPLE 3

Electrostatic Repulsion

Let's calculate the force of repulsion between two 1 C charges 1 m apart. From Coulomb's law (Equation 23.1) we have

$$F = (8.99 \times 10^9 \text{ N} \cdot \text{m}^2/\text{C}^2) \cdot \frac{(1 \text{ C})^2}{(1 \text{ m})^2}$$
$$= 8.99 \times 10^9 \text{ N}$$

This is a force of about 1 million tons. Clearly, one coulomb is an enormous charge. In fact, this example is unrealistic in the sense that we could not get charges of 1 C to stay on small surfaces separated by 1 meter.

Coulomb's law of electrostatic interaction and Newton's law of universal gravitation have the same mathematical form; both are inverse square laws. But what about the relative strength of these two fundamental forces? Let's calculate the ratio of the electrostatic force and the gravitational force between an electron and a proton. These forces are described by Coulomb's law (Equation 23.1) and Newton's law of universal gravitation. The ratio is

$$\frac{F_{\text{elec}}}{F_{\text{grav}}} = \frac{k_e \left(\frac{q_e q_p}{r^2}\right)}{G\left(\frac{m_e m_p}{r^2}\right)} = \frac{k_e q_e q_p}{G m_e m_p}$$

Note that the distance factor cancels out. The value of the ratio is

$$\frac{F_{\rm elec}}{F_{\rm grav}} \approx 2 \times 10^{39}$$

This is an enormous number. Imagine grains of sand so fine that you can pack 10^6 grains in 1 cm³: 10^{39} of these grains would occupy the volume of a million earths! Clearly, the electrostatic force is far stronger than gravity.

The fact that Newton's law of gravitation and Coulomb's electrostatic law have the same $1/r^2$ distance dependence has impressed many scientists, including Einstein, as more than mere coincidence. So far, no profound relationship or common origin has been discovered.

23.3 SUPERPOSITION

Coulomb's law specifies the force between a pair of point charges. When more than two charges interact, experiment shows that the net force on any particular charge is the vector sum of the Coulomb forces exerted on it by the other charges.

EXAMPLE 4

Superposition

Charges of 3 μ C, 4 μ C, and 6 μ C are placed along a line (Figure 23.4). Let's use Coulomb's law to calculate the two separate forces exerted on the 6 μ C charge. First,

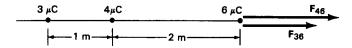


FIGURE 23.4

The total force on the 6- μ C charge is the sum of the forces exerted by the 3- μ C and 4- μ C charges.

consider the force exerted by the 3- μ C charge. From Coulomb's law (Equation 23.1) the force exerted on the 6- μ C charge is

$$F_{36} = \frac{8.99 \times 10^9 \text{ N} \cdot \text{m}^2/\text{C}^2 (3 \times 10^{-6} \text{ C})(6 \times 10^{-6} \text{ C})}{(3 \text{ m})^2}$$
$$= 1.80 \times 10^{-2} \text{ N} \qquad \text{(directed to the right)}$$

Next, we consider the force exerted by the 4 μ C charge.

$$F_{46} = \frac{8.99 \times 10^9 \text{ N} \cdot \text{m}^2/\text{C}^2 (4 \times 10^{-6} \text{ C})(6 \times 10^{-6} \text{ C})}{(2 \text{ m})^2}$$
$$= 5.39 \times 10^{-2} \text{ N} \qquad \text{(directed to the right)}$$

Superposing F_{36} and F_{46} yields the total force on the 6 μ C charge:

$$F_6 = F_{36} + F_{46} = 7.19 \times 10^{-2} \,\mathrm{N}$$

To within the limits of experimental accuracy the total force on the 6 μ C charge has been confirmed to be the sum of F_{36} and F_{46} , or 7.19×10^{-2} N. In other words, experiment shows that the presence of a third charge does not influence the Coulomb force between the other two charges.

We can generalize the experimental result stated in Example 4 by saying that electrical forces obey a **principle of superposition**:

The net force exerted by two or more charges on a single charge Q is the vector sum of the individual forces exerted on Q.

Keep in mind that this principle is the result of experiment.

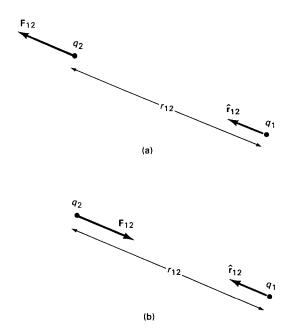
Vector Form of Coulomb's Law

The electrostatic force is a vector quantity—it has direction as well as magnitude. We can write Coulomb's law in vector form by introducing a unit vector to indicate direction. In Figure 23.5, $\hat{\mathbf{r}}_{12}$ is a unit vector directed from q_1 toward q_2 . The force \mathbf{F}_{12} exerted by q_1 on q_2 is

$$\mathbf{F}_{12} = k_e \frac{q_1 q_2}{r_{12}^2} \hat{\mathbf{r}}_{12} \tag{23.3}$$

If the charges q_1 and q_2 are both positive or both negative, the force is repulsive, and \mathbf{F}_{12} is parallel to $\hat{\mathbf{r}}_{12}$ (Figure 23.5a). If q_1 and q_2 have opposite signs, then the force is attractive, indicating that q_1 is urged toward q_2 (Figure 23.5b).

Example 4 involves only parallel forces. Now let's apply Equation 23.3 and the principle of superposition to a system where the forces are not parallel. We build in enough symmetry so that we can check our results.





 ${\sf F}_{12}$ denotes the force exerted by q_1 on q_2 . The unit vector $\hat{\sf r}_{12}$ is directed from q_1 toward q_2 . (a) The direction of ${\sf F}_{12}$ indicates a repulsive force between like charges. (b) When q_1 and q_2 have opposite signs the force is attractive.

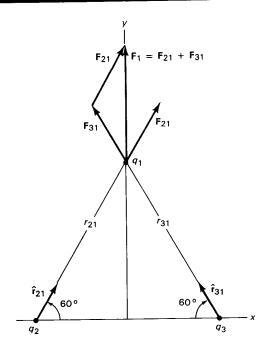


FIGURE 23.6

A 1- μ C charge is located at each vertex of the equilateral triangle. The net force F_1 on q_1 is the vector sum of the forces F_{31} and F_{21} exerted by q_3 and q_2 .

EXAMPLE 5

Vector Addition for Coulomb Forces

Consider three 1 μ C charges at the vertices of an equilateral triangle, 1 m on a side (Figure 23.6). What is the net force that the two bottom charges exert on the top charge (q_1) ?

Figure 23.6 shows that the array of three equal charges has left-right symmetry relative to a vertical line through q_1 . We know from this symmetry that the net force on q_1 will be vertical and in the upward direction. (All charges have the same sign; all forces are repulsive.) The net force on q_1 is the vertical component of the force exerted by q_2 plus the vertical component of the force exerted by q_3 . Since the two vertical components are equal by symmetry, the magnitude of the force on q_1 is

$$F_1 = 2k_e \left(\frac{q_1 q_2}{r^2}\right) \cdot \cos 30^\circ$$

$$= 2(8.99 \times 10^9 \text{ N} \cdot \text{m}^2/\text{C}^2) \left[\frac{10^{-6} \text{ C} \cdot 10^{-6} \text{ C}}{1 \text{ m}^2}\right] \cdot (0.866)$$

$$= 1.56 \times 10^{-2} \text{ N}^{\circ}$$

Now, let's go through the calculation in detail using the vector form of Coulomb's law. The unit vectors are illustrated in Figure 23.7. For $\mathbf{F_{21}}$ —the force that q_2 exerts on q_1 —we have

$$\mathbf{F}_{21} = k_e \left(\frac{q_1 q_2}{r_{21}^2}\right) \hat{\mathbf{r}}_{21}$$

$$= (8.99 \times 10^9 \text{ N} \cdot \text{m}^2/\text{C}^2) \left[\frac{10^{-6} \text{ C} \cdot 10^{-6} \text{ C}}{(1 \text{ m})^2}\right] \hat{\mathbf{r}}_{21}$$

$$= 8.99 \times 10^{-3} \hat{\mathbf{r}}_{21} \text{ N}$$

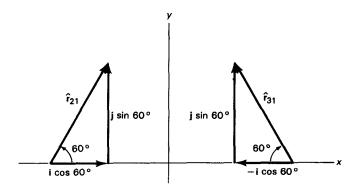


FIGURE 23.7

The unit vectors $\hat{\mathbf{r}}_{21}$ and $\hat{\mathbf{r}}_{31}$ can be resolved into x- and y-components.

We can resolve the unit vector $\hat{\mathbf{r}}_{21}$ into its Cartesian components (Figure 23.7)

$$\hat{\mathbf{r}}_{21} = \mathbf{i} \cos 60^{\circ} + \mathbf{j} \sin 60^{\circ}$$

This gives

$$\mathbf{F}_{21} = (8.99 \times 10^{-3} \text{ N}) \cos 60^{\circ} \mathbf{i} + (8.99 \times 10^{-3} \text{ N}) \sin 60^{\circ} \mathbf{j}$$

= $(4.49 \times 10^{-3} \text{ N})\mathbf{i} + (7.78 \times 10^{-3} \text{ N})\mathbf{j}$

The force F_{31} is given by

$$\mathbf{F_{31}} = k_e \left(\frac{q_1 q_3}{r_{31}^2} \right) \hat{\mathbf{r}}_{31}$$

The unit vector $\hat{\mathbf{r}}_{31}$ is given by

$$\hat{\mathbf{r}}_{31} = -\mathbf{i}\cos 60^{\circ} + \mathbf{j}\sin 60^{\circ}$$

This gives

$$F_{31} = (-4.49 \times 10^{-3} \text{ N})i + (7.78 \times 10^{-3} \text{ N})j$$

The net force on q_1 is the vector sum of \mathbf{F}_{21} and \mathbf{F}_{31} . The horizontal components cancel each other because of the symmetry of the system. The result is

$$F_1 = F_{21} + F_{31}$$

= $(1.56 \times 10^{-2} \text{ N})i$

This shows that the net force is vertically upward with a magnitude of 1.56×10^{-2} N. This solution agrees with the first calculation.

Using symmetry made it easier to find a solution. If symmetry is not present, however, we can still find the net force by using the vector form of Coulomb's law and the principle of superposition.

Continuously Distributed Charge

All electric charge distributions are collections of discrete charges such as electrons and protons. However, when we consider a large number of closely packed charges, we can treat the distributed discrete charges as continuous. To determine forces exerted by continuous distributions of charge the principle of superposition may be applied, but integrations replace discrete sums.

Figure 23.8 shows a **line charge**, a collection of charges spread continuously along a line. A point charge Q located at the point P experiences forces exerted