

The Complete Guide for Managers and Engineers

Peter B. Scott with a Foreword by Tom M. Husband

The Robotics Revolution

THE COMPLETE GUIDE FOR MANAGERS AND ENGINEERS

Peter B. Scott

Basil Blackwell

@ Peter B. Scott, 1984

First published 1984

Basil Blackwell Publisher Ltd 108 Cowley Road, Oxford OX4 1JF, UK

Basil Blackwell Inc. 432 Park Avenue South, Suite 1505, New York, NY 10016, USA

All rights reserved. Except for the quotation of short passages for the purposes of criticism and review, no part of this publication may be reproduced, stored in a retrieval system, or transmitted, in any form or by any means, electronic, mechanical, photocopying, recording or otherwise, without the prior permission of the publisher.

Except in the United States of America, this book is sold subject to the condition that it shall not, by way of trade or otherwise, be lent, re-sold, hired out, or otherwise circulated without the publisher's prior consent in any form of binding or cover other than that in which it is published and without a similar condition including this condition being imposed on the subsequent purchaser.

British Library Cataloguing in Publication Data

Scott, Peter B.

The robotics revolution.

1. Robots, Industrial

I. Title

629.8'92 TS191.8

ISBN 0-631-13162-0

Typeset by Katerprint Co. Ltd, Oxford Printed in Great Britain by Bell & Bain Ltd, Glasgow

The Robotics Revolution

The Complete Guide for Managers and Engineers

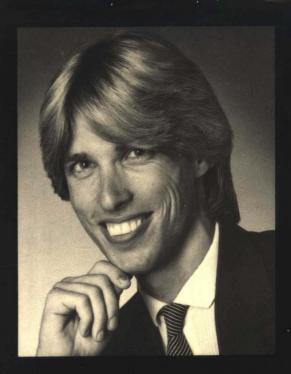
Peter B. Scott

with a foreword by Tom M. Husband

Long-predicted in science fiction, the robotics revolution is now hard technological fact. This book is the complete guide for everyone affected by the transformation of outmoded industrial processes now under way. Written clearly and with the non-specialist in mind, yet not fighting shy of technical detail and terminology, **The Robotics Revolution** addresses all aspects of the subject.

Areas covered include what robots actually are, how they have evolved, how they work and how they are programmed. How are they currently used in industry and what is their future? What are their limitations? Can modern industry afford them — or afford to be without them? And, just as important as their impact on industry, what will be their effect on employment and society at large?

The Robotics Revolution provides a comprehensive introduction to a subject of vital importance to all industrialised societies. For managers, engineers and students, technical and non-technical, this is essential reading.



Peter B. Scott is a roboticist at the Centre for Robotics and Automated Systems at the Imperial College of Science and Technology, University of London, and managing director of Ultratech Video, a high-technology-oriented video company.

Contents

Foreword Tom M. Husband

Preface

Introduction

- I Robotics Background
- **II** Robotics Technology
- III Robotics in Action
- IV Social, Organisational and Economic Considerations

V Current Prospects

Further Reading

Glossary

Index

Jacket illustration is reproduced by kind permission of ASEA.
Photograph of author: Neville Miles

Printed in Great Britain

The Robotics Revolution

With sincere gratitude for friends', relatives', and numerous colleagues' inestimable support

FOREWORD

Tom M. Husband

As the title of this book proclaims, we truly are in the midst of a robotics revolution. The speed at which both software and hardware have developed is breathtaking. Robotics applications are about to change the face of many work (and non-work!) activities.

In the early 1970s industrial engineers grudgingly conceded that the shop floor robot might eventually be useful in simple materials handling work. Soon the role perceived for the robot included straightforward spray painting and spot welding. By the late 1970s the momentum of the emerging technology forced even the most conservative and sceptical engineers to review the horizon. They now accepted that the second and third generation industrial robots available in the 1980s and 1990s would have a significant role to play in inspection, assembly and many other established activities long associated with human skills of manual and mental dexterity.

The picture is possibly even more dramatic in non-industrial applications. The use of robotics technology in space exploration, in security work, in farming, in helping the disabled and in a host of other fields of activity is quickly gaining acceptance.

From a strictly technological viewpoint this revolution is fascinating. Robotics engineers have developed an impenetrable jargon, robot-user clubs are mushrooming, hobbyist magazines are flourishing. Yet the impact of the robotics revolution is much too important to be left solely to the technologists. It is essential that others resist the jargon (or at least the worst of it) and set about broad understanding of the limits of this particular technological revolution.

There is a special need for social scientists, trade union officials and senior managers to get to grips with robotics. The effects of introducing robotics into an organization are not well understood. There is no empirical 'case law' yet available. It is clear, however, that many traditional work and organizational relationships will be altered. Equally,

xii Foreword

there are clear implications for skill displacement. From a strictly managerial perspective there is the question of assessing the cost-effectiveness of certain potential robotic applications.

For all of these reasons this book by Peter Scott is especially welcome. He tackles the subject on a broad front. The jargon is dealt with head-on. For readers who might flinch from such a confrontation he offers a convenient glossary at the end of the book. Questions of a social, economic and organisational nature are considered in an open and honest fashion.

It is often argued that robotics technology exemplifies all of the advanced technologies currently emerging in the developed world. Like information technology or biotechnology, robotics requires technical expertise on many fronts. It carries with it important social implications – relating particularly to employment levels; it implies major upheavals in the way we operate our organisations, the way we educate the younger members of our community, and re-train those in midcareer. It is a very persuasive argument.

Take the question of the breadth of technical expertise required. The robotics engineer needs a good understanding of mechanical, electrical, electronic, hydraulic and pneumatic engineering. He (or, increasingly, she) must also be conversant with appropriate software procedures. Yet we still do not train engineers in this fashion in the great majority of our universities. Robotics technology, like so many other technologies, call for *systems* engineers. Engineers in mid-career face particular difficulties in catching up, and keeping up, with developments across such broad frontiers.

This book is, I believe, the first to tackle these problems in the context of robotics. As the author points out, there are sections of the technical chapters which will seem simplistic to readers who are specialists in one particular field. Similarly, readers with a management background may be familiar with certain of the material on the economic aspects of robitics. It is very unlikely, however, that many readers will have been exposed to the breadth of material discussed in this book.

For this reason the book should prove particularly valuable for both student and professional coourses, in addition to providing an ideal introduction and overview for all busy professionals who may come into contact with robotics, in however slight a fashion. Final year undergraduates in, for example, computing will find much of value in the chapters relating to mechanical and control engineering. Similarly, undergraduate mechanical engineers will derive benefit from Peter Scott's treatment of software and sensor technology. The book will surely also be of great use to teachers and students on the growing

The second of th

Foreword xiii

number of specialist postgraduate courses in robotics and automation. For mid-career short courses the book offers a sound background text for a very wide range of mature students, whether managers or technologists.

At Imperial College we set up a Centre for Robotics and Automated Systems in 1981. We run postgraduate and short courses in robotics. We also pursue research and development activities involving robotic applications ranging from pork deboning to television assembly. In the course of our work we collaborate closely with engineers and managers from robot-maker and robot-user firms. We also supervise, naturally, young project students and research workers. In all of our dealings we meet a recurring problem. It is the need for a broad, basic, minimal awareness of the total technology of robotics. This includes an understanding of the economics and the social implications. Since 1981 we have regularly bemoaned the lack of a basic text which tackled the field in the necessary breadth.

I am delighted therefore that one of our own Centre colleagues has now produced the goods. I know this book will be invaluable to those we deal with at Imperial College. I am sure it will be equally useful to a very wide range of others in education, industry and elsewhere.

PREFACE

Of all the years to publish a book on robotics, 1984 must surely be the most theatrical! Yet the world we live in is, thank goodness, very different from that portrayed in Orwell's view of the future, and there is hope in that. I am essentially optimistic about the future of mankind and of the role robotics is to play in it, yet our options on both scores are far from settled.

As with any major discovery, robotics has potential for evil as well as good – indeed there are those who feel it is far from 'neutral'. Yet it must always be remembered that robotics is a *dynamic* discipline. It is, to a large extent, what we make it. Many have fears that robots may gradually take over the work of humans yet provide nothing to 'fill the vacuum'. But the field is not quite like a runaway train. If sufficient numbers wish to change its course it can be steered – as has been demonstrated by many government robotics initiatives throughout the world. Some roboticists, for example, suggest that enhancement of man (rather than his replacement as at present) is, in the long run to be preferred both economically and socially. Robotics will not decide on which course to take – people will. The responsibility for the robotic future is ours.

A decade ago I was studying science, and soon after, computing science. For fun, I learned everything that I could about robotics – even though I had been told that it was a 'a dead-end subject'! But times were changing, and in the nick of time great men like Joe Engelberger opened the world's eyes to robotics, so that I was able at last proudly to put ROBOTICIST on the sections of forms asking for 'occupation'! Suddenly I am living the science fiction of my youth.

It is pure luck to be paid to do one's hobby, but then to be asked to write a book on it, is a great privilege. I am extremely grateful to all those who have been involved at Blackwells, especially Tony Sweeney and René Olivieri who have helped me through the course. At Imperial College, many of my overworked colleages have gone beyond the call of duty and actually read and commented on some of my draft chapters,

Preface xv

for which I give my sincere thanks – most of all to Tom Husband, friend and professor, without whose constant encouragement and practical support I could never have written the book. I am particularly indebted to him for being willing, despite his very heavy workload, to write a Foreword. Special mention must also go to Steve Bedley and all those others who so kindly sacrificed much time and peace of mind during the preparation of photographs and also to Francis Morgan, who provided such invaluable assistance during the preparation of the index. Finally, deepest thanks to my close friends and family who supported and helped me during the writing process – at the end of the day, however wonderful the robots, it is the *humans* who mean the most.

ACKNOWLEDGEMENTS

Photographs courtesy of:

ASEA Ltd: 4.7, 9.1, 16.2; S. Bedley, photographer, Imperial College: 1.10, 1.11, 2.1, 2.2, 6.1, 6.4, 7.3, 8.1, 8.2, 8.6, 13.1, 15.1, 16.1, 17.2b, 17.7; British Nuclear Fuels plc: 12.1; Laboratoire d'Automatique et d'Analyse des Systèmes, Centre National de la Recherche Scientifique, France: 17.2a; Industrial Robot Division, Cincinnati Milacron UK Co: 9.2, 10.4, 13.4, 17.4, 18.2; B. L. Davies, Imperial College, London: 1.2; The DeVilbiss Company Ltd: 6.2, 16.6; Engineering & Scientific Equipment Ltd: 1.1, 8.8; Fairey Systems, Fairey Automation Ltd: 7.2; 600 Fanuc Robotics Ltd: 3.4, 4.6; Ferranti plc, Dundee: 10.3; GEC Electrical Projects Ltd, Rugby: 6.3; General Electric Research and Development Centre (USA): 10.2, 12.5; Marconi Research Centre, GEC Research Laboratories: 1.9; Odetics Inc, Anaheim, California (USA): 12.6; Spine Robotics AB, Sweden: 13.2, 17.1; Wagner Indumat Systems Ltd: 12.2, 13.3, 18.3; Faculty of Science and Engineering, Waseda University, Japan: 12.4, 17.5; Zenith Data Systems Ltd: 12.3.

CONTENTS

For	Foreword by Tom M. Husband	
Pre	Preface	
	nat's in it for you! roduction	1
Par	rt I: Robotics Background	
1	What all the fuss is about Fundamental Robotics	9
	Robotics, not robots 9 Origins of robotics 9 What is a robot? 11 The robot arm 14 Different arm configurations 16 Robot classifications 22 What can current robots do? 24	
2	From Ancient Greece to factory grease The Evolution of Robotics Development of modern robotics 27 Development of industrial robotics 34 Robotics worldwide 37	27
Pa	art II: Robotics Technology	
3	Strong arm tactics Robot Mechanics – I Structures and Description Techniques	4.
	Manipulator anatomies 43	

ANGLER BU

Contents

	Transformations 47 Euler angles 50 Kinematics 53 Dynamics 55 Mobile platforms 56	
4	Power to one's elbow Robot Mechanics – II Drive Systems	61
	Hydraulic drives 61 Electrical drives 67 Other drives 72 Mobility considerations 74 Transmissions 76 Performance 79	
5	Steam engines and computers Control Systems – I Cybernetics	83
	Robots and control 83 Feedback 84 Internal-state transducers 89 Point-to-point control 92 Continuous-path control 92 Additional sophistication 93	
6	Do as you're told Control Systems – II Programming and Software	95
	Types of hardware 95 Types of programming 98 Types of software 102 User-programming with software 105 Textual programming 108 Future software 111	
7	Sense and sensibility External-State Sensors	113
	The principles of sensing 113 Taction 116 Noncontact sensing 118	

	Contents	vii
8	Hand in hand End-Effectors and Parts Presentation	129
	Types of grippers 129 Flexibility 132 Compliance 135 Tools and sensors 138 PARTS PRESENTATION Feeding workpieces 139 Transfer systems 141 Parts feeders and storage 142	
Par	rt III: Robotics in Action	
9	Robots with hands Workpiece Manipulation	147
	Deburring 148 Diecasting 148 Fettling 149 Forging 151 Heat treatment 152 Investment casting 152 Machine loading/unloading 153 Packing, palletising and stacking 155 Plastic moulding 155 Press work 156	
10	Robots with tools Wrist-Mounted Devices	158
	Adhesive and sealant application 158 Arc welding 159 Lasers 163 Power tools 165 Spot welding 165 Spray painting and coating 166 Water jets 167	
11	The massive future market Robotic Assembly	169
	Product design 170	

A

VIII	Contents
4 7 7 7	00

VIII	Contents	
	Assembly sequencing 174 Layout, analysis and evaluation 176 Optimal robotic assembly 178	
12	Science fact from science fiction Mobile and other Robot-Related Devices	183
	Autonomy versus teleoperation 183 Terrestrial robots 186 Marine robots 193 Space robots 194 Bionics 195	
Par	t IV: Social, Organisational and Economic Considerations	
13	'What about my job?' Robotics and People	199
	Worries 199 Why do it? 201 Social implications 203 A new revolution? 205 A history of deskilling 208 Economic determinism 210 The wrong road? 213 Other options 215 The road to follow 217	
14	Managing with robots Robotics and the Firm	218
	Success and failure 218 Are you ready for robots? 220 Forward march! 222	
15	Danger - robot working/not working Safety and Reliability	233
	Safety problems 233 Safety solutions 235 Reliability 240 Maintenance 244	