

15444

Fundamentals of Magnetohydrodynamics

R. V. Polovin and
V. P. Demutskii

Fundamentals of Magnetohydrodynamics

R. V. Polovin and
V. P. Demutskii

*Institute of Physics and Technology
Academy of Sciences of the Ukrainian SSR
Khar'kov, USSR*

Translated from Russian by
D. ter Haar

CONSULTANTS BUREAU
NEW YORK AND LONDON

Polovin, R. V. (Rivol'd Vasil'evich)

[Osnovy magnitnoĭ gidrodinamiki. English]

Fundamentals of magnetohydrodynamics / R.V. Polovin and V.P.

Demutskii ; translated from Russian by D. ter Haar.

p. cm.

Translation of: Osnovy magnitnoĭ gidrodinamiki.

Includes bibliographical references.

ISBN 0-306-11027-X

1. Magnetohydrodynamics. I. Demutskii, V. P. (Viktor Petrovich)

II. Title.

QC718.5.M36P6513 1990

538'.6--dc20

89-25382

CIP

© 1990 Consultants Bureau, New York
A Division of Plenum Publishing Corporation
233 Spring Street, New York, N.Y. 10013

All rights reserved

No part of this book may be reproduced, stored in a retrieval system, or transmitted in any form or by any means, electronic, mechanical, photocopying, microfilming, recording, or otherwise, without written permission from the Publisher

Printed in the United States of America

PREFACE

In this book we attempt to introduce the reader to the ideas of magnetohydrodynamics (MHD), to show him various methods which are used in MHD, and to prepare him for reading the original literature. These aims have determined our choice of material and the way we have presented it.

Often researchers aim at getting good agreement between experimental data and theoretical expositions, but this often is obtained at the expense of clarity and simplicity. The theory may be exact, but it is very complicated and often connected with computer solutions that describe only one particular solution of the equations and that are valid only for finite times. In other words, the theory may describe some experiments, but may not give any impulse to look for fundamentally new ideas—unexpected experiments or unexpected applications. Moreover, numerical solutions may not show ways for increasing the efficiency of MHD devices and the domains where they can be applied optimally. Finally, such approximate solutions cannot serve for finding the nature of the solution for infinite times.

This is the reason why researchers are sometimes driven to another extreme—crude qualitative reasoning is substituted for mathematical proof. However, the sad experience of *perpetuum mobile* inventors shows that qualitative arguments must be supplemented by a quantitative analysis.

We have chosen a “golden mean”: a mathematical study of simplified models. Solutions obtained from simple models can serve as

guides for approximate solutions of more complicated models. The unification of hydrodynamics and electromagnetism not only creates new difficulties, but it also leads to new physical phenomena. Solutions to simple problems can serve as a bridgehead for penetrating into the inner core of physical processes.

We restrict ourselves to a relatively small number of relatively straightforward main topics, but we shall work them out in detail. We shall use detailed calculations and analytical means to study the assumptions made and the methods applied. There are only a few cases where we consider for the sake of completeness of exposition problems which need cumbersome solutions and in those cases we refer the reader to the relevant literature.

We have tried to make the book easy to read and understand for readers who are not MHD specialists. Unfortunately, we did not have space for examples to illustrate the theory and, especially, for applications. Our main focus is on the concepts of MHD and on the physical picture of MHD phenomena without cluttering them with details. On the other hand, we explain in some detail various theoretical difficulties.

The subject of this book touches upon a great many important disciplines—electrodynamics, hydrodynamics, plasma physics, thermodynamics, aerodynamics, astrophysics, rheology, as well as such applied disciplines as electrical engineering, chemical technology, thermonuclear fusion, and jet technology. This has meant that we have had to incorporate some elementary discussions of some basic topics. Specialists in those subjects may find these discussions superfluous, but we found them necessary for specialists in other fields and for students.

Our book is mainly theoretical in character, but because it is short and simple, we feel that it comprises a “theoretical minimum” in MHD for experimental physicists and research engineers. We hope that the book will be used by lecturers and students of technical institutes and universities. It may also be useful for mathematicians who are interested in applications and—because of its extensive subject index—as a reference book.

A characteristic feature of the book is the width of the scope of methods and results of modern MHD and the exposition of its main ideas. In that respect it differs from many textbooks and sur-

vey articles which are devoted to particular applications. We may mention as such the books by Jeffrey and Taniuti,¹¹⁹† Anderson,¹²⁸ Bateman,⁷³ and Moffatt,¹² or the papers by Freidberg,⁴⁸ Liberman and Velikovich,¹²⁹ and Sagdeev.¹²⁵ The books by Pai,¹⁶² Sutton and Sherman,²³ and Shercliff¹⁶³ give a wide coverage, but are now out-of-date as they do not cover recent developments, such as nonlinear waves, stability of equilibrium configurations, magnetoaerodynamics, and nonclassical MHD, which includes non-Newtonian fluids, magnetoelasticity, magnetoplasticity, ferrohydrodynamics, or electrohydrodynamics. The same is, of course, true of the pioneering books by Alfvén and Fälthammer³ and by Kulikovskii and Lyubimov.⁹

The closest to the present book is the relevant chapter in Landau and Lifshitz's "Electrodynamics of Continuous Media," but because it is only one chapter many topics are of necessity not covered there. In particular, we may mention nonlinear waves, stability problems, shock wave structure, energy release or absorption, magnetoaerodynamics, and nonclassical MHD.

We are grateful to A. I. Akhiezer, A. S. Bakai, E. M. Lifshitz, and V. V. Yanovskii for useful discussions of a number of problems arising in the writing of the book.

R. V. Polovin
V. P. Demutskii

† The numbers refer to the reference section at the end of the book.

CONTENTS

Part I. Electrically Conducting Viscous Fluids

Chapter 1. Basic equations	3
1.1. Magnetohydrodynamic approximations	3
1.2. Magnetohydrodynamical effects	7
1.3. Conservation laws	10
1.4. Ideal magnetohydrodynamics	18
1.5. Isotropic transport processes	25
1.6. Anisotropic transport processes	32
1.7. Estimates of kinetic coefficients	37
1.8. Nonideal magnetohydrodynamics	46
Chapter 2. Magnetohydrodynamic waves	55
2.1. Magnetohydrodynamic wave equations	55
2.2. Linear waves	57
2.3. Continuous spectrum	65
2.4. Instability of magnetohydrodynamic waves	67
2.5. Weak discontinuities	75
2.6. Self-similar waves	81
Chapter 3. Magnetohydrostatics	89
3.1. Equilibrium configurations	89
3.2. Axially symmetric configurations	93
3.3. Closed magnetic traps	98
3.4. Plasma diffusion	101

Chapter 4. Stability of equilibrium configurations	105
4.1. Lyapunov stability of a continuous configuration	105
4.2. Eigenfunction method	112
4.3. Energy principle	116
4.4. Stochastic instability	124
Chapter 5. Shock waves and discontinuities	131
5.1. Boundary conditions on a discontinuity surface	131
5.2. Classification of strong discontinuities	134
5.3. Lyapunov stability of discontinuities	139
5.4. Evolutionarity of discontinuities	142
5.5. Jumps in MHD quantities in discontinuity waves	148
5.6. Parallel shock waves	151
5.7. Switch-on and switch-off shock waves	154
5.8. Wave sequence	157
5.9. The piston problem	158
5.10. Splitting-up of a discontinuity	162
5.11. Discontinuities with energy release or absorption	165
5.12. Discontinuity structure	173
5.13. Structure of a perpendicular shock wave	179
5.14. Isomagnetic jump	185
5.15. Ionizing wave in a nonconducting medium with a magnetic field	187
Chapter 6. Stationary flow	197
6.1. Boundary conditions at a solid wall surface	197
6.2. Hartmann flow	200
6.3. Ideal magnetoaerodynamics	206
6.4. Non-ideal magnetoaerodynamics	213
Chapter 7. Turbulence	217
7.1. The turbulent state	217
7.2. Anomalous resistivity	224
7.3. Weak turbulence	229
7.4. Strong turbulence	232
7.5. Turbulence spectrum	237

Chapter 8. Hydromagnetic dynamos	241
8.1. Laminar dynamos	241
8.2. Turbulent dynamos	245

Part II. More Complicated Models of Continuous Media

Chapter 9. Non-Newtonian Media	253
9.1. Magnetoelasticity	253
9.2. Delayed relaxation	255
9.3. Quasilinear viscosity	262
9.4. Magnetoplasticity	268
9.5. Nonlinear viscosity	274
9.6. Fluids with a memory	279
Chapter 10. Other models of continuous media	287
10.1. Two-fluid magnetohydrodynamics	287
10.2. Relativistic magnetohydrodynamics	297
10.3. Ferrohydrodynamics	303
10.4. Anisotropic pressure	309
10.5. Electrohydrodynamics	316
References	321
Index	333

PART I

**ELECTRICALLY CONDUCTING
VISCOUS FLUIDS**

CHAPTER 1

Basic Equations

1.1. *Magnetohydrodynamic Approximations*

When a conducting fluid or an ionized gas—a plasma—moves in a magnetic field an electric field is produced and an electric current appears. In turn, the interaction of the current with the magnetic field changes the motion of the fluid and changes the magnetic field.

Magnetohydrodynamics is that part of the mechanics of continuous media which studies the motion of electrically conducting media in the presence of a magnetic field.⁶³ In other words, magnetohydrodynamics studies the physics of fluid—or gaseous—conductors in a magnetic field. Apart from this definition, in which the subject of the studies is indicated, but not the *approximation* which is applied (magnetohydrodynamics in the **wider sense**), one understands by magnetohydrodynamics the *low-frequency limit* when one neglects not only kinetic effects, which occur due to the thermal spread of the particles, but also the difference in motion of the various components of the plasma—the electrons, various kinds of ions, and neutral

particles. In magnetohydrodynamics in the narrower sense—the MHD model—one considers the medium as a single fluid which in each point of space $\mathbf{r}(x, y, z)$ and at each time t has a well-defined density ρ , pressure p , and velocity \mathbf{v} . Apart from these purely hydrodynamic quantities, the state of the medium is characterized by the magnetic induction $\mathbf{B}(\mathbf{r}, t)$. We assume that the magnetic permittivity μ is equal to unity and we do not distinguish between the magnetic induction \mathbf{B} and the magnetic field strength \mathbf{H} .

We can use a hydrodynamic description if the frequency ω which is characteristic for the process we consider is appreciably smaller than the collision frequency ν of the separate particles: $\omega \ll \nu$. If we introduce a characteristic length L —size of the object—and a characteristic time τ —the time it takes ions with a thermal velocity v_{Ti} to traverse a length L ,

$$\tau \sim \frac{L}{v_{Ti}},$$

we have a characteristic frequency

$$\omega \sim \frac{1}{\tau} \sim \frac{v_{Ti}}{L},$$

and the condition $\omega \ll \nu$ takes the form $l \ll L$, where l is the mean free path.

Introducing the Knudsen number Kn ,

$$\text{Kn} = \frac{l}{L}, \quad (1.1)$$

we can say that the hydrodynamic description is valid for small Knudsen numbers, $\text{Kn} \ll 1$. In this case, each kind of particles α —electrons, ions, neutrals—is described by their own density ρ_α , pressure p_α , and velocity \mathbf{v}_α . This is *many-fluid magnetohydrodynamics*. In particular, a fully ionized plasma, consisting only of electrons and a single kind of ions, corresponds to *two-fluid magnetohydrodynamics*.

If the characteristic frequency ω is appreciably smaller than the frequency ν_{ei} for the exchange of energy between electrons and ions, the electron pressure p_e and the ion pressure p_i manage to become equal and the plasma is characterized by a single pressure p . Since

the electrons are much lighter than the ions, the mass density ρ and the velocity \mathbf{v} of the medium are then determined by the ions, and the current density \mathbf{j} by the electrons. Such a fluid, considered as a single entity, is called a *simple fluid*.

Magnetohydrodynamics in the narrower sense is thus the low-frequency limit of magnetohydrodynamics in the wider sense. The importance of the low-frequency limit is due to the fact that low frequencies correspond to long wavelengths. Therefore, large amounts of matter are involved in the low-frequency motions. As to high-frequency, that is, short-wavelength, processes, small-scale details of motion correspond to them, like ripples on the water surface. Moreover, the interference of different frequencies, that is, different wavelengths, contained in a wavepacket leads to damping of the short-wavelength components. This effect is well known from acoustics—far from an orchestra only the drum is heard. Therefore, over long time intervals and at large distances from the source the long-wavelength terms of the relevant quantities play the main role.

In what follows, we mean by magnetohydrodynamics magnetohydrodynamics in the narrower sense.

For slow motions of the medium the electrons are displaced in the direction in which the electrical potential increases in such a way that the gradient of this potential becomes zero. The electrical field \mathbf{E}' in the eigenframe,^{2†}

$$\mathbf{E}' = \mathbf{E} + \frac{1}{c} [\mathbf{v} \times \mathbf{B}], \quad (1.2)$$

is then equal to zero, that is,

$$\mathbf{E} = -\frac{1}{c} [\mathbf{v} \times \mathbf{B}] \quad (1.3)$$

(we assume that the plasma velocity is nonrelativistic, $v \ll c$, and we therefore neglect terms of order v^2/c^2).

† We neglect the effects of the polarization and magnetization of the medium; we thus put the electric induction¹ \mathbf{D} equal to the electric field strength \mathbf{E} and we put the magnetic induction \mathbf{B} equal to the magnetic field strength \mathbf{H} . In other words, we assume that the electric permittivity ϵ and the magnetic permeability μ are equal to unity.

It is clear from (1.3) that the electric field in nonrelativistic magnetohydrodynamics is appreciably smaller than the magnetic field:

$$E \sim \frac{v}{c} B. \quad (1.4)$$

The magnetic field therefore is independent of the frame of reference.

It is clear from (1.4) that the energy $B^2/8\pi$ of the magnetic field in nonrelativistic magnetohydrodynamics is much larger than the energy $E^2/8\pi$ of the electrical field and that we can neglect the latter.

The single-fluid hydrodynamic approximation describes a large class of phenomena in *nonionized gases* very well. In contrast, single-fluid *magnetohydrodynamics* describes the experimental data satisfactorily only on cosmic scales. In the case of a laboratory plasma single-fluid magnetohydrodynamics is a rather coarse approximation to reality. As far as conducting fluids—liquid metals, sea water—under terrestrial conditions are concerned, they are well described in the framework of a single-fluid model.

In magnetohydrodynamics there are unusual relations between the various electrical quantities. For instance, in *electrical engineering* the current is basically determined by the electric field—Ohm's law—and the magnetic field causes only minor corrections. On the other hand, in *magnetohydrodynamics* the current is determined mainly by the magnetic field.

Indeed, let us estimate the different terms in the Maxwell equation

$$\text{curl } \mathbf{B} = \frac{1}{c} \frac{\partial \mathbf{E}}{\partial t} + \frac{4\pi}{c} \mathbf{j}. \quad (1.5)$$

Using Eq.(1.4) we get

$$|\text{curl } \mathbf{B}| \sim \frac{B}{L}, \quad \frac{1}{c} \left| \frac{\partial \mathbf{E}}{\partial t} \right| \sim \frac{v}{c^2 \tau} B,$$

where L is a characteristic length and τ a characteristic time. Noting that the ratio L/τ is equal to a characteristic velocity V and that v is also of order V , we find that

$$\frac{1}{c} \left| \frac{\partial \mathbf{E}}{\partial t} \right| / |\text{curl } \mathbf{B}| \sim \frac{V^2}{c^2}.$$

Hence, in the nonrelativistic case, $V \ll c$, the displacement current on the right-hand side of Eq. (1.5) can be neglected. Equation (1.5) thus enables us to express the current density in terms of the magnetic induction:

$$\mathbf{j} = \frac{c}{4\pi} \operatorname{curl} \mathbf{B}. \quad (1.6)$$

If the characteristic velocity is of the order of or larger than the sound velocity, we must take the compressibility of the medium into account, that is, assume the density ρ to be variable. To emphasize this fact one sometimes uses instead of the term "magnetohydrodynamics" the term "magnetogasdynamics." Sometimes the terms *magnetohydrodynamical* and *magnetogasdynamical* replace the equivalent terms *hydromagnetic* and *gasmagnetic*. We shall call a magnetohydrodynamical medium a "fluid" or a "plasma" depending on the applications and the traditional nomenclature.

We note that the magnetohydrodynamics approximation of an incompressible fluid is sometimes used outside the limits of its applicability. This is connected with the fact that taking the compressibility into account considerably complicates the MHD effects whereas these effects show up more clearly in an incompressible fluid.

In thermonuclear studies the magnetohydrodynamical equations were at the end of the fifties used as a first approximation. Later the center of attention was shifted to the more exact, but more complex, kinetic theory. However, the kinetic description contains much more information. It is impossible to solve the set of kinetic equations, not even numerically in the case of a nontrivial geometry.

In the seventies interest shifted again to magnetohydrodynamics in connection with the transition in thermonuclear studies to denser plasmas and more complex methods of containment.

1.2. Magnetohydrodynamical Effects

A number of physical conclusions and technical applications follow from the equations of § 1.1. It is, first of all, clear from Eq. (1.3) that the motion of a conducting medium across a magnetic field produces a difference in electric potentials. This effect can be used to produce magnetohydrodynamical generators^{4,5} for electric energy in

which a direct transition from thermal to electric energy occurs. In order that a gas becomes electrically conducting, it is heated to some thousands of degrees, which produces ionization, that is, changes the gas into a plasma. The main advantage of MHD generators over thermal ones—such as gas turbines—consists in the fact that the plasma has a high temperature T and this leads to an increase in the maximum efficiency which is known to equal⁶

$$\eta_{\max} = 1 - \frac{T_0}{T},$$

where T_0 is the temperature of the surrounding medium and T the temperature of the working body. For increasing η_{\max} we need high temperatures T , which cannot be reached in gas turbines since at high temperatures their blades lose strength and break.

Other applications of Eq. (1.3) include magnetohydrodynamic flow meters⁷ and velocity gauges. The advantage of an MHD flow meter is its small inertia.

It also follows from (1.3) that a plasma placed in crossed electric and magnetic fields is set in motion. If, for instance, the electric field is along the y -axis and the magnetic field along the z -axis, there is a component of the velocity of the medium along the x -axis:

$$v_x = \frac{cE_y}{B_z}. \quad (1.7)$$

Such a motion, which is perpendicular to both the electric and the magnetic fields, is called *drift* and its velocity is called the *drift velocity*. This effect is used to produce magnetohydrodynamic engines for rockets.⁸ The plasma can in this case be given a velocity which is much larger than the sound velocity with which the gases are ejected from the nozzle of the usual rocket. The thrust developed per unit mass of fuel in a magnetohydrodynamic reactive engine is thus much larger than in a thermal engine.

The motion of an electrically conducting fluid in crossed electric and magnetic fields is also used to produce conduction type magnetohydrodynamic pumps, the motion of the fluid is accompanied by a conduction current of density j_y which is directed across the pipe and caused by the electrical field E_y . The advantage of MHD pumps