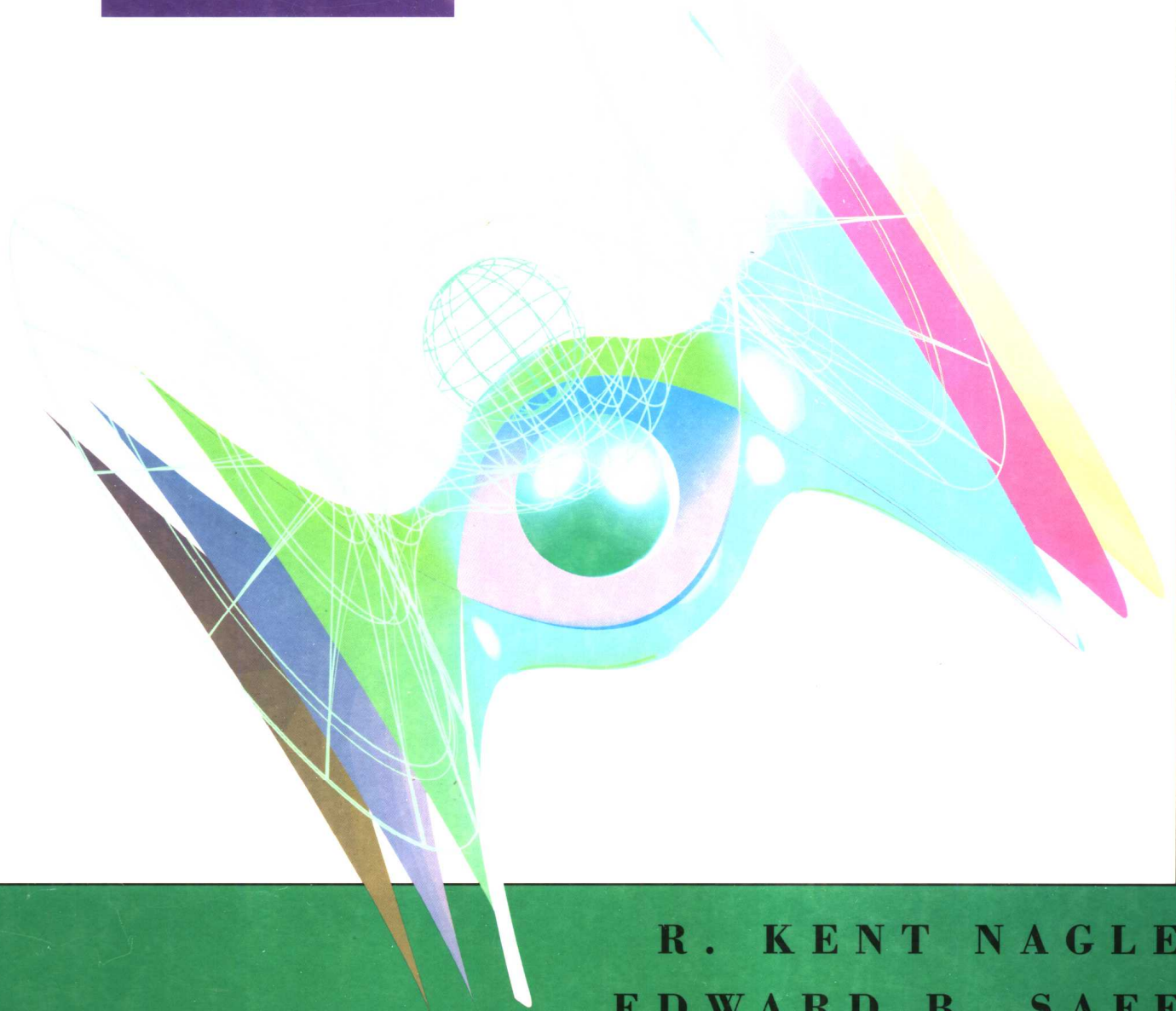


FUNDAMENTALS OF DIFFERENTIAL EQUATIONS

FOURTH
EDITION



R. KENT NAGLE
EDWARD B. SAFF

Fundamentals of Differential Equations

Fourth Edition

R. Kent Nagle & Edward B. Saff

UNIVERSITY OF SOUTH FLORIDA

with contributions by

A. D. Snider

UNIVERSITY OF SOUTH FLORIDA



Addison-Wesley Publishing Company

READING, MASSACHUSETTS	MENLO PARK, CALIFORNIA	NEW YORK		
DON MILLS, ONTARIO	WOKINGHAM, ENGLAND	AMSTERDAM	BONN	SYDNEY
SINGAPORE	TOKYO	MADRID	SAN JUAN	MILAN PARIS

Acquisitions Editor Laurie Rosatone
Senior Production Supervisor Karen Wernholm
Senior Marketing Manager Andrew Fisher
Prepress Buyer Caroline Fell
Art Buyer Joseph Vetere
Senior Manufacturing Manager Roy Logan
Editorial Production Services Barbara Pendergast
Art Editor Alena Konecny
Text Design Ron Kosciak, Dragonfly Design
Cover Design Diana C. Coe
Composition EPS Group, Beacon Graphics
Technical Illustration Academy Artworks

Library of Congress Cataloging-in-Publication Data

Nagle, R. Kent.

Fundamentals of differential equations.—4th ed.

/ R. Kent Nagle, Edward B. Saff ; with contributions by Arthur David Snider.

p. cm.

Includes bibliographical references and index.

ISBN 0-201-80875-7

I. Differential equations. I. Saff, E.B. II. Snider, Arthur David. III. Title.

QA371.N24 1996

95-9799

515'.35—dc20

CIP

Reprinted with corrections, February 1999

Copyright © 1996 by Addison-Wesley Publishing Company, Inc. All rights reserved. No part of this publication may be reproduced, stored in a retrieval system, or transmitted, in any form or by any means, electronic, mechanical, photocopying, recording, or otherwise, without the prior written permission of the publisher. Printed in the United States of America.

5 6 7 8 9 10-DOC-01 00 99

In Memoriam: R. Kent Nagle

He has left his imprint not only on these pages but upon all who knew him. He was that rare mathematician who could effectively communicate at all levels, imparting his love for the subject with the same ease to undergraduates, graduates, precollege students, public school teachers, and his colleagues at the University of South Florida.

Kent was at peace in life—a peace that emanated from the depth of his understanding of the human condition and the strength of his beliefs in the institutions of family, religion, and education. He was a research mathematician, an accomplished author, a Sunday school teacher, and a devoted husband and father.

Kent was also my dear friend and my jogging partner who has left me behind still struggling to keep pace with his high ideals.

E. B. Saff

Preface

OUR GOAL

Fundamentals of Differential Equations is designed to serve the needs of a one-semester course in basic theory as well as applications of differential equations. We have striven to create a flexible text that affords the instructor substantial latitude in designing a syllabus (we provide some sample syllabi later in this preface), in course emphasis (theory, applications and techniques, numerical methods), and in using commercially available computer software and/or the software utility programs specifically designed for this text.

IMPROVEMENTS IN THIS EDITION

In response to requests of users and reviewers, and recognizing recent developments in teaching and learning, we offer the following:

**Focus on
Analytical,
Graphical, and
Numerical
Methods**

Certainly these three aspects strengthen conceptual learning. Moreover, current trends in education increasingly reflect the ideology that all three are essential pedagogical ingredients that are best utilized in combination with one another. With this in mind, we have substantially augmented our discussions of theory and methods with many new graphical illustrations and have enhanced both graphical and numerical techniques by providing the reader with a software utility package that is keyed to the text. With these new features, students are free of the burden of computations and graphing and can focus more immediately on interpretative aspects. Also, more Group Projects have been included (see discussion below) since they provide the student with a vehicle for blending analytical, graphical, and numerical methods in the framework of a challenging joint problem-solving activity. At the same time, we have retained a substantial number of practice exercises that are essential for building basic skills.

**New Group
Projects**

Twenty percent of the group projects are new. As a result of a national search sponsored by Addison-Wesley, instructors contributed their own most successful classroom-tested group projects (see acknowledgments below). Group projects appear at the end of each chapter and

relate to the material covered in the chapter. They often involve a more challenging application, delve deeper into theory, or introduce more advanced topics. New projects include:

- Chapter 2 *Torricelli's Law of Fluid Flow*
 Equilibrium Points of Autonomous First Order Equations
- Chapter 3 *Aircraft Guidance in a Crosswind*
 Bang-Bang Controls
- Chapter 5 *Designing a Landing System for Interplanetary Travel*
 Things That Bob
 A Growth Model for Phytoplankton—Part I
- Chapter 9 *Undamped Second Order Systems*

- Revised Exercises** Twenty percent of the exercises are new, including computer implementation problems as well as exercises that require students to interpret solutions, building conceptual knowledge.
- New Figures** To help students visualize concepts, dozens of new illustrations have been added, including direction field plots (Section 1.3), graphs of power series solutions (Chapter 8), and three-dimensional plots of solutions to partial differential equations (Chapter 10).
- Software** New exploratory software that is pedagogically tied to the text is available. It is student friendly, functional, and easy to use. A complete description appears under “Supplements” later in this preface.
- World Wide Web** The new exploratory software is also available for downloading from the World Wide Web. Point your web browser to <http://hepg.awl.com>, keyword: Nagle-Saff.

CONTENT CHANGES

- **Direction Fields** Now a separate section, 1.3, that includes analytical examples and exercises dealing with population growth and motion of particles. Graphs illustrate the basic existence-uniqueness theorem.
- **Introduction to Systems of First Order Equations** The concept is introduced much earlier, in Section 4.10, following the basic theory and techniques for second order linear equations. The material is presented in a manner that does not require background in linear algebra.
- **Introduction to Phase Plane Analysis** This section, 5.7, is presented earlier. It introduces the study of trajectories of autonomous systems, critical points, and stability.

- **Introduction to Laplace Transforms: A Mixing Problem** This new section, 7.1, emphasizes advantages of the Laplace method in solving linear equations when the forcing function is discontinuous. It includes a schematic comparing the Laplace method with the standard method.
- **Chapter 2** The section on linear equations is now presented before exact equations.

PREREQUISITES

While some universities make linear algebra a prerequisite for differential equations, many schools (especially engineering) only require calculus. With this in mind, we have designed the text so that only Chapter 6 (Theory of Higher-Order Linear Differential Equations) and Chapter 9 (Matrix Methods for Linear Systems) require more than high school linear algebra. Moreover, Chapter 9 contains a review section on matrices and vectors as well as specific references for the deeper results used from the theory of linear algebra. We have also written Section 4.10 and Chapter 5 so as to give an introduction to systems of differential equations—including methods of solving, applications, numerical procedures, phase plane analysis, and Poincaré maps—that does not require a background in linear algebra.

SAMPLE SYLLABI

As a rough guide in designing a syllabus related to this text, we provide three sample syllabi that can be used for a 15-week course that meets three hours per week: the first emphasizes methods, computations, and applications; the second, theory and methods; and the third, methods and partial differential equations. Chapters 1, 2, and 4 provide the core for any course. The rest of the chapters are, for the most part, independent of each other.

	Methods, Computations, and Applications	Theory and Methods (linear algebra prerequisite)	Methods and Partial Differential Equations
<u>Week</u>	<u>Sections</u>	<u>Sections</u>	<u>Sections</u>
1	1.1, 1.2, 1.3	1.1, 1.2, 1.3	1.1, 1.2, 1.3
2	1.4, 2.2	2.2, 2.3	1.4, 2.2
3	2.3, 2.4	2.4, 4.2	2.3, 2.4
4	3.2, 3.4, 3.5	4.3, 4.4	3.2, 3.4
5	3.6, 4.2	4.5, 4.6, 4.7	4.2, 4.3
6	4.3, 4.5	4.8, 4.9	4.5, 4.6, 4.7
7	4.6, 4.7, 4.8	4.10, 6.1	4.8, 4.9

(continued)

<u>Week</u>	<u>Sections</u>	<u>Sections</u>	<u>Sections</u>
8	4.9, 4.10	6.2, 6.3	4.10, 5.7
9	5.1, 5.2, 5.3	7.2, 7.3	7.2, 7.3
10	5.4, 5.6, 5.7	7.4, 7.5	7.4, 7.5
11	7.2, 7.3	7.6, 8.2	7.6, 8.2
12	7.4, 7.5	8.3, 8.5, 8.6	8.3, 8.5, 8.6
13	7.6, 7.7	9.2, 9.3	10.2, 10.3
14	8.2, 8.3	9.4, 9.5	10.4, 10.5
15	8.5, 8.6	9.6, 9.7	10.6, 10.7

RETAINED FEATURES

Flexible Organization Most of the material is modular in nature to allow for various course configurations and emphasis (theory, applications and techniques, and concepts).


Optional Use of Computer Software The availability of computer packages such as MATHEMATICA®, DERIVE®, and MAPLE® provides an opportunity for the student to conduct numerical experiments and tackle realistic applications that give additional insights into the subject. Consequently, we have added several exercises and projects throughout the text that are designed for the student to employ available software in phase plane analysis, eigenvalue computations, and the numerical solutions of various equations.

Choice of Applications Because of syllabus constraints, some courses will have little or no time for sections (such as those in Chapters 3 and 5) that exclusively deal with applications. Therefore, we have made the sections in these chapters almost completely independent of each other. To afford the instructor even greater flexibility, we have built in a variety of applications in the exercises for the theoretical sections. In addition, we have included many projects that deal with such applications.

Technical Writing Exercises Communication skills are, of course, an essential aspect of professional activities. Yet few texts provide opportunities for the reader to develop these skills. Thus we have added at the end of most chapters a set of clearly marked technical writing exercises which invite students to make documented responses to questions dealing with the concepts in the chapter. In so doing, students are encouraged to make comparisons between various methods and to present examples that support their analysis.

Historical Footnotes Throughout the text historical footnotes are set off by colored daggers (†). These footnotes typically provide the name of the person who developed the technique, the date, and the context of the original research.

Motivating Problem Most chapters begin with a discussion of a problem from physics or engineering that motivates the topic presented and illustrates the methodology.

- Chapter Summary and Review Problems** All of the main chapters contain a set of review problems along with a synopsis of the major concepts presented.
- Computer Graphics** Most of the figures in the text were generated on a microcomputer. Computer graphics not only ensure greater accuracy in the illustrations, they demonstrate the use of numerical experimentation in studying the behavior of solutions.
- Proofs** While more pragmatic students may balk at proofs, most instructors regard these justifications as an essential ingredient in a textbook on differential equations. As with any text at this level, certain details in the proofs must be omitted. When this occurs, we flag the instance and refer readers either to a problem in the exercises or to another text. For convenience, the end of a proof is marked by the symbol ■ End.
- Linear Theory** We have developed the theory of linear differential equations in a gradual manner. In Chapter 4 (Linear Second Order Equations) we present the basic theory for linear second order equations and discuss various techniques for solving these equations. Higher-order equations are briefly mentioned in this chapter. A more detailed discussion of linear higher-order differential equations is given in Chapter 6 (Theory of Higher-Order Linear Differential Equations). For a beginning course emphasizing methods of solution, the presentation in Chapter 4 is sufficient and Chapter 6 can be skipped.
- Numerical Algorithms** Several numerical methods for approximating solutions to differential equations are presented along with program outlines that are easily implemented on a microcomputer. These methods are introduced early in the text so that teachers and/or students can use them for numerical experimentation and for tackling complicated applications. All algorithms discussed in the text are implemented on the software package available with this text.
- Exercises** An abundance of exercises is graduated in difficulty from straightforward, routine problems to more challenging ones. Deeper theoretical questions, along with applications, usually occur toward the end of the exercise sets. Throughout the text we have included problems and projects that require the use of a microcomputer. These exercises are denoted by the symbol . The software specifically designed for use with this text greatly facilitates the solutions to these numerical problems.
- Optional Sections** These sections can be omitted without affecting the logical development of the material. They are marked with an asterisk in the table of contents. As mentioned earlier, the sections in Chapters 3 and 5 are almost completely independent of each other.
- Laplace Transforms** We provide a detailed chapter on Laplace transforms since this is a recurring topic for engineers. Our treatment emphasizes discontinuous forcing terms and includes a section on the Dirac delta function.

Power Series Power series solutions is a topic that occasionally causes student anxiety. Possibly, this is due to inadequate preparation in calculus where the more subtle subject of convergent series is (not infrequently) covered at a rapid pace. Our solution has been to provide a thorough treatment of power series solutions that also includes a review of their properties as well as a discussion of real analytic functions. Unlike many texts, this one provides an extensive section on the *method of Frobenius* (Section 8.6) and two sections on the various methods for finding a second linearly independent solution.

While we have given considerable space to power series solutions, we have also taken great care to accommodate the instructor who only wishes to give a basic introduction to the topic. *An introduction to solving differential equations using power series and the method of Frobenius can be accomplished by covering the materials in Section 8.2, Section 8.3, and Section 8.6.*

Partial Differential Equations An introduction to this subject is provided in Chapter 10, which covers the method of separation of variables, Fourier series, the heat equation, the wave equation, and Laplace's equation. Examples in two and three dimensions are included.

SUPPLEMENTS

Student Solutions Manual By Anne Kusmierczyk and E. B. Saff. Containing complete, worked-out solutions to selected exercises, this provides students with an excellent study tool. ISBN 0-201-80877-3

Instructor's Resource Guide Contains short answers to all exercises and additional group projects. ISBN 0-201-80876-5

Software Available free to adopters, this DOS-based software is student-friendly, requiring little learning time. It is designed not only to aid the student in solving numerical problems in the text, but also as a convenient utility to encourage students to experiment. The software includes direction field plots, improved Euler's method, Runge-Kutta methods (also for systems), phase plane diagrams, eigenvalues and eigenvectors, computational methods such as Newton's method for solving equations, Simpson's rule, plots and tabulation of one or several functions, and many other useful algorithms. ISBN 0-201-82688-7

World Wide Web The new exploratory software is also available for downloading from the World Wide Web. Point your web browser to <http://hepg.awl.com>, keyword: Nagle-Saff.

An expanded version of this text, entitled *Fundamentals of Differential Equations and Boundary Value Problems*, Second Edition (ISBN 0-201-80879-X), contains three additional chapters: Chapter 11, *Eigenvalue Problems and Sturm-Liouville Equations*; Chapter 12, *Stability of Autonomous Systems*; and Chapter 13, *Existence and Uniqueness Theory*.

ACKNOWLEDGMENTS

The staging of the original text involved considerable behind-the-scenes activity. We want to thank Frank Glaser (California State Polytechnic University, Pomona) for many of the historical footnotes. We are indebted to Herbert E. Rauch (Lockheed Research Laboratory) for help with Section 3.3 on heating and cooling of buildings, Project B in Chapter 3 on aquaculture, and other application problems. Our appreciation goes to George Fix and R. Kannan (University of Texas, Arlington) for their useful suggestions concerning Section 3.7. We give special thanks to Richard H. Elderkin (Pomona College), Jerrold Marsden (University of California, Berkeley), T. G. Proctor (Clemson University), and Philip W. Schaefer (University of Tennessee), who read and reread the manuscript for the original text, making numerous suggestions that greatly improved the book. We are also indebted to the many people who reviewed the manuscript for this new edition:

Dean Brown, YOUNGSTOWN STATE UNIVERSITY
Alfred Clark, Jr., UNIVERSITY OF ROCHESTER
Don Hartig, CALIFORNIA POLYTECHNIC STATE UNIVERSITY
D. J. Kaup, CLARKSON UNIVERSITY
Paul Kumpel, STATE UNIVERSITY OF NEW YORK AT STONY BROOK
Glenn Ledder, UNIVERSITY OF NEBRASKA—LINCOLN
Benedict Pollina, UNIVERSITY OF HARTFORD
Mark W. Winstead, UNIVERSITY OF CALIFORNIA—SAN DIEGO

In addition, we would like to offer our sincere thanks to all of the instructors who shared their own group projects with us for inclusion in this edition:

Oliver Bernard, STATION ZOOLOGIQUE DE VILLEFRANCHE-SUR-MER
Richard Bernatz, LUTHER COLLEGE
Randall K. Campbell-Wright, UNIVERSITY OF TAMPA
Alfred Clark, Jr., UNIVERSITY OF ROCHESTER
Leopoldo P. Franca, UNIVERSITY OF COLORADO—DENVER
Jean-Luc Gouzé, INRIA, SOPHIA-ANTIPOLIS
T. L. Pearson, ACADIA UNIVERSITY
David Stapleton, UNIVERSITY OF CENTRAL OKLAHOMA

The timely completion of this edition would not have been possible without the contributions and dedication of my colleague and collaborator, Dr. Dave Snider. He not only lent his mathematical expertise, his engineering perspective, and his lively writing style, but also provided the entire project with a reassuring calm during the difficult period surrounding the passing of Kent Nagle.

The newly developed software that accompanies this text was expertly developed by Emil Moskona and Spas Tashev of the Bulgarian Academy of Sciences. Their efforts not only enhance the usefulness of this text, but also provide a convenient utility for calculus/differential equations problem solving.

We are grateful for the encouragement we received from our students and staff here at the University of South Florida. Maria Carvalho, through her untiring efforts and devotion

to duty, somehow lent order to an otherwise chaotic existence during the creation of this edition.

Finally, we want to thank the staff at Addison-Wesley for their dedicated assistance in bringing this edition to fruition. Special kudos go to mathematics editor Laurie Rosatone for her help, encouragement, and sensitivity. The production phase was carefully guided by Karen Wernholm and Barbara Pendergast, who admirably put up with my frequent outbursts of anxiety.

E. B. SAFF

TAMPA, FLORIDA

Index

- Abel's formula, 532
- Abel's identity, 167, 173, 326, 329, 532
- Aging spring, 459, 511
- Aircraft guidance, 145
- Airy's equation, 510
- Algorithms
 - fourth order Runge-Kutta,
 - for first order equations, 132–133
 - for systems, 279–280, A-9
 - improved Euler, 123–124
- Alligators, population of, 99
- Allometric equation, 143
- Amplitude modulation, 260
- Analog simulation, 274
- Analytic coefficients, equations with, 453
- Analytic functions, 437
- Angular frequencies, 243, 263, 547
- Annihilator, 337
- Annihilator method, 202, 339
- Aquaculture, 143
- Archimedes' principle, 312
- Arms race, 216
- Asymptotic behavior of solutions
 - for first order linear equations, 81
 - for second order linear equations, 232
- Asymptotic stability, 418, 544
- Automatic pilot, 385
- Autonomous system, 84, 288
- Auxiliary equations, 175, 330, 460. *See also*
 - Characteristic equation and Indicial equation
 - with complex roots, 182, 332
 - for difference equations, 220
 - with distinct roots, 175, 330
 - with repeated roots, 176, 332
- Bang-bang controls, 149
- Beam
 - with concentrated load, 418
 - deflection of, under axial force, 345
 - transverse vibrations of, 349
- Beats, 260
- Bernoulli equations, 53, 73
- Bessel functions
 - of the first kind, 497, 652
 - modified, 643
 - spherical, 503
 - of the second kind, 497
- Bessel's equation, 206, 496, 505, 511, 643
- Bessel's inequality, 602
- Blasius equation, 287
- Bode plots, 427
- Boundary conditions, 159, 575
 - Dirichlet, 635, 638, 642
 - mixed, 635
 - Neumann, 635, 641
- Boundary value problems, 159, 577
- Buoyancy, 311
- Buckling columns, 486
- Buckling of a tower, 510
- Capacitance, 268
- Carbon dating, 106
- Casoratian, 219n
- Cauchy-Euler equations, 178, 459
 - higher-order, 335
 - second order, 178, 187, 459
 - systems, 543, 548
- Cauchy product, 434
- Cayley-Hamilton theorem, 559n
- Centered-difference approximation, 97, 656
- Chaos, 147, 304, 306
- Chaos machine, 309
- Characteristic equation, 534. *See also*
 - Auxiliary equations
- Characteristic polynomial, 534
- Chebyshev (Tchebichef) polynomials, 502, 504, 601
- Chemical diffusion, 621
- Chemical reactions, 137
- Clairaut equations, 83
- Classical orthogonal polynomials, 502
- Coffee problem, 106
- Combat law
 - linear, 77
 - parabolic, 78
- Combat model
 - conventional, 556
 - conventional versus guerrilla, 287
 - guerrilla, 77
 - mixed, 77
- Compartmental analysis, 88
- Competing species, 77, 287
 - strange behavior of, 316, 572
- Complete equation, 219
- Complex eigenvalues, 545
- Complex residues, 380
- Confluent hypergeometric equation, 503
- Convolution, 231, 402
- Cramer's rule, 343, A-5
- Critically damped motion, 248
- Critical point, 289, 292
- Curve of pursuit, 144
- d'Alembert's solution, 627
- Damped vibrations, 246, 253
- Damping constant, 242
- Deflection of beams, 345
- Delay differential equations, 92, 142
- Determinant, 520
- Difference equations, 217, 446
- Differential operator, 153, 188
 - with constant coefficients, 159
- Dirac delta function, 411
- Direction field, 16
- Dirichlet boundary conditions, 635
- Discontinuous coefficients, 53
- Discontinuous forcing terms, 54, 201, 352
- Dispersion relation, 634
- Dispersive waves, 634
- Drag race, 6
- Duffing equation, 285, 304, 442
- Duhamel's formulas, 426
- Dynamical system, 299
- Ecological systems, 77. *See also* Competing species and Predator-prey systems
- Eigenfunctions, 578
- Eigenspace, 535
- Eigenvalues, 533, 578
 - complex, 545
 - repeated, 541, 542, 559, 561
- Eigenvectors, 533
 - generalized, 560
 - linear independence of, 538
- Electric circuits, 267–275
- Electric network, 271, 275, 549, 556
- Electric units, 269
- Elimination method, 208
- Emden's equation, 429n, 452. *See also*
 - Lane-Emden equation

- Emphatic remark (joke!), 398
- Energy argument, 631
- Epidemic model, 298
- Equations, with linear coefficients, 74
- Equidimensional equations. *See* Cauchy-Euler equations
- Equilibrium solution, 84, 289
- Error
 - absolute, 124
 - local versus global, 127
 - relative, 124
- Escape velocity, 116
- Euler equations. *See* Cauchy-Euler equations
- Euler's formulas
 - for complex exponential, 183, 274
 - for Fourier coefficients, 591
- Euler's method, 25, 118, 146, 285
 - improved, 121, 146, 285
- Exact equations, 59
- Existence of solutions
 - analytic solutions, 453
 - for first order equations, 12
 - for heat equation, 619
 - for Laplace's equation, 644
 - for linear difference equations, 218
 - for linear differential equations, 322
 - for linear first order equations, 51, 54
 - for linear second order equations, 157
 - for linear systems, 525
 - for wave equation, 630
- Explicit solutions, 7
- Exponential of matrix, 557
- Exponential order, 360
- Exponents of a regular singular point, 465
- Factorial function, 494
- Feedback system, with pooling delay, 215
- Finite-difference method
 - for Laplace's equation, 655
- Fixed point, A-3
- Fluid flow, 69, 137, 285
 - around a corner, 647
- Forced vibrations, 202, 253
- Fourier series, 586, 591
 - complex form of, 601
 - convergence of, 597
 - cosine series, 605
 - differentiation of, 599
 - double, 618, 626
 - generalized, 595
 - half-range expansions, 605
 - integration of, 600
 - sine series, 605
 - uniform convergence of, 598
- Free fall, 1, 35, 46, 109
- Free motion, 242, 246
- Frequency gain, 255
- Frequency response curve, 256, 427n
- Frequency response modeling, 426
- Friction, coefficient of, 115
- Frobenius, method of, 469
- Fundamental matrix, 528, 558, 560
- Fundamental solution set
 - for difference equations, 219
 - for equations, 162, 324
 - for system, 528
- Gamma function, 398, 495
- Gaussian hypergeometric function, 495
- General solution
 - for difference equation, 219
 - for first order linear equation, 36, 48
 - for higher-order linear equation, 324, 327
 - for linear systems, 211, 528, 530
 - for second order linear equation, 161, 190
- Generating functions
 - for Hermite polynomials, 504
 - for Legendre polynomials, 502
- Geometric series, 434
- Gibb's phenomenon, 602
- Gompertz equation, 99
- Great Lakes, model for, 317
- Green's function, 653
- Green's second formula, 646
- Harmonic function, 645
- Harmonic motion, 152, 243
- Heat equation, 575, 577, 609
- Heat flow model, 573, 609
- Heating and cooling of buildings
 - with one zone, 100
 - with two zones, 216
- Heaviside's expansion formula, 380
- Hermite polynomials, 502, 504
- Hermite's equation, 173
- Higher-order equations, 321. *See also* Linear equations
 - conversion to normal form, 208
 - numerical methods for, 275, A-9
- Homogeneous equations
 - difference equation, 218
 - first order, 70
 - higher order, 322, 329
 - second order, 153, 159, 174
 - systems of linear, 525, 528, 533
- Hooke's law, 240, 261
- Hypergeometric equations, 493
- Impedance, 239
- Implicit function theorem, 8, 15
- Implicit solution, 8
- Improved Euler's method, 121, 146, 285
- Impulse, 412
- Impulse response function, 407, 416, 426
- Indicial admittance, 425
- Indicial equation. *See also* Auxiliary equations
 - for a Cauchy-Euler equation, 460
 - for regular singular point, 465
- Inductance, 268
- Initial-boundary value problem, 575
- Initial value problem. *See also* Existence of solutions
 - available codes for, 137
 - for first order equations, 37
 - for higher-order equations, 10
 - Laplace transforms in solving, 380
 - for systems, 208, 525
- Inner product, 524, 601
- Integral curve, 77, 291
- Integral equation, 32, 406
- Integrating factor, 47, 65
- Integro-differential equation, 406
- Interval of definition problem, 45
- Inverse Laplace transform, 371
- Irregular singular point, 463
- Isocline, 21
- Jump discontinuity, 359, 586
- Kirchhoff's laws, 3, 268
- Korteweg-de Vries equation (KdV), 634
- Laguerre polynomials, 487, 504
- Laguerre's equation, 173, 487
- Landing system, 311
- Lane-Emden equation, 429n, 452. *See also* Emden's equation
- Laplace's equation, 576, 635, 641
- Laplace transforms, 351
 - for constant coefficient equations, 380
 - for constant coefficient systems, 419
 - definition of, 355
 - of the Dirac delta function, 413
 - existence of, 361
 - of the Heaviside step function, 388
 - for integro-differential equations, 406
 - inverse of, 371
 - for matrices, 570
 - of a periodic function, 396
 - properties of, 368, inside back cover
 - table of, 362, inside back cover
 - of the unit gate function, 402
 - for variable coefficient equations, 384
 - for wave equation, 653
- Laplacian, 576
- Least-squares linear fit, 97, A-6
- Least squares approximation, 602
- Legendre polynomials, 459, 500, 601
- Legendre's equation, 173, 459, 500
- Limit cycles, 315
- Limiting (terminal) velocity, 37, 111
- Linear dependence (independence)
 - of constant vectors, 163, 521
 - of functions, 163, 325
 - of vector functions, 526
- Linear difference equations, 217
- Linear differential operators, 154, 188, 210
- Linear equations, 5
 - Cauchy-Euler equations, 178, 187, 335, 459, 543, 548
 - constant coefficients, 153, 174, 329
 - first order, 46
 - higher-order, 321
 - homogeneous, 153, 159, 174, 329
 - nonhomogeneous, 153, 188, 327
 - power series solutions, 442
 - second order, 153
 - undetermined coefficients, 193, 198, 336
 - variable coefficients, 152, 178, 202, 342
 - variation of parameters, 202, 342
- Linear independence. *See* linear dependence
- Linearization of nonlinear problems, 232
- Linearized Korteweg-de Vries (KdV) equation, 634
- Linear systems
 - applications of, 260, 267
 - Cauchy-Euler, 543, 548
 - elimination method for, 208, 261
 - fundamental matrix, 528
 - general solution, 211, 528, 530
 - homogeneous, 525, 528, 533
 - Laplace transform, 419
 - matrix methods, 513
 - nonhomogeneous, 525, 549
 - in normal form, 207, 513
 - uncoupled, 569
 - undetermined coefficients, 549
 - variation of parameters, 551

Contents

Chapter 1	INTRODUCTION	1
	1.1 Background	1
	1.2 Solutions and Initial Value Problems	6
	1.3 Direction Fields	16
	*1.4 The Approximation Method of Euler	24
	Chapter Summary	30
	Technical Writing Exercises	30
	Group Projects for Chapter 1	31
	<i>A. Taylor Series Method</i>	31
	<i>B. Picard's Method</i>	32
	<i>C. Magnetic "Dipole"</i>	33
 Chapter 2	 FIRST ORDER DIFFERENTIAL EQUATIONS	 35
	2.1 Introduction: Motion of a Falling Body	35
	2.2 Separable Equations	38
	2.3 Linear Equations	46
	2.4 Exact Equations	55
	*2.5 Special Integrating Factors	65
	*2.6 Substitutions and Transformations	69
	Chapter Summary	78
	Review Problems	79
	Technical Writing Exercises	80
	Group Projects for Chapter 2	81

*Denotes optional sections that can be omitted without compromising the logical flow.

<i>A. The Snowplow Problem</i>	81
<i>B. Asymptotic Behavior of Solutions to Linear Equations</i>	81
<i>C. Torricelli's Law of Fluid Flow</i>	82
<i>D. Clairaut Equations and Singular Solutions</i>	83
<i>E. Equilibrium Points of Autonomous First Order Equations</i>	84

Chapter 3 **MATHEMATICAL MODELS AND NUMERICAL METHODS INVOLVING FIRST ORDER EQUATIONS** 86

3.1 Mathematical Modeling	86
3.2 Compartmental Analysis	88
3.3 Heating and Cooling of Buildings	100
3.4 Newtonian Mechanics	108
3.5 Improved Euler's Method	117
3.6 Higher-Order Numerical Methods: Taylor and Runge-Kutta	128
3.7 Some Available Codes for Initial Value Problems	137
Group Projects for Chapter 3	142
<i>A. Delay Differential Equations</i>	142
<i>B. Aquaculture</i>	143
<i>C. Curve of Pursuit</i>	144
<i>D. Aircraft Guidance in a Crosswind</i>	145
<i>E. Stability of Numerical Methods</i>	146
<i>F. Period Doubling and Chaos</i>	147
<i>G. Bang-Bang Controls</i>	149

Chapter 4 **LINEAR SECOND ORDER EQUATIONS** 150

4.1 Introduction: The Simple Pendulum	150
4.2 Linear Differential Operators	153
4.3 Fundamental Solutions of Homogeneous Equations	159
*4.4 Reduction of Order	169
4.5 Homogeneous Linear Equations with Constant Coefficients	174
4.6 Auxiliary Equations with Complex Roots	182
4.7 Superposition and Nonhomogeneous Equations	188
4.8 Method of Undetermined Coefficients	193

4.9	Variation of Parameters	202
4.10	Introduction to Systems of First Order Equations	207
*4.11	Linear Difference Equations	217
	Chapter Summary	225
	Review Problems	229
	Technical Writing Exercises	230
	Group Projects for Chapter 4	231
	<i>A. Convolution Method</i>	231
	<i>B. Asymptotic Behavior of Solutions</i>	232
	<i>C. Linearization of Nonlinear Problems</i>	232
	<i>D. Nonlinear Equations Solvable by First Order Techniques</i>	233
	<i>E. Simple Pendulum</i>	235
	<i>F. Phase Plane Diagrams and Periodic Solutions</i>	236
	<i>G. Critical Damping of a Vibrating Spring</i>	237
	<i>H. Undetermined Coefficients Using Complex Arithmetic</i>	238

Chapter 5

APPLICATIONS AND NUMERICAL METHODS FOR SECOND ORDER EQUATIONS AND SYSTEMS

		240
5.1	Mechanical Vibrations and Simple Harmonic Motion	240
5.2	Damped Free Vibrations	246
5.3	Forced Vibrations	253
5.4	Coupled Spring-Mass Systems	260
5.5	Electric Circuits	267
5.6	Numerical Methods for Higher-Order Equations and Systems	275
5.7	Introduction to Phase Plane Analysis	287
5.8	Dynamical Systems, Poincaré Maps, and Chaos	299
	Chapter Summary	309
	Group Projects for Chapter 5	311
	<i>A. Designing a Landing System for Interplanetary Travel</i>	311
	<i>B. Things That Bob</i>	312
	<i>C. Effects of Hunting on Predator-Prey Systems</i>	313
	<i>D. Periodic Solutions to Volterra-Lotka Systems</i>	314
	<i>E. Limit Cycles and the van der Pol Equation</i>	315
	<i>F. Strange Behavior of Competing Species—Part I</i>	316