

Proceedings



**Institute of  
Acoustics**

**ACOUSTICS '89**

**1989 Spring Conference**

Outdoor Sound Propagation

Aircraft Noise

Environmental Noise

**Vol. 11, Part 5 pp189 - 436 (1989)**

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# CONTENTS

## 1989 R W B STEPHENS LECTURE

Review of Outdoor Sound Propagation - the Sound Field, Micrometeorology and Topography 1

*T F W Embleton*

*National Research Council, Canada*

## Warning Signals and Behavioural Response

Guidelines for the design of auditory warning sounds 17

*R D Patterson*

*University of Cambridge*

The effects of warning format and keyboard layout on reaction times to auditory warnings 25

*S H James & M R James*

*Royal Aerospace Establishment*

Sound levels for the British Rail inductive loop warning system 43

*M C Lower (1), R D Patterson (2), P Cosgrove (2) & R Milroy (2)*

*(1) University of Southampton*

*(2) University of Cambridge*

Auditory warnings for the British Rail inductive loop warning system 51

*R D Paterson (1), P Cosgrove (1), R Milroy (1) & M C Lower (2)*

*(1) University of Cambridge*

*(2) University of Southampton*

Auditory warnings for fixed and rotary wing aircraft 59

*G M Rood*

*Royal Aerospace Establishment*

The perceived urgency of auditory warnings 73

*J Edworthy, S Loxley, E Greenhead & J Dennis*

*Polytechnic South West*

The specification of a toxic gas warning system for a large chemical plant complex 81

*G Taylor, A Giles & B D Claybrook*

*ICI plc*

Auditory icons 91

*W W Gaver*

*Rank Xerox Ltd*

## **Vibration and Human Response**

- Groundborne vibration generated by HGVs - effects of vehicle, road and ground parameters 99  
*G R Watts*  
*Transport and Road Research Laboratory*
- The wayside vibration from trains 111  
*T M Dawn*  
*British Railways Board*
- Ground vibration and its effects on building habitability 121  
*R Randell*  
*University of Southampton*
- Comparative annoyance from railway noise and building vibration 129  
*H J Woodroof*  
*University of Southampton*
- Improved operator performance from reduced vibration 135  
*J A Lines & R M Stayner*  
*A F R C Engineering*
- Active engine mounts for improving vehicle comfort 143  
*C F Ross, G P Eatwell, A J Langley & C M Dorling*  
*Topexpress Ltd*
- Effects of low frequency whole-body sinusoidal vibration on speech 151  
*M R Taylor*  
*Smiths Industries*
- Vibration dose values - notes for consultants 159  
*A W James*  
*Sound Research Laboratories Ltd*
- Measurement and analysis techniques for the evaluation of human exposure to vibration 167  
*C M Nelson*  
*ISVR, University of Southampton*
- Survey of exposure to hand-arm vibration in Great Britain 175  
*K Kyriakides*  
*Health and Safety Executive*

## **Outdoor Sound Propagation**

- Acoustic scattering by sub-surface inhomogeneities 189  
*D L Berry (1), S N Chandler-Wilde (2) & K Attenborough (1)*  
*(1) The Open University*  
*(2) Coventry Polytechnic*

Long distance sound propagation over grounds <i>J N B Harriott (1), S N Chandler-Wilde (2) &amp; D C Hothersall (1)</i> <i>(1) Bradford University</i> <i>(2) Coventry Polytechnic</i>	197
Numerical modelling of noise propagation over barriers <i>D C Hothersall (1), S N Chandler-Wilde (2) &amp; N M Hajmirzae (1)</i> <i>(1) Bradford University</i> <i>(2) Coventry Polytechnic</i>	207
Interface waves at air/air-filled poroelastic media boundaries <i>Y Chen &amp; K Attenborough</i> <i>The Open University</i>	215
An acoustic propagation model allowing a multiply layered poro-elastic ground surface <i>S Tooms &amp; K Attenborough</i> <i>The Open University</i>	223
Analysis of spherical-wave propagation over absorbing ground <i>F P Mechel</i> <i>Fraunhofer Institut für Bauphysik</i>	231
Calculation of sound propagation from a point source over an impedance boundary <i>C Howorth, K Attenborough &amp; N W Heap</i> <i>The Open University</i>	257
The ground wave in outdoor sound propagation <i>J Wempen</i> <i>University of Oldenburg</i>	265
Ground characterisation from short range propagation measurements <i>H M Hess, K Attenborough &amp; N W Heap</i> <i>The Open University</i>	273
The prediction of sound due to a panel radiating over an impedance plane <i>K M Li, K Attenborough &amp; N W Heap</i> <i>The Open University</i>	281
Reverberation and attenuation by trees: measured and modelled <i>W H T Huisman</i> <i>University of Nijmegen</i>	289
Creeping wave theory applied to impulse propagation in the atmosphere <i>C G Don &amp; A J Cramond</i> <i>Chisholm Institute of Technology</i>	297

Propagation of sound from a point source into the acoustic shadow produced by wind speed and temperature gradients close to the ground <i>M West, F Walkden &amp; R A Sack</i> <i>University of Salford</i>	305
Measurement of acoustic propagation through the atmosphere <i>P J Soilleux</i> <i>Royal Signals Research Establishment</i>	311
The prediction of noise from construction sites <i>R Wentang &amp; K Attenborough</i> <i>The Open University</i>	323

### **Aircraft Noise**

A study of annoyance due to general and business aviation noise <i>J B Ollerhead (1), I D Diamond (2), J G Walker (2), J B Critchley (3) &amp; S A Bradshaw (2)</i> <i>(1) Loughborough University</i> <i>(2) University of Southampton</i> <i>(3) Civil Aviation Authority</i>	331
Practical measurement of ground noise and its implications on prediction techniques <i>P Henson &amp; J G Charles</i> <i>Bickerdike Allen Partners</i>	339
Insulation of mobile homes subjected to military aircraft noise <i>D M Bexon (1), S M Dryden (2), P Moore (2) &amp; R J Weston (1)</i> <i>(1) RAF ICOM</i> <i>(2) WS Atkins Engineering Sciences</i>	347
Experience in the measurement of noise from military aircraft <i>W Stubbs &amp; R B Gillham</i> <i>Wimpey Laboratories Ltd</i>	361
In-flight measurement of boundary layer noise and its vibration effects <i>D Sims</i> <i>British Aerospace (Dynamics) Ltd</i>	369

### **Environmental Noise**

Neighbourhood noise disturbance <i>W A Utley &amp; E C Keighley</i> <i>Building Research Establishment</i>	377
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The suitability of A-weighted sound power for labelling domestic appliances <i>J R Brookes &amp; K Attenborough</i> <i>The Open University</i>	385
Some applications for the single number rating of hearing protectors <i>R J Weston</i> <i>RAF ICOM</i>	391
The Noise Council survey of clay pigeon shooting noise <i>H G Leventhall</i> <i>Commins-BBM Partnership</i>	397
Progressing motorcycle noise control - a Noise Council perspective <i>A J Gilbert (1) &amp; J D Clegg (2)</i> <i>(1) Warrington Borough Council</i> <i>(2) Bolton Metropolitan Borough Council</i>	405
Industrial claddings: Sound absorption and transmission <i>N J H Alexander, D E O'Connor &amp; R J Orlowski</i> <i>University of Salford</i>	409
Prediction of community response to noise from urban light rail systems <i>B M Shield, D W Birden, J P Roberts &amp; M L Vuillermoz</i> <i>Southbank Polytechnic</i>	419
Environmental noise aspects of a gas turbine power generating plant <i>B C Postlethwaite</i> <i>Acoustic Technology Ltd</i>	429

### **Physical Acoustics and Ultrasonics**

Deconvolution by the maximum entropy method as applied to ultrasonic surface characterisation <i>P F Smith &amp; M A Player</i> <i>University of Aberdeen</i>	437
Acoustic nonlinearity parameters and higher-order elastic constants of crystals <i>J H Cantrell</i> <i>University of Cambridge</i>	445
Piezoelectric detection of signals in scanning electron acoustic microscopy <i>M Qian, J H Cantrell &amp; F J Rocca</i> <i>University of Cambridge</i>	453



The pulse enhancement of unstable cavitation by the mechanisms of bubble migration T G Leighton (1), M J W Pickworth (2), A J Walton (1) & P P Dendy (2) (1) <i>University of Cambridge</i> (2) <i>Addenbrookes Hospital</i>	461
Reflection from media with continuous variation of density, sound speed and attenuation R C Chivers <i>University of Surrey</i>	471
Ultrasonic absorption measurements in thin films of adhesive polymers R E Challis & T Alper <i>University of Keele</i>	477
A wide bandwidth ultrasonic absorption spectrometer for liquid materials R E Challis & A K Holmes <i>University of Keele</i>	487
<b>Instrumentation</b>	
Calibration at high power of pulsed acoustic transducers R A Hazelwood <i>Aconics Partners</i>	495
Measured transducer field distributions for improved measurement and imaging J R Blakey, R C Chivers & R A Bacon <i>University of Surrey</i>	503
Application of acoustic reciprocity principles F J Fahy <i>University of Southampton</i>	513
A two-microphone technique for measuring acoustic impedance in the free field: Effects of sample area and measurement errors D C Waddington & R J Orlowski <i>University of Salford</i>	521
<b>Student Session</b>	
The influence of airflow resistance on the acoustic absorption properties of polyurethane foams G Rodwell & C G Rogers <i>Sheffield City Polytechnic</i>	533
Air absorption in acoustic scale models and the substitution of nitrogen P Wright <i>University of Salford</i>	541

The effect of loading on the impact sound insulation of concrete floors with a floating raft on a resilient layer	543
<i>M A Stewart, D J Mackenzie &amp; D G Falconer</i>	
<i>Heriot-Watt University</i>	
Annoyance and impulsivity judgements of environmental noises	551
<i>C G Swift, I H Flindell &amp; C G Rice</i>	
<i>University of Southampton</i>	
Loudness of low frequency impulses	559
<i>C W Dilworth</i>	
<i>University of Salford</i>	
Analysis of the amplitude statistics of random signals	561
<i>A Shadbolt</i>	
<i>University of Salford</i>	
A hemispherical cap array for noise source location	567
<i>M H D Santer</i>	
<i>University of Southampton</i>	
An expert systems approach to understanding signals and systems	569
<i>A M Raper (1) &amp; J K Hammond (2)</i>	
<i>(1) Anderson Consulting</i>	
<i>(2) ISVR, Southampton University</i>	
<i>(1988 Simon Alport Prize Lecture)</i>	
SWCC for predicting the differences between shallow and deep water explosions	583
<i>N Hogwood</i>	
<i>University of Southampton</i>	
The effects of bubble curtains on underwater shockwave propagation	589
<i>S P Boyle</i>	
<i>University of Southampton</i>	
Auditory hazard to divers from underwater explosions	597
<i>C Herbert</i>	
<i>University of Southampton</i>	
The acoustic loading of enclosures on loudspeakers	599
<i>D R Philip</i>	
<i>University of Salford</i>	
The viewing of loudspeaker modes by laser speckle	607
<i>M Brooke</i>	
<i>University of Wales, Cardiff</i>	

## Open Session

Computerised auto-testing of sound level meters <i>C P Stollery</i> <i>Cirrus Research Ltd</i>	613
The effect of flanged joints on noise and vibrational transmission <i>R S Ming, G Stimpson &amp; N Lalor</i> <i>University of Southampton</i>	619
Transmission of noise through rubber-metal composite springs <i>A H Muhr</i> <i>Malaysian Rubber Producers Research Association</i>	627
The use of time-reversed decay measurements in speech studios <i>B Rasmussen (1) &amp; J H Rindel (2)</i> <i>(1) Bruel &amp; Kjaer, Denmark</i> <i>(2) Technical University of Denmark</i>	635
Sound generation in a duct with a bulk-reacting liner <i>A Cummings</i> <i>University of Hull</i>	643
A study of stick-slip for selected materials <i>G J McNulty (1), G R Symmons (1) &amp; Z Ming (2)</i> <i>(1) Sheffield City Polytechnic</i> <i>(2) Chengdu University, P R China</i>	651

## ACOUSTIC SCATTERING BY SUB-SURFACE INHOMOGENEITIES

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### INTRODUCTION

The application of the boundary integral equation (BIE) method to problems of acoustic scattering is widely known ([1] - [3]). The method has been used, in the context of outdoor sound propagation, to predict the propagation of acoustic waves over a plane of homogeneous impedance, perturbed by the introduction of a region of inhomogeneous impedance ([4], [5]), or by the introduction of a noise barrier [6]. Here, the BIE method is applied to the problem of the prediction of the acoustic field due to a point source in a homogeneous quiescent atmosphere, above a homogeneous rigid porous half-space containing a rigid inhomogeneity.

### THEORY

#### THE BOUNDARY VALUE PROBLEM

The geometry is shown in figure 1. An obstacle, labelled  $S$ , with smooth, rigid surface  $\partial S$  is embedded in a porous half-space, characterised by a complex impedance  $Z_2$  and a complex wavenumber  $k_2$ . The upper half-space, denoted  $U_+$ , contains air, and is assumed to be characterised by real impedance and wavenumber,  $Z_1$  and  $k_1$ , respectively. To define the other notation in figure 1,  $U_- := \mathbb{R}^3 \setminus (\overline{S} \cup U_+)$  denotes the porous medium, and  $\Gamma = \{(x, y, z) \in \mathbb{R}^3 | z = 0\}$  the boundary between the two half spaces. It is intended to determine the value of the complex acoustic pressure  $p(r, r_0)$ , at points  $r \in \mathbb{R}^3$  given a source point  $r_0 \in U_+$ , when the plane surface,  $\Gamma$ , is insonified by a monofrequency point source. The complex acoustic pressure is assumed to satisfy the following boundary value problem:

an inhomogeneous Helmholtz equation for  $r \in U_+$ ,

$$(\nabla^2 + k_1^2)p(r, r_0) = \delta(r - r_0); \quad (1)$$

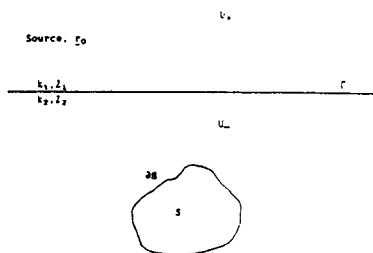


Figure 1: The physical situation

the Helmholtz equation for  $r \in U_-$ ,

$$(\nabla^2 + k_2^2)p(r, r_0) = 0; \quad (2)$$

the Neumann boundary condition for  $r \in \partial S$ , for a rigid scatterer,

$$\frac{\partial p(r, r_0)}{\partial n(r)} = 0; \quad (3)$$

continuity of complex acoustic pressure, for  $r \in \Gamma$ ,

$$p_+(r, r_0) = p_-(r, r_0); \quad (4)$$

continuity of normal velocity, for  $r \in \Gamma$ ,

$$\alpha \frac{\partial p_+(r, r_0)}{\partial z} = \frac{\partial p_-(r, r_0)}{\partial z}; \quad (5)$$

and Sommerfield's radiation conditions in  $U_+$  and  $U_-$ . In the above, a time dependence  $e^{-i\omega t}$  is assumed and suppressed;  $p(r, r_0)$  denotes the complex pressure at  $r = (x, y, z)$  due to a source at  $r_0 = (x_0, y_0, z_0)$ ; the subscripts  $+/-$  denote the limiting values of a function as  $\Gamma$  is approached from the  $U_+/U_-$  side;  $n(r)$  denotes the normal to the surface  $\partial S$  directed into  $S$  at point  $r$ ;  $\nabla^2 = \partial^2/\partial x^2 + \partial^2/\partial y^2 + \partial^2/\partial z^2$  denotes the Laplacian; and  $\alpha$  is defined by,  $\alpha = (Z_2 k_2)/(Z_1 k_1)$ .

#### REFORMULATION AS AN INTEGRAL EQUATION

To formulate the integral equation, the solution to the following simpler problem is required. Let the Green's function  $G(r, r_0)$ , satisfy the following boundary value problem, for each  $r_0 \in \mathbb{R}^3 \setminus \Gamma$ : an inhomogeneous Helmholtz equation for  $r \in U_+$ ,

$$(\nabla^2 + k_1^2)G(r, r_0) = \delta(r - r_0); \quad (6)$$

an inhomogeneous Helmholtz equation for  $r \in U_-$ ,

$$(\nabla^2 + k_2^2)G(r, r_0) = \alpha \delta(r - r_0); \quad (7)$$

jump conditions for  $r \in \Gamma$ ,

$$G_+(r, r_0) = G_-(r, r_0); \quad (8)$$

and

$$\alpha \frac{\partial G_+(r, r_0)}{\partial z} = \frac{\partial G_-(r, r_0)}{\partial z}; \quad (9)$$

and Sommerfield's radiation conditions in  $U_+$  and  $U_-$ . Note that in the case when no obstacle is present,

$$p(r, r_0) = G(r, r_0), \quad (10)$$

for  $r \in \mathbb{R}^3$  and  $r_0 \in U_+$ ; but  $G(r, r_0)$  is defined also when  $r_0 \in U_-$ . In physical terms,  $G(r, r_0)$  is the complex acoustic pressure at point  $r$  in a medium consisting of two half spaces of different impedances and/or propagation constants due to a simple point source at point  $r_0$  of unit volume strength; the point  $r_0$  may lie in either half space. The factor  $\alpha$ , included in equation (7), ensures that  $G$  satisfies reciprocity.

To obtain an integral equation, consider regions  $V_1$  and  $V_2$ ,  $V_1/V_2$  consisting of that part of  $U_+/U_-$  contained within a large sphere of radius  $R$ , centred on the origin, and the boundary,  $\Gamma$ , but excluding small spheres,  $\sigma_r$  and  $\sigma_{r_0}$  of radii  $\epsilon$ , centred on  $r$  and  $r_0$ . The interiors of the spheres  $\sigma_r$  and  $\sigma_{r_0}$  are excluded so that the conditions of Green's second theorem are satisfied by  $p$  and  $G$  in regions  $V_1$  and  $V_2$ . Applying Green's second theorem to regions  $V_1$  and  $V_2$ , the following two equations are obtained:

$$\int_{\partial V_1} (p(r_s, r_0) \frac{\partial G(r_s, r)}{\partial n(r_s)} - G(r_s, r) \frac{\partial p(r_s, r_0)}{\partial n(r_s)}) ds(r_s) = 0, \quad (11)$$

for  $i = 1, 2$ ,  $r_0 \in U_+$  and  $r \in \mathbb{R}^3$ . Letting the radius of the small spheres,  $\epsilon$ , tend to zero, and the radius of the large hemisphere,  $R$ , tend to infinity, and using the Sommerfeld radiation conditions satisfied by  $p$  and  $G$ , these two equations become

$$\kappa_1(r)p(r, r_0) = G(r_0, r) - \int_{\Gamma} p_+(r_s, r_0) \frac{\partial G_+(r_s, r)}{\partial z_s} - G_+(r_s, r) \frac{\partial p_+(r_s, r_0)}{\partial z_s} ds(r_s), \quad (12)$$

where  $\kappa_1(r) := 1$  for  $r \in U_+$ ,  $1/2$  for  $r \in \Gamma$ ,  $0$  for  $r \in U_- \cup \bar{S}$ ; and,

$$\alpha \kappa_2(r)p(r, r_0) = \int_{\Gamma} p_-(r_s, r_0) \frac{\partial G_-(r_s, r)}{\partial z_s} - G_-(r_s, r) \frac{\partial p_-(r_s, r_0)}{\partial z_s} ds(r_s) + \int_{\partial S} p(r_s, r_0) \frac{\partial G(r_s, r)}{\partial n(r_s)} ds(r_s), \quad (13)$$

where  $\kappa_2(r) := 1$  for  $r \in U_-$ ,  $1/2$  for  $r \in \Gamma \cup \partial S$ ,  $0$  for  $r \in U_+$ . Multiplying equation (12) by  $\alpha$ , and adding this to equation (13) and making use of the conditions on  $\Gamma$  satisfied by  $p$  and  $G$  (equations (4), (5), (8) and (9)), equations (12) and (13) can be combined to give the following equation, for  $r_0 \in U_+$  and  $r \in \mathbb{R}^3$ :

$$\alpha \kappa(r)p(r, r_0) = \alpha G(r_0, r) + \int_{\partial S} p(r_s, r_0) \frac{\partial G(r_s, r)}{\partial n(r_s)} ds(r_s), \quad (14)$$

where  $\kappa(r) := 1$  for  $r \in \mathbb{R}^3 \setminus \bar{S}$ ,  $1/2$  for  $r \in \partial S$ . Provided  $\text{Im} k_2 > 0$ , as argument similar to ([1], p.103) shows, this BIE has a unique solution, so that this formulation of the problem is equivalent to the boundary value problem, equations (1) to (5). The condition  $\text{Im} k_2 > 0$  is satisfied since  $k_2$  is the propagation constant for a porous medium.

## SOLUTION OF THE INTEGRAL EQUATION

In general, a closed form solution of equation (14) is not possible. A numerical solution can be obtained by a simple boundary element method as follows. Firstly,  $p$  is determined on  $\partial S$  by forming and solving a set of linear equations. Once  $p$  on  $\partial S$  is found, the value of  $p$  at any other point,  $r \in \mathbb{R}^3 \setminus S$  can be determined by performing the integral of equation (14).

Equation (14), restricted to  $r \in \partial S$ , is a weakly singular Fredholm integral equation of the second kind. A difficulty in the numerical solution of this integral equation is that the kernel function tends to infinity as  $r$  approaches  $r_s$ . This difficulty is resolved by applying the modification of Burton [7]. For  $r \in \partial S$ , equation (14) is written:

$$\begin{aligned} \frac{1}{2} p(r, r_0) = & \alpha G(r_0, r) + \int_{\partial S} p(r_s, r_0) \frac{\partial G(r_s, r)}{\partial n(r_s)} - p(r, r_0) \frac{\partial G_0(r_s, r)}{\partial n(r_s)} ds(r_s) \\ & + p(r, r_0) \int_{\partial S} \frac{\partial G_0(r_s, r)}{\partial n(r_s)} ds(r_s). \end{aligned} \quad (15)$$

where  $G_0(\mathbf{r}_s, \mathbf{r}) = -\alpha/(4\pi|\mathbf{r}_s - \mathbf{r}|)$  is the principal singularity of  $G(\mathbf{r}_s, \mathbf{r})$ . From Gauss' theorem, the last integral can be integrated exactly, giving:

$$\int_{\partial S} \frac{\partial G_0(\mathbf{r}_s, \mathbf{r})}{\partial \mathbf{n}(\mathbf{r}_s)} ds(\mathbf{r}_s) = -\frac{\alpha}{2}, \quad (16)$$

for  $\mathbf{r} \in \partial S$ . Hence, equation (15) can be rewritten as:

$$\alpha p(\mathbf{r}, r_0) = \alpha G(\mathbf{r}_0, \mathbf{r}) + \int_{\partial S} p(\mathbf{r}_s, r_0) \frac{\partial G(\mathbf{r}_s, \mathbf{r})}{\partial \mathbf{n}(\mathbf{r}_s)} - p(\mathbf{r}, r_0) \frac{\partial G_0(\mathbf{r}_s, \mathbf{r})}{\partial \mathbf{n}(\mathbf{r}_s)} ds(\mathbf{r}_s). \quad (17)$$

According to Burton [7], the new integrand, taken as a whole, remains finite as  $\mathbf{r}$  approaches  $\mathbf{r}_s$ .

Now, if the surface  $\partial S$  is split into  $N$  boundary elements,  $\partial S_1, \partial S_2, \dots, \partial S_N$ , from equation (17) it follows that:

$$\alpha p(\mathbf{r}_j, r_0) = \alpha G(\mathbf{r}_0, \mathbf{r}_j) + \sum_{i=1}^N I_{ji}, \quad (18)$$

for  $j = 1(1)N$ , where  $\mathbf{r}_j$  is the midpoint of element  $\partial S_j$ , and:

$$I_{jl} = \int_{\partial S_l} p(\mathbf{r}_s, r_0) \frac{\partial G(\mathbf{r}_s, \mathbf{r}_j)}{\partial \mathbf{n}(\mathbf{r}_s)} - p(\mathbf{r}_j, r_0) \frac{\partial G_0(\mathbf{r}_s, \mathbf{r}_j)}{\partial \mathbf{n}(\mathbf{r}_s)} ds(\mathbf{r}_s). \quad (19)$$

For  $j \neq l$ , the approximation can be made that:

$$I_{jl} \approx A_l \left( p(\mathbf{r}_l, r_0) \frac{\partial G(\mathbf{r}_l, \mathbf{r}_j)}{\partial \mathbf{n}(\mathbf{r}_l)} - p(\mathbf{r}_j, r_0) \frac{\partial G_0(\mathbf{r}_l, \mathbf{r}_j)}{\partial \mathbf{n}(\mathbf{r}_l)} \right), \quad (20)$$

where  $A_l$  is the area of  $\partial S_l$ , and for  $j = l$ :

$$I_{jl} \approx 0. \quad (21)$$

Thus, the following linear equations are satisfied approximately by the unknown values  $p(\mathbf{r}_j, r_0)$ :

$$\alpha p(\mathbf{r}_j, r_0) = \alpha G(\mathbf{r}_0, \mathbf{r}_j) + \sum_{l=1(l \neq j)}^N A_l \left( p(\mathbf{r}_l, r_0) \frac{\partial G(\mathbf{r}_l, \mathbf{r}_j)}{\partial \mathbf{n}(\mathbf{r}_l)} - p(\mathbf{r}_j, r_0) \frac{\partial G_0(\mathbf{r}_l, \mathbf{r}_j)}{\partial \mathbf{n}(\mathbf{r}_l)} \right), \quad (22)$$

for  $j = 1(1)N$ . These approximately satisfied set of  $N$  linear equations for the values of  $p$  at the midpoints  $\mathbf{r}_l$  of  $\partial S_l$  can be written in the standard form:

$$\sum_{l=1}^N a_{jl} p(\mathbf{r}_l, r_0) = \alpha G(\mathbf{r}_0, \mathbf{r}_j) \quad (23)$$

for  $j = 1(1)N$ , and where:

$$a_{jl} = \left[ \alpha + \sum_{i=1(i \neq j)}^N \frac{\partial G_0(\mathbf{r}_i, \mathbf{r}_j)}{\partial \mathbf{n}(\mathbf{r}_i)} A_i \right] \delta_{jl} - (1 - \delta_{jl}) \frac{\partial G(\mathbf{r}_l, \mathbf{r}_j)}{\partial \mathbf{n}(\mathbf{r}_l)} A_l \quad (24)$$

where  $\delta_{jl}$  is the Kronecker delta.

If the obstacle is axisymmetric about an axis perpendicular to the surface  $\Gamma$  and if the elements are numbered as indicated in figure 2, the matrix  $\{a_{jl}\}$  is *Block - Circulant* of order  $N = m \times n$ , with

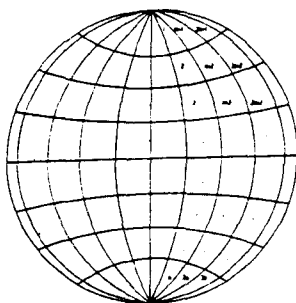


Figure 2: Element configuration for a sphere, including numbering system for the elements.

block entries of order  $m$ . A definition of this matrix type may be found in Davis [8]. The solution of equation (23) can be performed using the subroutine CGSLC of the Toeplitz package, from the Argonne National Laboratory [9]. The value of  $p$  at any point elsewhere in  $r \in \mathbb{R}^3 \setminus S$ , is then given approximately by substituting the calculated values of  $p$  on  $\partial S$  into:

$$\alpha \kappa(r) p(r, r_0) = \alpha G(r_0, r) + \sum_{l=1}^N p(r_l, r_0) \frac{\partial G(r_l, r)}{\partial n(r_l)} A_l, \quad (25)$$

where  $\kappa(r) := 1$  for  $r \in \mathbb{R}^3 \setminus \bar{S}$ ,  $1/2$  for  $r \in \partial S$ .

## THE GREEN'S FUNCTIONS AND IMPEDANCE MODELS

The Green's function can be expressed exactly as an inverse Hankel transform ([10], equation (1)), which can, by various transformations, and by deformation of the path of integration, be expressed in a form more suitable for numerical integration. But, for the calculations performed in this paper, the following simple approximation was used:

$$G(r, r_0) \approx -\frac{\epsilon}{4\pi} \left\{ \frac{e^{ik|r-r_0|}}{|r-r_0|} + R_p \frac{e^{ik|r-r'_0|}}{|r-r'_0|} \right\} \quad (26)$$

when  $r$  and  $r_0$  are both on the same side of the interface, where  $r'_0$  denotes the geometrical image point of  $r_0$  in the plane  $\Gamma$ ,  $k = k_1/k_2$  and  $\epsilon = 1(\alpha)$  if  $r_0$  is in  $U_+(U_-)$ , and  $R_p$  denotes the plane wave reflection coefficient:

$$R_p = (\alpha \cos \theta - (n^2 - \sin^2 \theta)^{\frac{1}{2}}) / (\alpha \cos \theta + (n^2 - \sin^2 \theta)^{\frac{1}{2}}) \quad (27)$$

( $\text{Re}\{(n^2 - \sin^2 \theta)^{\frac{1}{2}}\} > 0$ ) if the source and receiver lie in  $U_+$ , where  $\theta = \cos^{-1}(|z+z_0|/|r-r'_0|)$  is the angle of incidence, and  $n = k_2/k_1$  is the refractive index. If the source and receiver lie in  $U_-$  then  $R_p$  is given by (27) but with  $\alpha$  and  $n$  replaced by  $\alpha^{-1}$  and  $n^{-1}$  respectively.

To calculate  $G(r, r_0)$  when  $r_0 \in U_+$ ,  $r \in U_-$  the approximation of Richards *et al* ([10], equation (25)) has been used, i.e.:

$$G(r, r_0) \approx \exp \left[ -ik_1 z (n^2 - \sin^2 \theta)^{\frac{1}{2}} \right] G(r_\Gamma, r_0) \quad (28)$$



Receiver position /m		Boundary Element Method $P_{\text{scattered}}/P_{\text{direct}}$			Classical Theory $P_{\text{scattered}}/P_{\text{direct}}$
x	y	m = 8 n = 16 h = 0.1963 m	m = 16 n = 32 h = 0.0982 m	m = 32 n = 64 h = 0.0491 m	
1	0	-0.0057 + 0.5853 i	-0.0051 + 0.5824 i	-0.0050 + 0.5817 i	-0.0045 + 0.5808 i
$1/\sqrt{2}$	$1/\sqrt{2}$	-0.2030 + 0.0804 i	-0.1919 - 0.0804 i	-0.1971 - 0.0805 i	-0.1965 - 0.0807 i
0	1	0.0693 + 0.1626 i	0.0645 + 0.1609 i	0.0635 + 0.1606 i	0.0628 + 0.1606 i
$-1/\sqrt{2}$	$1/\sqrt{2}$	-0.2486 + 0.0798 i	-0.2455 + 0.0762 i	-0.2449 - 0.0754 i	-0.2448 - 0.0755 i
-1	0	-0.0391 - 0.2797 i	-0.0426 - 0.2761 i	-0.0434 - 0.2754 i	-0.0437 - 0.2754 i

Table 1: Comparison of the values of the ratio of the scattered field to the direct field using the boundary element method and classical theory for a rigid sphere of radius 0.5m, in an infinite medium of propagation constant  $k = (5.0 + 0.05i)/m$ . For the boundary element method, the source is taken at  $x = -1000.0m$ .

where  $r_r = (x, y, 0)$  denotes the point on  $\Gamma$  directly above  $r$  and  $\theta = \cos^{-1}(z_0/|r_r - r_0|)$ . When using the approximation (28),  $G(r_r, r_0)$  is approximated by equation (26). The approximation (28) is stated [10] to be valid provided  $n$  has an appreciable imaginary component.  $G(r, r_0)$ , when  $r_0 \in U_-$ ,  $r \in U_+$  is calculated from the approximation (28) by using reciprocity.

In the absence of the obstacle, the lower medium is assumed to react like a semi - infinite rigid porous half space. A simple four parameter model of Attenborough [11] can be used to predict the values of normalised propagation constant, and normalised surface impedance for such media. The normalised surface impedance and normalised propagation constant both require characteristic values for the lower medium, i.e. pore shape factor ratio, grain shape factor, effective flow resistivity and porosity.

#### COMPARISON WITH ANALYTICAL RESULTS

If, in the above theory,  $k_1 = k_2$  and  $Z_1 = Z_2$  then equation (14) predicts the values of the pressure field in the presence of the rigid obstacle but in the absence of the plane boundary, i.e. the rigid obstacle is in an infinite homogeneous medium. This means that a direct comparison with the classical results for the scattering of sound from a rigid obstacle can be made. Morse and Ingard, [12], give expressions for the field scattered by a rigid sphere, where the incident plane wave is  $\exp(ikx)$ , travelling in the positive  $x$ -direction. If, in the above theory, the source is positioned sufficiently far from the obstacle, such that the incident field at the obstacle is assumed approximately plane then such a direct comparison can be made. Table 1 shows the results for the ratio of the scattered field to the direct field, at several points close to a sphere of radius 0.5 m, within a porous medium of propagation constant  $k = (5.0 + 0.05i)/m$ . The source for the BIE method is positioned at  $x = -1000.0m$  ( $y = 0, z = 0$ ), the centre of the sphere being taken as the origin and the number of elements is varied. It is observed that there is convergence as the number of elements is increased.

#### COMPARISON WITH EXPERIMENTAL RESULTS

A set of simple laboratory measurements within a small anechoic chamber were carried out to compare with the theory. In these experiments, a porous half-space was modelled by a 0.5m thick layer of pea-gravel (maximum grain size 0.95cm). A wooden hemisphere of 0.125m diameter was used as the