DEVELOPMENTS IN GEOTECHNICAL ENGINEERING 53

NONLINEAR ANALYSIS IN SOIL MECHANICS

Theory and Implementation

NONLINEAR ANALYSIS IN SOIL MECHANICS

Theory and Implementation

W.F. CHEN

School of Civil Engineering, Purdue University, West Lafayette, IN 47907, U.S.A.

and

E. MIZUNO

Department of Civil Engineering, Nagoya University, Nagoya 464, Japan



ELSEVIER
Amsterdam — Oxford — New York — Tokyo 1990

ELSEVIER SCIENCE PUBLISHERS B.V.
Sara Burgerhartstraat 25
P.O. Box 211, 1000 AE Amsterdam, The Netherlands

Distributors for the United States and Canada:

ELSEVIER SCIENCE PUBLISHING COMPANY INC. 655, Avenue of the Americas New York, NY 10010, U.S.A.

ISBN 0-444-43043-1

© Elsevier Science Publishers B.V., 1990

All rights reserved. No part of this publication may be reproduced, stored in a retrieval system or transmitted in any form or by any means, electronic, mechanical, photocopying, recording or otherwise, without the prior written permission of the publisher, Elsevier Science Publishers B.V./ Physical Sciences & Engineering Division, P.O. Box 330, 1000 AH Amsterdam, The Netherlands.

Special regulations for readers in the USA – This publication has been registered with the Copyright Clearance Center Inc. (CCC), Salem, Massachusetts. Information can be obtained from the CCC about conditions under which photocopies of parts of this publication may be made in the USA. All other copyright questions, including photocopying outside of the USA, should be referred to the publisher.

No responsibility is assumed by the Publisher for any injury and/or damage to persons or property as a matter of products liability, negligence or otherwise, or from any use or operation of any methods, products, instructions or ideas contained in the material herein.

This book is printed on acid-free paper

Printed in The Netherlands

PREFACE

A complete analysis of stress and strain in a structure, as the load is increased to failure, is known to be very complicated. This is particularly true in soil mechanics and soil-structure interaction problems where, unlike traditional structural engineering, the analysis almost always involves two- and three-dimensional continua. With the present state of development of finite-element computer softwares and high-speed digital computer hardwares, we can confidently say that an almost unlimited range of solutions can now be obtained. These are not limited to linear elastic small-deformation solid mechanics but can be extended to include problems of various kinds involving material and geometric nonlinearities. This book is concerned with the development of numerical tools for solutions of nonlinear analysis problems in soil mechanics.

The mathematical theories of elasticity and plasticity are employed for the constitutive modeling of the soil behavior. The theoretical foundation and basic concepts of material modeling are described in details in PART II including critical discussions of the Theory of Elasticity and Modeling in Chapter 3, the Theory of Perfect Plasticity and Modeling in Chapter 4, and the Theory of Hardening Plasticity and Modeling in Chapter 5.

The material nonlinearity is represented in PART III by an elastic-plastic cap-type model which can treat either strain-hardening or strain-softening materials. The plasticity formulation and calibration (Chapter 6) together with the numerical algorithm developed for its implementation and predictions (Chapter 7) provide a general format for incorporating various plasticity models described previously in PART II into the cap-type of plasticity relationship of PART III suitable for direct finite-element applications. In particular, the Drucker-Prager model with an elliptic hardening cap illustrated in details in Chapter 6 and coded in Chapter 7 as a SUBROUTINE CAPMDL represents an adequate constitutive model for the short-time behavior of many geological materials over a wide range of loadings.

The geometric nonlinearity for large-deformation analyses is described in details in PART IV. The theoretical foundation of large-deformation formulation and its simplification are described in details in Chapter 8. The nonlinear finite-element equations for large deformation and material inelasticity are solved by a combined incremental and iterative solution technique (Chapter 9). Two types of iterations are carried out, the first being iteration on the material parameters and the second equilibrium iterations. The method of analysis is based on a displacement formulation of the finite-element method. Large displacements are accounted for using a total Lagrangian formulation and an updated Lagrangian formulation.

Applications of the nonlinear theory are presented for a wide range of numerical examples throughout the book. In particular, several case studies using the computer program developed are presented in PART v (Chapter 10). First the material nonlinearities involving associated as well as non-associated flow rules with different procedures for the determination of the material parameters from the experimental data are examined for strip footings on stratum of clay. The algorithms for the behavior of the clay are then tested and checked for the simplification of small-strain small-rotation formulation. Finally, small-strain large-rotation analyses of elasto-plastic behavior are carried out for vertical slopes under seismic loading. This analytical simplification is reasonable for most large-displacement problems in geotechnical engineering applications and results in symmetric governing equations in the large-displacement finite-element analysis. The complete progressive failure behavior of slopes at all stress levels leading up to collapse is obtained. The collapse loads of the slopes and their associated failure mechanisms by the finite-element method are compared with those of the limit analysis method.

The book can be used for nonlinear analysis courses in geotechnical engineering of various lengths, involving mathematical modeling of materials (PART II and PART III), large-deformation finite-element description of structures (PART IV), and computer implementation and numerical predictions (PART V). In writing this book, we have endeavored to make the prerequisites as few as possible. Some background on the theory of linear elasticity and the finite-element method is assumed. The book is aimed to the graduate student in civil engineering who has sufficient background in soil mechanics and is learning about inelastic behavior of materials and large-displacement description of structures for the first time. The inclusion of computer subroutines for soil cap models is intended to encourage the reader to try out these models in a direct manner.

May, 1988

W.F. Chen E. Mizuno

CONTENTS

Preface	v
Part I: Fundamentals	1
Chapter 1 INTRODUCTION	
1.1 Introduction 1.2 Characteristics of soil behavior 1.3 Idealizations and material modeling 1.4 Historical review of plasticity in soil mechanics 1.5 Nonlinear stress analyses in geotechnical engineering 1.6 Need, objectives and scope References	3 5 7 9
Chapter 2 BASIC CONCEPT OF CONTINUUM MECHANICS	٠.
2.1 Introduction 2.2 Notations 2.3 Stresses in three dimensions 2.3.1 Definitions and notations 2.3.2 Cauchy's formulas, index notation, and summation convention 2.3.3 Principal axes of stresses 2.3.4 Deviatoric stress 2.3.5 Geometrical representation of stresses 2.4.1 Definitions and notations 2.4.2 Deviatoric strain 2.4.3 Octahedral strains and principal shear strains 2.5 Equations of solid mechanics 2.5.1 Equations of equilibrium (or motion) 2.5.2 Geometric (compatibility) conditions 2.5.3 Constitutive relations 2.6 Summary References	30 39 39 40 41 45 45
PART II: Material modeling—Basic concepts	53
Chapter 3 ELASTICITY AND MODELING	
3.1 Introduction 3.2 Elastic models in geotechnical engineering 3.2.1 Linear elastic model (generalized Hooke's law) 3.2.2 Cauchy elastic model 3.2.3 Hyperelastic model 3.2.4 Hypoelastic model	55 56 56 57 58 65

3.3	Uniqueness, stability, normality, and convexity for elastic materials	70
	3.3.1 Uniqueness	70
	3.3.2 Drucker's stability postulate	72
	3.3.3 Existence of W and Ω	73
	3.3.4 Restrictions – normality and convexity	76
3.4	Linear elastic stress-strain relations	81
	3.4.1 Generalized Hooke's law	81
	3.4.2 A plane of symmetry	. 82
	3.4.3 Two planes of symmetry (orthotropic symmetry)	84
	3.4.4 Transverse and cubic isotropies	85
	3.4.5 Full isotropy	86
3.5	Isotropic linear elastic stress-strain relations	87
	3.5.1 Tensor forms	88
	3.5.2 Three-dimensional matrix forms	93
	3.5.3 Plane stress case	94
	3.5.4 Plane strain case	94
	3.5.5 Axisymmetric case	96
3.6	Isotropic nonlinear elastic stress-strain relations based on total formulation	96
	3.6.1 Nonlinear elastic model with secant moduli	97
	3.6.2 Cauchy elastic model	100
	3.6.3 Hyperelastic (Green) model	103
3.7	Isotropic nonlinear elastic stress-strain relations based on incremental formulation	104
	3.7.1 Nonlinear elastic model with secant moduli	104
	3.7.2 Cauchy elastic model	108
	3.7.3 Hyperelastic model	112
	3.7.4 Hypoelastic model	113
3.8	Summary '	119
	References	121
Char	oter 4 PERFECT PLASTICITY AND MODELING	
о. р	Lad Lot I modelli i Middle Modelli i d	
4.1	Introduction	123
4.2	Deformation theory	124
	4.2.1 An illustrative example	124
	4.2.2 Variable moduli models	126
4.3	Flow theory	127
	4.3.1 Yield criteria	127
	4.3.2 Flow rule	128
	4.3.3 Basic requirements	129
4.4	Perfect plasticity models	130
4.5	Tresca and von Mises models	132
4.6	Coulomb model	139
4.7	Drucker-Prager model	143
4.8	Prandtl-Reuss stress-strain relations	151
4.9	Generalized stress-strain relations	161
4.10	Stiffness formulation	163
	4.10.1 General description	
	4.10.2 Stiffness coefficients	163 164
4.11	Summary	170
	References	170
		1/2

5.1 Introduction 173 5.2 Flow theory 174 5.2.1 Hardening rule 175 5.2.2 Hardening rule 175 5.2.3 Flow rule 177 5.2.4 Drucker's postulate 189 5.3 Lade Drucker's postulate 181 5.3 Historical hardening model 181 5.3.1 Kinematic hardening model 182 5.3.2 Kinematic hardening model 183 5.4 Lade-Duncan model 183 5.5 Lade model 192 5.6 Nested yield surface models 202 5.7 Generalized multi-surface models 202 5.8 Bounding surface models 202 5.9 Prandtl-Reuss equations 217 5.9.1 Prandtl-Reuss equations 217 5.9.2 Prandtl-Reuss equations 225 5.10 Generalized stress-strain relations 236 5.10.2 Incremental stress-strain relations 236 5.10.3 Kinematic hardening 239 5.10.3	Chap		
5.2. Flow theory 174 5.2.1 Loading function 174 5.2.2 Hardening rule 175 5.2.3 Flow rule 177 5.2.4 Portcker's postulate 179 5.3. Hardening plasticity models 181 5.3.1 Isotropic hardening model 182 5.3.2 Kinematic hardening model 183 5.4 Lade-Duncan model 183 5.5 Lade model 192 5.6 Nested yield surface models 202 5.7 Generalized multi-surface models 202 5.8 Bounding surface models 202 5.9 Prandt-Reuss stress-strain relations 217 5.9.1 Prandt-Reuss equations 217 5.9.2 Matrix form of Prandtl-Reuss equations 217 5.10.1 Incremental stress-strain relations 236 5.10.2 Isotropic hardening 238 5.10.2 Isotropic hardening 238 5.10.2 Isotropic hardening 238 5.10.2 Surfiness formulation 243 5.11.2 Stiffness formulation 243 5.11.2 Summary 255 References 259 Part III: Material nonlinearity—Cap models 277	5 1	ntraduction	
5.2.1 Loading function 174 5.2.2 Hardening rule 175 5.2.3 Flow rule 177 5.2.4 Drucker's postulate 179 5.3 Hardening plasticity models 181 5.3.1 Isotropic hardening model 182 5.3.2 Kinematic hardening model 183 5.3.2 Lade-Duncan model 183 5.4 Lade-Duncan model 183 5.5 Lade model 192 5.6 Nested yield surface models 206 5.7 Generalized multi-surface models 202 5.8 Bounding surface models 202 5.9 Prandtl-Reuss equations 210 5.9 Prandtl-Reuss equations 217 5.9.1 Prandtl-Reuss equations 225 5.10 Generalized stress-strain relations 236 5.10.1 Incremental stress-strain relations 236 5.10.2 Isotropic hardening 238 5.10.3 Kinematic hardening 238 5.10.3 Kinematic hardening 238 5.10.3 Stiffness formulation 243 5.11 Stiffness formulation 243 5.12 Stiffness formulation 243 5.12 Stuffness officients 246		79	
5.2.2 Hardening rule 177 5.2.3 Flow rule 177 5.2.4 Drucker's postulate 181 5.3.1 Miscreating model 181 5.3.2 Kinematic hardening model 182 5.3.3 Mixed hardening model 183 5.4 Lade-Duncan model 183 5.5 Lade model 192 5.6 Nested yield surface models 202 5.7 Generalized multi-surface models 202 5.8 Bounding surface models 210 5.9 Prandtl-Reuss stress-strain relations 217 5.9.1 Prandtl-Reus equations 217 5.9.2 Matrix form of Prandtl-Reuss equations 225 5.10 Generalized stress-strain relations 236 5.10.1 Incremental stress-strain relations 236 5.10.2 Isotropic hardening 238 5.10.3 Sinematic hardening 239 5.10.4 Mixed hardening 239 5.11 Stiffness formulation 244 5.11.2 Sitifness coefficients 246 5.12 Summary 255 References 259 Part III: Material nonlinearity—Cap models 261 Chapter of CAP MODEL FORMULATION AND CALIBRATION <td>•</td> <td>5.2.1 Loading function</td> <td></td>	•	5.2.1 Loading function	
5.2.3 Flow rule 179 5.2.4 Drucker's postulate 179 5.3 Hardening plasticity models 181 5.3.1 Isotropic hardening model 182 5.3.2 Kinematic hardening model 183 5.4 Lade-Duncan model 183 5.5 Lade model 192 5.6 Nested yield surface models 192 5.7 Generalized multi-surface models 202 5.8 Bounding surface models 202 5.9 Prandtl-Reuss stress-strain relations 217 5.9.1 Prandtl-Reuss sequations 217 5.9.2 Matrix form of Prandtl-Reuss equations 225 5.10.2 Isotropic hardening 236 5.10.2 Isotropic hardening 236 5.10.3 Kinematic hardening 239 5.10.4 Mixed hardening 239 5.11.2 Stiffness formulation 243 5.11.2 Stiffness formulation 244 5.11.2 Stiffness officients 246 5.12 Summary 255 References 259 Part III: Material nonlinearity—Cap models 261 Chapter 6 CAP MODEL FORMULATION AND CALIBRATION 6.1 Introduction 263 <		r a a structura mala	
5.2.4 Drucker's postulate 181 5.3. Hardening plasticity models 181 5.3.1 Isotropic hardening model 182 5.3.2 Kinematic hardening model 183 5.4 Lade-Duncan model 183 5.5 Lade model 192 5.6 Nested yield surface models 202 5.7 Generalized multi-surface models 202 5.8 Bounding surface models 210 5.9 Prandtl-Reuss stress-strain relations 217 5.9.1 Prandtl-Reuss equations 217 5.9.2 Matrix form of Prandtl-Reuss equations 225 5.10.1 Incremental stress-strain relations 236 5.10.2 Isotropic hardening 238 5.10.3 Kinematic hardening 238 5.10.4 Mixed hardening 238 5.10.1 Stiffness formulation 243 5.11.1 General description 244 5.11.2 Sulfness coefficients 246 5.12 Summary 255 References 259 Part III: Material nonlinearity—Cap models 6.1 Introduction 263 6.2 Cap models 277 6.4.2 Simple plane cap model 272		C23 Flow rule	-
5.3.1 Isotropic hardening model 182 5.3.2 Kinematic hardening model 183 5.3.3 Mixed hardening model 183 5.5 Lade Duncan model 192 5.6 Nested yield surface models 192 5.7 Generalized multi-surface models 202 5.8 Bounding surface models 210 5.9 Prandtl-Reuss equations 217 5.9.1 Prandtl-Reuss surfaces-strain relations 217 5.9.2 Matrix form of Prandtl-Reuss equations 225 5.10 Generalized stress-strain relations 236 5.10.1 Incremental stress-strain relations 236 5.10.2 Isotropic hardening 238 5.10.3 Kinematic hardening 238 5.10.4 Mixed hardening 243 5.11.1 General description 244 5.11.2 Stiffness coefficients 245 5.12.2 Summary 255 References 259 Part III: Material nonlinearity—Cap models 261 Chapter 6 CAP MODEL FORMULATION AND CALIBRATION 261 6.1 Introduction 263 6.2 Cap models 277 6.4.2 Simple plane cap model 277 6.4.2 Simple plan		5.2.4 Denoker's postulate	
5.3.2 Kinematic hardening model 182 5.3.3 Mixed hardening model 183 5.4 Lade-Duncan model 192 5.6 Nested yield surface models 196 5.7 Generalized multi-surface models 202 5.8 Bounding surface models 210 5.9 Prandtl-Reuss stress-strain relations 217 5.9.1 Prandtl-Reuss equations 217 5.9.2 Matrix form of Prandtl-Reuss equations 225 5.10 Generalized stress-strain relations 236 5.10.1 Incremental stress-strain relations 236 5.10.2 Isotropic hardening 238 5.10.3 Kinematic hardening 239 5.10.4 Mixed hardening 244 5.11. General description 244 5.12 Summary 255 References 259 Part III: Material nonlinearity—Cap models 261 Chapter 6 CAP MODEL FORMULATION AND CALIBRATION 263 6.2 Historical developments 266 6.2.1 Cambridge models (concept of critical state) 267 6.3 Modified Cam-clay model 272 6.4 Elliptic cap model 277 6.4.2 Simple plane cap model 279 <	5.3	Hardening plasticity models	
5.3.3 Mixed hardening model 183 5.4 Lade-Duncan model 183 5.5 Lade model 192 5.6 Nested yield surface models 206 5.7 Generalized multi-surface models 202 5.8 Bounding surface models 210 5.9 Prandtl-Reuss stress-strain relations 217 5.9.1 Prandtl-Reuss equations 217 5.9.2 Matrix form of Prandtl-Reuss equations 225 5.10 Generalized stress-strain relations 236 5.10.1 Incremental stress-strain relations 236 5.10.2 Isotropic hardening 238 5.10.3 Kinematic hardening 239 5.10.4 Mixed hardening 243 5.11 Stiffness formulation 243 5.11.2 Suiffness formulation 243 5.11.2 Stiffness coefficients 246 5.12 Summary 255 References 259 Part III: Material nonlinearity—Cap models 261 Chapter 6 CAP MODEL FORMULATION AND CALIBRATION 261 6.1 Introduction 263 6.2 Cap models (concept of critical state) 267 6.3 Modified Cam-clay model 277 6.4.1 Elliptic		5.3.1 Isotropic hardening model	
5.4 Lade-Duncan model 183 5.5 Lade model 192 5.6 Nested yield surface models 202 5.7 Generalized multi-surface models 210 5.8 Bounding surface models 217 5.9 Prandtl-Reuss stress-strain relations 217 5.9.1 Prandtl-Reuss equations 227 5.9.2 Matrix form of Prandtl-Reuss equations 225 5.10.1 Incremental stress-strain relations 236 5.10.1 Incremental stress-strain relations 236 5.10.2 Isotropic hardening 239 5.10.4 Mixed hardening 239 5.10.5 Stiffness formulation 243 5.11.2 Stiffness formulation 244 5.11.2 Stiffness formulation 244 5.12 Summary 255 References 259 Part III: Material nonlinearity—Cap models 261 Chapter 6 CAP MODEL FORMULATION AND CALIBRATION 6.1 Introduction 263 6.2.1 Cap models 277 <t< td=""><td></td><td>5.3.2 Kinematic hardening model</td><td>•</td></t<>		5.3.2 Kinematic hardening model	•
5.5 Lade model 192 5.6 Nested yield surface models 202 5.7 Generalized multi-surface models 202 5.8 Bounding surface models 210 5.9 Prandtl-Reuss equations 217 5.9.2 Matrix form of Prandtl-Reuss equations 225 5.10 Generalized stress-strain relations 236 5.10.1 Incremental stress-strain relations 236 5.10.1 Incremental stress-strain relations 236 5.10.2 Isotropic hardening 238 5.10.3 Kinematic hardening 239 5.10.4 Mixed hardening 241 5.11 Generalized confliction 243 5.11.1 Generalized scription 244 5.12 Summary 255 References 259 Part III: Material nonlinearity—Cap models 6.1 Introduction 263 6.2.1 Cambridge models (concept of critical state) 261 6.2 Historical developments 266 6.2.1 Cambridge models (concept of critical state) 2		5.3.3 Mixed hardening model	
5.6 Nested yield surface models 202 5.7 Generalized multi-surface models 210 5.8 Bounding surface models 217 5.9 Prandtl-Reuss equations 217 5.9.1 Prandtl-Reuss equations 227 5.9.2 Matrix form of Prandtl-Reuss equations 236 5.10.1 Incremental stress-strain relations 236 5.10.2 Isotropic hardening 238 5.10.3 Kinematic hardening 239 5.10.4 Mixed hardening 241 5.11 Stiffness formulation 243 5.11.1 Stiffness coefficients 246 5.12 Summary 255 References 259 Part III: Material nonlinearity—Cap models 261 Chapter 6 CAP MODEL FORMULATION AND CALIBRATION 6.1 Introduction 263 6.2 Historical developments 266 6.2.1 Cambridge models (concept of critical state) 267 6.2 Generalized cap model 277 6.4.1 Elliptic cap model 277 <tr< td=""><td>5.4</td><td>Lade-Duncan model</td><td></td></tr<>	5.4	Lade-Duncan model	
5.7 Generalized multi-surface models 200 5.8 Bounding surface models 210 5.9 Prandtl-Reuss stress-strain relations 217 5.9.1 Prandtl-Reuss equations 225 5.10 Generalized stress-strain relations 236 5.10.1 Incremental stress-strain relations 236 5.10.2 Isotropic hardening 238 5.10.3 Kinematic hardening 239 5.10.4 Mixed hardening 241 5.11 General description 243 5.11.1 General description 244 5.12 Summary 255 References 259 Part III: Material nonlinearity—Cap models 261 Chapter 6 CAP MODEL FORMULATION AND CALIBRATION 6.1 Introduction 263 6.2.1 Cambridge models (concept of critical state) 267 6.2.1 Cambridge models (concept of critical state) 267 6.2.2 Cap models 277 6.4.2 Simple plane cap model 277 6.4.2 Simple plane cap model 279 <td>5.5</td> <td>Lade model</td> <td></td>	5.5	Lade model	
5.8 Bounding surface models 210 5.9 Prandtl-Reuss stress-strain relations 217 5.9.1 Prandtl-Reuss equations 225 5.10 Generalized stress-strain relations 236 5.10.1 Incremental stress-strain relations 236 5.10.2 Isotropic hardening 238 5.10.2 Stortopic hardening 239 5.10.3 Kinematic hardening 239 5.10.4 Mixed hardening 244 5.11.1 General description 244 5.11.2 Stiffness formulation 243 5.11.2 Stiffness coefficients 246 5.12 Summary 255 References 259 Part III: Material nonlinearity—Cap models 261 Chapter 6 CAP MODEL FORMULATION AND CALIBRATION 6.1 Introduction 263 6.2 Cap models (concept of critical state) 267 6.3 Modified Cam-clay model 277 6.4.1 Elliptic cap model 277 6.5 Stress-strain relations 279	5.6	Nested yield surface models	
5.9 Prandtl-Reuss stress-strain relations 217 5.9.1 Prandtl-Reuss equations 225 5.9.2 Matrix form of Prandtl-Reuss equations 236 5.10 Generalized stress-strain relations 236 5.10.1 Incremental stress-strain relations 236 5.10.2 Isotropic hardening 238 5.10.3 Kinematic hardening 239 5.10.4 Mixed hardening 241 5.11 Stiffness formulation 243 5.11.1 General description 244 5.11.2 Stiffness coefficients 246 5.12 Summary 255 References 259 Part III: Material nonlinearity—Cap models 261 Chapter 6 CAP MODEL FORMULATION AND CALIBRATION 263 6.2 Historical developments 266 6.2.1 Cambridge models (concept of critical state) 267 6.2.2 Cap models 270 6.4.3 Modified Cam-clay model 277 6.4.2 Simple plane cap model 277 6.4.2 Simple plane cap model 279 6.5 Stress-strain relations 279 6.6 Stiffness coefficients 280 6.7 Cap model in fitting procedure 285	5.7	Generalized multi-surface models	
5.9.1 Prandtl-Reuss equations 217 5.9.2 Matrix form of Prandtl-Reuss equations 225 5.10 Generalized stress-strain relations 236 5.10.1 Incremental stress-strain relations 238 5.10.2 Isotropic hardening 239 5.10.4 Mixed hardening 241 5.11 Stiffness formulation 243 5.11.1 General description 244 5.12 Summary 255 References 259 Part III: Material nonlinearity—Cap models 6.1 Introduction 263 6.2 Historical developments 266 6.2.1 Cambridge models (concept of critical state) 267 6.3 Modified Cam-clay model 277 6.4 Generalized cap models 277 6.4.2 Simple plane cap model 277 6.5 Stress-strain relations 279 6.6 Stiffness coefficients 280 6.6.1 General description 280 6.6.2 Stiffness coefficients 282 6.7 Cap model in fitting procedure 285 6.7.1 Stress paths in experiments 285 6.8 Cap model in simple tests 294 6.8.1 Uniaxial strain test	5.8	Bounding surface models	
5.9.2 Matrix form of Prandtl-Reuss equations 225 5.10 Generalized stress-strain relations 236 5.10.1 Incremental stress-strain relations 238 5.10.2 Isotropic hardening 239 5.10.3 Kinematic hardening 241 5.11 Stiffness formulation 243 5.11.1 General description 244 5.11.2 Stiffness coefficients 246 5.12 Summary 255 References 259 Part III: Material nonlinearity—Cap models 6.1 Introduction 263 6.2 Historical developments 266 6.2.1 Cambridge models (concept of critical state) 267 6.2.2 Cap models 270 6.4.1 Elliptic cap model 277 6.4.2 Simple plane cap model 277 6.4.2 Simple plane cap model 279 6.5 Stress-strain relations 279 6.6.2 Stiffness formulation 280 6.6.1 General description 280 6.6.2 Stiffness coefficients 282 6.7.1 Stress paths in experiments 285 6.7.2 Determination of material constants 291 6.8 Cap model in simple tests <td>5.9</td> <td>Prandtl-Reuss stress-strain relations</td> <td></td>	5.9	Prandtl-Reuss stress-strain relations	
5.10 Generalized stress-strain relations 236 5.10.1 Incremental stress-strain relations 238 5.10.2 Isotropic hardening 239 5.10.3 Kinematic hardening 241 5.11 Stiffness formulation 243 5.11.1 General description 244 5.12 Summary 255 References 259 Part III: Material nonlinearity—Cap models 6.1 Introduction 263 6.2 Historical developments 266 6.2.1 Cambridge models (concept of critical state) 267 6.2.2 Cap models 277 6.4.1 Elliptic cap model 277 6.4.2 Simple plane cap model 277 6.5 Stiffness formulation 280 6.6.2 Stiffness coefficients 280 6.6.2 Stiffness coefficients 282 6.7 Cap model in fitting procedure 285 6.7.1 Stress paths in experiments 285 6.7.2 Determination of material constants 291 6.8 Cap model in simple tests 294 6.8.1 Uniaxial strain test 294		5.9.1 Prandtl-Reuss equations	
5.10.1 Incremental stress-strain relations 236 5.10.2 Isotropic hardening 238 5.10.3 Kinematic hardening 239 5.10.4 Mixed hardening 241 5.11 Stiffness formulation 243 5.11.1 General description 244 5.12 Summary 255 References 259 Part III: Material nonlinearity—Cap models 261 Chapter 6 CAP MODEL FORMULATION AND CALIBRATION 263 6.1 Introduction 263 6.2 Historical developments 266 6.2.1 Cambridge models (concept of critical state) 267 6.2.2 Cap models 270 6.4.1 Elliptic cap model 277 6.4.2 Simple plane cap model 279 6.5 Stress-strain relations 279 6.5 Stiffness formulation 280 6.6.2 Stiffness coefficients 280 6.7 Cap model in fitting procedure 285 6.7.1 Stress paths in experiments 285 6.7.2 Determination of material constants 291 6.8 Cap model in simple tests 294 6.8.1 Uniaxial strain test 294		5.9.2 Matrix form of Prandtl-Reuss equations	
5.10.2 Isotropic hardening 238 5.10.3 Kinematic hardening 239 5.10.4 Mixed hardening 241 5.11 Stiffness formulation 243 5.11.1 General description 244 5.11.2 Stiffness coefficients 246 5.12 Summary 255 References 259 Part III: Material nonlinearity—Cap models 261 Chapter 6 CAP MODEL FORMULATION AND CALIBRATION 6.1 Introduction 263 6.2 Historical developments 266 6.2.1 Cambridge models (concept of critical state) 267 6.3 Modified Cam-clay model 270 6.4 Generalized cap models 277 6.4.1 Elliptic cap model 277 6.5 Stress-strain relations 279 6.6 Stiffness formulation 280 6.6.2 Stiffness coefficients 280 6.7.1 General description 280 6.6.2 Stiffness coefficients 282 6.7.1 Determination of material constants 285 6.7.2 Determination of material constants 294 6.8 Cap model in simple tests 294 6.8.1 Uniaxial strain test	5.10	Chengianized successing in telanions	
S.10.2 Stiffness formulation 239		5.10.1 Incremental stress-strain relations	
5.10.4 Mixed hardening 241 5.11 Stiffness formulation 243 5.11.1 General description 244 5.11.2 Stiffness coefficients 246 5.12 Summary 255 References 259 Part III: Material nonlinearity—Cap models Chapter 6 CAP MODEL FORMULATION AND CALIBRATION 6.1 Introduction 263 6.2 Historical developments 266 6.2.1 Cambridge models (concept of critical state) 267 6.2 am models 270 6.3 Modified Cam-clay model 272 6.4 Generalized cap models 277 6.4.1 Elliptic cap model 277 6.4.2 Simple plane cap model 279 6.5 Stress-strain relations 279 6.6 Stiffness formulation 280 6.6.1 General description 280 6.6.2 Stiffness coefficients 283 6.7.1 Stress paths in experiments 285 6.7.2 Determination of material constants 291 6.8 Cap model in simple tests 294 6.8.1 Uniaxial strain test 294 6.8.1 Uniaxial strain test 294 </td <td></td> <td>J. IU.Z ISOUODIC HAIGCHING</td> <td></td>		J. IU.Z ISOUODIC HAIGCHING	
5.11 Stiffness formulation 243 5.11.1 General description 244 5.11.2 Stiffness coefficients 246 5.12 Summary 255 References 259 Part III: Material nonlinearity—Cap models 261 Chapter 6 CAP MODEL FORMULATION AND CALIBRATION 6.1 Introduction 263 6.2 Historical developments 266 6.2.1 Cambridge models (concept of critical state) 267 6.2.2 Cap models 270 6.3 Modified Cam-clay model 272 6.4 Generalized cap models 277 6.4.1 Elliptic cap model 277 6.4.2 Simple plane cap model 279 6.5 Stress-strain relations 279 6.6 Stiffness formulation 280 6.6.1 General description 280 6.6.2 Stiffness coefficients 282 6.7 Cap model in fitting procedure 285 6.7.1 Stress paths in experiments 285 6.7.2 Determination of material constants 294 6.8 Cap model in simple tests 294 6.8.1 Uniaxial strain test 294		5.10.3 Kinematic hardening	
5.11.1 General description 244 5.11.2 Stiffness coefficients 246 5.12 Summary 255 References 259 Part III: Material nonlinearity—Cap models Chapter 6 CAP MODEL FORMULATION AND CALIBRATION 6.1 Introduction 263 6.2 Historical developments 266 6.2.1 Cambridge models (concept of critical state) 267 6.2 Cap models 270 6.3 Modified Cam-clay model 272 6.4 Generalized cap models 277 6.4.1 Elliptic cap model 277 6.5 Stress-strain relations 279 6.5 Stiffness formulation 280 6.6.1 General description 280 6.6.2 Stiffness coefficients 283 6.7 Cap model in fitting procedure 285 6.7.1 Stress paths in experiments 285 6.7.2 Determination of material constants 294 6.8 Cap model in simple tests 294 6.8.1 Uniaxial strain test 294 6.8.1 Uniaxial strain test 294 6.8.2 Uniaxial strain test 294 6.8.2 Uniaxial strain test		5.10.4 Mixed hardening	
5.11.2 Stiffness coefficients 246 5.12 Summary 255 References 259 Part III: Material nonlinearity—Cap models Chapter 6 CAP MODEL FORMULATION AND CALIBRATION 6.1 Introduction 263 6.2 Historical developments 266 6.2.1 Cambridge models (concept of critical state) 267 6.2.2 Cap models 270 6.4 Generalized cap models 277 6.4.1 Elliptic cap model 277 6.4.2 Simple plane cap model 279 6.5 Stress-strain relations 279 6.5 Stiffness formulation 280 6.6.1 General description 280 6.6.2 Stiffness coefficients 282 6.7.1 Stress paths in experiments 285 6.7.2 Determination of material constants 294 6.8 Cap model in simple tests 294 6.8.1 Uniaxial strain test 294 6.8.1 Uniaxial strain test 294	5.11	Sulffices formulation	
5.12 Summary 255 References 259 Part III: Material nonlinearity—Cap models Chapter 6 CAP MODEL FORMULATION AND CALIBRATION 6.1 Introduction 263 6.2 Historical developments 266 6.2.1 Cambridge models (concept of critical state) 267 6.3 Modified Cam-clay model 270 6.4 Generalized cap models 277 6.4.1 Elliptic cap model 277 6.4.2 Simple plane cap model 279 6.5 Stress-strain relations 279 6.6 Stiffness formulation 280 6.6.1 General description 280 6.6.2 Stiffness coefficients 282 6.7 Cap model in fitting procedure 285 6.7.1 Stress paths in experiments 285 6.7.2 Determination of material constants 291 6.8 Cap model in simple tests 294 6.8.1 Uniaxial strain test 294		5.11.1 General description	
References 259 Part III: Material nonlinearity—Cap models 261 Chapter 6 CAP MODEL FORMULATION AND CALIBRATION 6.1 Introduction 263 6.2 Historical developments 266 6.2.1 Cambridge models (concept of critical state) 267 6.2 Cap models 270 6.3 Modified Cam-clay model 272 6.4 Generalized cap models 277 6.4.1 Elliptic cap model 279 6.5 Stress-strain relations 279 6.5 Stiffness formulation 280 6.6.1 General description 280 6.6.2 Stiffness coefficients 280 6.7 Cap model in fitting procedure 285 6.7.1 Stress paths in experiments 285 6.7.2 Determination of material constants 291 6.8 Cap model in simple tests 294 6.8.1 Uniaxial strain test 294		5.11.2 Stiffness coefficients	
Part III: Material nonlinearity—Cap models 261 Chapter 6 CAP MODEL FORMULATION AND CALIBRATION 6.1 Introduction 263 6.2 Historical developments 266 6.2.1 Cambridge models (concept of critical state) 267 6.2 Cap models 270 6.3 Modified Cam-clay model 277 6.4 Generalized cap models 277 6.4.1 Elliptic cap model 279 6.5 Stress-strain relations 279 6.6 Stiffness formulation 280 6.6.1 General description 280 6.6.2 Stiffness coefficients 282 6.7 Cap model in fitting procedure 285 6.7.1 Stress paths in experiments 285 6.7.2 Determination of material constants 291 6.8 Cap model in simple tests 294 6.8.1 Uniaxial strain test 294	5.12	Summary	
Chapter 6 CAP MODEL FORMULATION AND CALIBRATION 6.1 Introduction 263 6.2 Historical developments 266 6.2.1 Cambridge models (concept of critical state) 267 6.2 Cap models 270 6.3 Modified Cam-clay model 272 6.4 Generalized cap models 277 6.4.1 Elliptic cap model 279 6.5 Stress-strain relations 279 6.5 Stiffness formulation 280 6.6.1 General description 280 6.6.2 Stiffness coefficients 282 6.7 Cap model in fitting procedure 285 6.7.1 Stress paths in experiments 285 6.7.2 Determination of material constants 291 6.8 Cap model in simple tests 294 6.8.1 Uniaxial strain test 294		Keterences	237
Chapter 6 CAP MODEL FORMULATION AND CALIBRATION 6.1 Introduction 263 6.2 Historical developments 266 6.2.1 Cambridge models (concept of critical state) 267 6.2 Cap models 270 6.3 Modified Cam-clay model 272 6.4 Generalized cap models 277 6.4.1 Elliptic cap model 279 6.5 Stress-strain relations 279 6.5 Stiffness formulation 280 6.6.1 General description 280 6.6.2 Stiffness coefficients 282 6.7 Cap model in fitting procedure 285 6.7.1 Stress paths in experiments 285 6.7.2 Determination of material constants 291 6.8 Cap model in simple tests 294 6.8.1 Uniaxial strain test 294			261
6.1 Introduction 263 6.2 Historical developments 266 6.2.1 Cambridge models (concept of critical state) 267 6.2.2 Cap models 270 6.3 Modified Cam-clay model 272 6.4 Generalized cap models 277 6.4.1 Elliptic cap model 277 6.4.2 Simple plane cap model 279 6.5 Stress-strain relations 279 6.6 Stiffness formulation 280 6.6.1 General description 280 6.6.2 Stiffness coefficients 282 6.7 Cap model in fitting procedure 285 6.7.1 Stress paths in experiments 285 6.7.2 Determination of material constants 291 6.8 Cap model in simple tests 294 6.8.1 Uniaxial strain test 294	Part	III: Material nonlinearity—Cap models	201
6.1 Introduction 263 6.2 Historical developments 266 6.2.1 Cambridge models (concept of critical state) 267 6.2.2 Cap models 270 6.3 Modified Cam-clay model 272 6.4 Generalized cap models 277 6.4.1 Elliptic cap model 277 6.4.2 Simple plane cap model 279 6.5 Stress-strain relations 279 6.6 Stiffness formulation 280 6.6.1 General description 280 6.6.2 Stiffness coefficients 282 6.7 Cap model in fitting procedure 285 6.7.1 Stress paths in experiments 285 6.7.2 Determination of material constants 291 6.8 Cap model in simple tests 294 6.8.1 Uniaxial strain test 294			
6.2 Historical developments 266 6.2.1 Cambridge models (concept of critical state) 267 6.2.2 Cap models 270 6.3 Modified Cam-clay model 272 6.4 Generalized cap models 277 6.4.1 Elliptic cap model 277 6.4.2 Simple plane cap model 279 6.5 Stress-strain relations 279 6.6 Stiffness formulation 280 6.6.1 General description 280 6.6.2 Stiffness coefficients 282 6.7 Cap model in fitting procedure 285 6.7.1 Stress paths in experiments 285 6.7.2 Determination of material constants 291 6.8 Cap model in simple tests 294 6.8.1 Uniaxial strain test 294	Cha	ter 6 CAP MODEL FORMULATION AND CALIBRATION	
6.2 Historical developments 266 6.2.1 Cambridge models (concept of critical state) 267 6.2.2 Cap models 270 6.3 Modified Cam-clay model 272 6.4 Generalized cap models 277 6.4.1 Elliptic cap model 277 6.4.2 Simple plane cap model 279 6.5 Stress-strain relations 279 6.6 Stiffness formulation 280 6.6.1 General description 280 6.6.2 Stiffness coefficients 282 6.7 Cap model in fitting procedure 285 6.7.1 Stress paths in experiments 285 6.7.2 Determination of material constants 291 6.8 Cap model in simple tests 294 6.8.1 Uniaxial strain test 294	61	Introduction	263
6.2.1 Cambridge models (concept of critical state) 267 6.2.2 Cap models 270 6.3 Modified Cam-clay model 272 6.4 Generalized cap models 277 6.4.1 Elliptic cap model 277 6.4.2 Simple plane cap model 279 6.5 Stress-strain relations 279 6.6 Stiffness formulation 280 6.6.1 General description 280 6.6.2 Stiffness coefficients 282 6.7 Cap model in fitting procedure 285 6.7.1 Stress paths in experiments 285 6.7.2 Determination of material constants 291 6.8 Cap model in simple tests 294 6.8.1 Uniaxial strain test 294		Historical developments	266
6.2.2 Cap models 270 6.3 Modified Cam-clay model 272 6.4 Generalized cap models 277 6.4.1 Elliptic cap model 277 6.4.2 Simple plane cap model 279 6.5 Stress-strain relations 279 6.6 Stiffness formulation 280 6.6.1 General description 280 6.6.2 Stiffness coefficients 282 6.7 Cap model in fitting procedure 285 6.7.1 Stress paths in experiments 285 6.7.2 Determination of material constants 291 6.8 Cap model in simple tests 294 6.8.1 Uniaxial strain test 294	•	6.2.1 Cambridge models (concept of critical state)	267
6.3 Modified Cam-clay model 272 6.4 Generalized cap models 277 6.4.1 Elliptic cap model 277 6.4.2 Simple plane cap model 279 6.5 Stress-strain relations 279 6.6 Stiffness formulation 280 6.6.1 General description 280 6.6.2 Stiffness coefficients 282 6.7 Cap model in fitting procedure 285 6.7.1 Stress paths in experiments 285 6.7.2 Determination of material constants 291 6.8 Cap model in simple tests 294 6.8.1 Uniaxial strain test 294			270
6.4.1 Elliptic cap model 277 6.4.2 Simple plane cap model 279 6.5 Stress-strain relations 279 6.6 Stiffness formulation 280 6.6.1 General description 280 6.6.2 Stiffness coefficients 282 6.7 Cap model in fitting procedure 285 6.7.1 Stress paths in experiments 285 6.7.2 Determination of material constants 291 6.8 Cap model in simple tests 294 6.8.1 Uniaxial strain test 294	6.3	Modified Cam-clay model	272
6.4.1 Elliptic cap model 277 6.4.2 Simple plane cap model 279 6.5 Stress-strain relations 279 6.6 Stiffness formulation 280 6.6.1 General description 280 6.6.2 Stiffness coefficients 282 6.7 Cap model in fitting procedure 285 6.7.1 Stress paths in experiments 285 6.7.2 Determination of material constants 291 6.8 Cap model in simple tests 294 6.8.1 Uniaxial strain test 294		Generalized cap models	277
6.4.2 Simple plane cap model 279 6.5 Stress-strain relations 279 6.6 Stiffness formulation 280 6.6.1 General description 280 6.6.2 Stiffness coefficients 282 6.7 Cap model in fitting procedure 285 6.7.1 Stress paths in experiments 285 6.7.2 Determination of material constants 291 6.8 Cap model in simple tests 294 6.8.1 Uniaxial strain test 294		6.4.1 Elliptic cap model	
6.6 Stiffness formulation 280 6.6.1 General description 280 6.6.2 Stiffness coefficients 282 6.7 Cap model in fitting procedure 285 6.7.1 Stress paths in experiments 285 6.7.2 Determination of material constants 291 6.8 Cap model in simple tests 294 6.8.1 Uniaxial strain test 294		6.4.2 Simple plane cap model	
6.6.1 General description 280 6.6.2 Stiffness coefficients 282 6.7 Cap model in fitting procedure 285 6.7.1 Stress paths in experiments 285 6.7.2 Determination of material constants 291 6.8 Cap model in simple tests 294 6.8.1 Uniaxial strain test 294	6.5	Stress-strain relations	
6.6.2 Stiffness coefficients 282 6.7 Cap model in fitting procedure 285 6.7.1 Stress paths in experiments 285 6.7.2 Determination of material constants 291 6.8 Cap model in simple tests 294 6.8.1 Uniaxial strain test 294	6.6	Stiffness formulation	
6.7 Cap model in fitting procedure 285 6.7.1 Stress paths in experiments 285 6.7.2 Determination of material constants 291 6.8 Cap model in simple tests 294 6.8.1 Uniaxial strain test 294			
6.7.1 Stress paths in experiments 285 6.7.2 Determination of material constants 291 6.8 Cap model in simple tests 294 6.8.1 Uniaxial strain test 294		6.6.2 Stiffness coefficients	
6.7.2 Determination of material constants 291 6.8 Cap model in simple tests 294 6.8.1 Uniaxial strain test 294	6.7	Cap model in fitting procedure	
6.8 Cap model in simple tests		The second of th	
6.8.1 Uniaxial strain test			
6.8.1 Uniaxial strain test	6.8	Cap model in simple tests	
6.8.2 Isotropic consolidation test			
		6.8.2 Isotropic consolidation test	296

y.	6.8.3 Drained triaxial shear test	297
P.	6.8.4 Undrained triaxial shear test	301
6.9		309
6.10	Cap model in Boston Blue Clay	317
•	6.10.1 Simulation of pore pressure	318
	6.10.2 Comments on simulation of undrained response by Cap model	319
	6.10.3 Model calibration	320
	6.10.4 Analyses of three embankments	333
	6.10.5 Concluding remarks	345
6.11		346
V. 1	References	347
		•
Cha	pter 7 CAP MODEL IMPLEMENTATION AND PREDICTIONS	
•	• '	
7.1	Introduction	351
7.2	General implementation of elastic-plastic models	353
.,	7.2.1 Elastic stress increment	353
	7.2.2 Scaling factor	354
	7.2.3 Plastic stress increment	356
	7.2.4 Stress scaling back to yield surface	356
7.3	Implementation of Coulomb and Drucker-Prager models	358
	7.3.1 Implementation for mid-increment	358
	7.3.2 Implementation for full increment	368
	7.3.3 Two-dimensional finite-element subroutine	370
	7.3.4 Utilization of the model subroutine	382
7.4	Uniaxial strain behavior: demonstration of SUBROUTINE CDPMDL	383
	7.4.1 Initialization of input data	383
	7.4.2 Calculation step	385
	7.4.3 Numerical results	386
7.5	Implementation of cap models	393
7.5	7.3.1 Loading functions	393 394
	7.5.2 Elastic trial stresses	394
	7.5.3 Elastic coding	
	7.5.4 Viold confere and inc	397
	7.5.4 Yield surface coding	398
	7.5.5 Corner coding	402
	7.5.6 Hardening surface coding	405
	75.7 Tensile coding	410
	7.5.8 Model subroutine	411
7.6	Uniaxial strain behavior: demonstration of SUBROUTINE CAPMDL	422
	7.6.1 Input data	422
	7.6.2 Numerical results	423
7.7	Summary	429
	References	431
Part	IV: Geometric monlinearity — Large-deformation analyses	433
Chap	New 8 LARGE-DEFORMATION FORMULATION AND SIMPLIFICATION	
8.1	Introduction	435
8.2		436
	8.2.1 Small strains	436
0 4	8.2.2 Finite strains	442
5.3	Rate of deformation and strain rates	454

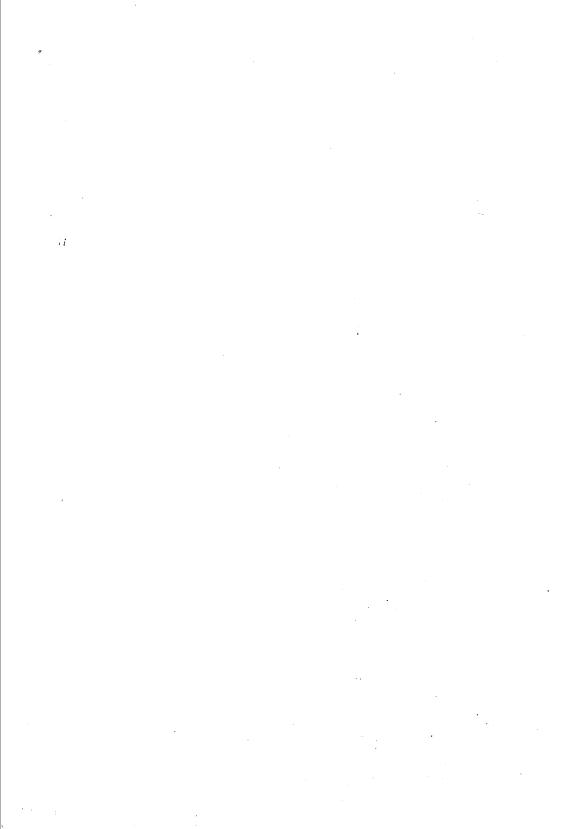
X . . .

8.4	Measures of stress
	8.4.1 Stress tensors:
•	8.4.2 Stress rates
8.5	Virtual work equation
	8.5.1 Total Lagrangian description in general
	8.5.2 Updated Lagrangian description in general
8.6	Constitutive relations for large-deformation formulations
0.0	8.6.1 Constitutive relation for total Lagrangian formulation
	8.6.2 Constitutive relation for updated Lagrangian formulation
8.7	Updated Lagrangian formulation and simplification
0.7	8.7.1 Mixed incremental formulation
	8.7.2 Linearized incremental equation (large strain and large rotation)
	8.7.3 Linearized incremental equation (small strain and large rotation)
8.8	Summary
	References
Chap	ter 9 LARGE-DEFORMATION IMPLEMENTATION AND PREDICTIONS
9.1	Introduction
9.2	Displacement models and shape functions
	9.2.1 Generalized coordinate displacement model
	9.2.2 Interpolation displacement model
	9.2.3 Shape functions for various finite elements
9.3	
7.3	Incremental finite-element equations
	9.3.1 General equation based on total Lagrangian description
	9.3.2 General equation based on updated Lagrangian description
	9.3.3 Updated Lagrangian formulation equation
9.4	Numerical procedures for elastic-plastic problems
	9.4.1 Incremental procedure
	9.4.2 Iterative procedure
	9.4.3 Iterative solution techniques
	9.4.4 Applicability of the finite-element method
9.5	Large-deformation finite-element predictions of vertical slope
	9.5.1 Analyses of vertical slopes with Drucker-Prager models
	9.5.2 Load-displacement curves
	9.5.3 Deformed shape
	9.5.4 Limit loads
	9.5.5 Stress distributions
	9.5.6 Yielded zones
	957 Valority fields
	9.5.7 Velocity fields
9.6	9.5.8 Concluding remarks
7.0	Summary
	References
Part '	V: Case study
	•
	ter 10 CASE STUDIES
Chap	
	Introduction
l0.1	Introduction
l0.1	Example I. Flexible and smooth strip footings on stratum of clay
10.1 10.2	Example I. Flexible and smooth strip footings on stratum of clay 10.2.1 Drucker-Prager models with different material constants
10.1 10.2	Example I. Flexible and smooth strip footings on stratum of clay 10.2.1 Drucker-Prager models with different material constants 10.2.2 Drucker-Prager models with non-associated flow rule
10.1 10.2	Example I. Flexible and smooth strip footings on stratum of clay 10.2.1 Drucker-Prager models with different material constants
10.1 10.2	Example I. Flexible and smooth strip footings on stratum of clay 10.2.1 Drucker-Prager models with different material constants 10.2.2 Drucker-Prager models with non-associated flow rule
10.1 10.2	Example I. Flexible and smooth strip footings on stratum of clay 10.2.1 Drucker-Prager models with different material constants 10.2.2 Drucker-Prager models with non-associated flow rule

10.5	Example II. Rigid and rough strip footings on stratum of clay
	10.3.1 Drucker-Prager models
	10.3.2 Cap models
10.4	Example III. Seismic analyses of slopes
	10.4.1 Prior to seismic loadings
	10.4.2 During seismic loadings
	10.4.3 After slidings
0.5	Summary
	References

Part I

FUNDAMENTALS



INTRODUCTION

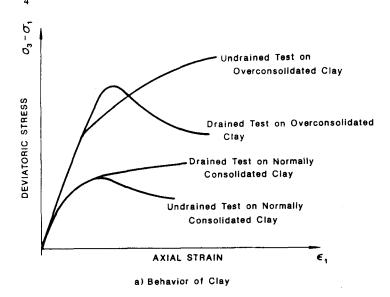
1.1 INTRODUCTION

For a long time, soil mechanics has been based on Hooke's law of linear elasticity for stress and deformation analysis for a soil mass under a footing, or behind a retaining wall, when no failure of the soil is involved. This is known as the *elasticity* problem in soil mechanics. On the other hand, the theory of perfect plasticity is used to deal with the conditions of ultimate failure of a soil mass. Problems of earth pressure, retaining walls, bearing capacity of foundations, and stability of slopes are all considered in the realm of perfect plasticity. These are called *stability problems*. Long-term settlement problems and consolidation problems, however, are treated in soil mechanics as essentially viscoelastic problems.

Partly for simplicity in practice and partly because of the historical development of mechanics of solids, the elasticity problems and the stability problems in soil mechanics are treated separately and in unrelated ways. The essential connection between the elasticity problems and the stability problems is known as the progressive failure problems. The progressive failure problems deal with the elastic-plastic transition from the initial linear elastic state to the ultimate state of the soil by plastic flow. The essential set of equations for the solutions of progressive failure problems is the constitutive equations of soils, which give a unique relationship of stress and strain for different geotechnical materials. These relationships and applications to soils and rocks are discussed in the following Chapters.

1.2 CHARACTERISTICS OF SOIL BEHAVIOR

Some typical stress-strain curves for soils in the triaxial tests are shown in Fig. 1.1. As can be seen from Fig. 1.1a, the relation of the deviatoric stress σ_3 - σ_1 v.s. axial strain ϵ_1 for a normally consolidated clay in a drained test is characterized by a nonlinear response curve which rises at a slower rate after reaching a certain stress level. Here, the further straining is always associated with an increase in stress. This phenomenon is known as strain-hardening. The stress-strain curve for overconsolidated clay in an undrained test exhibits the same behavior as that of normally consolidated clay in a drained test. The overconsolidated clay in a drained test and normally consolidated clay in an undrained test behave differently from those mentioned above. The stress-strain curves both have a clearly defined peak occurring at a low strain level. An element of these clays, strained beyond the strain



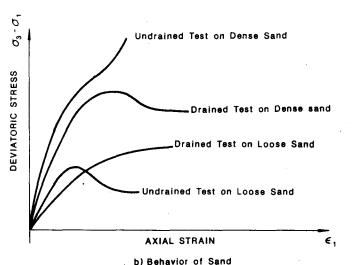


Fig. 1.1. Typical soil stress-strain curves.

corresponding to the peak stress point, becomes weaker than it was at this peak point. This phenomenon is known as *strain-softening*.

Similar conclusions can be made from Fig. 1.1b for the behavior of sand. Dense sand in an undrained test and loose sand in a drained test show the strain-hardening. Dense sand in a drained test and loose sand in an undrained test show a peak

stress followed by strain-softening to a residual stress. The behavior of dense sand in a drained test is similar to that of overconsolidated clay in a drained test. The similar behavior also occurs in the other corresponding cases for clay and sand.

1.3 IDEALIZATIONS AND MATERIAL MODELING

The typical stress-strain behavior of soils presented in the previous Section is not linearly elastic for the entire range of loading of practical interest. In fact, actual behavior of soils is much complicated and they show a great variety of behavior when subjected to different conditions. Drastic idealizations are therefore essential in order to develop simple mathematical models for practical applications. No mathemetical model can completely describe the complex behavior of real soils under all conditions. Each soil model aims at a certain class of phenomena, captures their essential features, and disregards what is considered to be of minor importance in that class of applications. Thus, this constitutive model meets its limits of applicability where a disregarded influence becomes important. As mentioned previously, Hooke's law has been used successfully in soil mechanics to describe the general behavior of soil media under short-term working load condition, but it fails to predict the behavior and strength of a soil-structure interaction problem near ultimate strength condition, because plastic deformation at this load level attains a dominating influence, while elastic deformation becomes of minor importance.

Under a short-term loading, soil behavior may be idealized as time-independent where the effects of time can be neglected. This time-independent idealization of soils can be further idealized as elastic behavior and plastic behavior. As the first step in constitutive modeling of soils, it is therefore logical to utilize and refine the classical theories of elasticity and plasticity as developed for such an idealized material. However, there are in many cases considerable differences between the properties of soils and those of the idealized bodies. These differences may have a significant influence on the solution of some boundary value problems in soil mechanics. In such cases, the classical theories must be modifed and extended so that the special properties of soils in certain practical applications are taken into consideration.

A material for which there exists a one-to-one coordination between stress and strain is known as elastic material. Thus, a body that consists of this idealized material returns to its original shape whenever all stresses are reduced to zero. The linear theory of elasticity used most commonly is the Hooke type or Cauchy type of constitutive models for soils, in spite of its obvious shortcomings. These linear elastic models can be significantly improved by assuming bilinear or higher polynomial type of nonlinear fit for the stress-strain relationship of soil in the form of secant formulations. This is known as the Hooke type or Cauchy type of elastic formulation. These types of elastic models must be combined with criteria defining "failure" of the soil.

In a more restricted sense, an elastic material must satisfy the energy equation of thermodynamics. The elastic material characterized by this additional requirement is known as hyperelastic material. On the other hand, the minimal requirement for a material to qualify as elastic in any sense is that there exists a one-to-one coordination between stress increment and strain increment. Thus, a body that consists of this material returns to its original state of deformation whenever all stress increments are reduced to zero. This reversibility in the infinitesimal sense justifies the use of the term hypoelastic for elastic materials satisfying only this minimal requirement. The incremental constitutive formulations based on hypoelastic models have been increasingly used in recent years by geotechnical engineers for soils in which the state of stress is generally a function of the current state of stresses and strains as well as of the stress path followed to reach that state (Chen and Saleeb, 1982).

The elastic modeling in the form of secant or incremental formulations can be quite accurate for soils sustaining proportional loading. However, this reversibility associated with these formulations is not the case for a plastic material. Thus, these formulations fail to identify plastic deformations when unloading occurs. This can, to some extent, be rectified by introducing loading criteria as in the deformation theory of plasticity. Although the deformation theory and the existence of loading function are incompatible even in the most limited sense, it is still a very attractive alternative for solution of large classes of soil and soil-structure interaction problems, because of its simplicity.

The flow theory of plasticity represents a necessary and correct extension of elastic stress-strain relations into the plastic range at which permanent plastic strain is possible in addition to elastic strain. This plastic strain remains when the stresses are removed. Thus, the strain in a plastic material may be considered as the sum of the reversible elastic strain and the permanent irreversible plastic strain. Since an elastic stress-strain law as mentioned above is usually assumed to provide the relation between the incremental changes of stress and elastic strain, the stress-strain law for a plastic material reduces, essentially, to a relation involving the current state of stresses and strains and the incremental changes of stress and plastic strain. This relation is generally assumed to be homogeneous and linear in the incremental changes of the components of stress and plastic strain. This assumption precludes viscosity effects and thus constitutes the time-independent idealization.

The first step towards such a mathematical model is to establish the yield limit of an elastic material. This is known as the yield function which is a certain function of the stress components. A plastic material is called perfectly plastic or work-hardening or softening according to whether the yield function as represented by a certain hypersurface in six-dimensional stress space is fixed or it admits changes (expansion or contraction) as plastic strain develops. For moderate strains, mild steel behaves approximately like a perfectly plastic material. It is therefore not surprising that in early years (1950–1965) this perfect plasticity model was used almost exclusively and extensively in the analysis and design of steel structures because of its simplicity. The general theorems of limit analysis, developed on the basis of perfect