# Handbook of Moduli

(VolumeII)

模手册(卷Ⅱ)

Editors: Gavril Farkas · Ian Morrison





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Editors: Gavril Farkas · Ian Morrison

常州大学山书馆 藏 书 章

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# Parameter spaces of curves

## Joe Harris

**Abstract.** In this article I will try to survey the state of our knowledge (and the much greater area of our ignorance) of the geometry of spaces parametrizing curves in projective space.

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#### 1. Introduction

Robin Hartshorne, in [6], describes the problem of classifying algebraic varieties as the guiding problem of algebraic geometry. I'd agree, for the most part; and, since you're currently reading a book entitled "Handbook of Moduli," presumably you would too.

But the question remains: what exactly are we classifying? To be specific, consider the problem of smooth, complete algebraic curves over  $\mathbb{C}$ . If you ask mathematicians today to describe the problem of classifying curves, they would naturally take "curve" to mean "abstract curve," in which case the answer to the problem, "classify all smooth complete curves" would consist of two parts. Algebraic

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curves are classified first by their sole discrete numerical invariant, the genus, which can assume any value  $g \in \mathbb{N}$ ; and the set of curves of a given genus g has naturally the structure of an irreducible quasi-projective variety  $M_g$ . Beyond this, the problem of classifying algebraic curves consists of studying the geometry of the variety  $M_g$ , and of relating properties of curves to the loci in  $M_g$  of curves with that property.

If you had posed the same question to an algebraic geometer of the 19<sup>th</sup> century, however, it would of necessity have been interpreted differently. Abstract curves didn't exist then (or, depending on your philosophical point of view, they hadn't been discovered); the word "curve" would have been taken to mean a subset of projective space defined by polynomial equations, smooth and irreducible of dimension 1. As such, a curve had not one but three numerical invariants: its degree d; the dimension r of the projective space in which it lay (or, more properly, the dimension of its span); and of course its genus. The problem of classifying all algebraic curves would thus amount to two things:

- (1) To say for which triples g, r and d there exists a smooth, irreducible and nondegenerate curve of degree d and genus g in  $\mathbb{P}^r$ ; and
- (2) To describe, for each such triple (g, r, d), the geometry of the space  $\mathcal{H}_{g,r,d}^{\circ}$  parametrizing such curves: its irreducible components, their dimensions and so on.

In this volume, there are many articles that address aspects of the problem of classification in its modern sense. But the classical version is still very much of interest, and has many fascinating aspects that are not fully understood: we haven't answered the first of the questions above; and we know the answer to the second only in an extremely limited range of cases. The goal of this article is to give a survey of what we do know about this problem, and likewise to suggest some of the numerous open problems.

The remainder of this paper will consist of three parts. In Section 2, we'll discuss the notion of parameter spaces of curves, and compare the two most commonly used such spaces, primarily the Hilbert scheme and the Kontsevich space. This may in a sense not be necessary if we're only concerned with smooth, irreducible curves in projective space, since the Hilbert scheme and the Kontsevich space have a common open subset parametrizing such curves (and indeed the reader can skip this section and go directly to the following ones). But for many purposes it's useful to have a compactification of the space of curves, and here the Hilbert scheme and the Kontsevich space differ dramatically, as we'll see.

In Section 3, we'll describe the conjectured answer to the Existence Problem, the first of the two questions listed above. This actually tells us a lot about curves of high genus: when g is more than roughly half the maximal possible genus of an irreducible, nondegenerate curve of degree d in  $\mathbb{P}^r$ , in addition to simply saying which triples (g, r, d) occur, we learn about the geometry of such curves, and the dimension

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and irreducible components of their families. But for g below this bound, all we can say is that such curves exist; we can't say much about the spaces parametrizing them

Finally, in Section 4, we address this issue. We can in fact give a pretty explicit description of the spaces of curves of low genus, using what we know about the moduli space of abstract curves and Brill-Noether theory. Again, our knowledge—even conjectured—drops off as we approach the middle range of possible genera; we'll try to indicate what are some of the main unresolved questions in this area.

### 2. Parameter spaces

First of all, some terminology. We propose to call a space whose points correspond naturally to isomorphism classes of varieties or schemes X of a given type a moduli space; we'll call a space whose points correspond naturally to subschemes  $X \subset Z$  of a fixed scheme Z (not up to isomorphism) a parameter space. There is not always a clear line dividing the two—for example, the Kontsevich space parameterizing stable maps has elements of both—but it does reflect an important duality in how we view geometric objects. One of the fundamental ideas underlying much recent progress in the theory of curves, for example, is the fact that whenever we have a one-parameter family  $\{C_t \subset \mathbb{P}^r\}_{t \in \Delta}$  of curves in projective space, with  $C_t$ smooth for  $t \neq t_0$ , we have two distinct notions of the "limit"  $\lim_{t \to t_0} C_t$  of the curves  $C_t$ : the flat limit, which is a subscheme of  $\mathbb{P}^r$  whose geometry can be pretty much arbitrarily messy; and the stable limit, which is the limit of the abstract curves C<sub>t</sub> and has at worst nodes as singularities. (Other articles in this volume discuss alternative notions of stability, and correspondingly alternative definitions of the limit of the abstract curves C<sub>t</sub>; as for the flat limit, we really don't have much of an alternative to that.)

That said, what should we take as the parameter space for curves of degree d and genus g in  $\mathbb{P}^r$ ? There are principally three answers to this question: the *Chow variety*, the *Hilbert scheme* and the *Kontsevich space*. These agree on the common open subset  $\mathcal{H}_{g,r,d}^{\circ}$  parametrizing smooth curves (at least if we ignore the scheme structure on these spaces), but give very different compactifications of  $\mathcal{H}_{g,r,d}^{\circ}$ . Now, the questions we raised earlier—when do there exist such curves  $C \subset \mathbb{P}^r$ , what are the irreducible components of  $\mathcal{H}_{g,r,d}^{\circ}$  and what are their dimensions—really don't depend on the choice of compactification, as long as we restrict our attention to the closure of  $\mathcal{H}_{g,r,d}^{\circ}$  in each. But for many other questions it is important to have a complete parameter space, and so we start with a brief discussion of the properties of each. Actually, we'll pretty much ignore the Chow variety—in many ways, it has all the drawbacks of the Hilbert scheme and the Kontsevich space, and none of the virtues—and focus primarily on the other two.

The following discussion is adapted from a forthcoming book, 3264 and All That: Intersection Theory in Algebraic Geometry, by the author and David Eisenbud.