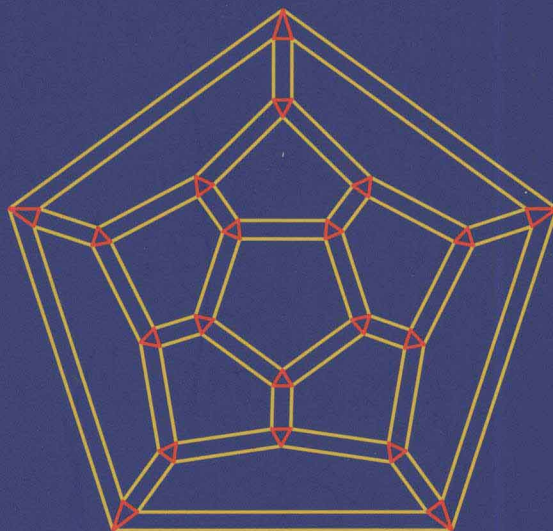


EMS Textbooks in Mathematics

Oleg Bogopolski

# Introduction to Group Theory



European Mathematical Society

**Oleg Bogopolski**

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European Mathematical Society

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# Preface

This English edition differs from the Russian original by the addition of a new chapter. In this new Chapter 3 we give an account of the theory of train tracks for automorphisms of free groups, which was developed in the seminal paper of M. Bestvina and M. Handel [9]. Our exposition is more algebraic than in this paper, but it is less technical than the account in the book [29] of W. Dicks and E. Ventura. In Section 10 of Chapter 3 we consider two examples in detail. We have added an appendix containing the famous Perron–Frobenius Theorem on nonnegative matrices, which is used in this chapter. Also we have added solutions to selected exercises.

The reader is assumed to have the knowledge of algebra expected after the first semester of university (permutations, fields, matrices, vector spaces; see [23], [39] or [55]).

My sincere thanks go to Derek Robinson for invaluable help with the translation of this book and for useful comments that helped to improve the exposition. I also like to thank Hans Schneider and Enric Ventura for their suggestions on the improvement of the appendix and Chapter 3. Last but not least, I thank my wife Marie-Theres for her constant support.

Dortmund, January 2008

O. Bogopolski

## Preface to the Russian Edition

This book is an extended version of a course given by me at Novosibirsk University from 1996 to 2001. The purpose of the book is to present the fundamentals of group theory and to describe some nontrivial constructions and techniques, which will be useful to specialists. The fundamentals are given in Sections 1–9 of Chapter 1; also one can read Chapters 1 and 2 independently.

In Chapter 1 we quickly introduce beginners to the classification of finite simple groups. It is shown that such complicated combinatorial objects as the Mathieu group  $M_{22}$  and the Higman–Sims group  $HS$  have a natural geometric description. In Section 17 we describe the relationship between Mathieu groups and Steiner systems with coding theory.

In Chapter 2 we describe the Bass–Serre theory of groups acting on trees. This theory gives a clear and natural explanation of many results about free groups and free constructions. We also explain the theory of coverings: the attentive reader will see a bridge from one theory to the other. I hope that numerous examples, exercises and figures will help to give a deeper understanding of the subject.

The reader is assumed to have the knowledge of algebra expected after the first semester of university (permutations, fields, matrices, vector spaces; see [39]). In addition, the fundamentals of group theory (especially abelian, nilpotent and solvable groups) can be read in the excellent book of M. I. Kargapolov and Ju. I. Merzljakov [38].

I thank many colleagues whose comments helped to improve the content and exposition of the material presented in this book. In particular I thank V. G. Bardakov, A. V. Vasiljev, E. P. Vdovin, A. V. Zavarnitzin, V. D. Mazurov, D. O. Revin, O. S. Tishkin and V. A. Churkin.

I thank M.-T. Bochnig for the help in designing this book.

Novosibirsk, May 11, 2002

O. Bogopolski



A tree in the neighborhood of Sprockhövel (Germany)

# Contents

Preface	v
Preface to the Russian Edition	vi
<b>1 Introduction to finite group theory</b>	<b>1</b>
1 Main definitions . . . . .	1
2 Lagrange's theorem. Normal subgroups and factor groups . . . .	4
3 Homomorphism theorems . . . . .	6
4 Cayley's theorem . . . . .	7
5 Double cosets . . . . .	9
6 Actions of groups on sets . . . . .	10
7 Normalizers and centralizers. The centers of finite $p$ -groups . . .	12
8 Sylow's theorem . . . . .	13
9 Direct products of groups . . . . .	15
10 Finite simple groups . . . . .	16
11 The simplicity of the alternating group $A_n$ for $n \geq 5$ . . . . .	18
12 $A_5$ as the rotation group of an icosahedron . . . . .	19
13 $A_5$ as the first noncyclic simple group . . . . .	20
14 $A_5$ as a projective special linear group . . . . .	22
15 A theorem of Jordan and Dickson . . . . .	23
16 Mathieu's group $M_{22}$ . . . . .	25
17 The Mathieu groups, Steiner systems and coding theory . . . . .	32
18 Extension theory . . . . .	35
19 Schur's theorem . . . . .	37
20 The Higman–Sims group . . . . .	39
<b>2 Introduction to combinatorial group theory</b>	<b>45</b>
1 Graphs and Cayley's graphs . . . . .	45
2 Automorphisms of trees . . . . .	50
3 Free groups . . . . .	52
4 The fundamental group of a graph . . . . .	56
5 Presentation of groups by generators and relations . . . . .	58
6 Tietze transformations . . . . .	60
7 A presentation of the group $S_n$ . . . . .	63
8 Trees and free groups . . . . .	64
9 The rewriting process of Reidemeister–Schreier . . . . .	69
10 Free products . . . . .	71
11 Amalgamated free products . . . . .	72



12	Trees and amalgamated free products . . . . .	74
13	Action of the group $SL_2(\mathbb{Z})$ on the hyperbolic plane . . . . .	76
14	HNN extensions . . . . .	81
15	Trees and HNN extensions . . . . .	84
16	Graphs of groups and their fundamental groups . . . . .	84
17	The relationship between amalgamated products and HNN extensions . . . . .	87
18	The structure of a group acting on a tree . . . . .	88
19	Kurosh's theorem . . . . .	92
20	Coverings of graphs . . . . .	93
21	$S$ -graphs and subgroups of free groups . . . . .	96
22	Foldings . . . . .	98
23	The intersection of two subgroups of a free group . . . . .	101
24	Complexes . . . . .	104
25	Coverings of complexes . . . . .	106
26	Surfaces . . . . .	109
27	The theorem of Seifert and van Kampen . . . . .	115
28	Grushko's Theorem . . . . .	115
29	Hopfian groups and residually finite groups . . . . .	117
<b>3</b>	<b>Automorphisms of free groups and train tracks</b>	<b>121</b>
1	Nielsen's method and generators of $Aut(F_n)$ . . . . .	123
2	Maps of graphs. Tightening, collapsing and expanding . . . . .	126
3	Homotopy equivalences . . . . .	128
4	Topological representatives . . . . .	129
5	The transition matrix. Irreducible maps and automorphisms . . . . .	130
6	Train tracks . . . . .	132
7	Transformations of maps . . . . .	132
8	The metric induced on a graph by an irreducible map . . . . .	137
9	Proof of the main theorem . . . . .	138
10	Examples of the construction of train tracks . . . . .	141
11	Two applications of train tracks . . . . .	151
	<b>Appendix. The Perron–Frobenius Theorem</b>	<b>153</b>
	<b>Solutions to selected exercises</b>	<b>157</b>
	<b>Bibliography</b>	<b>169</b>
	<b>Index</b>	<b>173</b>

## Chapter 1

# Introduction to finite group theory

## 1 Main definitions

A *binary operation*  $\cdot$  on a set  $G$  assigns to any two elements  $a, b$  of  $G$  an element of  $G$  denoted by  $a \cdot b$ . A binary operation can be denoted not only by  $\cdot$  but by any other symbol, for example by  $+$ . Usually one writes  $ab$  instead of  $a \cdot b$ .

A set  $G$  with a binary operation is called a *group* if the following holds:

- 1) the operation is *associative*, i.e.,  $(ab)c = a(bc)$  for all  $a, b, c$  in  $G$ ;
- 2) in  $G$  there is an element  $e$  – called the *identity element* – such that  $ae = ea = a$  for all  $a$  in  $G$ ;
- 3) for each  $a$  in  $G$  there is in  $G$  an element  $b$  – called *the inverse* of  $a$  – such that  $ab = ba = e$ .

The identity element can be denoted by  $1$  if the operation is denoted by  $\cdot$ , and it can be denoted by  $0$  if the operation is denoted by  $+$ .

**1.1 Exercise.** 1) The identity element of any group  $G$  is unique. Each element  $a$  in  $G$  has a unique inverse (denoted by  $a^{-1}$ ).

2) For any element  $a$  in  $G$ , the mapping  $\varphi_a: G \rightarrow G$  given by the rule  $\varphi_a(g) = ag$  ( $g \in G$ ) is a bijection.

A group is called *trivial* if it only contains the identity element.

A group  $G$  is called *abelian* or *commutative* if  $ab = ba$  for any  $a, b$  in  $G$ . The set  $\mathbb{Z}$  of integers with the usual addition is an abelian group. Examples 1.3 show that there exist nonabelian groups.

Two groups  $G$  and  $G_1$  are called *isomorphic* (one writes  $G \cong G_1$ ) if there exists an *isomorphism*  $\varphi: G \rightarrow G_1$ , i.e., a bijection  $\varphi$  from  $G$  onto  $G_1$  such that  $\varphi(ab) = \varphi(a)\varphi(b)$  for all  $a, b$  in  $G$ .

Thanks to the associative law for groups, the product  $a_1 a_2 \dots a_n$  of  $n$  elements of a group does not depend on the bracketing. The product of  $n$  elements all equal to  $a$  is denoted by  $a^n$ . We define  $a^0 = e$  and  $a^m = (a^{-1})^{-m}$  for negative integers  $m$ .

If  $a^n = e$  for some  $n > 0$ , then the smallest  $n$  with this property is called the *order of the element*  $a$  and is denoted by  $|a|$ . If  $a^n \neq e$  for every  $n > 0$ , we say that  $a$  has *infinite order* and write  $|a| = \infty$ . The cardinality  $|G|$  of a group  $G$  is called the *order* of  $G$ . If this cardinality is finite, then we say that the group is *finite*, and in the contrary case *infinite*. A finite group  $G$  is called a *p-group* if  $|G| = p^k$  for a prime number  $p$  and an integer  $k \geq 1$ .

**1.2 Exercise.** 1) If  $a^n = e$ , then  $|a|$  divides  $n$ .

2) If  $a$  and  $b$  commute, that is  $ab = ba$ , and their orders are relatively prime, then  $|ab| = |a| \cdot |b|$ .

A nonempty subset  $H$  of a group  $G$  is called a *subgroup* of  $G$  if for any  $a, b$  from  $H$  the elements  $ab$  and  $a^{-1}$  also lie in  $H$ . In that case we write  $H \leq G$ . A subgroup  $H$  of a group  $G$  is itself a group under the restriction of the operation of the group  $G$ . If  $H \leq G$  and  $H \neq G$ , then  $H$  is called a *proper* subgroup of  $G$ ; in symbols  $H < G$ .

Following the terminology of the textbooks [39], [55], we use the following rule for composition of two mappings:  $(fg)(x) = f(g(x))$ . Thus we multiply permutations from the right to the left.

**1.3 Examples.** 1) An *isometry* of the Euclidean plane is any mapping of the plane onto itself, preserving the distances between any two points.

Let  $F$  be a figure in the Euclidean plane. The set of all isometries of the plane, sending  $F$  onto itself, is a group under the composition of isometries. This group is called the *symmetry group* of  $F$ .

Let  $P_n$  be a regular  $n$ -gon. The symmetry group of  $P_n$  has exactly  $2n$  elements:  $n$  clockwise rotations through the angles  $\frac{2\pi k}{n}$  ( $k = 0, 1, \dots, n-1$ ) about the center of  $P_n$  and  $n$  reflections across the lines, passing through its center and one of its vertices, or through its center and the middle point of one of its sides. All rotations in the symmetry group of  $P_n$  form a subgroup, which is called the *rotation group* of  $P_n$ .

2) The set of all permutations of the set  $\{1, 2, \dots, n\}$  is a group under the usual multiplication of the permutations. This group is called the *symmetric group of degree  $n$*  and is denoted by  $S_n$ . All even permutations in  $S_n$  form a subgroup which is denoted by  $A_n$  and is called the *alternating group of degree  $n$* . The order of the group  $S_n$  is  $n!$  and the order of the group  $A_n$  is  $n!/2$  for  $n \geq 2$ .

3) The set  $GL_n(K)$  of all invertible matrices of size  $n \times n$  over a field  $K$  is a group under the usual matrix multiplication. It is called the *general linear group* of degree  $n$  over the field  $K$ . Its subgroup  $SL_n(K)$  consisting of all matrices with determinant 1 is called the *special linear group* of degree  $n$  over  $K$ . The group  $SL_n(K)$  contains a subgroup  $UT_n(K)$  consisting of those matrices with all entries below the main diagonal zero, and with the entries on the main diagonal equal to the identity. This subgroup is called the *unitriangular group* of degree  $n$  over  $K$ .

It is known (see [39] or [55] for example) that a finite field is defined up to an isomorphism by the number of its elements, and this number must be a power of a prime number. Therefore if a field  $K$  contains exactly  $q$  elements, we will write  $GL_n(q)$  instead of  $GL_n(K)$ , and similarly for the other matrix groups.

**1.4 Exercise.** The symmetry group of a regular triangle is isomorphic to the group  $S_3$ .

For any nonempty subset  $M$  of a group  $G$  the set

$$\{a_1^{\epsilon_1} \dots a_m^{\epsilon_m} \mid a_i \in M, \epsilon_i = \pm 1, m = 1, 2, \dots\}$$

forms a subgroup of  $G$ . This subgroup is called the subgroup *generated* by the set  $M$  and is denoted by  $\langle M \rangle$ . It is easily seen that  $\langle M \rangle$  is the smallest subgroup of  $G$  containing the set  $M$ .

For ease of notations we write  $\langle a, b, \dots, c \rangle$  instead of  $\langle \{a, b, \dots, c\} \rangle$  and we say that this subgroup is *generated* by the elements  $a, b, \dots, c$ . Some other simplifications of notations are also allowed. For example, if  $A$  and  $B$  are two subsets of a group  $G$  and  $c$  is an element of  $G$ , then we write  $\langle A, B, c \rangle$  instead of  $\langle A \cup B \cup \{c\} \rangle$ .

A group is called *finitely generated* if it can be generated by a finite number of elements.

A group  $G$  is called *cyclic* if in  $G$  there exists an element  $a$  with  $G = \langle a \rangle$ . In this case  $G = \{a^n \mid n \in \mathbb{Z}\}$ . Notice: it may happen that  $a^n$  coincides with  $a^m$  for some  $n \neq m$ . In that case  $G$  is finite. An example of an infinite cyclic group is the group  $\mathbb{Z}$  of all integers under the usual addition (as  $a$  one can take 1 or  $-1$ ).

Let  $n \geq 1$  be a natural number. To each integer  $i$  there corresponds the remainder on division of  $i$  by  $n$ , i.e., an integer  $\bar{i}$  such that  $0 \leq \bar{i} \leq n-1$  and  $n \mid (i - \bar{i})$ . It is easy to verify that the set  $\mathbb{Z}_n = \{0, 1, \dots, n-1\}$  with the operation  $\oplus$ , defined by the rule  $i \oplus j = \overline{i+j}$ , is a cyclic group generated by 0 if  $n = 1$  and by 1 if  $n > 1$ .

**1.5 Exercise.** The rotation group of a regular  $n$ -gon is isomorphic to the group  $\mathbb{Z}_n$ .

**1.6 Theorem.** Any infinite cyclic group is isomorphic to the group  $\mathbb{Z}$ , and any finite cyclic group of order  $n$  is isomorphic to the group  $\mathbb{Z}_n$ .

*Proof.* Let  $\langle a \rangle$  be an infinite cyclic group. Define a mapping  $\varphi: \mathbb{Z} \rightarrow \langle a \rangle$  by the rule  $\varphi(i) = a^i$ . Clearly,  $\varphi(i+j) = \varphi(i)\varphi(j)$  and  $\varphi$  is onto. Moreover,  $\varphi$  is injective: if we had  $a^i = a^j$  for some  $i < j$ , then  $a^{j-i} = e$  and the group  $\langle a \rangle$  would contain only the elements  $e, a, \dots, a^{j-i-1}$ , which is impossible. Therefore  $\varphi$  is an isomorphism.

If  $\langle a \rangle$  is a cyclic group of order  $n$ , then the mapping  $\varphi: \mathbb{Z}_n \rightarrow \langle a \rangle$ , given by the same rule  $\varphi(i) = a^i$ , is an isomorphism.  $\square$

An arbitrary infinite cyclic group will be denoted by  $Z$  and an arbitrary finite cyclic group of order  $n$  will be denoted by  $Z_n$ .

**1.7 Theorem.** Any subgroup of a cyclic group is cyclic.

*Proof.* Let  $\langle a \rangle$  be a cyclic group. Clearly, the trivial subgroup is cyclic. Let  $H$  be a nontrivial subgroup of  $\langle a \rangle$  and let  $m$  be the smallest positive integer such that  $a^m \in H$ . Clearly  $\langle a^m \rangle \leq H$ . We will prove that  $\langle a^m \rangle = H$ . An arbitrary element of  $H$  has the form  $a^k$ . Dividing  $k$  by  $m$ , we get  $k = mq + r$ ,  $0 \leq r < m$ . Then  $a^r = a^k (a^m)^{-q} \in H$ . By the minimality of  $m$  it follows that  $r = 0$ . Hence  $a^k = (a^m)^q \in \langle a^m \rangle$ .  $\square$

**1.8 Exercise.** 1) The order of any subgroup of  $Z_n$  is a divisor of  $n$ . Moreover, for any divisor  $d$  of  $n$  there exists a unique subgroup of  $Z_n$  of order  $d$ .

2) The number of solutions of the equation  $x^k = 1$  in the group  $Z_n$  is equal to  $\gcd(n, k)$ , the greatest common divisor of  $n$  and  $k$ .

The *center* of a group  $G$  is the subset

$$Z(G) = \{z \in G \mid zg = gz \text{ for all } g \in G\}.$$

Clearly  $Z(G)$  is a subgroup of  $G$  and  $G$  is abelian if and only if  $Z(G) = G$ .

The *commutator* of two elements  $a$  and  $b$  is the element  $aba^{-1}b^{-1}$ . We denote it by  $[a, b]$ . The *commutator subgroup* or *derived subgroup* of a group  $G$  is the subgroup  $G' = \langle [a, b] \mid a, b \in G \rangle$ .

We say that an element  $a$  of a group  $G$  is *conjugate* to an element  $b$  by an element  $g$  if  $a = bgb^{-1}$ . Similarly, we say that a subgroup  $A$  of a group  $G$  is conjugate to a subgroup  $B$  by an element  $g$  if  $A = \{gbg^{-1} \mid b \in B\}$ . This set will be denoted by  $gBg^{-1}$ . It is easy to verify that the orders of conjugate elements (subgroups) are the same.

The *conjugacy class* of an element  $b$  of a group  $G$  is the set of all elements in  $G$  which are conjugate to  $b$ . The group  $G$  is divided into disjoint conjugacy classes, one of them being  $\{e\}$ .

An *automorphism* of a group  $G$  is an isomorphism of  $G$  onto itself. The set of all automorphisms of  $G$  with functional composition is a group, denoted by  $\text{Aut}(G)$ .

**1.9 Exercise.** 1) Prove that  $\text{Aut}(\mathbb{Z}) \cong Z_2$ .

2) Find the center, the commutator subgroup and the conjugacy classes of the permutation group  $S_3$ .

3) Prove that  $S_n = \langle (12), (13), \dots, (1n) \rangle$ .

4) Prove that the group  $\mathbb{Q}$  of rational numbers under addition is not finitely generated.

## 2 Lagrange's theorem. Normal subgroups and factor groups

Let  $H$  be a subgroup of a group  $G$ . The sets  $gH = \{gh \mid h \in H\}$ , where  $g \in G$ , are called *left cosets* of the subgroup  $H$  in the group  $G$ . *Right cosets*  $Hg$  are defined similarly. It is easy to verify that

$$g_1H = g_2H \quad \text{if and only if} \quad g_1^{-1}g_2 \in H.$$

**2.1 Example.** The set of all left cosets of the subgroup  $\{e, (12)\}$  in the group  $S_3$  consists of

$$\{e, (12)\}, \quad \{(13), (123)\}, \quad \{(23), (132)\}.$$

The set of all right cosets of the subgroup  $\{e, (12)\}$  in the group  $S_3$  consists of

$$\{e, (12)\}, \quad \{(13), (132)\}, \quad \{(23), (123)\}.$$

The correspondence  $xH \leftrightarrow Hx^{-1}$  is one-to-one, and therefore the cardinality of the set of left cosets of  $H$  coincides with the cardinality of the set of right cosets of  $H$ . This cardinality is called the *index* of the subgroup  $H$  in the group  $G$  and is denoted by  $|G : H|$ .

**2.2 Theorem** (Lagrange). *If  $H$  is a subgroup of a finite group  $G$ , then*

$$|G| = |H| \cdot |G : H|.$$

*Proof.* Since  $g \in gH$ , the group  $G$  is the union of the left cosets of  $H$  in  $G$ . Any two different cosets have empty intersection: if  $g_1H \cap g_2H \neq \emptyset$ , then  $g_1h_1 = g_2h_2$  for some  $h_1, h_2 \in H$  and so  $g_1H = g_2h_2h_1^{-1}H = g_2H$ . It remains to notice that these left cosets have the same cardinality: a bijection  $H \rightarrow gH$  is given by the rule  $h \mapsto gh, h \in H$ .  $\square$

**2.3 Corollary.** 1) *The order of an element of a finite group divides the order of this group.*

2) *Any group of prime order  $p$  is isomorphic to the group  $Z_p$ .*

*Proof.* If  $g$  is an element of a finite group  $G$ , then  $|g| = |\langle g \rangle|$  and  $|\langle g \rangle|$  divides  $|G|$ . In particular, if  $|G| = p$  is a prime number and  $g \neq e$ , then  $|\langle g \rangle| = |G|$ , hence  $G = \langle g \rangle \cong Z_p$ .  $\square$

The product of two subsets  $A$  and  $B$  of a group  $G$  is defined as  $AB = \{ab \mid a \in A, b \in B\}$ . Let  $H \leq G$  and  $g \in G$ . Then the product  $\{g\}H$  coincides with the left coset  $gH$ . Moreover, we have  $HH = H$ .

We say that a subgroup  $H$  of  $G$  is *normal* in  $G$  and write  $H \trianglelefteq G$  if  $gH = Hg$  for every  $g \in G$ . Let  $H \trianglelefteq G$ . Then the product of any two cosets of  $H$  in  $G$  is again a coset of  $H$  in  $G$ :

$$g_1H \cdot g_2H = g_1(Hg_2)H = g_1(g_2H)H = g_1g_2H.$$

The set of all cosets of  $H$  in  $G$  with this product forms a group. Its identity element is the coset  $H$ , the inverse of the coset  $xH$  is the coset  $x^{-1}H$ . This group is called the *quotient group* or the *factor group* of the group  $G$  by the normal subgroup  $H$  and is denoted by  $G/H$ . By Lagrange's theorem, if  $G$  is finite then  $|G| = |H| \cdot |G/H|$ .

**2.4 Example.** The subgroup  $K = \{e, (12)(34), (13)(24), (14)(23)\}$  of  $S_4$  is normal and

$$S_4/K = \{K, (12)K, (13)K, (23)K, (123)K, (132)K\} \cong S_3.$$

**2.5 Exercise.** 1) Prove that  $Z(G) \trianglelefteq G$ ,  $G' \trianglelefteq G$  and  $G/G'$  is an abelian group.

2) If  $H_1 \leq H \leq G$ , then  $|G : H_1| = |G : H| \cdot |H : H_1|$ .

3) If  $H$  is a subgroup of index 2 in a group  $G$ , then  $H \trianglelefteq G$ .

4) The product of any two subsets  $H_1, H_2$  of a group  $G$  need not be a subgroup, even if both  $H_1$  and  $H_2$  are subgroups. If both  $H_1$  and  $H_2$  are subgroups and one of them is normal in  $G$ , then  $H_1 H_2$  is a subgroup in  $G$ . If both subgroups  $H_1$  and  $H_2$  are normal in  $G$ , then the subgroup  $H_1 H_2$  is also normal in  $G$ .

5) If  $A, B$  are finite subgroups of a group  $G$ , then

$$|AB| = \frac{|A| \cdot |B|}{|A \cap B|}.$$

### 3 Homomorphism theorems

A mapping  $\varphi$  from a group  $G$  to a group  $G_1$  is called a *homomorphism*, if  $\varphi(ab) = \varphi(a)\varphi(b)$  for every  $a, b \in G$ . The *kernel* of the homomorphism  $\varphi$  is the set  $\ker \varphi = \{g \in G \mid \varphi(g) = e\}$ . The *image* of the homomorphism  $\varphi$  is the set  $\text{im } \varphi = \{\varphi(g) \mid g \in G\}$ .

**3.1 Exercise.** Let  $\varphi: G \rightarrow G_1$  be a homomorphism. Then the following assertions are valid.

- 1)  $\varphi(e) = e$ ,  $\varphi(g^{-1}) = (\varphi(g))^{-1}$  for  $g \in G$ .
- 2) If  $g \in G$  is an element of a finite order, then  $|\varphi(g)|$  divides  $|g|$ .
- 3)  $\ker \varphi \trianglelefteq G$ ,  $\text{im } \varphi \leq G_1$ .
- 4) For any two nonempty subsets  $A, B$  of a group  $G$  holds<sup>1</sup>

$$\varphi(A) = \varphi(B) \iff A \cdot \ker \varphi = B \cdot \ker \varphi.$$

**3.2 Example.** 1) Let  $K^*$  be a *multiplicative group* of a field  $K$ , i.e., the group of all its nonzero elements under multiplication. The mapping  $\varphi: \text{GL}_n(K) \rightarrow K^*$ , assigning to a matrix its determinant, is a homomorphism with kernel  $\text{SL}_n(K)$ .

2) Let  $H \trianglelefteq G$ . The mapping  $\varphi: G \rightarrow G/H$  given by the rule  $\varphi(g) = gH$  is a homomorphism with kernel  $H$ .

Given a subgroup  $H$  of a group  $G$ , we denote by  $L(G, H)$  the set of all subgroups of  $G$  containing  $H$ . In particular  $L(G, \{1\})$  is the set of all subgroups of the group  $G$ .

**3.3 Theorem.** Let  $\varphi: G \rightarrow G_1$  be a homomorphism onto a group  $G_1$ . Then

- 1) the mapping  $\psi: L(G, \ker \varphi) \rightarrow L(G_1, \{1\})$ , sending a subgroup from the first set into its image under  $\varphi$  is a bijection;
- 2) this bijection preserves indexes:

$$\text{if } \ker \varphi \leq H_1 \leq H_2, \text{ then } |H_2 : H_1| = |\varphi(H_2) : \varphi(H_1)|;$$

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<sup>1</sup>We use the notation  $\varphi(A) = \{\varphi(a) \mid a \in A\}$ .

3) *this bijection preserves the normality:*

$$\text{if } \ker \varphi \leq H_1 \leq H_2, \text{ then } H_1 \trianglelefteq H_2 \iff \varphi(H_1) \trianglelefteq \varphi(H_2).$$

*Proof.* 1) The mapping  $\psi$  is onto, since the full preimage of the subgroup of the group  $G_1$  is a subgroup of  $G$  containing  $\ker \varphi$ . The mapping is one-to-one: this follows from Exercise 3.1.4 and the fact that  $H \cdot \ker \varphi = H$  for any subgroup  $H$  of the group  $G$  containing  $\ker \varphi$ .

2) The mapping from the set of the left cosets of  $H_1$  in  $H_2$  to the set of the left cosets of  $\varphi(H_1)$  in  $\varphi(H_2)$ , given by the rule  $xH_1 \mapsto \varphi(x)\varphi(H_1)$ , is onto. The mapping is one-to-one since  $\varphi(xH_1) = \varphi(yH_1)$  implies  $xH_1 \cdot \ker \varphi = yH_1 \cdot \ker \varphi$ , that is  $xH_1 = yH_1$ .

3) We have  $H_1 \cdot \ker \varphi = H_1$  and  $x \cdot \ker \varphi = \ker \varphi \cdot x$  for  $x \in G$ . Therefore the condition  $xH_1 = H_1x$  is equivalent to  $xH_1 \cdot \ker \varphi = H_1x \cdot \ker \varphi$ , which is equivalent to  $\varphi(x)\varphi(H_1) = \varphi(H_1)\varphi(x)$  because of Exercise 3.1.4.  $\square$

**3.4 Theorem.** *If  $\varphi: G \rightarrow G_1$  is a homomorphism, then  $G/\ker \varphi \cong \text{im } \varphi$ .*

*Hint.* The isomorphism is given by the rule  $g \ker \varphi \mapsto \varphi(g)$ ,  $g \in G$ .

**3.5 Theorem.** *Let  $A \leq B \leq G$ ,  $A \trianglelefteq G$ ,  $B \trianglelefteq G$ . Then  $B/A \trianglelefteq G/A$  and  $(G/A)/(B/A) \cong G/B$ .*

*Hint.* Apply Theorem 3.4 to the homomorphism  $\varphi: G/A \rightarrow G/B$  given by the rule  $gA \mapsto gB$ .

**3.6 Theorem.** *Let  $H \trianglelefteq G$ ,  $B \leq G$ . Then  $BH/H \cong B/B \cap H$ .*

*Hint.* The homomorphism  $\varphi: BH \rightarrow B/B \cap H$  given by the rule  $bh \mapsto b(B \cap H)$ ,  $b \in B$ ,  $h \in H$ , has the kernel  $H$ .

Finally we explain some terminology. A homomorphism  $\varphi: G \rightarrow G_1$  is called an *epimorphism* if its image is equal to  $G_1$ . A homomorphism is called a *monomorphism* (or an *embedding*) if its kernel is trivial. The group  $G$  is *embeddable* into the group  $G_1$  if there exists an embedding of  $G$  into  $G_1$ . Obviously, an isomorphism is an epimorphism and a monomorphism simultaneously.

## 4 Cayley's theorem

For any set  $M$  we denote by  $S(M)$  the group of all bijections of  $M$  onto itself, i.e., permutations of  $M$ . If the cardinality  $m$  of  $M$  is finite, then we can identify the group  $S(M)$  with the group  $S_m$ .



**4.1 Theorem (Cayley).** *Let  $H$  be a subgroup of a group  $G$  and let  $M$  be the set of all left cosets of  $H$  in  $G$ . Define the mapping  $\varphi: G \rightarrow S(M)$  by the rule: for any  $g \in G$  the permutation  $\varphi(g)$  sends a coset  $xH$  to the coset  $gxH$ .*

*Then  $\varphi$  is a homomorphism (not necessarily onto) with kernel*

$$\ker \varphi = \bigcap_{x \in G} xHx^{-1}.$$

*Proof.* Clearly  $\varphi(g_1g_2) = \varphi(g_1)\varphi(g_2)$  since  $g_1g_2(xH) = g_1(g_2xH)$  for any  $x \in G$ . Moreover,

$$g \in \ker \varphi \iff (xH = gxH \text{ for all } xH) \iff (g \in xHx^{-1} \text{ for all } x). \quad \square$$

If  $H = \{1\}$ , the homomorphism  $\varphi$  from Cayley's theorem is called the (left) regular representation of the group  $G$ .

**4.2 Corollary.** 1) *The regular representation of a group  $G$  is an embedding of the group  $G$  into the group  $S(G)$ . The image of any nontrivial element of  $G$  under this embedding is a permutation, which sends each element of  $G$  to a different element of  $G$ .*

*Any finite group  $G$  can be embedded into the group  $S_m$  where  $m = |G|$ .*

2) *Any finite group  $G$  can be embedded into the group  $\text{GL}_m(F)$ , where  $F$  is any field and  $m = |G|$ .*

*Proof.* The first claim follows from Cayley's theorem, the second from the first, using the embedding of  $S_m$  into  $\text{GL}_m(F)$  given by the rule  $\sigma \mapsto A_\sigma$ , where  $(A_\sigma)_{ij} = 1$  if  $\sigma(j) = i$  and  $(A_\sigma)_{ij} = 0$  otherwise.  $\square$

**4.3 Exercise.** Any group of order 4 is isomorphic to the group  $Z_4$  or to the group  $K = \{e, (12)(34), (13)(24), (14)(23)\}$ .

*Solution.* Let  $G$  be a group of order 4. We identify  $G$  with its image under the regular representation into  $S_4$ . Then any nontrivial element of the group  $G$  is either a cycle of length 4, or the product of two disjoint transpositions (otherwise a fixed element would appear). If  $G$  contains a cycle of length 4, then  $G \cong Z_4$  and otherwise  $G \cong K$ .

**4.4 Corollary (Poincaré).** *Every subgroup  $H$  of finite index  $m$  in a group  $G$  contains a subgroup  $N$  which is normal in  $G$  and has finite index  $k$  such that  $m \mid k$  and  $k \mid (m!)$ .*

*Proof.* We set  $N = \ker \varphi$ , where  $\varphi$  is the homomorphism from Cayley's theorem. Let  $k = |G : N|$ . By Theorem 3.4,  $k = |\text{im } \varphi|$ . Since  $\text{im } \varphi$  is a subgroup of the group  $S_m$ , we obtain  $k \mid (m!)$ . The claim that  $m \mid k$  follows from  $\ker \varphi \leq H \leq G$  with the help of Exercise 2.5.2.  $\square$