

COMPUTER GRAPHICS C VERSION

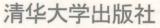
SECOND EDITION

计算机图形学

C语言版 (第2版)

Donald Hearn M. Pauline Baker

著



大学计算机教育国外著名教材系列(影印版)

Computer Graphics

C Version

Second Edition

计算机图形学

C语言版

(第2版)

Donald Hearn

Department of Computer Science and National Center for Supercomputing Applications University of Illinois

M. Pauline Baker

National Center for Supercomputing Applications University of Illinois

清华大学出版社 北京

English reprint edition copyright © 2004 by PEARSON EDUCATION ASIA LIMITED and TSINGHUA UNIVERSITY PRESS.

Original English language title from Proprietor's edition of the Work.

Original English language title: Computer Graphics: C Version, Second Edition by Donald Hearn, M. Pauline Baker, Copyright © 1997 All Rights Reserved.

Published by arrangement with the original publisher, Pearson Education, Inc., publishing as Prentice Hall, Inc.

This edition is authorized for sale and distribution only in the People's Republic of China (excluding the Special Administrative Region of Hong Kong, Macao SAR and Taiwan).

本书影印版由 Pearson Education (培生教育出版集团) 授权给清华大学出版社出版发行。

For sale and distribution in the People's Republic of China exclusively (except Taiwan, Hong Kong SAR and Macao SAR).

仅限于中华人民共和国境内(不包括中国香港、澳门特别行政区和中国台湾地区)销售发行。

北京市版权局著作权合同登记号 图字 01-2003-8449

本书封面贴有 Pearson Education (培生教育出版集团) 激光防伪标签,无标签者不得销售。

图书在版编目(CIP)数据

计算机图形学: C 语言版 (第 2 版) = Computer Graphics: C Version, Second Edition / (美) 赫恩 (Hearn, D.), (美) 贝克 (Baker, M. P.) 著. 一影印本. 一北京: 清华大学出版社, 2004 (大学计算机教育国外著名教材系列)

ISBN 7-302-08084-4

I. 计··· Ⅱ. ①赫··· ②贝··· Ⅲ. 计算机图形学一高等学校-教材-英文 Ⅳ. TP391.41

中国版本图书馆 CIP 数据核字(2004)第 008209号

出版者: 清华大学出版社

地 址: 北京清华大学学研大厦

http://www.tup.com.cn

邮 编: 100084

社总机: (010) 6277 0175

客户服务: (010) 6277 6969

责任编辑: 周维煜

印装者:清华大学印刷厂

发 行 者: 新华书店总店北京发行所

开 本: 185×230 印张: 42.25 彩插: 6

版 次: 2004年3月第2版 2004年3月第1次印刷

书 号: ISBN 7-302-08084-4/TP • 5846

印 数: 1~5000

定 价: 69.00元

本书如存在文字不清、漏印以及缺页、倒页、脱页等印装质量问题,请与清华大学出版社出版部联系调换。联系电话: (010) 62770175-3103 或 (010) 62795704

Preface

Computer graphics remains one of the most exciting and rapidly growing computer fields. Since the appearance of the first edition of this book, computer graphics has now become a common element in user interfaces, data visualization, television commercials, motion pictures, and many, many other applications. Hardware devices and algorithms have been developed for improving the effectiveness, realism, and speed of picture generation, and the current trend in computer graphics is to incorporate more physics principles into three-dimensional graphics algorithms to better simulate the complex interactions between objects and the lighting environment.

Software Standards

Significant improvements in graphics software standards have been developed since the acceptance of the first graphics package, the Graphical Kernel System (GKS), by the International Standards Organization (ISO) and the American National Standards Institute (ANSI). The Programmer's Hierarchical Interactive Graphics Standard (PHIGS) is now both an ANSI and an ISO standard. Both PHIGS and the expanded PHIGS+ packages are widely available. In addition, a number of popular industry packages have emerged, including Silicon Graphics GL (Graphics Library), OpenGL, the Pixar RenderMan interface, PostScript interpreters for page descriptions, and a variety of painting, drawing, and design systems.

New Topics

Because of the tremendous number of changes that have occurred in the field of computer graphics, we decided to completely rewrite the book for the second edition, while maintaining the general organization of the first edition. All topics from the first edition were expanded to include discussions of current technology, and a great many new topics have been added. Topics that have been significantly expanded include antialiasing, fractal and other object-representation methods, ray tracing, spline curves and surfaces, illumination models, surface-rendering methods, and computer animation. New topics that have been added to this second edition include virtual reality, parallel implementations for graphics algorithms, superquadrics, BSP trees, shape grammars, particle systems, physically based modeling, scientific visualization, business visualization, quaternion methods in graphics algorithms, distribution ray tracing, fast-Phong

shading, radiosity, bump mapping, morphing, and discussions of various mathematical methods useful in graphics applications.

This second edition can be used both as a text for students with no prior background in computer graphics and as a reference for graphics professionals. We emphasize basic principles needed to design, use, and understand computer graphics systems. Both hardware and software components of graphics systems are discussed, as well as various applications of computer graphics. We also include programming examples written in C to demonstrate the implementation and applications of the graphics algorithms. And we explore the features of PHIGS, PHIGS+, GKS, and other graphics libraries, while using PHIGS and PHIGS+ functions in the C programs to illustrate algorithm implementations and graphics applications.

Required Background

We assume no prior familiarity with computer graphics, but we do assume the reader has some knowledge of computer programming and basic data structures. A variety of mathematical methods are used in computer graphics algorithms, and these methods are discussed in some detail in the appendix. Mathematical topics covered in the appendix include techniques from analytic geometry, linear algebra, vector and tensor analysis, complex numbers, quaternions, and numerical analysis.

How to Use This Book as a Text

The material in this second edition evolved from notes used in a number of courses we have taught over the past several years, including introductory computer graphics, advanced graphics topics, scientific visualization, and graphics project courses. For a one-semester course, a subset of topics dealing with either two-dimensional methods or a combination of two-dimensional and three-dimensional topics can be chosen, depending on the requirements of a particular course. A two-semester course sequence can be used to cover the basic graphics concepts and methods in the first course and advanced three-dimensional methods and algorithms in the second course. For the self-study reader, early chapters can be used to provide an understanding of graphics concepts, with individual topics selected from the later chapters according to the interests of the reader.

At the undergraduate level, an introductory two-dimensional graphics course can be organized with a detailed treatment of fundamental topics from Chapters 2 through 8 plus the introduction to three-dimensional concepts and methods given in Chapter 9. Selected topics, such as color models, animation, spline curves, or two-dimensional fractal representations, from the later chapters could be used as supplemental material. For a graduate or upper-level undergraduate course, basic two-dimensional concepts and methods can be covered in the first half of the course, with selected topics from three-dimensional modeling, viewing, and rendering covered in the second half. A second, or advanced-topics,

xviii

course can be used to cover selected topics from object representations, surface rendering, and computer animation.

Chapter 1 is a survey of computer graphics, illustrating the diversity of applications areas. Following an introduction to the hardware and software components of graphics systems in Chapter 2, fundamental algorithms for the representation and display of two-dimensional graphics objects are presented in Chapters 3 and 4. These two chapters examine methods for producing basic picture components and techniques for adjusting size, color, and other object attributes. This introduces students to the programming techniques necessary for implementing graphics routines. Chapters 5 and 6 discuss two-dimensional geometric transformations and viewing algorithms. Methods for modeling and organizing two-dimensional picture components into separate structures are given in Chapter 7. In Chapter 8, we present graphics methods for user interfaces and for interactive input in various applications, including virtual-reality systems.

Three-dimensional techniques are introduced in Chapter 9. We then discuss in Chapter 10 the different ways that three-dimensional objects can be graphically represented, depending on the characteristics of the objects. Chapter 11 presents methods for modeling and performing geometric transformations in three-dimensions. Methods for obtaining views of a three-dimensional scene are detailed in Chapter 12. The various algorithms for identifying visible surfaces in a scene are discussed in Chapter 13. Illumination models and surface-rendering methods, such as ray tracing and radiosity, are taken up in Chapter 14. Color models and methods are discussed in Chapter 15, and animation techniques are explored in Chapter 16.

Acknowledgments

Many people have contributed to this project in a variety of ways over the years. To the organizations and individuals who furnished photographs and other materials, we again express our appreciation. We also acknowledge the many helpful comments received form our students in various computer graphics and visualization courses and seminars. We are indebted to all those who provided reviews or suggestions for improving the material covered in this book, and we extend our apologies to anyone we may have failed to mention. Thank you: Ed Angel, Norman Badler, Phillip Barry, Brian Barsky, Hedley Bond, Bart Braden, Lara Burton, Robert Burton, Greg Chwelos, John Cross, Steve Cunningham, John DeCatrel, Victor Duvaneko, Gary Eerkes, Parris Egbert, Tony Faustini, Thomas Foley, Thomas Frank, Don Gillies, Jack Goldfeather, Georges Grinstein, Eric Haines, Robert Herbst, Larry Hodges, Eng-Kiat Koh, Mike Krogh, Michael Laszlo, Suzanne Lea, Michael May, Nelson Max, David McAllister, Jeffrey Mc-Connell, Gary McDonald, C. L. Morgan, Gred Nielson, James Oliver, Lee-Hian Quek, Laurence Rainville, Paul Ross, David Salomon, Günther Schrack, Steven Shafer, Cliff Shaffer, Pete Shirley, Carol Smith, Stephanie Smullen, Jeff Spears, William Taffe, Wai Wan Tsang, Spencer Thomas, Sam Uselton, David Wen, Bill Wicker, Andrew Woo, Angelo Yfantis, Marek Zaremba, and Michael Zyda. Our thanks go also to Robert Burton's Fall 1995 Computer Graphics course at Preface

Brigham Young University for running and testing the C code for this book. And we thank our editor Alan Apt, Sondra Chavez, and the Colorado staff for their help, suggestions, and encouragement during the preparation of this C version of the second edition. To our production editors, Bayani DeLeon and Joe Scordato, and the Prentice Hall staff, we offer our thanks for another outstanding production job. Finally, a special thanks goes to Carol Hubbard for her help in developing the C code.

Urbana-Champaign

Donald Hearn M. Pauline Baker

Contents

PREFACE		xvii	,	Stereoscopic and Virtual-Reality Systems	
1	A Survey of Computer Graphics	2	2-2	Raster-Scan Systems Video Controller	50 53 53
1-1	Computer-Aided Design	4		Raster-Scan Display Processor	55
1-2	Presentation Graphics	11	2-3	Random-Scan Systems	56
1-3	Computer Art		2-4	Graphics Monitors and Workstations	57
1-3	Entertainment	13	2-5	Input Devices	60
10. 0		18		Keyboards	61
1-5	Education and Training	21		Mouse	61
1-6	Visualization	25		Trackball and Spaceball	63
1-7	Image Processing	32		Joysticks	63
1-8	Graphical User Interfaces	34		Data Glove	64
				Digitizers	64
				Image Scanners	67
				Touch Panels	68
	Overview of Graphics			Light Pens	70
L	Systems	35		Voice Systems	70
	7		2-6	Hard-Copy Devices	72
2-1	Video Display Devices	36	2-7	Graphics Software	75
	Refresh Cathode-Ray Tubes	37		Coordinate Representations	76
	Raster-Scan Displays	40		Graphics Functions	77
	Random-Scan Displays	41		Software Standards	78
	Color CRT Monitors	42		PHIGS Workstations	79
	Direct-View Storage Tubes	45		Summary	79
	Flat-Panel Displays	45		References	81
	Three-Dimensional Viewing Devices	49		Exercises	81

<u>3</u>	Output Primitives	83		Summary Applications References	134 136 140
3-1	Points and Lines	84		Exercises	140
3-2	Line-Drawing Algorithms	86			
	DDA Algorithm	87			
	Bresenham's Line Algorithm	88			
	Parallel Line Algorithms	92	A	Attributes of Output	
3-3	Loading the Frame Buffer	94	4	Primitives	143
3-4	Line Function	95	_		- 13
3-5	Circle-Generating Algorithms	97	4-1	Line Attributes	144
	Properties of Circles	97		Line Type	144
	Midpoint Circle Algorithm	98		Line Width	146
3-6	Ellipse-Generating Algorithms	102		Pen and Brush Options	149
	Properties of Ellipses	102		Line Color	149
	Midpoint Ellipse Algorithm	103	4-2	Curve Attributes	152
3-7	Other Curves	110	4-3	Color and Grayscale Levels	154
	Conic Sections	110		Color Tables	155
	Polynomials and Spline Curves	112		Grayscale	157
3-8	Parallel Curve Algorithms	112	4-4	Area-Fill Attributes	158
3-9	Curve Functions	113		Fill Styles	158
3-10	Pixel Addressing			Pattern Fill	159
	and Object Geometry	114		Soft Fill	162
	Screen Grid Coordinates	114	4-5	Character Attributes	163
	Maintaining Geometric Properties			Text Attributes	163
	of Displayed Objects	114		Marker Attributes	167
3-11	Filled-Area Primitives	117	4-6	Bundled Attributes	168
	Scan-Line Polygon Fill Algorithm	117		Bundled Line Attributes	168
	Inside-Outside Tests	125		Bundled Area-Fill Attributes	169
	Scan-Line Fill of Curved Boundary			Bundled Text Attributes	169
	Areas	126		Bundled Marker Attributes	170
	Boundary-Fill Algorithm	127	4-7	Inquiry Functions	170
	Flood-Fill Algorithm	130	4-8	Antialiasing	171
	Fill-Area Functions	131		Supersampling Straight Line	
	Cell Array	131		Segments	172
3-14	Character Generation	131		Pixel-Weighting Masks	174

Conten	ts
--------	----

	Area Sampling Straight Line Segments Filtering Techniques Pixel Phasing Compensating for Line Intensity Differences Antialiasing Area Boundaries Summary References Exercises	174 174 175 175 176 178 180 180	5-6 5-7 5-8	Affine Transformations Transformation Functions Raster Methods for Transformations Summary References Exercises Two-Dimensional Viewing	208 208 210 212 213 213
<u>5</u>	Two-Dimensional Geome Transformations	etric 183	6-1 6-2 6-3	The Viewing Pipeline Viewing Coordinate Reference Frame Window-to-Viewport Coordinate Transformation	217 219 220
5-1	Basic Transformations Translation Rotation Scaling	184 184 186 187	6-4 6-5 6-6 6-7	Two-Dimensional Viewing Functions Clipping Operations Point Clipping Line Clipping	222 224 225 225
5-2 5-3	Matrix Representations and Homogeneous Coordinates Composite Transformations Translations Rotations	188 191 191 191		Cohen-Sutherland Line Clipping Liang-Barsky Line Clipping Nicholl-Lee-Nicholl Line Clipping Line Clipping Using Nonrectangular Clip Windows Splitting Concave Polygons	226 230 233 235 235
	Scalings General Pivot-Point Rotation General Fixed-Point Scaling General Scaling Directions Concatenation Properties General Composite Transformations and Computational Efficiency	192 192 193 193 194	6-8	Polygon Clipping Sutherland-Hodgeman Polygon Clipping Weiler-Atherton Polygon Clipping Other Polygon-Clipping Algorithms Curve Clipping	237 238 242
5-4 5-5	Other Transformations Reflection Shear Transformations Between Coordinate	201 201 203	6-10 6-11	Text Clipping Exterior Clipping Summary References	244 245 245 248
	Systems	203		Exercises	248

7	Structures and Hierarch Modeling	ical 250		Accommodating Multiple Skill Levels Consistency	27 3
7-1	Structure Concepts Basic Structure Functions Setting Structure Attributes	250 250 253		Minimizing Memorization Backup and Error Handling Feedback	274 274 275
7-2	Editing Structures Structure Lists and the Element Pointer Setting the Edit Mode Inserting Structure Elements Replacing Structure Elements Deleting Structure Elements Labeling Structure Elements Copying Elements from One Struct to Another	254 255 256 256 257 257 258	8-2 8-3	Input of Graphical Data Logical Classification of Input Devices Locator Devices Stroke Devices String Devices Valuator Devices Choice Devices Pick Devices Input Functions	276 276 277 277 277 279 279 279
7-3	Basic Modeling Concepts Model Representations Symbol Hierarchies Modeling Packages	260 261 262 263	0 3	Input Modes Request Mode Locator and Stroke Input in Request Mode	281 282 282
7-4	Hierarchical Modeling with Structures Local Coordinates and Modeling Transformations Modeling Transformations Structure Hierarchies Summary	265 265 266 266 268		String Input in Request Mode Valuator Input in Request Mode Choice Input in Request Mode Pick Input in Request Mode Sample Mode Event Mode Concurrent Use of Input Modes	283 284 284 284 285 285 287
~ ×	References Exercises Graphical User Interface	269 269 es	8-4	Initial Values for Input-Device Parameters Interactive Picture-Construction Techniques Basic Positioning Methods Constraints	287 288 288 288
<u>8</u>	and Interactive Input Methods	271		Grids Gravity Field Rubber-Band Methods	289 290 290
8-1	The User Dialogue Windows and Icons	272 273		Dragging Painting and Drawing	290 291 291

Content	c

8-6	Virtual-Reality Environments	292	10-4	Superquadrics	312
	Summary	293		Superellipse	312
	References	294		Superellipsoid	313
	Exercises	294	10-5	Blobby Objects	314
			10-6	Spline Representations	315
				Interpolation and Approximation	
^	Three-Dimensional			Splines	316
Y		206		Parametric Continuity	
_	Concepts	296		Conditions	317
9-1	There Disease I District I			Geometric Continuity	
9-1	Three-Dimensional Display Methods Parallel Projection			Conditions	318
		298		Spline Specifications	319
	Perspective Projection Depth Cueing	299	10-7	Cubic Spline Interpolation	
	Visible Line and Surface	299		Methods	320
	Identification	300		Natural Cubic Splines	321
	Surface Rendering	300		Hermite Interpolation	322
	Exploded and Cutaway Views	300		Cardinal Splines	323
	Three-Dimensional and Stereoscopi			Kochanek-Bartels Splines	325
	Views	300	10-8	Bézier Curves and Surfaces	327
9-2	Three-Dimensional Graphics	300		Bézier Curves	327
J-2	Packages	302		Properties of Bézier Curves	329
	Lachages	302		Design Techniques Using Bézier	121212
				Curves	330
	TI D:			Cubic Bézier Curves	331
	Three-Dimensional			Bézier Surfaces	333
11	∩ Object		10-9	B-Spline Curves and Surfaces	334
Ц	Representations	304		B-Spline Curves	335
	Representations	304		Uniform, Periodic B-Splines	336
10-1	Polygon Surfaces	205		Cubic, Periodic B-Splines	339
10-1	Polygon Tables	305 306		Open, Uniform B-Splines	341
	Plane Equations	307		Nonuniform B-Splines	344
	Polygon Meshes	309		B-Spline Surfaces	344
10-2	, ,	- 2	10-10	Beta-Splines	345
10-2	Curved Lines and Surfaces	310		Beta-Spline Continuity	
10-3	Quadric Surfaces Sphere	310		Conditions	345
	Ellipsoid	311		Cubic, Periodic Beta-Spline	
	Torus	311	10.44	Matrix Representation	346
	iorus	311	10-11	Rational Splines	347

10-12	Conversion Between Spline Representations	349		Visual Representations for Multivariate Data Fields	402
10-13	Displaying Spline Curves			Summary	404
	and Surfaces	351		References	404
	Horner's Rule	351		Exercises	404
	Forward-Difference Calculations	351			
	Subdivision Methods	353		Three-Dimensional	
10-14	Sweep Representations	355			1.
10-15	Constructive Solid-Geometry Methods	356	11	Geometric and Mode Transformations	407
10-16	Octrees	359		Iransjormations	407
10-17	BSP Trees	362	11-1	Translation	408
10-18	Fractal-Geometry Methods	362	11-2	Rotation	409
	Fractal-Generation Procedures	363	11.2	Coordinate-Axes Rotations	409
	Classification of Fractals	364		General Three-Dimensional	
	Fractal Dimension	364		Rotations	413
	Geometric Construction			Rotations with Quaternions	419
	of Deterministic Self-Similar Fractals	367	11-3	Scaling	420
	Geometric Construction	30	11-4	Other Transformations	422
	of Statistically Self-Similar			Reflections	422
	Fractals	369		Shears	423
	Affine Fractal-Construction		11-5	Composite Transformations	423
	Methods	372	11-6	Three-Dimensional Transformati	
	Random Midpoint-Displacement	272		Functions	425
	Methods	373 376	11-7	Modeling and Coordinate Transformations	426
	Controlling Terrain Topography Self-Squaring Fractals	378			429
	Self-Inverse Fractals	385		Summary References	429
10.10	Shape Grammars and Other	303		Exercises	430
10-19	Procedural Methods	387		Exercises	430
10-20	Particle Systems	390			
10-21	Physically Based Modeling	393	17	Three-Dimensional	
10-22	Visualization of Data Sets	395	14	Viewing	431
.0 22	Visual Representations	000	-		
	for Scalar Fields	395	12-1	Viewing Pipeline	432
	Visual Representations		12-2	Viewing Coordinates	433
	for Vector Fields	400		Specifying the View Plane	433
	Visual Representations for Tensor Fields	401		Transformation from World to Viewing Coordinates	437

12-3	Projections Parallel Projections Perspective Projections	438 439 443	13-12 13-13	Wireframe Methods Visibility-Detection Functions Summary	490 490 491
12-4	View Volumes and General Projection Transformations General Parallel-Projection Transformations	447 452		References Exercises	492 492
	General Perspective-Projection Transformations	454		Illumination Models	
12-5	Clipping Normalized View Volumes Viewport Clipping	456 458 460	<u>14</u>	and Surface-Renderin Methods	g 494
	Clipping in Homogeneous Coordinates	461	14-1	Light Sources	496
12-6	Hardware Implementations	463	14-2	Basic Illumination Models	497
12-7	Three-Dimensional Viewing	403		Ambient Light Diffuse Reflection	497 497
12-7	Functions	464		Specular Reflection	47/
	Summary	467		and the Phong Model	500
	References	468		Combined Diffuse and Specular	
	Exercises	468		Reflections with Multiple Light	
				Sources	504
4.	Visible-Surface Detec	tion		Warn Model	504
13	Made all			Intensity Attenuation Color Considerations	505 507
<u>10</u>	Methods	469		Transparency	508
13-1	Classification of Visible-Surface			Shadows	511
15-1	Detection Algorithms	470	14-3	Displaying Light Intensities	511
13-2	Back-Face Detection	471		Assigning Intensity Levels	512
13-3	Depth-Buffer Method	472	š.	Gamma Correction and Video	
13-4	A-Buffer Method	475		Lookup Tables	513
13-5	Scan-Line Method	476		Displaying Continuous-Tone	
13-6	Depth-Sorting Method	478		Images	515
13-7	BSP-Tree Method	481	14-4	Halftone Patterns and Dithering Techniques	F1.0
13-8	Area-Subdivision Method	482		Halftone Approximations	516 516
13-9	Octree Methods	485		Dithering Techniques	519
13-10	Ray-Casting Method	487	14-5	Polygon-Rendering Methods	522
13-11	Curved Surfaces	488		Constant-Intensity Shading	522
	Curved-Surface Representations			Gouraud Shading	523
	Surface Contour Plots	489		Phong Shading	525

XYZ Color Model CIE Chromaticity Diagram 569 CIE Chromaticity Diagram 569 A-1 Coordinate-Reference Fram Two-Dimensional Cartesia RGB Color Model 572 Reference Frames	
Basic Ray-Tracing Algorithm Ray-Surface Intersection Calculations Reducing Object-Intersection Calculations Space-Subdivision Methods Antialiased Ray Tracing Distributed Ray Tracing Sasic Radiosity Lighting Model Basic Radiosity Model Progressive Refinement Radiosity Method Adding Surface Detail With Polygons Texture Mapping Procedural Texturing Methods Bump Mapping Frame Mapping Frame Mapping Summary Soummary References Exercises 15-1 Properties of Light Soummary References Exercises A Mathematics for Oraphics Antialiased Ray Tracing Summary References Exercises Antialiased Ray Tracing Summary References Exercises Antialiased Ray Tracing Summary References Exercises Antialiased Ray Tracing Summary References Sound-Directed Systems Kinematics and Dynami Summary References Exercises Antialiased Ray Tracing Summary References Exercises Antialiased R	Y Color Model 574
Ray-Surface Intersection Calculations Reducing Object-Intersection Calculations Space-Subdivision Methods Space-Subdivision Methods Antialiased Ray Tracing Distributed Ray Tracing Space-Subdivision Methods Antialiased Ray Tracing Space-Subdivision Methods Antialiased Ray Tracing Space-Subdivision Methods Antialiased Ray Tracing Space-Subdivision Methods Submary Space-Subdivision Methods Submary Space-Subdivision Methods Space-Subdivision Methods Submary Subdivision Methods Space-Subdivision Methods Space-Subdivision Methods Submary Subdivision Methods Space-Subdivision Methods Submary Subdivision Methods Space-Subdivision Methods Space-Subdivision Methods Space-Subdivision Methods Subdivision Methods Space-Subdivision Methods Space-Subdivision Methods Space-Subdivision Methods Space-Subdivision Methods Submary Reference Space-Space Space-Space Space-	/ Color Model 575
Calculations Reducing Object-Intersection Calculations Space-Subdivision Methods Antialiased Ray Tracing Distributed Ray Tracing Saliculations Summary Antialiased Ray Tracing Distributed Ray Tracing S40 14-7 Radiosity Lighting Model Basic Radiosity Model Progressive Refinement Radiosity Method S44 Progressive Refinement Radiosity Method S54 14-8 Environment Mapping S55 Texture Mapping Procedural Texturing Methods Bump Mapping Frame Mapping S58 Frame Mapping S59 Summary S60 References S61 Exercises 16-1 Design of Animation 16-2 General Computer-Anim Functions Functions Functions 16-3 Raster Animations 16-4 Computer-Animation Lar Key-Frame Systems Morphing Simulating Acceleration Direct Motion Specifications Direct Motion Specifi	version Between HSV
Reducing Object-Intersection Calculations Space-Subdivision Methods Antialiased Ray Tracing Distributed Ray Tracing Sassic Radiosity Model Progressive Refinement Radiosity Method Progressive Refinement Radiosity Method Adding Surface Detail With Polygons Texture Mapping Procedural Texturing Methods Bump Mapping Summary Summary Summary Summary Seferences Summary Frame Mapping S54 16-1 Design of Animation 16-2 General Computer-Animations Functions Functions Functions Functions Functions Frame Mapping S55 Frame Mapping S56 Frame Mapping S57 Summary S60 References S61 Exercises 16-6 Motion Specifications Summary S60 Applications Summary References S61 Exercises 16-6 Motion Specifications Direct Motion Specifications Summary References Exercises 15-1 Properties of Light S65 Standard Primaries and the Chromaticity Diagram XYZ Color Model CIE Chromaticity Diagram XYZ Color Model S69 CIE Chromaticity Diagram S15-4 RGB Color Model S72 A-1 Coordinate-Reference Fram Two-Dimensional Cartesia Reference Frames	
Calculations Space-Subdivision Methods Antialiased Ray Tracing Distributed Ray Tracing S40 References Exercises 14-7 Radiosity Lighting Model Basic Radiosity Model Progressive Refinement Radiosity Method Design of Animation 14-8 Environment Mapping S53 Texture Mapping Modeling Surface Detail with Polygons Texture Mapping Procedural Texturing Methods Bump Mapping Methods Bump Mapping S54 Frame Mapping S55 Frame Mapping S55 Summary S60 References S61 Exercises S62 Computer Animation 16-1 Design of Animation Sequate Computer-Animation Lar Computer-Animations Functions Functions Functions Functions 16-2 General Computer-Animation Lar Computer-Animation Lar Computer-Animation Lar Modeling Surface Detail with Polygons Texture Mapping Methods S55 Frame Mapping S55 Frame Mapping Simulating Acceleration Direct Motion Specifications	
Space-Subdivision Methods Antialiased Ray Tracing Distributed Ray Tracing Distributed Ray Tracing Sasic Radiosity Lighting Model Basic Radiosity Model Progressive Refinement Radiosity Method Sasic Radiosity Method The Progressive Refinement Radiosity Method Sasic References Sasic References Sasic References Sasic References Sasic Radiosity Method Sasic References Sasic References Sasic Radiosity Method Sasic References Sasic Refer	
Antialiased Ray Tracing Distributed Ray Tracing Distributed Ray Tracing Progressive Refinement Radiosity Method Progressive Refinement Radiosity Method S44 Progressive Refinement Radiosity Method S45 Idea Computer Animation Idea Computer Idea Compu	
14-7 Radiosity Lighting Model	
14-7 Radiosity Lighting Model Basic Radiosity Model Progressive Refinement Radiosity Method 14-8 Environment Mapping 14-9 Adding Surface Detail With Polygons Texture Mapping Procedural Texturing Methods Bump Mapping Frame Mapping Summary Summary Summary Seferences Exercises 16-1 Design of Animation 16-2 General Computer-Anim Functions Functions Functions 16-4 Computer-Animations Functions Functions 16-4 Computer-Animation Lar Key-Frame Systems Morphing Simulating Acceleration Direct Motion Specifications Summary References Exercises 15-1 Properties of Light Standard Primaries and the Chromaticity Diagram XYZ Color Model CIE Chromaticity Diagram 15-3 Intuitive Color Concepts TS-1 RGB Color Model STAN Animation 15-4 RGB Color Model S49 16-1 Design of Animation Sector Animation 16-2 General Computer-Anim Functions Functions 16-2 General Computer-Anim Functions 16-4 Computer-Animations Functions 16-4 Computer-Animation Lar 16-5 Key-Frame Systems Morphing Simulating Acceleration Direct Motion Specifications Direct Motion Specifications Summary References Exercises A Mathematics for Organical Cartesia Reference Frames	T. T. I
Progressive Refinement Radiosity Method 14-8 Environment Mapping 14-9 Adding Surface Detail With Polygons Texture Mapping Procedural Texturing Methods Bump Mapping Frame Mapping Summary Summary Summary References Exercises 15-1 Properties of Light 15-2 Standard Primaries and the Chromaticity Diagram XYZ Color Model CIE Chromaticity Diagram 15-4 RGB Color Model 15-4 RGB Color Model 15-5 Environment Mapping S54 S55 S55 S55 S55 S56 S57 S57 S58 S69	Cises 302
Radiosity Method 14-8 Environment Mapping 14-9 Adding Surface Detail	
14-8 Environment Mapping 552 14-9 Adding Surface Detail 553 16-1 Design of Animation Sequence Modeling Surface Detail with Polygons 553 Feature Mapping 554 16-3 Raster Animations Functions Sequence Frame Mapping 554 16-3 Raster Animations Functions Functi	
Adding Surface Detail Modeling Surface Detail with Polygons Texture Mapping Procedural Texturing Methods Bump Mapping Frame Mapping Summary References Exercises Color Models and Color Applications Toolor Model Standard Primaries and the Chromaticity Diagram XYZ Color Model CIE Chromaticity Diagram Sumary CIE Chromaticity Diagram Standard Primaries and the Chromaticity Diagram CIE Chromaticity Diagram Standard Primaries and Color Concepts ARGB Color Model Standard Primaries Standard Primaries Standard Standard Primaries Standar	imation 583
Modeling Surface Detail with Polygons Texture Mapping Procedural Texturing Methods Bump Mapping Frame Mapping Summary Summary References Exercises Color Models and Color Applications Tolor Models Standard Primaries and the Chromaticity Diagram XYZ Color Model CIE Chromaticity Diagram Sumary Solutions Standard Primaries and the Chromaticity Diagram CIE Chromaticity Diagram Sumary Solutions So	
with Polygons Texture Mapping Procedural Texturing Methods Bump Mapping Frame Mapping Summary References Exercises Color Models and Color Applications Texture Mapping Summary South Texturing Methods South Texture Mapping South Texture Systems Morphing Simulating Acceleration Motion Specifications Direct Motion Specifications South Texture Mapping Simulating Acceleration Motion Specifications South Texture Mapping Simulating Acceleration Motion Specifications Summary References Exercises Functions Raster Animation Lar Key-Frame Systems Morphing Simulating Acceleration Motion Specifications Summary References Exercises Functions Raster Animation Lar Key-Frame Systems Morphing Simulating Acceleration Motion Specifications Summary References Exercises Functions	
Procedural Texturing Methods Bump Mapping Frame Mapping Summary References Exercises Color Models and Color Applications Tolor Applications Tolor Standard Primaries and the Chromaticity Diagram XYZ Color Model CIE Chromaticity Diagram CIE Chromaticity Diagram Tolor References Solutions Solutions Simulating Acceleration Motion Specifications Direct Motion Specifications Direct Motion Specifications Summary References Exercises Analysis Mathematics for Coraphics Analysis Analysis Coordinate-Reference Fram Two-Dimensional Cartesia Reference Frames	
Methods Bump Mapping Frame Mapping Summary References Exercises Color Models and Color Applications Tolor Applications Tolor Standard Primaries and the Chromaticity Diagram XYZ Color Model CIE Chromaticity Diagram CIE Chromaticity Diagram Summary S60 S160 S160 Simulating Acceleration Motion Specifications Direct Motion Specificat Goal-Directed Systems Kinematics and Dynami Summary References Exercises Mathematics for Cienchy Simulating Acceleration Motion Specifications Summary References Exercises Anthematics for Cienchy Simulating Acceleration Motion Specifications Direct Motion Specifications Summary References Exercises Tolor Summary References Exercises Anthematics for Cienchy Simulating Acceleration Motion Specifications Direct Motion Specifications Direct Motion Specifications Direct Motion Specifications Mathematics and Dynami Summary References Exercises Tolor Summary References Exercises Anthematics for Cienchy Simulating Acceleration Summary References Exercises Tolor Summary References Exercises Anthematics for Cienchy Simulating Acceleration Simulating Acceleration Motion Specifications Direct Motion Specifications Summary References Exercises Anthematics for Cienchy Simulating Acceleration Simulating Acceleration Motion Specifications Direct Motion Specifications Summary References Exercises Anthematics for Cienchy Simulating Acceleration Simulating Acceleration Motion Specifications Direct Motion Specifications Summary References Exercises Anthematics for Cienchy Simulating Acceleration Simulating Acceleration Motion Specifications Direct Motion Specifications Summary References Exercises For Coordinate-Reference Fram Two-Dimensional Cartesia Reference Frames	
Bump Mapping 558 16-5 Key-Frame Systems Morphing Simulating Acceleration Simulating Acceleration Simulating Acceleration Motion Specifications Direct Motion Specifications Simulating Acceleration Motion Specifications Direct Motion Specifications Simulating Acceleration Motion Specifications Direct Motion Specifications Simulating Acceleration Motion Specifications Direct Motion Specifications Summary References Exercises 15-1 Properties of Light 565 15-2 Standard Primaries and the Chromaticity Diagram Simulating Acceleration Motion Specifications Direct Motion Specifications Summary References Exercises 15-1 Properties of Light 565 15-2 Standard Primaries and the Chromaticity Diagram 569 CIE Chromaticity Diagram 569 15-3 Intuitive Color Concepts 571 15-4 RGB Color Model 572 Nathematics for Coordinate-Reference Fram Two-Dimensional Cartesia Reference Frames	
Frame Mapping 559 Summary 560 References 561 Exercises 562 Color Models and Color Applications 564 Tolor Models and Color Applications 568 Tolor Models and Color Applications 568 Tolor Models 568	
Summary References Exercises 561 Froperties of Light Standard Primaries and the Chromaticity Diagram XYZ Color Model CIE Chromaticity Diagram CIE Chromaticity Diagram Simulating Acceleration Motion Specifications Direct Motion Specifications Summary References Exercises Mathematics and Dynami Summary References Exercises Mathematics for Circle Graphics A-1 Coordinate-Reference Fram Two-Dimensional Cartesia Reference Frames	
References Exercises 561 Exercises 562 Motion Specifications Direct Motion Specificat Goal-Directed Systems Kinematics and Dynami Summary References Exercises 15-1 Properties of Light 565 Standard Primaries and the Chromaticity Diagram XYZ Color Model CIE Chromaticity Diagram CIE Chromaticity Diagram Sofe CIE Chromaticity Diagram	-:
Exercises 561 Direct Motion Specificat Goal-Directed Systems Kinematics and Dynami Summary References Exercises 15-1 Properties of Light 15-2 Standard Primaries and the Chromaticity Diagram XYZ Color Model CIE Chromaticity Diagram CIE Chromaticity Diagram Sofe Sofe Coordinate-Reference Fram Two-Dimensional Cartesia Reference Frames	tion Specifications 594
Color Models and Color Applications 564 Properties of Light Standard Primaries and the Chromaticity Diagram XYZ Color Model CIE Chromaticity Diagram CIE Chromaticity Diagram Soft Standard Primaries and the Chromaticity Diagram Soft Soft A-1 Coordinate-Reference Fram Two-Dimensional Cartesia Reference Frames	
Color Models and Color Applications 564 Properties of Light 565 Standard Primaries and the Chromaticity Diagram XYZ Color Model CIE Chromaticity Diagram 569 CIE Chromaticity Diagram 569 CIE Chromaticity Diagram 569 Intuitive Color Concepts 571 RGB Color Model 572 RGB Color Model 572 RGB Color Model 572 Summary References Exercises And Mathematics for Coraphics Graphics A-1 Coordinate-Reference Fram Two-Dimensional Cartesia Reference Frames	al-Directed Systems 595
Applications 564 References Exercises 15-1 Properties of Light 565 Standard Primaries and the Chromaticity Diagram XYZ Color Model CIE Chromaticity Diagram CIE Chromaticity Diagram 15-3 Intuitive Color Concepts RGB Color Model 571 Coordinate-Reference Fram Two-Dimensional Cartesia Reference Frames	ematics and Dynamics 595
Exercises 15-1 Properties of Light 565 15-2 Standard Primaries and the Chromaticity Diagram XYZ Color Model CIE Chromaticity Diagram 569 15-3 Intuitive Color Concepts 571 15-4 RGB Color Model 572 Reference Frames	nmary 596
Exercises 15-1 Properties of Light 565 15-2 Standard Primaries and the Chromaticity Diagram XYZ Color Model CIE Chromaticity Diagram 569 15-3 Intuitive Color Concepts 571 15-4 RGB Color Model 572 Reference Frames	erences 597
Standard Primaries and the Chromaticity Diagram XYZ Color Model CIE Chromaticity Diagram Intuitive Color Concepts Intuitive Color Model September 15-4 RGB Color Model September 15-2 RGB Color Model September 15-2 RGB Color Model September 15-2 Reference Frames September 15-2 Reference Frames	rcises 597
Chromaticity Diagram XYZ Color Model CIE Chromaticity Diagram 15-3 Intuitive Color Concepts RGB Color Model S72 A-1 Coordinate-Reference Fram Two-Dimensional Cartesia Reference Frames	
XYZ Color Model CIE Chromaticity Diagram 569 CIE Chromaticity Diagram 569 A-1 Coordinate-Reference Fram Two-Dimensional Cartesia RGB Color Model 572 Reference Frames	hematics for Computer
CIE Chromaticity Diagram 569 A-1 Coordinate-Reference Fram Two-Dimensional Cartesia RGB Color Model 572 Reference Frames	
15-3 Intuitive Color Concepts 571 Coordinate-Reference Fram Two-Dimensional Cartesia Reference Frames	prines 333
15-4 RGB Color Model 572 Reference Frames	linate-Reference Frames 600
372 Reference Frames	
	000
15-5 YIQ Color Model 574 Polar Coordinates in the x_1	Coordinates in the xy Plane 601

Co		

	Three-Dimensional Cartesian			Matrix Transpose	613
	Reference Frames	602		Determinant of a Matrix	613
	Three-Dimensional Curvilinear			Matrix Inverse	614
	Coordinate Systems	602	A-5	Complex Numbers	615
	Solid Angle	604	A-6	Quaternions	617
A-2	Points and Vectors	605	A-7	Nonparametric Representations	618
	Vector Addition and Scalar Multiplication	607	A-8	Parametric Representations	619
	Scalar Product of Two Vectors	607	A-9	Numerical Methods	620
	Vector Product of Two Vectors	608		Solving Sets of Linear Equations	620
A-3	Basis Vectors and the Metric Tensor Orthonormal Basis	609 609		Finding Roots of Nonlinear Equations	621
	Metric Tensor	610		Evaluating Integrals	622
A-4	Matrices	611		Fitting Curves to Data Sets	625
	Scalar Multiplication and Matrix Addition	612	BIBLIO	GRAPHY	626
	Matrix Multiplication	612	INDEX		639

Computer Graphics C Version