# GENERAL AVIATION AIRCRAFT DESIGN

APPLIED METHODS AND PROCEDURES SNORRI GUDMUNDSSON





# GENERAL AVIATION AIRCRAFT DESIGN: APPLIED METHODS AND PROCEDURES

SNORRI GUDMUNDSSON BScAE, MScAE, FAA DER(ret.)

Assistant Professor of Aerospace Engineering, Embry-Riddle Aeronautical University







Butterworth-Heinemann is an imprint of Elsevier The Boulevard, Langford Lane, Kidlington, Oxford OX5 1GB, UK 225 Wyman Street, Waltham, MA 02451, USA

First edition 2014

Copyright © 2014 Elsevier Inc. All rights reserved.

No part of this publication may be reproduced, stored in a retrieval system or transmitted in any form or by any means electronic, mechanical, photocopying, recording or otherwise without the prior written permission of the publisher

Permissions may be sought directly from Elsevier's Science & Technology Rights Department in Oxford, UK: phone (+44) (0) 1865 843830; fax (+44) (0) 1865 853333; email: permissions@elsevier.com. Alternatively you can submit your request online by visiting the Elsevier web site at http://elsevier.com/locate/permissions, and selecting Obtaining permission to use Elsevier material

#### Notice

No responsibility is assumed by the publisher for any injury and/or damage to persons or property as a matter of products liability, negligence or otherwise, or from any use or operation of any methods, products, instructions or ideas contained in the material herein. Because of rapid advances in the medical sciences, in particular, independent verification of diagnoses and drug dosages should be made

#### Library of Congress Cataloging-in-Publication Data

A catalog record for this book is available from the Library of Congress

#### British Library Cataloguing-in-Publication Data

A catalogue record for this book is available from the British Library

ISBN: 978-0-12-397308-5

For information on all Butterworth-Heinemann publications visit our website at elsevierdirect.com

Printed and bound in United States of America

13 14 15 16 17 10 9 8 7 6 5 4 3 2 1



### Contents

	1. The Aircraft Design Process	3.2	Constraint Analysis 57 3.2.1 General Methodology 58	
.1	Introduction 2		3.2.2 Introduction of Stall Speed Limits into	
	1.1.1 The Content of this Chapter 5		the Constraint Diagram 65	
	1.1.2 Important Elements of a New Aircraft	3.3	Introduction to Trade Studies 66	
	Design 5		3.3.1 Step-by-step: Stall Speed — Cruise Speed	
	General Process of Aircraft Design 11		Carpet Plot 67	
	1.2.1 Common Description of the Design Process 11		3.3.2 Design of Experiments 69	
	1.2.2 Important Regulatory Concepts 13		3.3.3 Cost Functions 72	
1.3	Aircraft Design Algorithm 15		Exercises 74	
	1.3.1 Conceptual Design Algorithm for a GA Aircraft 16		Variables 75	
	1.3.2 Implementation of the Conceptual Design Algorithm 16		4. Aircraft Conceptual Layout	
1.4	Elements of Project Engineering 19	4 1	Introduction 77	
	1.4.1 Gantt Diagrams 19	1.1	4.1.1 The Content of this Chapter 78	
	1.4.2 Fishbone Diagram for Preliminary		4.1.2 Requirements, Mission, and Applicable Regulations	7
	Airplane Design 19		4.1.3 Past and Present Directions in Aircraft Design 79	
	1.4.3 Managing Compliance with Project		4.1.4 Aircraft Component Recognition 79	
	Requirements 21	4.2	The Fundamentals of the Configuration Layout 82	
	1.4.4 Project Plan and Task Management 21		4.2.1 Vertical Wing Location 82	
	1.4.5 Quality Function Deployment and a House		4.2.2 Wing Configuration 86	
	of Quality 21		4.2.3 Wing Dihedral 86	
1.5	Presenting the Design Project 27		4.2.4 Wing Structural Configuration 87	
	Variables 32		4.2.5 Cabin Configurations 88	
	References 32		4.2.6 Propeller Configuration 89	
			4.2.7 Engine Placement 89	
	2. Aircraft Cost Analysis	*	4.2.8 Landing Gear Configurations 91	
			4.2.9 Tail Configurations 92	
2.1	Introduction 33		4.2.10 Configuration Selection Matrix 92	
	2.1.1 The Content of this Chapter 34		Variables 93 References 95	
	2.1.2 A Review of the State of the GA		References 93	
2 2	Industry 34 Estimating Project Development Costs 36		5 A: C C	
L.L	2.2.1 Quantity Discount Factor 36		5. Aircraft Structural Layout	
	2.2.2 Development Cost of a GA Aircraft — the Eastlake		1 1 1 07	
	Model 37	5.	Introduction 97	
	2.2.3 Development Cost of a Business Aircraft — the Eastlake		5.1.1 The Content of this Chapter 98 5.1.2 Notes on Aircraft Loads 98	
	Model 44	5 3	2 Aircraft Fabrication and Materials 98	
2.3	Estimating Aircraft Operational Costs 46	9.4	5.2.1 Various Fabrication Methods 100	
	2.3.1 Operational Cost of a GA Aircraft 46		5.2.2 Aluminum Alloys 103	
	2.3.2 Operational Cost of a Business Aircraft 49		5.2.3 Steel Alloys 106	
	Exercises 51		5.2.4 Titanium Alloys 107	
	Variables 52		5.2.5 Composite Materials 108	
	References 53	5.3	3 Airframe Structural Layout 116	
			5.3.1 Important Structural Concepts 116	
	3. Initial Sizing		5.3.2 Fundamental Layout of the Wing Structure 120	
			5.3.3 Fundamental Layout of the Horizontal	
3.1	Introduction 55		and Vertical Tail Structures 126	
	3.1.1 The Content of this Chapter 56		5.3.4 Fundamental Layout of the Fuselage Structure 128	
	3.1.2 Fundamental Concepts 56		Variables 131	
	3.1.3 Software Tools 57		References 131	

#### 6. Aircraft Weight Analysis

6.1	Introd	uction	134
0.1	Introd	uction	134

6.1.1 The Content of this Section 135

6.1.2 Definitions 135

6.1.3 Fundamental Weight Relations 137

6.1.4 Mission Analysis 137

6.2 Initial Weight Analysis Methods 138

6.2.1 Method 1: Initial Gross Weight Estimation Using Historical Relations 138

6.2.2 Method 2: Historical Empty Weight Fractions 140

6.3 Detailed Weight Analysis Methods 141

6.4 Statistical Weight Estimation Methods 142

6.4.1 Method 3: Statistical Aircraft Component Methods 142

6.4.2 Statistical Methods to Estimate Engine
Weight 145

6.5 Direct Weight Estimation Methods 147

6.5.1 Direct Weight Estimation for a Wing 147

6.5.2 Variation of Weight with AR 154

6.6 Inertia Properties 161

6.6.1 Fundamentals 161

6.6.2 Reference Locations 162

6.6.3 Total Weight 162

6.6.4 Moment about (X<sub>0</sub>, Y<sub>0</sub>, Z<sub>0</sub>) 162

6.6.5 Center of Mass, Center of Gravity 164

6.6.6 Determination of CG Location by Aircraft Weighing 165

6.6.7 Mass Moments and Products of Inertia 165

6.6.8 Moment of Inertia of a System of Discrete Point Loads 167

6.6.9 Product of Inertia of a System of Discrete Point Loads 168

6.6.10 Inertia matrix 168

6.6.11 Center of Gravity Envelope 168

6.6.12 Creating the CG Envelope 169

6.6.13 In-flight Movement of the CG 173

6.6.14 Weight Budgeting 173

6.6.15 Weight Tolerancing 174

Exercises 176

Variables 178

References 180

#### 7. Selecting the Power Plant

#### 7.1 Introduction 182

7.1.1 The Content of this Section 183

7.1.2 Power Plant Options for Aviation 183

7.1.3 The Basics of Energy, Work, and Power 183

7.1.4 Thermodynamics of the Power Plant 183

7.1.5 General Theory of Thrust Generation 184

7.1.6 Fundamental Definitions 185

7.1.7 Fuel Basics 187

7.2 The Properties of Selected Engine Types 190

7.2.1 Piston Engines 190

7.2.2 Turboprops 196

7.2.3 Turbojets 199

7.2.4 Turbofans 200

#### 7.2.5 Electric Motors 203

7.2.6 Computer code: Thrust as a Function of Altitude and Mach Number 207

7.3 Aircraft Power Plant Installation 209

7.3.1 Piston Engine Installation 210

7.3.2 Piston Engine Inlet and Exit Sizing 213

7.3.3 Installation of Gas Turbines 222

7.3.4 Jet Engine Inlet Sizing 223

#### 7.4 Special Topics 227

7.4.1 The Use of Gearboxes 227

7.4.2 Step-by-step: Extracting Piston Power from Engine Performance Charts 228

7.4.3 Extracting Piston Power Using the Petty Equation 229

Exercises 232

Variables 232

References 234

#### 8. The Anatomy of the Airfoil

#### 8.1 Introduction 236

8.1.1 The Content of this Section 237

8.1.2 Dimensional Analysis – Buckingham's Π Theorem 237

8.1.3 Representation of Forces and Moments 238

8.1.4 Properties of Typical Airfoils 239

8.1.5 The Pressure Coefficient 241

8.1.6 Chordwise Pressure Distribution 242

8.1.7 Center of Pressure and Aerodynamic Center 243

8.1.8 The Generation of Lift 245

8.1.9 Boundary Layer and Flow Separation 247

8.1.10 Estimation of Boundary Layer Thickness 250

8.1.11 Airfoil Stall Characteristics 251

8.1.12 Analysis of Ice-accretion on Airfoils 252

8.1.13 Designations of Common Airfoils 253

8.1.14 Airfoil Design 254

8.2 The Geometry of the Airfoil 256

8.2.1 Airfoil Terminology 256

8.2.2 NACA Four-digit Airfoils 257

8.2.3 NACA Five-digit Airfoils 261

8.2.4 NACA 1-series Airfoils 263

8.2.5 NACA 6-series Airfoils 264

8.2.6 NACA 7-series Airfoils 266

8.2.7 NACA 8-series Airfoils 267

8.2.8 NACA Airfoils in Summary – Pros and Cons and Comparison of Characteristics 267

8.2.9 Properties of Selected NACA Airfoils 267

8.2.10 Famous Airfoils 267

8.3 The Force and Moment Characteristics of the Airfoil 275

8.3.1 The Effect of Camber 276

8.3.2 The Two-dimensional Lift Curve 276

8.3.3 The Maximum Lift Coefficient, C<sub>lmax</sub> 276

8.3.4 The Effect of Reynolds Number 277

8.3.5 Compressibility Effects 278

8.3.6 Compressibility Modeling 280

8.3.7 The Critical Mach Number, M<sub>crit</sub> 281

8.3.8 The Effect of Early Flow Separation 282

8.3.9 The Effect of Addition of a Slot or Slats 283

8.3.10 The Effect of Deflecting a Flap 284

8.3.11 The Effect of Cruise Flaps 284

8.3.12 The Effect of Deploying a Spoiler 285

CONTENTS

vii

C <sub>Lmax</sub> for Selected Aircraft 360 Estimation of Oswald's Span Efficiency 363
tall Characteristics 366
rowth of Flow Separation on an Aircraft 367
eneral Stall Progression on Selected Wing
Planform Shapes 369
eviation from Generic Stall Patterns 369
ailoring the Stall Progression 369
ause of Spanwise Flow for a Swept-back
Wing Planform 374
itch-up Stall Boundary for a Swept-back
Wing Planform 375
of Manufacturing Tolerances
on Stall Characteristics 378
cal Analysis of the Wing 379
randtl's Lifting Line Theory 379
randtl's Lifting Line Method — Special Case:
The Elliptical Wing 384
randtl's Lifting Line Method — Special Case:
Arbitrary Wings 386
accounting for a Fuselage in Prandtl's Lifting
Line Method 390
Computer code: Prandtl's Lifting
Line Method 393
es 396
es 397
ices 398
. The Anatomy of Lift Enhancement
,
uction 402
The Content of this Chapter 403
ng Edge High-lift Devices 403
Hinged Leading Edge (Droop Nose) 403
Variable-camber Leading Edge 405
Fixed Slot 406
The Krüger Flap 408
The Leading Edge Slat 412
Summary of Leading Edge Device Data 416
ng Edge High-lift Devices 417
Plain Flap 417
Split Flap 420
Junkers Flap or External Flap 423
The Single-slotted Flap 425
Double-slotted Flaps 427
Fowler Flaps 430
Gurney Flap 432
Summary of Trailing Edge Device Data 434
of Deploying High-lift Devices on Wings 436
Lift Distribution on Wings with Flaps
Deflected 436 Wing Portition Method 437
Wing Partition Method 437
tip Design 441 The Round Wingtip 443
Hoerner Wingtip 446
Raked Wingtin 446
The Spherical Wingtip 443 The Square Wingtip 444 Booster Wingtips 444
Ное

9.1

9.2

9.3

9.4

9.5

10.5.7 Endplate Wingtip 448

10.5.7 Endplate Wingtip 448	12. The Anatomy of the Fuselage
10.5.8 The Winglet 448	,
10.5.9 The Polyhedral Wing(tip) 452	12.1 Introduction 521
10.5.10 Comparison Based on Potential Flow Theory 453	12.1.1 The Content of this Chapter 521
Variables 455	12.1.2 The Function of the Fuselage 522
References 456	12.2 Fundamentals of Fuselage Shapes 523
	12.2.1 The Frustum-shaped Fuselage 523
11. The Anatomy of the Tail	12.2.2 The Pressure Tube Fuselage 523
•	12.2.3 The Tadpole Fuselage 524
11.1 Introduction 460	12.3 Sizing the Fuselage 526
11.1.1 The Content of this Chapter 461	12.3.1 Initial Design of the External Shape
11.1.2 The Process of Tail Sizing 461	of the Fuselage 526
11.2 Fundamentals of Static Stability and Control 462	12.3.2 Refining the External Shape of the Fuselage 529
11.2.1 Fundamentals of Static Longitudinal Stability 463	12.3.3 Internal Dimensions of the Fuselage 531
11.2.2 Modeling the Pitching Moment for a Simple	12.3.4 Cockpit Layout 532
Wing-HT System 466	12.4 Estimating the Geometric Properties of the Fuselage 535
11.2.3 Horizontal Tail Downwash Angle 466	12.4.1 Simple Estimation of the Surface Area of a Body
11.2.4 Historical Values of C <sub>mα</sub> 468	of Revolution 536
11.2.5 Longitudinal Equilibrium for Any Configuration 468	12.4.2 Fundamental Properties of Selected Solids 536
11.2.6 The Stick-fixed and Stick-free Neutral Points 472	12.4.3 Surface Areas and Volumes of a Typical
11.2.7 Fundamentals of Static Directional and Lateral	Tubular Fuselage 538
Stability 475	12.4.4 Surface Areas and Volumes of a Tadpole Fuselage 539
11.2.8 Requirements for Static Directional Stability 476	12.4.5 Surface Areas and Volumes of a Pod-style Fuselage 544
11.2.9 Requirements for Lateral Stability 477	12.5 Additional Information 544
11.2.10 Historical Values of $C_{n\beta}$ and $C_{l\beta}$ 477	Variables 545
11.2.11 The Dorsal Fin 477	References 545
11.2.12 The Ventral Fin 480	
11.2.13 Tail Design and Spin Recovery 482	13. The Anatomy of the Landing Gear
11.3 On the Pros and Cons of Tail Configurations 483	,
11.3.1 Conventional Tail 483	13.1 Introduction 548
11.3.2 Cruciform Tail 486	13.1.1 The Content of this Chapter 548
11.3.3 T-tail 486	13.1.2 Landing Gear Arrangement 548
11.3.4 V-tail or Butterfly Tail 489	13.1.3 Landing Gear Design Checklist 549
11.3.5 Inverted V-tail 493	13.2 Tires, Wheels, and Brakes 551
11.3.6 Y-tail 493	13.2.1 Important Dimensions and Concepts for Landing
11.3.7 Inverted Y-tail 494	Gear Design 551
11.3.8 H-tail 494	13.2.2 Retractable Landing Gear 553
11.3.9 Three-surface Configuration 495	13.2.3 Types and Sizes of Tires, Wheels and Brakes 555
11.3.10 A-tail 495	13.2.4 Types of Landing Gear Legs 560
11.3.11 Twin Tail-boom or U-tail Configuration 496	13.2.5 Reaction of Landing Gear Forces 565
11.3.12 Canard Configuration 496	13.2.6 Comparing the Ground Characteristics
11.3.13 Design Guidelines when Positioning	of Taildragger and Tricycle Landing Gear 565
the HT for an Aft Tail Configuration 497	13.3 Geometric Layout of the Landing Gear 567
11.4 The Geometry of the Tail 499	13.3.1 Geometric Layout of the Tricycle Landing Gear 567
11.4.1 Definition of Reference Geometry 499	13.3.2 Geometric Layout of the Taildragger Landing
11.4.2 Horizontal and Vertical Tail Volumes 500	Gear 569
11.4.3 Design Guidelines for HT Sizing for Stick-fixed	13.3.3 Geometric Layout of the Monowheel Landing
Neutral Point 501	Gear with Outriggers 571
11.4.4 Recommended Initial Values for V <sub>HT</sub> and V <sub>VT</sub> 502	13.3.4 Tricycle Landing Gear Reaction Loads 571
11.5 Initial Tail Sizing Methods 502	13.3.5 Taildragger Landing Gear Reaction Loads 576
11.5.1 Method 1: Initial Tail Sizing Optimization	Variables 579
Considering the Horizontal Tail Only 503	References 580
11.5.2 Method 2: Initial Tail Sizing Optimization	
Considering the Vertical Tail Only 510	14. The Anatomy of the Propeller
11.5.3 Method 3: Initial Tail Sizing Optimization	21. The I material of the Hopeffel
Considering Horizontal and Vertical Tail 513	14.1 Introduction 582
Exercises 517	14.1.1 The Content of this Chapter 584
Variables 517	14.1.2 Propeller Configurations 584
References 519	14.1.3 Important Nomenclature 586

CONTENTS ix

14.1.4 Propeller Geometry 587	15.2 The Drag Model 665
14.1.5 Geometric Propeller Pitch 588	15.2.1 Basic Drag Modeling 666
14.1.6 Windmilling Propellers 593	15.2.2 Quadratic Drag Modeling 666
14.1.7 Fixed Versus Constant-speed Propellers 594	15.2.3 Approximating the Drag Coefficient at
14.1.8 Propulsive or Thrust Power 595	High Lift Coefficients 670
14.2 Propeller Effects 595	15.2.4 Non-quadratic Drag Modeling 672
14.2.1 Angular Momentum and Gyroscopic Effects 596	15.2.5 Lift-induced Drag Correction Factors 672
14.2.2 Slipstream Effects 597	15.2.6 Graphical Determination of $L/D_{\text{max}}$ 673
14.2.3 Propeller Normal and Side Force 598	15.2.7 Comparing the Accuracy of the Simplified
14.2.4 Asymmetric Yaw Effect 599	and Adjusted Drag Models 673
14.2.5 Asymmetric Yaw Effect for a Twin-engine	15.3 Deconstructing the Drag Model: the Drag Coefficients 674
Aircraft 599	15.3.1 Basic Drag Coefficient: C <sub>D0</sub> 674
14.2.6 Blockage Effects 602	
14.2.7 Hub and Tip Effects 604	15.3.2 The Skin Friction Drag Coefficient: C <sub>Df</sub> 675
14.2.8 Effects of High Tip Speed 605	15.3.3 Step-by-step: Calculating the Skin Friction
14.2.9 Skewed Wake Effects – A·q Loads 605	Drag Coefficient 680
14.2.10 Propeller Noise 606	15.3.4 The Lift-induced Drag Coefficient: C <sub>Di</sub> 686
14.3 Properties and Selection of the Propeller 607	15.3.5 Total Drag Coefficient: C <sub>D</sub> 691
	15.3.6 Various Means to Reduce Drag 691
14.3.1 Tips for Selecting a Suitable Propeller 607	15.4 The Drag Characteristics of the Airplane as a Whole 693
14.3.2 Rapid Estimation of Required Prop Diameter 608	15.4.1 The Effect of Aspect Ratio on a Three-dimensional
14.3.3 Rapid Estimation of Required Propeller	Wing 693
Pitch 610	15.4.2 The Effect of Mach Number 695
14.3.4 Estimation of Required Propeller Efficiency 610	15.4.3 The Effect of Yaw Angle β 695
14.3.5 Advance Ratio 611	15.4.4 The Effect of Control Surface Deflection —
14.3.6 Definition of Activity Factor 613	Trim Drag 695
14.3.7 Definition of Power- and Thrust-related	15.4.5 The Rapid Drag Estimation Method 696
Coefficients 614	15.4.6 The Component Drag Build-up Method 697
14.3.8 Effect of Number of Blades on Power 615	15.4.7 Component Interference Factors 700
14.3.9 Propulsive Efficiency 618	15.4.8 Form Factors for Wing, HT, VT, Struts,
14.3.10 Moment of Inertia of the Propeller 619	Pylons 700
14.4 Determination of Propeller Thrust 620	15.4.9 Form Factors for a Fuselage and a Smooth
14.4.1 Converting Piston BHP to Thrust 620	Canopy 701
14.4.2 Propeller Thrust at Low Airspeeds 621	15.5 Miscellaneous or Additive Drag 708
14.4.3 Step-by-step: Determining Thrust Using	15.5.1 Cumulative Result of Undesirable
a Propeller Efficiency Table 630	Drag (CRUD) 709
14.4.4 Estimating Thrust From Manufacturer's Data 631	15.5.2 Trim Drag 710
14.4.5 Other Analytical Methods 632	15.5.3 Cooling Drag 714
14.5 Rankine-Froude Momentum Theory 632	15.5.4 Drag of Simple Wing-like Surfaces 715
14.5.1 Formulation 633	15.5.5 Drag of Streamlined Struts and Landing
14.5.2 Ideal Efficiency 635	Gear Pant Fairings 715
14.5.3 Maximum Static Thrust 636	15.5.6 Drag of Landing Gear 718
14.5.4 Computer code: Estimation of Propeller	15.5.7 Drag of Floats 724
Efficiency Using the Momentum Theorem 638	15.5.8 Drag of Deployed Flaps 725
14.6 Blade Element Theory 640	15.5.9 Drag Correction for Cockpit Windows 726
14.6.1 Formulation 641	15.5.10 Drag of Canopies 727
14.6.2 Determination of $\alpha_i$ Using the Momentum	15.5.11 Drag of Blisters 728
Theory 650	15.5.12 Drag Due to Compressibility Effects 730
14.6.3 Compressibility Corrections 654	15.5.13 Drag of Windmilling and Stopped
14.6.4 Step-by-step: Prandtl's Tip and Hub Loss	Propellers 731
Corrections 655	15.5.14 Drag of Antennas 731
14.6.5 Computer code: Determination	15.5.15 Drag of Various Geometry 732
of the Propeller Induced Velocity 656	15.5.16 Drag of Parachutes 735
Variables 657	15.5.17 Drag of Various External Sources 736
References 658	15.5.18 Corrections of the Lift-induced Drag 737
	15.6 Special Topics Involving Drag 740
15. Aircraft Drag Analysis	15.6.1 Step-by-step: Extracting Drag
13. Tilletait Diag Milalysis	from $L/D_{\text{max}}$ 740
15.1 Introduction 663	15.6.2 Step-by-step: Extracting Drag from a Flight
15.1.1 The Content of this Chapter 665	Polar Using the Quadratic Spline Method 741

X

15.6.3 Step-by-step: Extracting Drag Coefficient for a Piston-powered Propeller Aircraft 744 15.6.4 Computer code 15-1: Extracting Drag	17.2 Fundamental Relations for the Take-Off Run 797 17.2.1 General Free-body Diagram of the T-O Ground Run 797
Coefficient from Published Data for Piston Aircraft 748	17.2.2 The Equation of Motion for a T-O Ground Run 79 17.2.3 Review of Kinematics 799
15.6.5 Step-by-step: Extracting Drag Coefficient for a Jet Aircraft 749	17.2.4 Formulation of Required Aerodynamic Forces 800 17.2.5 Ground Roll Friction Coefficients 800
15.6.6 Determining Drag Characteristics from Wind	17.2.6 Determination of the Lift-off Speed 800
Tunnel Data 750 15.7 Additional Information — Drag of Selected Aircraft 752	17.2.7 Determination of Time to Lift-off 802
15.7.1 General Range of Subsonic Minimum  Drag Coefficients 752	17.3 Solving the Equation of Motion of the T-O 802 17.3.1 Method 1: General Solution of the Equation of Motion 802
15.7.2 Drag of Various Aircraft by Class 752	17.3.2 Method 2: Rapid T-O Distance Estimation
Exercises 756	for a Piston-powered Airplane [5] 805
Variables 757 References 759	17.3.3 Method 3: Solution Using Numerical Integration Method 807
references	17.3.4 Determination of Distance During
16. Performance — Introduction	Rotation 813
20. 20.00	17.3.5 Determination of Distance for Transition 813
16.1 Introduction 761	17.3.6 Determination of Distance for Climb Over an Obstacle 814
16.1.1 The Content of this Chapter 762	17.3.7 Treatment of T-O Run for a Taildragger 815
16.1.2 Performance Padding Policy 762 16.2 Atmospheric Modeling 763	17.3.8 Take-off Sensitivity Studies 816
16.2.1 Atmospheric Ambient Temperature 763	17.4 Database — T-O Performance of Selected Aircraft 817
16.2.2 Atmospheric Pressure and Density for Altitudes	Exercises 817
below 36,089 ft (11,000 m) 764	Variables 819 References 820
16.2.3 Atmospheric Property Ratios 764 16.2.4 Pressure and Density Altitudes below 36,089 ft	References 020
(11,000 m) 765	18. Performance — Climb
16.2.5 Density of Air Deviations from a Standard	10. Tellormance Simile
Atmosphere 765	18.1 Introduction 821
16.2.6 Frequently Used Formulas for a Standard	18.1.1 The Content of this Chapter 822
Atmosphere 767 16.3 The Nature of Airspeed 768	18.2 Fundamental Relations for the Climb Maneuver 822 18.2.1 General Two-dimensional Free-body Diagram
16.3.1 Airspeed Indication Systems 768	for an Aircraft 822
16.3.2 Airspeeds: Instrument, Calibrated, Equivalent,	18.2.2 General Planar Equations of Motion
True, and Ground 769	of an Airplane 823
16.3.3 Important Airspeeds for Aircraft Design and Operation 771	18.2.3 Equations of Motion for Climbing Flight 823 18.2.4 Horizontal and Vertical Airspeed 824
16.4 The Flight Envelope 774	18.2.5 Power Available, Power Required,
16.4.1 Step-by-step: Maneuvering Loads	and Excess Power 824
and Design Airspeeds 775	18.2.6 Vertical Airspeed in Terms of Thrust
16.4.2 Step-by-step: Gust Loads 778	or Power 824
16.4.3 Step-by-step: Completing the Flight Envelope 782	18.2.7 Rate-of-climb 825 18.3 General Climb Analysis Methods 825
16.4.4 Flight Envelopes for Various GA Aircraft 782	18.3.1 General Rate-of-climb 825
16.5 Sample Aircraft 783	18.3.2 General Climb Angle 827
16.5.1 Cirrus SR22 783	18.3.3 Max Climb Angle for a Jet 827
16.5.2 Learjet 45XR 785 Exercises 786	18.3.4 Airspeed for $\theta_{\text{max}}$ for a Jet
Variables 787	(Best Angle-of-climb Speed) 828 18.3.5 ROC for $\theta_{max}$ for a Jet 829
References 789	18.3.6 Airspeed for Best ROC for a Jet 829
	18.3.7 Best ROC for a Jet 831
17. Performance — Take-Off	18.3.8 Airspeed for $\theta_{\text{max}}$ for a Propeller-powered
17.1 Introduction 791	Airplane 832 18.3.9 Airspeed for Best ROC for a Propeller-powered
17.1 Introduction 791 17.1.1 The Content of this Chapter 792	Airplane 833
17.1.2 Important Segments of the T-O Phase 792	18.3.10 Best Rate-of-climb for a Propeller-powered
17.1.3 Definition of a Balanced Field Length 795	Airplane 834

798

xi CONTENTS

	18.3.11 Time to Altitude 836 18.3.12 Absolute/Service Ceiling Altitude 838 18.3.13 Numerical Analysis of the Climb  Maneuver — Sensitivity Studies 840 Aircraft Database — Rate-of-climb of Selected  Aircraft 842 Variables 844 References 845		Range Analysis 899 20.2.1 Mission Profiles 899 20.2.2 Range Profile 1: Constant Airspeed/ Constant Altitude Cruise 899 20.2.3 Range Profile 2: Constant Altitude/Constant Attitude Cruise 901 20.2.4 Range Profile 3: Constant Airspeed/Constant Attitude Cruise 902 20.2.5 Range Profile 4: Cruise Range in the Absence
	19. Performance — Cruise		of Weight Change 903
	Introduction 848 19.1.1 The Content of this Chapter 849	20.3	20.2.6 Determining Fuel Required for a Mission 907 20.2.7 Range Sensitivity Studies 908 Specific Range 909
	19.1.2 General Free-body Diagram for Steady		20.3.1 Definitions 909 20.3.2 CAFE Foundation Challenge 910
	Level Flight 849  19.1.3 Planar Equations of Motion (Assumes No Rotation About y-axis) 849  19.1.4 Important Airspeeds for Propeller Aircraft 850  19.1.5 Important Airspeeds for Subsonic Jet Aircraft 851  General Cruise Analysis Methods for Steady Flight 851  19.2.1 Plotting the Drag Polar 852  19.2.2 Drag Breakdown 852	20.4	Fundamental Relations for Endurance Analysis 911 20.4.1 Endurance Profile 1: Constant Airspeed/ Constant Altitude Cruise 911 20.4.2 Endurance Profile 2: Constant Attitude/ Altitude Cruise 912 20.4.3 Endurance Profile 3: Constant Airspeed/ Attitude Cruise 913
	19.2.3 Required versus Available Thrust 855 19.2.4 Airspeed in Terms of Thrust 857 19.2.5 Minimum Airspeed, V <sub>min</sub> 860 19.2.6 Stalling Speed, V <sub>S</sub> 860 19.2.7 Airspeed of Minimum Power Required, V <sub>PRmin</sub> 864 19.2.8 Airspeed of Minimum Thrust Required, V <sub>TRmin</sub> , or Best Glide Speed, V <sub>BG</sub> , V <sub>LDmax</sub> 867 19.2.9 Best Range Airspeed for a Jet, V <sub>Rmax</sub> 875 19.2.10 Maximum Level Airspeed, V <sub>max</sub> 877 19.2.11 Flight Envelope 880 19.2.12 Power Required 882	20.5	Analysis of Mission Profile 914 20.5.1 Basics of Mission Profile Analysis 915 20.5.2 Methodology for Mission Analysis 916 20.5.3 Special Range Mission 1: IFR Cruise Mission 918 20.5.4 Special Range Mission 2: NBAA Cruise Mission 919 20.5.5 Payload-Range Sensitivity Study 919 Exercises 921 Variables 922 References 923
	19.2.13 Power Available for a Piston-powered Aircraft 883	Shortself at	21. Performance — Descent
19.3	19.2.14 Computer code: Determining Maximum  Level Airspeed, V <sub>max</sub> , for a Propeller Aircraft 883  19.2.15 Computer code: Determining Maximum  Level Airspeed, V <sub>max</sub> , for a Jet 884  General Analysis Methods for Accelerated Flight 885		Introduction 925 21.1.1 The Content of this Chapter 926 Fundamental Relations for the Descent Maneuver 926 21.2.1 General Two-dimensional Free-body Diagram for an Aircraft 926
	19.3.1 Analysis of a General Level Constant-velocity		21.2.2 Planar Equations of Motion
	Turn 885  19.3.2 Extremes of Constant-velocity Turns 889  19.3.3 Energy State 891  Variables 893  References 894  20. Performance — Range Analysis	21.3	(Assumes no Rotation about y-axis) 927 General Descent Analysis Methods 927 21.3.1 General Angle-of-descent 927 21.3.2 General Rate-of-descent 927 21.3.3 Equilibrium Glide Speed 929 21.3.4 Sink Rate 930 21.3.5 Airspeed of Minimum Sink Rate, V <sub>BA</sub> 931
20.1	Introduction 896 20.1.1 The Content of this Chapter 896 20.1.2 Basic Cruise Segment for Range Analysis 896 20.1.3 Basic Cruise Segment in Terms of Range		21.3.6 Minimum Angle-of-descent 931 21.3.7 Best Glide Speed, V <sub>BG</sub> 931 21.3.8 Glide Distance 932 Variables 933 References 934
	Versus Weight 896 20.1.4 The "Breguet" Range Equation 897 20.1.5 Basic Cruise Segment for Endurance		22. Performance — Landing
	Analysis 897 20.1.6 The "Breguet" Endurance Equation 898 20.1.7 Notes on SFC and TSFC 898	22.1	Introduction 935 22.1.1 The Content of this Chapter 936 22.1.2 Important Segments of the Landing Phase 936

xii CONTE

<b>K11</b>	CONT	EN15
22.2	Fundamental Relations for the Landing Phase 938 22.2.1 General Free-body Diagram of the Landing Roll 938	<ul><li>23.3.11 Natural Damping Capability 969</li><li>23.3.12 Fuel Tank Selector 969</li><li>23.3.13 Control System Stretching 969</li></ul>
	22.2.2 The Equation of Motion for the Landing Roll 938	23.3.14 Control System Jamming 970
	22.2.3 Formulation of Required Aerodynamic Forces 938	23.3.15 Ground Impact Resistance 970
	22.2.4 Ground Roll Friction Coefficients 939	23.3.16 Reliance Upon Analysis Technology 971
	22.2.5 Determination of the Approach Distance, S <sub>A</sub> 939	23.3.17 Weight Estimation Pitfalls 972
	22.2.6 Determination of the Flare Distance, S <sub>F</sub> 940	23.3.18 Drag Estimation Pitfalls 972
	22.2.7 Determination of the Free-roll Distance, SFR 940	23.3.19 Center of Gravity Travel During Flight 972
	22.2.8 Determination of the Braking Distance, S <sub>BR</sub> 940	23.3.20 Wing/Fuselage Juncture Flow Separation 972
	22.2.9 Landing Distance Sensitivity Studies 942	23.4 Faults and Fixes 972
	22.2.10 Computer code: Estimation of	23.4.1 Stability and Control – Dorsal Fin and Rudder
	Landing Performance 942	Locking 973
22.3	Database — Landing Performance of Selected Aircraft 944	23.4.2 Stability and Control – Ventral Fin and Deep
	Variables 945	Stall 973
	References 946	23.4.3 Stability and Control – Ventral Fin
		and Dutch Roll 973
	22 M: 11 D: M:	23.4.4 Stability and Control – Forebody Strakes 973
	23. Miscellaneous Design Notes	23.4.5 Stability and Control – Taillets
22 1	1 . 1 .: 040	and Stabilons 974
23.1	Introduction 948	23.4.6 Stability and Control – Control Horns 975
12 7	23.1.1 The Content of this Chapter 948	23.4.7 Stall Handling — Stall Strips 975
23.2	Control Surface Sizing 948 23.2.1 Introduction to Control Surface Hinge Moments 948	23.4.8 Stall Handling — Wing Fence 976 23.4.9 Stall Handling — Wing Pylons 977
	23.2.2 Fundamentals of Roll Control 949	23.4.10 Stall Handling — Writig Pytons 977
	23.2.3 Aileron Sizing 960	23.4.11 Stall Handling — Wing Droop
	23.2.4 Fundamentals of Pitch Control 962	(Cuffs, Leading Edge Droop) 978
	23.2.5 Fundamentals of Yaw Control 964	23.4.12 Flow Improvement – Vortex Generators 978
23.3	General Aviation Aircraft Design Checklist 964	23.4.13 Trailing Edge Tabs for Multi-element
	23.3.1 Crosswind Capability at Touch-Down 965	Airfoils 980
	23.3.2 Balked Landing Capability 965	23.4.14 Flow Improvement — Nacelle Strakes 981
	23.3.3 Take-off Rotation Capability 966	23.4.15 Flow Improvement — Bubble-drag, Turbulators
	23.3.4 Trim at Stall and Flare at Landing Capability 966	and Transition Ramps 981
	23.3.5 Stall Handling Capability 966	Variables 982
	23.3.6 Stall Margin for Horizontal Tail 967	References 983
	23.3.7 Roll Authority 967	
	23.3.8 Control System Harmony 968	Annendix A 985

Appendix A 985 Appendix B 997 Index 1007

For supporting materials please visit:

23.3.9 Climb Capability 968

http://booksite.elsevier.com/9780123973085

23.3.10 One-engine-inoperative Trim and Climb

Capability 969

# 1

# The Aircraft Design Process

1.1	Introduction	2	Technical Standard Order Authorization	
	1.1.1 The Content of this Chapter	5	(TSOA)	15
	1.1.2 Important Elements of a New Aircraft		Parts Manufacturer Approval (PMA)	15
	Design	5		15
	Definition of the Mission	5	1.3 Aircraft Design Algorithm 1.3.1 Conceptual Design Algorithm for a GA	15
	Performance Requirements and Sensitivity	5	Aircraft	16
	Handling Requirements (Stability and		1.3.2 Implementation of the Conceptual	10
	Control)	5	Design Algorithm	16
	Ease of Manufacturing	6		
	Certifiability	6	1.4 Elements of Project Engineering	19
	Features and Upgradability (Growth)	7	1.4.1 Gantt Diagrams	19
	Aesthetics	7	1.4.2 Fishbone Diagram for Preliminary Airplane	• • •
	Maintainability	8	Design	19
	Lean Engineering and Lean Manufacturing	8	1.4.3 Managing Compliance with Project	21
	Integrated Product Teams (IPT) Fundamental Phases of the Aircraft	9	Requirements 1.4.4 Project Plan and Task Management	21
	Design Process	9	1.4.4 Project Funt and Task Management 1.4.5 Quality Function Deployment and a House	21
	Design Process  Development Program Phase	11	of Quality	21
	Post-development Programs	11	Step 1: Customer Requirements	22
		11	Step 2: Technical Requirements	24
1.2	General Process of Aircraft Design	11	Step 3: Roof	25
	1.2.1 Common Description of the Design		Step 4: Interrelationship Matrix	26
	Process	11	Step 5: Targets	27
	Elementary Outline of the Design		Step 6: Comparison Matrix	27
	Process	11 12		25
	Design Process per Torenbeek Typical Design Process for GA Aircraft	13	1.5 Presenting the Design Project Three-view Drawings	27
	1.2.2 Important Regulatory Concepts	13	Images Using Solid Modelers	28
	Type Certificate (TC)	13	Images Using Solid Modelers	29
	Supplemental Type Certificate (STC)	14	Images Using Computational Fluid Dynamics	27
	Standard Airworthiness Certificate (AC)	14	Software	29
	Special Airworthiness Certificate (SAC)	14	Cutaway Drawings	30
	Maintenance Requirements	14	Engineering Reports	30
	Airworthiness Directives (AD)	14	Engineering Drawings	32
	Service Bulletin (SB)	15		
	Advisory Circular (AC)	15	Variables	32
	Technical Standard Order (TSO)	15	References	32

#### 1.1 INTRODUCTION

What is a design? It is probably appropriate to begin a book on design by discussing the term itself, especially considering the concept is often erroneously defined and sometimes even characterized through zeal rather than a true understanding of its meaning. The author recalls a past interview with a renowned designer who, during a TV interview, was asked to define the term. The show that ensued was a disappointing mixture of superficial self-importance and an embarrassing unpreparedness for the question. Following an artful tiptoeing around the issue the concluding response could be summarized as; "well, everything is designed." No, nothing could be further from the truth: not everything is designed. Some things are designed while other things are not. When self-proclaimed designers have a hard time defining the term properly it should not be surprising when laypeople misuse the word and apply it to things that are clearly not designed. The least we can expect of any designer is to accurately define the concept to laypeople, some of whom have openly demonstrated an inability to distinguish a regular pattern from a design.

Any attempt at defining the word properly requires an insight into how the brain perceives the geometry that surrounds us. It is a question of great intrigue. How can the brain tell apart a clamshell and a cloud, or a raccoon and a road? This is achieved using the brain's innate ability called *rapid pattern recognition*, common to all animals. It is one of the most important biological traits in any species that relies on optics as a primary sensory organ. In fact, this ability, a consequence of a biological evolution lasting over hundreds of millions of years, is imperative to the survival of the species. Its most important strength is that it allows animals to make a distinction between the facial features of a mother and the silhouette of a dangerous predator (for instance, see [1]).

If you see a face when you look at the front end of a typical car, or the silhouette of people or animals when looking at rock formations or clouds, you should know that this is your brain's pattern recognition subroutine working overtime. It is desperately trying to construct a recognizable image from any pattern that hits the retina to help you quickly identify friends from foes. The faster a member of a species can accomplish this feat, the greater is the chance it may escape a dangerous predator or identify a concealed prey, providing a clear evolutionary advantage. It helps a falcon see a rodent from great heights as much as it helps an antelope identify a lurking lion. However, just as rapid pattern recognition is capable of discerning predator and prey; it can also play tricks with the brain and cause it to assemble random patterns into images of easily recognizable things that are simply not there. This condition is called *apophenia*. The lack of public education on this elementary biological function is stunning and renders some laypeople altogether incapable of realizing that the interplay of dark and light areas on their toast or potato chip that looks like their favorite celebrity is not a design but only a random pattern the brain has managed to assemble into a recognizable shape. Deprived of knowledge to know any better, many yield to wishful thinking and allow the imagination to run wild.

In short, a regular pattern is a combination of geometrical, physical, or mathematical features that may or may not be random, but "appears" either repetitious or regular through some characterization, such as learning. In fact, our environment is jam-packed with regular patterns. The repetition (or regularity) of a pattern allows the brain to separate it from the truly random background. People, familiar with the term "design," erroneously deduce that since a pattern appears to be regular it must be designed, when in fact it is not. A design is a pattern of geometrical, physical, or mathematical features that is the consequence of an intent and purpose. A design requires an originator who intended for the pattern to look a certain way so it could serve its proposed purpose. This way, a design is a subset of regular patterns and one that has a preconceived goal, requires planned actions to prepare, and serves a specific purpose.

Consider the natural shapes in Figure 1-1. The mountain range to the left was not designed but formed by the mindless forces of nature. There was no preconceived plan that the range should look this way and not some other way. It just formed this way over a long time – it is a random but repetitious pattern. The contrails that criss-cross the sky over the Yosemite National Park, in the right image, were not planned either. They are a consequence of random departure times of different airplanes in different parts of the USA, headed in different directions at different altitudes. While the arrangement of the airway system is truly designed it was not conceived with the contrails in mind but for a different purpose altogether. No one planned the airway system so this pattern would form over El Capitan in this fashion and not some other. No one was ever tasked with figuring out that this particular day the winds aloft would allow the pattern to stay so regular. Its appearance is nothing but a coincidence. The geometry of the contrails, just like the mountain range in the left image, is the consequence of random events that were not designed. Claiming these are designs, automatically inflicts a burden-of-proof obligation on the petitioner: Show the plans, the originator, and explain the purpose and, if unable to, simply call it by its proper name until such plans surface: a pattern is a pattern until it can be shown to be a design.

1.1 INTRODUCTION 3





FIGURE 1-1 Examples of random patterns. The mountain range to the left is shaped by the random forces of nature. The pattern of contrails over the Yosemite National Park is the consequence of random departure times of the aircraft involved that are influenced by random decisions of air traffic controllers. There is absolutely no intentional intelligence that forms these shapes. They just appear that way. (Photos by Snævarr Guðmundsson)

With the philosophy of design behind us, we can now focus on the primary topic of this book - the design of aircraft, in particular General Aviation aircraft. According to the Federal Aviation Administration, the term General Aviation aircraft (from here on called GA aircraft) refers to all aircraft other than airlines and military operations [2]. This includes a large body of aircraft, ranging from sailplanes and airships to turbofan jets. Most aircraft are designed to comply with strict regulatory standards. In the USA these are managed and maintained by the Federal Aviation Administration (FAA). In Europe the standards are set by the European Aviation Safety Agency (EASA). These standards are similar in most ways, which results from an effort between the two agencies to harmonize them. Table 1-1 lists a number of standards for selected classes of aircraft.

In the USA, a light sport aircraft (LSA) is treated differently from an aircraft certified to 14 CFR Part 23 or 25. Instead of a direct involvement in the certification process, the FAA accepts compliance based on so-called consensus standards. These standards are neither established nor maintained by the agency itself but by some other organization. Some of these are really "watered down" FAA rules that are far less burdensome to comply with than the originals. This can partially be justified on the basis that the airplanes they apply to are much simpler than regular aircraft.

The acceptance of consensus standards (LSA) is effectively based on the "honor system." In other words, a manufacturer tells the FAA its product complies with the applicable standards and, in return, receives an airworthiness certificate. This is done as long as no "issues" surface. The system is a form of "self-regulation" and is designed to keep the FAA out of the loop. The LSA industry recognizes that responsible compliance is the only way to avoid more burdensome regulations. According to FAA officials in 2012, this system has been more or less problem free, excluding one instance [3].

Currently, the American Society for Testing and Materials (ASTM) is the primary organization that establishes and maintains consensus standards for LSA. ASTM has developed a number of standards that apply to different types of aircraft. The FAA accepts some of these in lieu of 14 CFR. Which standard ultimately depends on the subclass of aircraft (aircraft, glider, gyrocopter, lighterthan-air, powered parachutes, and weight-shift control)

TABLE 1-1 Certification Basis for Several Classes of Aircraft

	Certification Date to to	overal Olaboes of Tifferate
Class	Regulations	Comments
General Aviation	14 CFR Part 23 (USA) CS-23 (Europe)	
Commercial Aviation	14 CFR Part 25 (USA) CS-25 (Europe)	
Sailplanes	14 CFR 21.17(b) (USA) CS-22 (Europe)	14 CFR 21.17(b) allows the FAA to tailor the certification on a need-to basis to sailplanes. Then, by referring to AC 21.17-2A, the FAA accepts the former JAR-22 as a certification basis, which have now been superceded by CS-22.
Airships	14 CFR 21.17(b) (USA) CS-30 and CS-31HA	14 CFR 21.17(b) allows the FAA to tailor the certification on a need-to basis to airships.
Non- conventional Aircraft	14 CFR 21.17(b) (USA) CS-22 (Europe)	14 CFR 21.17(b) allows the FAA to tailor the certification on a need-to basis to non-conventional aircraft.
Light Sport Aircraft (LSA)	Consensus (USA) CS-LSA (Europe)	See discussion below regarding LSA acceptance in the USA.

and on a number of specific fields (design and performance; required equipment; quality assurance; and many others). For instance, for the subclass *aircraft*, design and performance is accepted if it complies with ASTM F2245, required equipment must also comply with ASTM F2245, but quality assurance must comply with ASTM F2279, maintenance and inspection with ASTM F2483, and so on. Gliders, gyroplanes, and other light aircraft must comply with different ASTM standards. The matrix of requirements can be obtained from the FAA website [4].

While this book will mostly focus on the design of new GA aircraft, other classes of aircraft will be discussed when needed. The designer of GA aircraft should be well rounded in other types of aircraft as well, a point that will be made repeatedly throughout this book.

GA aircraft certified under 14 CFR Part 23 are subject to a number of limitations as stipulated under 14 CFR Part 23.3-Airplane categories. The regulations place aircraft to be certified into four categories; *normal*, *utility*, *aerobatic*, and *commuter*. These categories must abide by the restrictions listed in Table 1-2. With the exception of the commuter category, an aircraft may be certified in more than one category provided all requirements of each are met.

New aircraft are designed for a variety of reasons, but most are designed to fulfill a specific role or a mission as dictated by prospective customers. For economic reasons, some aircraft (primarily military aircraft) are designed to satisfy more than one mission; these are *multi-role* aircraft. Others, for instance homebuilt aircraft, are designed for much less demanding reasons

and are often solely based on what appeals to the designer.

No matter the type of aircraft or the reason for its design, specific tasks must be completed before it can be built and flown. The order of these tasks is called the *design process*. This process is necessitated by the fact that it costs a lot of money to develop a new aircraft. Organizations that develop new aircraft do not invest large amounts of funds in a design project until convinced it can perform what it is intended to. A design process makes this possible by systematically evaluating critical aspects of the design. This is primarily done using mathematical procedures, as well as specific testing of structural configuration, materials, avionics, control system layout, and many more.

The order of the tasks that constitute the design process may vary depending on the company involved. Usually there is an overlap of tasks. For instance, it is possible that the design of the fuselage structure is already in progress before the sizing of the wing or stabilizing surfaces is fully completed. Generally, the actual process will depend on the size and maturity of the company in which it takes place and the order of tasks often varies. However, there are certain steps that must be completed in all of them; for instance, the estimation of weight; sizing of lifting surfaces and the fuselage; estimation of performance; and other essential tasks.

In mature companies, the design process is managed by individuals who understand the big picture. They understand the scope of the project and are aware of the many pitfalls in scheduling, hiring, design, and other

TABLE 1-2 Restrictions for Aircraft Classes Certified under 14 CFR Part 23

		S. BANKET SHOWN THE RESIDENCE OF THE PARKET		
Restriction	Commuter	Normal	Utility	Aerobatio
Number of pilots	1 or 2	1	1	1
Max number of occupants	19	9	9	9
Max T-O weight	19,000 lb <sub>f</sub>	12,500 lb <sub>f</sub>	12,500 lb <sub>f</sub>	12,500 lb <sub>f</sub>
Aerobatics allowed?	No	No	Limited	Yes
Non-aerobatic operations permitted	Normal flying Stalls (no whip stalls) Steep turns ( $\phi < 60^{\circ}$ )	Normal flying Stalls (no whip stalls) Lazy eights Chandelles Steep turns ( $\phi < 60^{\circ}$ )	Normal flying Stalls (no whip stalls) Lazy eights Chandelles Steep turns ( $\phi < 90^{\circ}$ ) Spins (if approved)	N/A
Max maneuvering $g$ -loading, $n_+$	$2.1 + \frac{24,000}{W + 10,000} < n_+ \le 3.8$		4.4	6.0
Min maneuvering $g$ -loading, $n$	$-0.4n_+ < n \le -1.52$		-1.76	-3.0

W = maximum T-O weight. Maneuvering loads are based on 14 CFR 23.337.

A whip stall may occur when the airplane is stalled while in a slip. This can cause the outer wing to stall first and drop abruptly [5].

1.1 INTRODUCTION 5

tasks, that many engineers consider less than glamorous. These people must be well-rounded in a number of disciplines: aerodynamics; performance analysis; stability and control; handling; power plants; weight analysis; structural layout; environmental restrictions; aviation regulations; history of aviation; and aircraft recognition, to name a few. Although not required to be an expert in any of these fields, their understanding must be deep enough to penetrate the surface. Knowing what to do, how to do it, and when to do it, is the key to a successful aircraft development program.

#### 1.1.1 The Content of this Chapter

- **Section 1.2** presents a general description of the aircraft design process.
- Section 1.3 presents two specific algorithms intended to guide the aircraft designer through the conceptual design process. If you are unsure of "what to do next," refer to these. They are based on actual industry experience and are not academic "cookbook" approaches.
- Section 1.4 presents project management tools. Many beginning project leaders are often at a loss as to how to manage a project. If this is your predicament you need to study these tools. Project management revolves around knowing what to do and when to do it. Thus, the manager must construct a chronological order of the tasks that need to be completed.
- Section 1.5 presents helpful approaches to describing engineering ideas using graphics ranging from threeview drawings to composite photo images. These are extremely helpful when trying to "sell" an idea.

## 1.1.2 Important Elements of a New Aircraft Design

Before going further, some specific topics must be brought up that the lead airplane designer must introduce and discuss thoroughly with the design team. Among those are:

#### Definition of the Mission

It is imperative that the mission of the new aircraft is very clearly defined. Is it primarily intended to serve as a cruiser? If so, what airspeed and cruising altitude is it most likely to see during its operation? Is it a cargo transport aircraft? How much weight must it carry? How fast, far, and high shall it fly? Is it a fighter? What energy state or loitering capabilities are required? The mission must be clearly defined because the airplane will be sized to meet that particular mission. An aircraft designed in this fashion will be most efficient when performing that mission. Clarity of this nature also has an

unexpected redeeming power for the designer: It is very common during the development of aircraft that modifications to capabilities are suggested by outside agencies. In spite of being well meant, some such suggestions are often detrimental to the mission. A clearly defined mission allows the designer to turn down a disadvantageous suggestion on the basis that it compromises the primary mission.

#### Performance Requirements and Sensitivity

Performance requirements must be clearly defined and are usually a part of the mission definition. It is imperative to quantify characteristics such as the takeoff distance, time to cruise altitude, cruise range, and even environmental noise for some types of aircraft. But it is also important to understand how deviations from the design conditions affect the performance. This is referred to as performance sensitivity. How does high altitude and a hot day affect the take-off distance? How about the upward slope of the runway? How does having to cruise, say, some 5000 ft below the design altitude affect the range? How about if the airplane is designed for a cruising speed higher than would be permitted by air traffic considerations and, therefore, is consistently operated at a lower cruising speed? How will that affect the range? Clearly, there are many angles to designing an aircraft, but rather than regarding it as a nuisance the designer should turn it into strength by making people in management and marketing aware of the deficiencies. And who knows perhaps the new aircraft is less sensitive than the competition and this could be turned into a marketing advantage.

#### Handling Requirements (Stability and Control)

How important is the handling of the aircraft? Is this a small aircraft that is operated manually, rendering stick forces and responsiveness imperative? Is it a heavy aircraft with hydraulic or electric actuators, so stick forces are fed back to the pilot electronically and, thus, can be adjusted to be whatever is considered good? How about unsuspected responses to, say, thrust forces?

The Lockheed SA-3 Viking, an anti-submarine warfare aircraft, features a high wing with two powerful turbofan engines mounted on pylons. When spooling up, the aircraft experiences a powerful nose pitch-up tendency that is captured by a stability augmentation system (SAS) that was not originally designed into the prototype. The Boeing B-52 Stratofortress uses spoilers for banking. When banking hard, the spoiler on the down-moving wing is deployed and this reduces lift on the outboard part of that wing. This, in turn, means the center of lift moves forward, causing a nose pitch-up tendency, which the pilot must react to by pushing the yoke forward (for nose pitch-down). Handling

issues of this nature must be anticipated and their severity resolved.

#### Ease of Manufacturing

Is it imperative that the aircraft will be easy to manufacture? Ease of manufacture will have a profound impact on the engineering of the product and its cost to the customer. A straight constant-chord wing can be manufactured at a lower cost than one that has tapered planform and compound surfaces, but it will be less efficient aerodynamically. Which is more important? The designer must have means to demonstrate why a particular geometry or raw material is required for the project. The concept of ease of marketing always looks good on paper, but this does not guarantee its success. For instance, it is simple to select composites for a new aircraft design on the grounds that this will make it easier to manufacture compound surfaces. But are they really needed? For some aircraft, the answer is a resounding yes, but for others the answer is simply no.

As an example, consider the de Havilland of Canada DHC-2 Beaver (see Figure 1-2). Designing this otherwise sturdy airplane from composites would be an unwise economic proposition. In the current environment it would simply be more expensive to build using composites and sell at the same or lower price than the aluminum version. To begin with, it is not easy to justify the manufacturing of an aerodynamically inefficient frustum-style fuselage<sup>1</sup> and constant-chord wing featuring a non-laminar flow airfoil with composites. Composites are primarily justifiable when compound surfaces or laminar flow wings must be manufactured. They require expensive molds to be built and maintained, and, if the aircraft ends up being produced in large numbers, the molds have to be manufactured as well; each may only last for perhaps 30–50 units.

The interested reader is encouraged to jump to Section 2.2, Estimating project development costs, for further information about manufacturing costs (in particular see Example 2-3, which compares development and manufacturing costs for a composite and aluminum aircraft). Cost analysis methods, such as the widely used DAPCA-IV, predict man-hours for the engineering development of composite aircraft to be around two times greater than that of comparable aluminum aircraft. They also predict tooling hours to double and manufacturing hours to be 25% greater than for aluminum aircraft. Labor and material are required not only to manufacture the airplane, but also to



FIGURE 1-2 The de Havilland of Canada DHC-2 Beaver. (Photo from Wikipedia Commons)

manufacture and maintain expensive tooling. As a result, composite aircraft are more expensive to manufacture in spite of substantial reduction in part count.

This inflicts an important and serious constraint on the scope of production. Composites require heating rooms to ensure the resin cures properly so it can provide maximum strength. Additionally, vacuum bagging or autoclaves are often required<sup>2</sup> to force tiny air bubbles out of the resin during cure to guarantee that the certified strength is achieved. The manufacturer must demonstrate to the authorities that material strength is maintained by a constant production of coupons for strength testing. Special provisions must be made to keep down moisture and prevent dust from entering the production area, not to mention supply protective clothing and respirators to all technicians who work with the material. All of this adds more cost and constraints to the production and all of it could have been avoided if the designer had realized that requiring composites was more a marketing ploy than a necessity. This is not to say that composites do not have their place they certainly do – but just because composites are right for one application, does not mean they are appropriate for another one.

#### Certifiability

Will the aircraft be certified? If the answer is yes, then the designer must explore all the stipulations this is likely to inflict. If no, the designer bears a moral obligation to ensure the airplane is as safe to operate as possible. Since non-certified airplanes are destined to be small, this can be accomplished by designing it to prevailing certification standards, for instance, something like 14 CFR Part 23 or ASTM F2245 (LSA aircraft).

Regulations often get a bad rap through demagoguery by politicians and ideologues, most of whom

<sup>&</sup>lt;sup>1</sup>A frustum-style fuselage is a tapered structure that does not feature compound surfaces. It is discussed in Chapter 12, *The Anatomy of the Fuselage*.

<sup>&</sup>lt;sup>2</sup>Note that some manufacturers of composite structures claim that curing composites using vacuum "bagging" is equally effective as using an autoclave — it is certainly more economical. For instance see: http://www.gmtcomposites.com/why/autoclave.