FOURIER TRANSFORMS

Principles and Applications

ERIC W. HANSEN

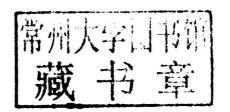
WILEY

FOURIER TRANSFORMS

Principles and Applications

ERIC W. HANSEN

Thayer School of Engineering, Dartmouth College



WILEY

Cover Image: @iStockphoto/olgaaltunina

Copyright © 2014 by John Wiley & Sons, Inc. All rights reserved.

Published by John Wiley & Sons, Inc., Hoboken, New Jersey. Published simultaneously in Canada.

No part of this publication may be reproduced, stored in a retrieval system, or transmitted in any form or by any means, electronic, mechanical, photocopying, recording, scanning, or otherwise, except as permitted under Section 107 or 108 of the 1976 United States Copyright Act, without either the prior written permission of the Publisher, or authorization through payment of the appropriate per-copy fee to the Copyright Clearance Center, Inc., 222 Rosewood Drive, Danvers, MA 01923, (978) 750-8400, fax (978) 750-4470, or on the web at www.copyright.com. Requests to the Publisher for permission should be addressed to the Permissions Department, John Wiley & Sons, Inc., 111 River Street, Hoboken, NJ 07030, (201) 748-6011, fax (201) 748-6008, or online at http://www.wiley.com/go/permission.

Limit of Liability/Disclaimer of Warranty: While the publisher and author have used their best efforts in preparing this book, they make no representations or warranties with respect to the accuracy or completeness of the contents of this book and specifically disclaim any implied warranties of merchantability or fitness for a particular purpose. No warranty may be created or extended by sales representatives or written sales materials. The advice and strategies contained herein may not be suitable for your situation. You should consult with a professional where appropriate. Neither the publisher nor author shall be liable for any loss of profit or any other commercial damages, including but not limited to special, incidental, consequential, or other damages.

For general information on our other products and services or for technical support, please contact our Customer Care Department within the United States at (800) 762-2974, outside the United States at (317) 572-3993 or fax (317) 572-4002.

Wiley also publishes its books in a variety of electronic formats. Some content that appears in print may not be available in electronic formats. For more information about Wiley products, visit our web site at www.wiley.com.

Library of Congress Cataloging-in-Publication Data is available.

ISBN: 978-1-118-47914-8

Printed in the United States of America.

FOURIER TRANSFORMS



PREFACE

The mathematical techniques known as "transform methods" have long been a basic tool in several branches of engineering and science, and no wonder. Fourier's simple idea, radical in its time, that a function can be expressed as a sum of sine waves, is ubiquitous. It underlies fields as diverse as communications, signal and image processing, control theory, electromagnetics, and acoustics. Electrical engineers typically encounter the rudiments of Fourier transforms in undergraduate systems and circuits courses, for modeling the spectral content of signals and designing frequency selective circuits (filters). The Laplace transform, a close cousin of the Fourier transform, enables the efficient analytical solution of ordinary differential equations and leads to the popular "S plane" and "root locus" methods for analyzing linear systems and designing feedback controllers. Discrete-time versions of the Fourier and Laplace transforms model spectra and frequency responses for digital signal processing and communications. Physics and engineering students meet the Fourier series when learning about harmonic motion or solving partial differential equations, for example, for waves and diffusion. The Fourier transform also models wave propagation from acoustics to radio frequencies to optics to X-ray diffraction. The widespread dissemination of the fast Fourier transform algorithm following its publication in 1965 added a computational dimension to all of these applications, from everyday consumer electronics to sophisticated medical imaging devices.

My purpose in writing this textbook is to pull these threads together and present a unified development of Fourier and related transforms for seniors and graduate students in engineering and physics—one that will deepen their grasp of how and why the methods work, enable greater understanding of the application areas, and perhaps motivate further pursuit of the mathematics in its own right. Drafts of the book have been used by myself and others for a 10-week course in Fourier transforms and complex variable theory at the Thayer School of Engineering, Dartmouth College. The prerequisites are an introductory course in lumped parameter systems (including the Laplace transform) or differential equations. Our course is itself prerequisite to courses in signal and image processing and a more advanced course in applied analysis taken by engineering and physics graduate students.

Philosophy and Distinctives

The book is more mathematically detailed and general in scope than a sophomore or junior level signals and systems text, more focused than a survey of mathematical methods, and less rigorous than would be appropriate for students of advanced mathematics. In brief, here is the approach I have taken.

- 1. The four types of Fourier transform on discrete and continuous domains—discrete Fourier transform (DFT), Fourier series, discrete-time Fourier transform (DTFT), and Fourier transform—are developed as orthogonal expansions within a vector space framework. They are introduced sequentially, starting with the DFT and working up to the continuous-time Fourier transform. The same important properties and theorems are revisited for each transform in turn, reinforcing the basic ideas as each new transform is introduced. This is in contrast with an approach that either begins with the continuous-time transform and works down to the others as special cases, or develops all four in parallel.
- 2. The early presentation of the DFT makes it immediately available as a tool for computing numerical approximations to the Fourier series and Fourier transform. Several homework problems give the student practice using numerical tools. Matlab® is used throughout the book to demonstrate numerical methods and to visualize important ideas, but whether to use Matlab or some other computational tool in the course is up to the instructor.
- **3.** The fundamentals of complex analysis and integration are included as a bridge to a more thorough understanding of the Laplace and Z transforms, and as an additional way to calculate Fourier transforms.
- 4. Physical interpretations and applications are emphasized in the examples and homework problems. My hope is that the student will cultivate intuition for how the mathematics work as well as gain proficiency with calculation and application.
- **5.** Starred sections, which may be skipped on a first reading, give brief introductions to more advanced topics and references for further reading.
- Each chapter has a table of key results, which should be particularly helpful for reference after the course is completed.

Any author of an applied mathematics book must decide the extent to which the development of the material will be supported by proofs. The level of rigor required by a mathematician generally exceeds what is needed to justify the trustworthiness of a result to an engineer. Moreover, to prove all the key theorems of Fourier analysis requires a facility with real analysis and even functional analysis that exceeds the usual mathematical background of an undergraduate engineer. The approach taken here, for the most part, is to include proofs when they build intuition about how the mathematics work or contribute to the student's ability to make calculations and apply the transforms. Otherwise, I will usually substitute informal plausibility arguments, derivations of weaker results either in the text or in the end-of-chapter problems, or computational illustrations of the principles involved. Footnotes refer the interested reader to detailed treatments in more advanced texts.

Flow of the Book

The book has 10 chapters, which are described briefly here to show how the book's main ideas are developed. *Chapter 1* is a review of the topics from geometry,

trigonometry, matrix algebra, and calculus that are needed for this course. *Chapter 2* then develops some fundamentals of vector spaces, particularly the generalizations of the geometric ideas of norm, inner product, orthogonality and orthogonal expansion from vectors to functions. This provides the unifying framework for the Fourier family and acquaints the student with concepts of broad importance in engineering mathematics.

Chapters 3–5 introduce, in sequence, the DFT, the Fourier series, the DTFT, and the (continuous-time) Fourier transform. The DFT has the easiest vector space interpretation of the four transforms, since it expands finite-dimensional vectors in terms of orthogonal finite-dimensional vectors. Some basic Fourier theorems (linearity, shift, energy conservation, convolution) are first presented here, then reappear later for the other transforms. Chapter 3 includes a derivation of the fast Fourier transform (FFT) algorithm and the discrete cosine transform (DCT), a close relative of the DFT that is the mathematical foundation of JPEG image compression.

The Fourier series, Chapter 4, is a representation of a periodic function as an infinite series of orthogonal sines and cosines. The appearance of the infinite series raises the question of convergence and leads to the important connections among convergence of the series, asymptotic behavior of the spectrum, and smoothness of the original function. The chapter includes applications to the diffusion and wave equations and to antenna arrays, and shows how to use the DFT to compute Fourier coefficients and partial sums of Fourier series. Swapping the time and frequency domains, the Fourier series becomes the DTFT, the basic tool for discrete-time system analysis and signal processing.

The Fourier transform, *Chapter 5*, expands an aperiodic function as a continuum of orthogonal sines and cosines rather than a set of discrete oscillatory modes. Despite the additional mathematical complication, it has many of the same properties as the DFT and the Fourier series and intuition developed earlier for these transforms will carry over to the Fourier transform. The chapter emphasizes using Fourier theorems for modeling systems (impulse response and transfer function) and performing calculations. It also shows how to use the DFT to compute transforms and convolutions. A brief introduction to time-frequency transforms and wavelet transforms concludes the chapter.

Chapter 6 begins by placing the impulse (delta) function on a more secure footing than the informal notion of "infinite height, zero width, unit area" that students sometimes bring with them from earlier classes. This is followed by development of a common, generalized framework for understanding ordinary functions together with impulses and other singular functions. Sampling theory, introduced informally in Chapter 3, is studied here in depth. It is also used to unify the four Fourier transforms, via the observation that sampling in the time domain produces periodicity in the frequency domain, and vice versa.

Chapters 7 and 8 are devoted to the theory of complex functions and methods of complex integration, with a focus on ultimately applying the theory to understanding and calculating transforms. Numerical calculations of the basic complex integral $\int z^n dz$ on different closed contours are used to help students visualize why the

XIV PREFACE

integral evaluates either to $2\pi i$ or to zero, before formally introducing the fundamental results, the Cauchy integral theorem and integral formula. The traditional subjects of conformal mapping and potential theory are omitted, but the complex variable introduction here is, I believe, sufficient preparation for subsequent courses, for example, in electromagnetism or fluid mechanics, where complex potentials may be useful.

Chapter 9 moves beyond the Fourier transform to the Laplace, Z, and Hilbert transforms. The Laplace transform is motivated by the need to handle functions, in particular ones that grow exponentially, that are beyond the reach of the Fourier transform. The familiar Laplace theorems, used to solve initial value problems, are derived and compared with their Fourier counterparts. The well-known partial fraction expansion method for Laplace inversion is connected with complex integration and extended beyond the rational functions encountered in linear system theory. The Z transform appears via the Laplace transform of a sampled function, and analogies between the transforms are emphasized. The Hilbert transform, which describes a special property of the Fourier transform of a one-sided function, is developed and applied to various problems in signal theory.

Chapter 10 concludes the book by revisiting the Fourier transform in two and three dimensions, with applications to wave propagation and imaging. The closely related Hankel and Radon transforms are introduced. Multidimensional transforms of arrays of impulses are developed and applied to sampling theory and X-ray crystallography.

Suggested Use

Most of Chapters 2–5, 7 and 8, and selected parts of Chapters 6 and 9, are covered in my 10-week (30-hour) course. In a full semester course, additional material from Chapters 6, 9, and 10 could be added. If students have already had a course in complex analysis, or if time does not permit, Chapters 7 and 8 may be skipped, with the caveat that portions of Chapter 9 are inaccessible without complex integration. However, this would permit a thorough coverage of Chapters 2–6 and 10 with selected topics from Chapter 9. While I naturally prefer the sequence of Chapters 2–4, they may be approached in a different order, with the Fourier series before the DFT, and with the vector space material presented "just in time" as the Fourier methods are introduced. End-of-chapter problems cover basic and more complex calculations, drawn from the theory itself and from many physical applications. I hope that instructors will find sufficient variety to suit their particular approaches to the material.

Acknowledgments

Ulf Österberg and Markus Testorf taught from various drafts at Dartmouth, and Ron June used portions of the text at University of California, Davis. Paul Hansen also read and commented on several chapters. My hearty thanks to all of them for being generous with their time and constructive ideas. Likewise, the anonymous comments of early reviewers both encouraged me that I was on the right track and challenged

me in valuable ways. I also thank George Telecki and Kari Capone at Wiley for taking on this project. Finally, to my students at the Thayer School, with whom it has been my privilege to teach and to learn over many years, thank you.

ERIC W. HANSEN

Hanover, New Hampshire July 2014

CONTENTS

PRE	FACE	xi
CHAP	PTER 1 REVIEW OF PREREQUISITE MATHEMATICS	1
1.1 1.2 1.3 1.4 1.5 1.6 1.7 1.8 1.9	Common Notation 1 Vectors in Space 3 Complex Numbers 8 Matrix Algebra 11 Mappings and Functions 15 Sinusoidal Functions 20 Complex Exponentials 22 Geometric Series 24 Results from Calculus 25 Top 10 Ways to Avoid Errors in Calculations 33 Problems 33	
СНАР	PTER 2 VECTOR SPACES	36
2.1 2.2 2.3 2.4 2.5 2.6	Signals and Vector Spaces 37 Finite-dimensional Vector Spaces 39 Infinite-dimensional Vector Spaces 64 * Operators 86 * Creating Orthonormal Bases—the Gram—Schmidt Process 94 Summary 99 Problems 101 PTER 3 THE DISCRETE FOURIER TRANSFORM	109
3.1 3.2 3.3 3.4 3.5 3.6 3.7	Sinusoidal Sequences 109 The Discrete Fourier Transform 114 Interpreting the DFT 117 DFT Properties and Theorems 126 Fast Fourier Transform 152 * Discrete Cosine Transform 156 Summary 164 Problems 165 PTER 4 THE FOURIER SERIES	177
4.1 4.2 4.3	Sinusoids and Physical Systems 178 Definitions and Interpretation 178 Convergence of the Fourier Series 187	

4.4 4.5 4.6 4.7 4.8 4.9 4.10	Fourier Series Properties and Theorems 199 The Heat Equation 215 The Vibrating String 223 Antenna Arrays 227 Computing the Fourier Series 233 Discrete Time Fourier Transform 238 Summary 256 Problems 259	
CHAP	TER 5 THE FOURIER TRANSFORM	273
5.1 5.2 5.3 5.4 5.5 5.6 5.7 5.8 5.9 5.10	From Fourier Series to Fourier Transform Basic Properties and Some Examples Fourier Transform Theorems 281 Interpreting the Fourier Transform 299 Convolution 300 More about the Fourier Transform 310 Time—bandwidth Relationships 318 Computing the Fourier Transform 322 * Time—frequency Transforms 336 Summary 349 Problems 351	
CHAP	TER 6 GENERALIZED FUNCTIONS	367
6.1 6.2 6.3 6.4	Impulsive Signals and Spectra 367 The Delta Function in a Nutshell 371 Generalized Functions 382 Generalized Fourier Transform 404	

455

454

494

6.5

6.6

6.7

7.1

7.2

7.3

7.4

7.5

7.6

8.1

8.2 8.3

CHAPTER 8

CHAPTER 7

Sampling Theory and Fourier Series 414

COMPLEX FUNCTION THEORY

Complex Functions and Their Visualization

exp z and Functions Derived from It 470

Log z and Functions Derived from It 472

COMPLEX INTEGRATION

The Basic Complex Integral: $\oint_{\Gamma} z^n dz$ 497 Cauchy's Integral Theorem 502

Line Integrals in the Plane 494

Unifying the Fourier Family 429

Summary 433 Problems 436

Differentiation 460

Summary 489 Problems 490

Analytic Functions 466

8.5 Laurent Series and Residues 520	
8.6 Using Contour Integration to Calculate Integrals of Real Functions 531	
8.7 Complex Integration and the Fourier Transform 543	
8.8 Summary 556	
Problems 557	
CHAPTER 9 LAPLACE, Z, AND HILBERT TRANSFORMS	563
9.1 The Laplace Transform 563	
9.2 The Z Transform 607	
9.3 The Hilbert Transform 629	
9.4 Summary 652	
Problems 654	
CHAPTER 10 FOURIER TRANSFORMS IN TWO AND THREE DIMENSIONS	669
CHAPTER 10 FOURIER TRANSFORMS IN TWO AND THREE DIMENSIONS 10.1 Two-Dimensional Fourier Transform 669	669
	669
10.1 Two-Dimensional Fourier Transform 669	669
10.1 Two-Dimensional Fourier Transform 669 10.2 Fourier Transforms in Polar Coordinates 684	669
10.1 Two-Dimensional Fourier Transform 669 10.2 Fourier Transforms in Polar Coordinates 684 10.3 Wave Propagation 696	669
10.1 Two-Dimensional Fourier Transform 669 10.2 Fourier Transforms in Polar Coordinates 684 10.3 Wave Propagation 696 10.4 Image Formation and Processing 709	669
 10.1 Two-Dimensional Fourier Transform 669 10.2 Fourier Transforms in Polar Coordinates 684 10.3 Wave Propagation 696 10.4 Image Formation and Processing 709 10.5 Fourier Transform of a Lattice 722 	669
 10.1 Two-Dimensional Fourier Transform 669 10.2 Fourier Transforms in Polar Coordinates 684 10.3 Wave Propagation 696 10.4 Image Formation and Processing 709 10.5 Fourier Transform of a Lattice 722 10.6 Discrete Multidimensional Fourier Transforms 731 	669
 10.1 Two-Dimensional Fourier Transform 669 10.2 Fourier Transforms in Polar Coordinates 684 10.3 Wave Propagation 696 10.4 Image Formation and Processing 709 10.5 Fourier Transform of a Lattice 722 10.6 Discrete Multidimensional Fourier Transforms 731 10.7 Summary 736 Problems 737 	
10.1 Two-Dimensional Fourier Transform 669 10.2 Fourier Transforms in Polar Coordinates 684 10.3 Wave Propagation 696 10.4 Image Formation and Processing 709 10.5 Fourier Transform of a Lattice 722 10.6 Discrete Multidimensional Fourier Transforms 731 10.7 Summary 736	743

8.4 Cauchy's Integral Formula 512