Electrical Power Equipment and Measurements

With heavy current electrical applications

Alan Symonds

econd Edition

Electrical power equipment and measurements: with heavy current electrical applications

Second edition

Alan Symonds

Formerly Lecturer in Electrical Engineering, Grimsby College of Technology

McGraw-Hill Book Company (UK) Limited

London · New York · St Louis · San Francisco · Auckland · Bogotá Guatemala · Hamburg · Johannesburg · Lisbon · Madrid · Mexico Montreal · New Delhi · Panama · Paris · San Juan · São Paulo Singapore · Sydney · Tokyo · Toronto

Published by

McGRAW-HILL Book Company (UK) Limited

MAIDENHEAD · BERKSHIRE · ENGLAND

British Library Cataloguing in Publication Data

Symonds, Alan

Electrical power equipment and measurements.—2nd ed.

1. Electric apparatus and appliances

I. Title

621.31'042

TK452

80-40505

ISBN 0-07-084625-1

Copyright © 1980 McGraw-Hill Book Company (UK) Limited. All rights reserved. No part of this publication may be reproduced, stored in a retrieval system, or transmitted, in any form or by any means, electronic, mechanical, photocopying, recording, or otherwise, without the prior permission of McGraw-Hill Book Company (UK) Limited, or of the original copyright holder.

12345

W&JM

83210

Electrical power equipment and measurements: with heavy current electrical applications

Second edition

Preface to the first edition

The primary purpose of this book is to provide Electrical Technician students with a textbook covering Electrical Power Equipment. The book is intended to cover two years' work, but in order to preserve subject continuity no attempt has been made to divide either the book or the individual chapters into two distinct parts.

Much of the subject matter is descriptive and illustrated by drawings, circuit diagrams, and phasor diagrams. In general, the theory and mathematics have been limited to that necessary to give an understanding of the principles, characteristics, and practical uses of particular pieces of equipment. From this point of view the practical technician in industry, whose days of studying may be behind him, may find the book helpful.

SI units have been used, although some units, for example the horsepower, have not been completely omitted since old machines will still carry the old rating on their nameplates.

Although based upon a particular syllabus, much of the book will be found useful for Electrical Installation students and students taking Electrical Craft Study courses.

The author wishes to thank the City and Guilds of London Institute for permission to use their Electrical Technician Course syllabus as a basis for the contents of this book and for the inclusion of questions from past examination papers; the East Midland Education Union for permission to use questions from past examination papers; the Institution of Electrical Engineers for permission to use information contained in their Regulations for the Electrical Equipment of Buildings; and Her Majesty's Stationery Office for permission to use material quoted in the 1969/70 Annual Report of the Central Electricity Generating Board.

Questions from past examination papers are printed in an Appendix. The order in which the questions appear corresponds with the sequence of chapters. The source of the questions is indicated but where numerical answers are given these are the author's, and the relevant examination body is in no way responsible for their accuracy.

In writing this book, the author has been helped by the reading of scripts and the constructive comments of several of his colleagues and wishes to thank Mr S. Busby, Mr D. V. Miles, Mr F. G. Vivian, and Mr R. Wilson for their help, and also Mr J. Cleveland and Mrs E. Cleveland for typing the scripts.

Alan Symonds

Preface to the second edition

Since the first edition was published in 1971 considerable changes have taken place in the structure of technical education courses. Many colleges are now offering courses based upon syllabuses issued by the Technical Education Council. In revising this book much material has been added to enable the book to give a complete coverage of the TEC Level III Syllabus Unit U76/362. The title of this unit, 'Heavy Current Electrical Applications', is used as a sub-title for this present edition.

Inevitably, some of the original material has had to be condensed to give space for the new and some material has been rearranged. This new edition will now appeal to students taking a number of TEC courses, but particularly Unit U76/362, and also to technicians, installation and craft students who have previously used the book.

Basically the chapters follow the same general order as in the first edition although some chapter headings have been changed and new chapters introduced, particularly on three-phase rectification and control systems.

Many colleges today introduce basic electronic theory at an early stage and in most cases students will be familiar with this work before reaching Level III. For this reason much of this basic work has now been omitted from the new edition.

Questions in the Appendix have now been placed under chapter headings.

The author wishes to thank those colleagues who have helped with this second edition by reading the scripts and making constructive comments. In particular he wishes to mention Mr S. Busby, Mr R. Wilson, Mr C. S. J. Evens, and Mr R. Taylor.

Alan Symonds

Contents

PREI	FACE TO THE FIRST EDITION	X
Prei	FACE TO THE SECOND EDITION	xi
CHA	APTER	
1	CONSUMER'S SUPPLY	1
1.1	From the Grid to the consumer	1
1.2	The local distribution system	2
1.3	Operating voltages	4
1.4	Consumers' supplies	4
1.5	Equipment at consumer's supply point	8
1.6	Factory layout	13
CHA	APTER	
2	SWITCHGEAR AND PROTECTION	18
2.1	Control and protection of circuits	18
2.2	Circuit protection	25
2.3	Earth-leakage protection	33
CHA	APTER	
3	ECONOMICS—TARIFFS	38
3.1	The basis of electricity tariffs	38
3.2	Application of the two-part tariff	43
3.3	Power factor improvement	45
CHA	APTER	
4	GENERATOR AND MOTOR PRINCIPLES	52
4.1	Generator effect in a single loop	52
4.2	The ring armature	53
4.3	Lap and wave windings	55
4.4	Generated e.m.f. and the e.m.f. equation	56
4.5	The motor effect	58
4.6	Generator and motor voltage equations	.58
4.7	Motor speed	59
4.8	Torque on a conductor in a magnetic field	61
40	Torque and output of a dic motor	61

CONTENTS

CHAI	PTER	
5	D.C. MACHINES	64
5.1	General construction	64
5.2	Types of machine	65
5.3	D.C. machine characteristics	65
5.4	Armature reaction in a d.c. generator	69
5.5	Armature reaction in a d.c. motor	71
5.6	Methods of minimizing armature reaction	72
5.7	Commutation	73
5.8	Methods of improving commutation	76
5.9	Care of the commutator and brushes	77
5.10	D.C. motor starter	78
5.11	Tests to find the efficiency of a d.c. machine	81
CHAF	PTER	
6	TRANSFORMERS	86
6.1	Outline of basic principles	86
6.2	Transformer construction	87
6.3	The transformer on no-load	89
6.4	The transformer on load	91
6.5	Example of a transformer on load	93
6.6	Transformer impedance and referred values	94
6.7	Voltage regulation	97
6.8	Transformer losses	99
6.9	Transformer tests	100
6.10	Transformer efficiency	102
6.11	Operation of a three-phase transformer	105
6.12	Three-phase transformer connections	107
6.13	Terminal markings	109
6.14	Transformer groupings	111
6.15	The auto-transformer	112
6.16	Instrument transformers	114
CHAP	TER	
7	THE THREE-PHASE A.C. GENERATOR	119
7.1	Construction	119
7.2	The stator	119
7.3	The rotor	121
7.4	Excitation supply	124
7.5	Relationship between number of poles, speed, and frequency	126
7.6	Synchronous generator characteristics	127
7.7	The open-circuit test	128
7.8	The short-circuit test	130
vi	The second secon	-20

C	0	N	T	FI	V	rs
	v				٧.	LO

7.9	Regulation	131
7.10	Load characteristics	135
7.10	Loud Maratti Miles	
СНА	PTER	
8	THE THREE-PHASE SYNCHRONOUS MOTOR	137
8.1	The synchronous motor—principle	137
8.2	Starting a synchronous motor	138
8.3	Synchronizing	140
8.4	Methods of synchronizing	140
8.5	Synchronous motor phasor diagram	143
8.6	Operating a synchronous motor with fixed excitation	145
8.7	Operating a synchronous motor at constant power	146
8.8	Synchronous motor V-characteristics	147
8.9	Use of synchronous motors	148
8.10	Synchronous motor examples	148
	and a communication of the com	
CHA	PTER	
9	THE THREE-PHASE INDUCTION MOTOR	152
9.1	Construction	152
9.2	Production of a rotating magnetic field	154
9.3	Production of torque	156
9.4	Slip	157
9.5	Rotor constants	158
9.6	Rotor current	160
9.7	Rotor copper loss	160
9.8	Torque equation	161
9.9	Maximum torque	161
9.10	Induction motor calculations	162
9.11	The torque-slip characteristic	165
9.12	The torque-speed characteristic	166
9.13	Three-phase induction motor performance	167
9.14	Starting of induction motors	167
9.15	Starting methods for the cage motor	168
9.16	Starting a wound-rotor motor	170
9.17	Induction motor load test	172
9.18	The synchronous induction motor	173
CHA	PTER	
10	SMALL A.C. MOTORS	176
10.1	Single-phase induction motor—principle	176
10.2	The split-phase induction motor	178
10.3	Capacitor-start induction motor	179
10.4	Capacitor motor	180
		vii
		T.44

CONTENTS

10.5	The shaded-pole motor	181
10.6	The single-phase series motor	182
CHA	PTER	
11	INDUSTRIAL DRIVES	184
11.1	Choice of an electric motor	184
11.2	Motors for industrial drives	185
11.3	Characteristics of motors	186
11.4	Motor enclosures	189
11.5	Motor rating—intermittent duty	192
СНА	PTER	
12	THREE-PHASE RECTIFIERS	195
12.1	Summary of single-phase rectifiers	195
12.2	Three-phase half-wave rectifier	195
12.3	Three-phase full-wave centre-tap rectifier	197
12.4	Three-phase bridge rectifier	198
12.5	Smoothing	199
12.6	The capacitor filter	199
12.7	The inductor filter	200
12.8	The choke input filter	201
12.9	The Π-filter	203
СНА	PTER	
13	CONTROL SYSTEMS	204
13.1	Control systems	204
13.2	Open-loop system	204
13.3	Closed-loop system	205
13.4	Regulator systems	208
13.5	Servomechanism or position control	209
13.6	Process control	212
13.7	A temperature control system	213
13.8	Feedback and stability	214
13.9	Transfer function in a control system	218
CHA	PTER	
14	MEASURING INSTRUMENTS AND TESTING	221
	Sources of error when using indicating instruments	221
14.2	Classification of instruments	222
14.3	Instrument calibration	223
14.4	Instrument characteristics and selection	225
14.5	Digital instruments	228
14.6	Effect of instruments in a circuit	230
viii		

	CONT	ENTS
14.7	The CRO as a voltmeter	232
14.8	Measurement of current using a CRO	234
14.9	The CRO as a null indicator	235
14.10	Display of a waveform	236
14.11	Measurement of phase difference	237
14.12	Measurement of frequency and periodic time-Lissajous	
	figures	238
14.13	The Wheatstone bridge	240
14.14	The potentiometer	242
14.15	A bridge measurement of inductance and Q-factor	244
14.16	The 'MEGGER'	246
14.17	Tests of an installation and equipment and the location of	
	faults	247
14.18	Tests to locate cable faults	250
CHAP	PTER	
15	THE MEASUREMENT OF POWER	254
15.1	The dynamometer wattmeter	254
15.2	Measurement of power in a single-phase circuit	255
15.3	Extension of wattmeter range	256
15.4	Measurement of power in a three-phase circuit	256
CHAP	OTED	
16	COMPLEX WAVES	261
16.1	Fundamental and harmonic components	261
16.1	Synthesis of waveforms	262
16.2	Production of harmonics	262
16.4	Effect of reactance in a circuit	265
16.5	R.M.S. value of a complex wave	265
16.6	Power and power-factor of a complex wave	268
16.7	Resonance due to a complex wave	268
16.8	Harmonics in a three-phase system	269
10.0	Trainionies in a unce-phase system	209
APPE	NDIX	272
	Test questions	
INDE	x	287
, ,	-	-01

ix

Consumer's supply

1.1 From the grid to the consumer

Since the initial 132 kV network was completed in 1936 the Grid has been extended until it now covers virtually the whole of Great Britain. The *Grid System* consists of an extensive interconnected transmission network supplying the whole country and is controlled by the Central Electricity Authority. When the supply industry was nationalized in 1948 generation also became part of the system. The Grid network is now supplied from a small number of very large and highly efficient power stations strategically placed where fuel (usually coal) and water are easily available. The basic networks are still 132 kV but increasing demands and the necessity to supply bulk power over long distances has brought about the introduction of the Super Grid. This consists of transmission lines with voltages of 275 kV and 400 kV forming the main 'arteries' of the supply system.

Figure 1.1 is typical of the Grid supply system from the generating plant to the consumer. Most consumers receive supplies from the medium-voltage (415/240 V) distribution system, but it will be seen from the diagram that supplies to some large industrial consumers may be given at 11 kV or even 33 kV.

The advantages of the Grid system can be summarized as follows:

- 1. The whole country is linked by a common e.h.v. network.
- 2. Best use is made of large, highly efficient generating stations built upon the most advantageous sites.
- Load flow is under a centralized control, enabling generating plant to be operated at its highest efficiency.
- 4. Small and inefficient stations are eliminated.
- 5. Standby plant and spares are kept to a minimum.
- 6. Supply frequency and voltage can be standardized.
- 7. Loss of supply due to breakdown is minimized.
- 8. Electricity is more readily available to isolated communities.

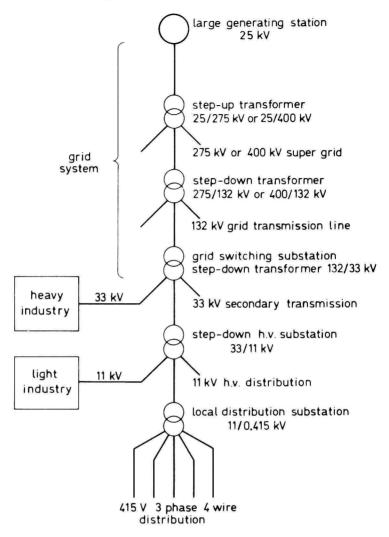


Fig. 1.1 Typical supply system

1.2 The local distribution system

The main substation feeding a particular area is usually placed as close to the load centre as possible. This substation will be supplied from the Grid transmission line, probably by means of a 33 kV secondary transmission line or underground cable. From the main substation there will be high-voltage distribution cables radiating outwards to feed the local distribution substations. This will probably be at 11 kV. The local substations

will also be interconnected by means of further 11 kV cables, so that a ring system of feeders is formed. By employing this ring system, it is possible to isolate any one of the cables without interrupting the supply to any substation. In the case of a fault, this may be done automatically by the use of suitable protective equipment at the substations. Transformers at each substation feed into a network of low-voltage distributors which radiate from the substation and to which the consumers' supplies are connected. These low-voltage cables may also be interconnected by means of link pillars or underground boxes, the use of which enables faulty cables to be isolated, feeds to be changed, and even a substation to be taken out of commission for maintenance work to be carried out, usually with no interuption to the consumer's supplies.

Figure 1.2 shows a typical arrangement for such a distribution system.

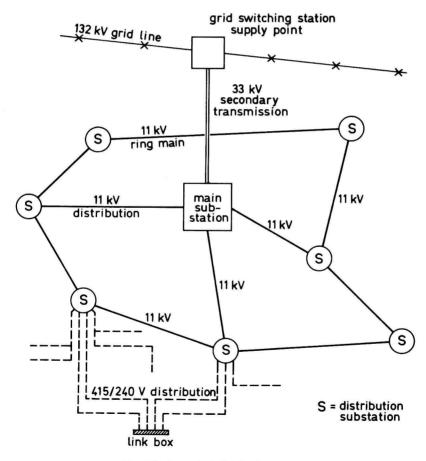


Fig. 1.2 Layout of distribution system

1.3 Operating voltages

On long transmission lines, the losses can be high. By raising the operating voltage, thereby reducing the current for a given power being delivered, the losses can be reduced and the efficiency of transmission increased. For any given line there is also a definite voltage which will give the minimum cost. This is the 'economic voltage' for the line. To find this voltage, a number of factors have to be taken into account, including local conditions, but a rough guide is 1000 V per mile of line. However, in order to standardize in the manufacture of equipment, certain standard voltages are used. These are:

400 kV and 275 kV for the Super Grid;

132 kV for the original Grid;

66 kV and 33 kV for secondary transmission;

11 kV, 6.6 kV, and 3.3 kV for h.v. distribution.

The standard distribution voltages for consumer's supplies are 415 V three-phase 50 Hz a.c. for power, and 240 V single-phase 50 Hz a.c. for lighting and heating supplies.

The voltages of consumer's circuits are normally classified as follows:

Extra-low voltage Not exceeding 50 V between conductors, and not

exceeding 30 V a.c. or 50 V d.c. between any con-

ductor and earth.

Low voltage Between 50 V and 250 V.

Medium voltage Over 250 V and not exceeding 650 V.

High voltage Over 650 V and not exceeding 3000 V.

Extra-high voltage Over 3000 V.

The above voltages are either between conductors or between one conductor and earth.

1.4 Consumer's supplies

Nowadays, the supply to the consumer is almost always a.c. However, there is still a need for d.c. for specific processes and even if the supply is a.c. there may still be a d.c. network within a factory supplied through either rectifiers or a motor-generator set. The following outline of supply systems includes both a.c. and d.c. supplies. The voltages shown are for standard supplies.

The main form of lighting is by means of the filament lamp. As it is uneconomical to manufacture such lamps much above a 250 V rating, this gives a limit to supply voltages for lighting circuits. Since such supplies are required in domestic premises there is also the safety aspect to be considered. Thus, the standard voltage for supplies to lighting circuits is limited to 250 V or less.

For power purposes, a higher voltage leads to greater efficiency. It will be seen below that by developing the three-wire and three-phase systems a higher voltage can be provided for power circuits while the lower voltage for lighting circuits is still maintained.

D.C. Two-wire System. This is the simplest system, consisting of two conductors known as the positive and negative leads (Fig. 1.3a). The voltage is limited to under 250 V for both lighting and power loads. Higher voltages may be used for power supplies only, as for traction where 1000 V or more may be used.

D.C. Three-wire System. By adding a third conductor, called the middle wire or neutral, the voltage of the system can be doubled for the supply of

positive lead

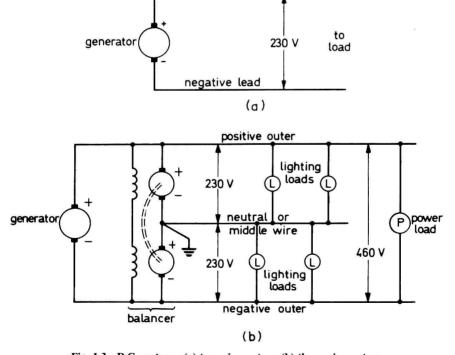


Fig. 1.3 D.C. systems: (a) two-wire system, (b) three-wire system

power loads. The full voltage will exist between the two *outers*, with half the voltage for lighting circuits between one of the outers and the middle wire. One problem with this system is that any out-of-balance between the positive and negative lighting loads will cause a rise in voltage on the lightly loaded side, with a corresponding reduction of voltage on the heavily loaded side. To overcome this, a *balancer*, consisting of two similar shunt machines coupled together, is connected into the circuit, as shown in Fig. 1.3b. The machine connected in the lightly loaded side operates as a motor to drive the other machine as a generator, thereby transferring power from one side to the other and thus reducing the out-of-balance and equalizing the voltages.

A.C. Single-phase Two-wire System (Fig. 1.4a). This is similar to the d.c. two-wire system, except that in this case the supply is normally from the secondary of a transformer at the distribution substation. One side of the secondary is always earthed, and the conductor connected to this side is

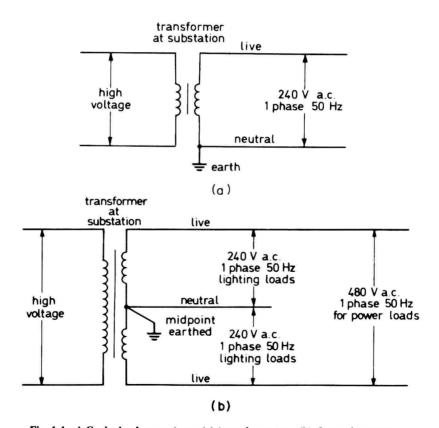


Fig. 1.4 A.C. single-phase systems: (a) two-wire system, (b) three-wire system