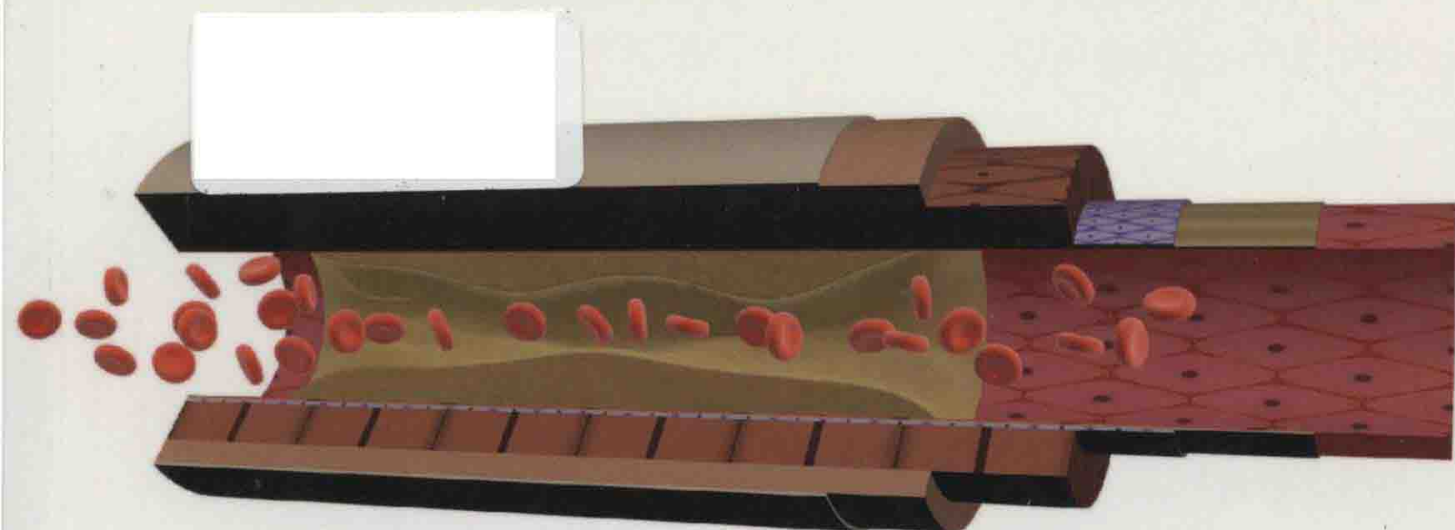




Vítězslav Štembera

Self-Excited Oscillations of Elastic Tubes

Induced by Fluid-Structure Interaction

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Self-Excited Oscillations of Elastic Tubes

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I declare that I have set up this thesis by myself using the mentioned sources only.

Prague, 25th May 2010

Vítězslav Štembera

This book contains a slightly enlarged version of the original dissertation from 2010.

Prague, 21th January 2013

Vítězslav Štembera

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Notations

Latin symbols

$[\cdot]$		matrix form of the fourth order tensor
A	$[\text{m}^2]$	cross-sectional area of the tube
A_0	$[\text{m}^2]$	cross-sectional area of the rigid tube
a_k, b_k		element shape functions
$\mathbf{a}_0, \mathbf{g}_0$		unit vectors describing fiber directions
$\mathbf{b} = \mathbf{F}\mathbf{F}^T$		left Cauchy-Green deformation tensor
c	$[\text{m s}^{-1}]$	sound speed in fluid
$\mathbf{c}$		right Cauchy-Green deformation tensor (matrix form)
$\mathbf{C} = \mathbf{F}^T\mathbf{F}$		right Cauchy-Green deformation tensor
$\mathbb{C}$	$[\text{Pa}]$	elasticity tensor
D	$[\text{m}]$	diameter of the tube
D_0	$[\text{m}]$	diameter of the rigid tube; tube diameter in undeformed state
$\mathbf{e}$		small deformation tensor
E	$[\text{N m}^{-2}]$	Young's modulus
$\mathcal{E}$		element index set
f	$[\text{Hz}]$	frequency
f	$[\text{N kg}^{-1}]$	frictional force exerted on one kilogram of mass
$\mathbf{F} = \frac{\partial \mathbf{x}}{\partial \mathbf{X}}$		the deformation tensor
g	$[\text{m s}^{-2}]$	Earth's gravitational acceleration
$\mathbf{g}$		Green-Langrange deformation tensor (vector form)
$\mathbf{G}$		Green-Langrange deformation tensor
h	$[\text{m}]$	distance between two neighboring nodes
h_0	$[\text{m}]$	tube thickness
I_1, I_2, I_3		invariants of tensor $\mathbf{C}$
$\mathbf{I}$		(second-order) identity tensor

$J = \det \mathbf{F}$		determinant of the deformation tensor
J_0	$[\text{m}^4]$	second moment of area
J_4		anisotropy pseudo-invariant
J_{m}		fiber extensibility parameter
$J_{\text{m}}^{\text{aniso}}$		anisotropic fiber extensibility parameter
$\mathcal{J}$		Jacobi matrix of mapping Ψ
k	$[\text{m}]$	roughness of the tube's inner surface
$\mathbf{K}$	$[\text{N m}^{-1}]$	stiffness matrix
l	$[\text{m}]$	length of the flexible tube
l_0	$[\text{m}]$	length of the rigid tube
m	$[\text{kg}]$	mass
M	$[\text{N m}]$	moment of a force
n_{LS}		number of load steps
N		number of element nodes; number of fluid grid points
N_p		number of element pressure unknowns
$\mathcal{N}$		node index set
p	$[\text{Pa}]$	separately interpolated pressure; fluid pressure
$\bar{p}$	$[\text{Pa}]$	pressure computed from displacement
p_{e}	$[\text{Pa}]$	pressure outside of the tube/channel
p_{u}	$[\text{Pa}]$	upstream fluid pressure
p_{d}	$[\text{Pa}]$	downstream fluid pressure
p_{S}	$[\text{Pa}]$	fluid pressure in reservoir
p_{in}	$[\text{Pa}]$	fluid pressure before the upstream restrictor
p_{I}	$[\text{Pa}]$	fluid pressure behind the upstream restrictor
p_{E}	$[\text{Pa}]$	fluid pressure before the downstream restrictor
p_{out}	$[\text{Pa}]$	fluid pressure behind the downstream restrictor
P_i		i -th element node
$\mathbf{q}$	$[\text{m}]$	discretized displacement vector
Q	$[\text{m}^3 \text{s}^{-1}]$	flow rate