Geometrical Product Specifications and Inspection

河南理工大学
2004年9月

Geometrical Product Specifications

中南大学图书馆藏

河南理工大学

2004 年 9 月

ACKNOWLEDGMENTS

The authoring team is extremely grateful to the *Commission of the European Communities* for support for the creation of this textbook and the attached multimedia CD received within the framework of the *European Community vocational training action programme Leonardo da Vinci*. The project *Geometrical Product Specifications – course for Technical Universities* was accepted in the 1999 call for proposals for *Leonardo da Vinci Programme Pilot Projects* as the project PL/99/1/86613/PI/I.1.1a/FPI.

This textbook would not have been possible without understanding and cosponsoring from the authorities of the project partner universities.

The need for a textbook that provides the fundamentals of dimensional and geometrical tolerancing was identified by the editor and his colleagues from other European universities during the International Conference on *Coordinate Measuring Technique* that is organised by Lódź Technical University the Bielsko-Biała Branch every two years. We furthermore discussed demands for such a textbook for students and lecturers in mechanical and production engineering faculties during the IMEKO World Congresses in 1999 in Osaka and in 2000 in Vienna.

I would also like to acknowledge the numerous colleagues from Technical Committee ISO/TC 213 *Dimensional and Geometrical Product Specifications and Verification* and the national standards committees who have contributed much to our understanding of the current state of the art in dimensional and geometrical tolerancing.

I am also deeply indebted to:

- **Prof. Peter Herbert Osanna**, Department of Interchangeable Manufacturing and Industrial Metrology, Vienna University of Technology (Austria);
- **Prof. Mart Tamre**, Chair of Engineering Design and Mechatronics, Tallinn Technical University (Estonia);
- **Prof. Albert Weckenmann**, Chair Quality Management and Manufacturing Metrology, Friedrich-Alexander University Erlangen-Nuremberg (Germany);
- **Dr Eng. Liam Blunt**, School of Engineering, University of Huddersfield (United Kingdom);
- **Dr Eng. Władysław Jakubiec**, Department of Manufacturing Technology and Automation, Łodź Technical University the Bielsko-Biała Branch (Poland)

who excellently managed their university authors' teams, as well as for smooth cooperation, advisable comments and suggestions.

Special thanks to **Prof. Sławomir Białas** of the Institute of Machine Design Fundamentals, Warsaw University of Technology, who encouraged me to discover and explore the intriguing field of dimensional and geometrical specifications. **Prof. Sławomir Białas** is truly one of the most knowledgeable people I have ever met.

Finally particular thanks are due to **Prof. Albert Weckenmann** who persuaded me to become this project promotor and to apply to the *Commision of the European Communities* for the grant for this project. **Prof. Albert Weckenmann** provided numerous valuable advices as well as gave me a great deal of support during the project execution.

I would like to express my gratitude to all coauthors for the sharing of valuable ideas and mutual help in their development.

Zbigniew Humienny
Warsaw, July 2001

PREFACE

In this textbook we present the science of dimensioning, geometrical tolerancing and measurement of geometrical characteristics in a carefully structured manner which emphasises their foundations as well as their application. Most of the material covered in this textbook is regarded as appropriate for core bachelor and master student courses in mechanical and production engineering disciplines.

It is not intended that basic course lectures cover every point made in the textbook. Some topics are discussed more in details and it is believed that the parts of textbook are also highly suitable for more advanced courses.

The content of this textbook is based on the authors discussions, years of teaching experience and the curricula that are offered to students at:

- Institute of Machine Design Fundamentals, Warsaw University of Technology (Poland);
- Department of Interchangeable Manufacturing and Industrial Metrology, Vienna University of Technology (Austria);
- Department of Mechatronics, Tallinn Technical University (Estonia);
- Chair of Quality Management and Manufacturing Metrology, Friedrich-Alexander University Erlangen-Nuremberg (Germany);
- School of Engineering, University of Huddersfield (United Kingdom);
- Department of Manufacturing Technology and Automation, Łodź Technical University the Bielsko-Biała Branch (Poland).

All of the chapters' contributors are active researchers in the area and many are well known scholars whose research results have guided progress in their particular research field. Other contributors are young and promising scholars.

The objective of the authoring team has throughout, remained that of developing a model course for geometrical product specification that may be regarded as the basic textbook for teaching/learning at technical universities in Europe.

The authors have attempted to highlight the latest achievements and standards developed by ISO/TC 213 *Dimensional and Geometrical Product Specifications and Verification* as well as by other ISO technical committees.

A novel feature of this textbook is the interactive CD that employs new information technology for teaching/learning and allows readers further study.

The text book is accompanied by the web page:

http://leonardo.simr.pw.edu.pl.

We encourage you to browse this web page to get the latest information in the GPS field as well as to send questions, comments and remarks to the autors.

Zbigniew Humienny (editor)
Peter Herbert Osanna
Mart Tamre
Albert Weckenmann
Liam Blunt
Władysław Jakubiec

CONTENTS

Acknowledgments

Preface

1 Introduction **1. 1**
(S. Białas)

2 Chains of GPS standards. Matrix model **2. 1**
(S. Białas)

3 Business environment. Quality management **3. 1**
(D. Geus, T. Killmaier, A. Weckenmann)

3.1 Introduction. 3. 1
3.2 Quality and costs. 3. 1
3.3 Standards 3. 4
3.3.1 EN ISO 9000-9004:1994 3. 4
3.3.2 VDA 6.1 3. 5
3.3.3 QS 9000 3. 6
3.3.4 ISO 9000:2000 and family – Differences from the 1994 version 3. 7
3.4 References 3. 8

4 Skin model **4. 1**
(D. Geus, T. Killmaier, A. Weckenmann)

4.1 Introduction 4. 1
4.2 Geometrical features 4. 4
4.3 Expanded feature definitions 4. 7
4.3.1 Motivation 4. 7
4.3.2 Geometrical features – general terms and definitions 4. 7
4.4 Operators 4. 9
4.4.1 Perfect operator 4. 10
4.4.2 Optimal operator 4. 10
4.4.3 Simplified operator 4. 10
4.5 References 4. 10

5 Size general principles **5. 1**
(D. Geus, T. Killmaier, A. Weckenmann)

5.1 Definitions of size 5. 1
5.1.1 Groups of sizes and dimensions 5. 2
5.1.2 Maximum and least material limit 5. 4
5.2 Principle of independency 5. 4
5.3 Envelope requirement 5. 7
5.4 Maximum material condition 5. 9
5.4.1 Maximum material virtual limit 5. 9
5.4.2 Example for maximum material condition 5. 10
5.4.3 Least material requirement 5. 10
5.4.4 Reciprocity requirement 5. 12
5.5 References 5. 13

试读结束，需要全本PDF请购买 www.ertongbook.com

6 ISO system of limits and fits **6. 1**
(I. Märtson, M. Tamre)
6.1 Brief history 6. 1
6.2 Tolerance grades 6. 1
6.2.1 Tolerance of a size as function of nominal size and tolerance grade 6. 1
6.2.2 Functions for various tolerance grades 6. 3
6.2.3 Rounding of calculated values of tolerances 6. 4
6.3 Fundamental deviations 6. 5
6.3.1 Layout of fundamental deviations 6. 5
6.3.2 Designation of toleranced sizes 6. 7
6.3.3 Recommended tolerance classes 6. 7
6.4 Fits and their characteristics 6. 7
6.4.1 The term of fit 6. 7
6.4.2 Types of fits 6. 9
6.4.3 Hole-basis and shaft-basis systems of fits 6. 11
6.4.4 General rules of designing fits 6. 12
6.4.5 Corrections of fundamental deviations due to the fit structure 6. 13
6.4.6 Recommended fits 6. 15
6.5 References 6. 16

7 Introduction to Geometrical Tolerancing **7. 1**
(W. Jakubiec, J. Malinowski, M. Starczak)
7.1 Classification 7. 1
7.2 Indication 7. 2
7.3 References 7. 7

8 Tolerances of form **8. 1**
(D. Geus, T. Killmaier, A. Weckenmann)
8.1 Introduction 8. 1
8.2 General concepts 8. 4
8.3 Straightness 8. 6
8.3.1 Definition 8. 6
8.3.2 Transmission band 8. 7
8.3.3 Probing system and probing force 8. 9
8.4 Roundness 8. 9
8.5 Flatness 8. 11
8.5.1 Definition 8. 11
8.5.2 Measurements 8. 12
8.6 Cylindricity 8. 12
8.7 Line and surface profile 8. 14
8.8 Rules for form tolerancing 8. 15
8.9 References 8. 16

9 Datums **9. 1**
(W. Jakubiec, M. Starczak)
9.1 Datums, datum features and simulated datum features 9. 1
9.2 Establishing datums 9. 2
9.2.1 Points as a datum 9. 2
9.2.2 Straight line or a plane as datum 9. 3
9.2.3 Axis of the cylinder or median plane as datum 9. 5
9.3 Datum targets 9. 6
9.4 Datum systems 9. 6
9.4.1 Common axis or common median plane as datums 9. 7

9.4.2 Plane and axis of a cylinder perpendicular to a plane as a datum 9. 8
9.4.3 Three-plane datum-system 9. 8
9.5 Groups of feature nominated as datums (pattern datums) 9. 11
9.6 Datums on CMM 9. 12
9.7 Datums for threads, gears and splines 9. 14
9.8 Datums for flexible parts 9. 15
9.9 References 9. 15

10 Tolerances of orientation **10. 1**

(W. Jakubiec, J. Malinowski)

10.1 Introduction 10. 1
10.2 Parallelism 10. 1
10.2.1 Parallelism tolerance of a straight line related to a datum system (straight line and plane) 10. 1
10.2.2 Parallelism tolerance of a straight line related to a datum straight line 10. 4
10.2.3 Parallelism tolerance of a straight line related to a datum plane 10. 4
10.2.4 Parallelism tolerance of a straight line related to a datum system (two planes) 10. 5
10.2.5 Parallelism tolerance of a plane related to a datum straight line 10. 5
10.2.6 Parallelism tolerance of a plane related to a datum plane 10. 6
10.3 Perpendicularity 10. 6
10.3.1 Perpendicularity tolerance of a straight line related to a datum straight line 10. 7
10.3.2 Perpendicularity tolerance of a straight line related to a datum system (two planes) 10. 7
10.3.3 Perpendicularity tolerance of a straight line related to a datum plane 10. 8
10.3.4 Perpendicularity tolerance of a plane related to a datum straight line 10. 9
10.3.5 Perpendicularity tolerance of a plane related to a datum plane 10. 9
10.4 Angularity 10. 9
10.4.1 Angularity tolerance of a straight line related to a datum straight line 10. 10
10.4.2 Angularity tolerance of a straight line related to a datum plane 10. 11
10.4.3 Angularity tolerance of a line related to a datum system (two planes) 10. 11
10.4.4 Angularity tolerance of a plane related to a datum straight line 10. 12
10.4.5 Angularity tolerance of a plane related to a datum system 10. 13
10.5 References 10. 13

11 Tolerances of location **11. 1**

(W. Jakubiec, W. Płowucha)

11.1 Introduction 11. 1
11.2 Position 11. 1
11.2.1 Position tolerance of a point 11. 1
11.2.2 Position tolerance of a line 11. 2
11.2.3 Position tolerance of a flat plane or a median plane 11. 5
11.2.4 The position of cylindrical surface related to an axis 11. 6
11.2.5. Position tolerance as an equivalent of any other location tolerance. 11. 6
11.3. Concentricity and coaxiality 11. 6
11.3.1 Concentricity tolerance of a point 11. 7
11.3.2 Coaxiality tolerance of an axis 11. 7
11.4 Symmetry 11. 9
11.5. References 11. 10

12 Tolerances of line or surface with or without datum **12. 1**
(P.H. Osanna, N.M. Durakbasa, A. Afjehi-Sada)†
12.1 Introduction 12. 1
12.2 Profile any line 12. 2
12.3 Profile any surface 12. 4

13 Tolerances of runout **13. 1**
(P.H. Osanna, N.M. Durakbasa, A. Afjehi-Sada)†
13. 1 Introduction 13. 1
13.2 Circular run-out 13. 1
13.2.1 Circular run-out in the radial direction 13. 1
13.2.2 Circular run-out in the axial direction 13. 4
13.2.3 Circular run-out in any direction 13. 5
13.3 Total runout 13. 7

14 Tolerances of angles and cones **14. 1**
(M. Tamre)
14.1 Angle and angle dimension 14. 1
14.2 Tolerancing of angles 14. 3
14.2.1 Tolerancing method by linear size 14. 3
14.2.2 Tolerancing method by angular deviation 14. 6
14.3 Tolerances for cones 14. 7
14.4 References 14. 9

15 General tolerances **15. 1**
(M. Tamre)
15.1 Principle of general tolerance 15. 1
15.2 Customary workshop accuracy 15. 2
15.3 Use of general tolerances 15. 3
15.4 General tolerances for dimensions 15. 4
15.4.1 General tolerances for linear dimensions 15. 4
15.4.2 General tolerances for angular dimensions 15. 5
15.5 General geometrical tolerances 15. 5
15.6 Indications on drawings 15. 8
15.7 References 15. 11

16 Roughness, waviness and primary profile **16. 1**
(L. Blunt, X. Jiang)
16.1 Introduction 16. 1
16.2 Surface profile parameters 16. 4
16.2.1 Surface mean line 16. 5
16.2.2 Amplitude parameters 16. 5
16.2.3 Spatial parameters 16. 9
16.2.4 Hybrid parameters 16. 9
16.2.5 Curves and related parameters 16. 10
16.2.6 Surface texture comparison rules 16. 11
16.3 Surface measurement 16. 12
16.3.1 Basic contact measurement 16. 12
16.3.2 Sources of error 16. 13
16.4 Filtering 16. 14
16.5 Limitations of 2D surface measurement 16. 18
16.6 Development of the areal approach 16. 20

16.7 Areal roughness parameters 16. 21
16.7.1 The field parameters 16. 21
16.7.2 Feature parameters 16. 23
16.8 Near future 16. 23
16.9 References 16. 24

17 Designation and interpretation of geometrical tolerances 17. 1
(D. Geus, T. Killmaier, A. Weckenmann)
17.1 Introduction 17. 1
17.2 Geometrical tolerances 17. 1
17.3 Principle of tolerancing 17. 3
17.4 Practical examples for application of geometrical tolerances 17. 4
17.4.1 Principle of independency 17. 5
17.4.2 Envelope requirement 17. 5
17.4.3 Maximum material requirement 17. 7
17.4.4 Projected tolerance zone 17. 10
17.4.5 Free state tolerancing 17. 11
17.5 Checklist for the interpretation of specified tolerances 17. 12
17.6 References 17. 13

18 Tolerances for specific manufacturing processes 18. 1
(S. Białas)
18.1 Introduction 18. 1
18.2 Tolerances for castings 18. 1
18.3 Tolerances for welded constructions 18. 4

19 Tolerances for selected complex geometrical features 19. 1
(S. Białas, W. Jakubiec)
19.1 Introduction 19. 1
19.2 Screw threads 19. 1
19.3 Splines 19. 8
19.4 Cylindrical gears 19. 10
19.4.1 Deviations relevant to corresponding flanks of gear teeth 19. 11
19.4.2 Radial composite deviations and runout 19. 17
19.4.3 Deviations of tooth thickness 19. 19
19.5 References 19. 23

20 Vectorial dimensioning and tolerancing 20. 1
(Z. Humienny)
20.1 Vectorial dimensioning and tolerancing state of art and perspectives 20. 1
20.2 Vectorial dimensioning and tolerancing concept 20. 2
20.3 Substitute elements 20. 4
20.4 Substitute datum system 20. 6
20.5 Substitute location 20. 8
20.6 Substitute orientation 20. 9
20.7 Substitute rotation 20. 9
20.8 Form, roughness and further requirements 20. 9
20.9 A case study – VDT of a car engine connecting rod 20. 11
20.9.1 Connecting rod – main sizes and tolerances 20. 11
20.9.2 Algorithm of the VDT 20. 13
20.10 Feedback from measurement to control manufacturing process provided by VDT 20. 18
20.11 References 20. 18

21 Statistical tolerancing of mechanical assemblies **21. 1**
(P.H. Osanna, N.M. Durakbasa, A. Afjehi-Sadat)

21.1 Introduction 21. 1
21.2 Background 21. 2
21.2.1 Elementary statistics 21. 2
21.2.2 Example 21. 3
21.3 Tolerance indications 21. 4
21.3.1 Workpiece drawings 21. 4
21.3.1 Process capability indices 21. 5
21.4 Assembly example 21. 7
21.4.1 Problem definition 21. 7
21.4.2 Analysis 21. 8
21.5 References 21. 11

22 Dimensional chains. Accumulation of tolerances **22. 1**
(K. Kiszka, A. Leśniewicz)

22.1 Operation on toleranced dimensions 22. 1
22.1.1 Tolerance calculations based on deterministic model 22. 1
22.2.1. Tolerance calculation based on stochastic model 22. 4
22.2 Types of dimensional chains 22. 7
22.3 Graphical presentation of dimensional chains 22. 9
22.4 Dimensional chain analysis 22. 11
22.5 Dimensional chain synthesis 22. 13
22.5.1 Equivalent tolerances method 22. 14
22.5.2 Equivalent standard tolerance grade method 22. 15
22.5.3 Equivalent influence method 22. 15
22.5.4 Optimisation method 22. 17
22.6 Computer aided tolerance analysis/synthesis 22. 19
22.7 References 22. 23

23 Inspection of dimensional and geometrical deviations – overview **23. 1**
(D. Geus, T. Killmaier, A. Weckenmann)

23.1 Introduction 23. 1
23.2 Testing of sizes and distances 23. 3
23.2.1 Calliper 23. 3
23.2.2 Micrometer gauges 23. 5
23.2.3 Dial gauges 23. 6
23.3 Testing of angles 23. 8
23.4 Gauging 23. 9
23.5 Measuring of form deviations 23. 9
23.6 Coordinate measurements 23. 12
23.7 Measurement uncertainty 23. 14
23.7.1 Measuring instrument 23. 16
23.7.2 Environment 23. 16
23.7.3 Workpiece 23. 16
23.7.4 Operator and measurement strategy 23. 17
23.7.5 Reasons for result differences from coordinate measurements 23. 17
23.8. Consequences for inspection of workpieces 23. 17
23.9 References 23. 18

24 Measurement uncertainty and statistical process control in manufacturing processes **24. 1**

(D. Geus, T. Killmaier, A. Weckenmann)

24.1 Introduction 24. 1
24.2 Characterization of production processes 24. 1
24.3 Characterization of measuring processes 24. 2
24.4 Observation of production processes with measuring instruments 24. 3
24.5 Determination of the real process capability 24. 4
24.6 Statistical process control 24. 5
24.7 Conclusions 24. 6
24.8 References 24. 6

25 Differences between EN-ISO standards and others standards **25. 1**

(S. Białas, T. Killmaier, K. Kiszka)

25.1 Differences between EN-ISO and DIN standards 25. 1
25.2 Differences between EN-ISO and ASME standardS 25. 2
25.3 Geometrical tolerances according to EN-ISO and SEV 25. 5
25.4 References 25. 7

26 Computer aided tolerancing and verification **26. 1**

(Z. Humienny, W Jakubiec)

26.1 Introduction 26. 1
26.2. Software implementation of ISO system of limits and fits 26. 2
26.3 Packages for computer aided dimensional analysis/synthesis 26. 2
26.4. Packages for geometrical tolerancing in CAD environment 26. 3
26.5 Educational packages 26. 4
26.6 Measurement systems software 26. 5
26.6.1 CMM software 26. 6
26.6.2 From CAD drawing to executable measurement programme 26. 10
26.7 References 26. 11

27 Glossary – terms and definitions **27. 1**

(K. Kiszka)

28 List of published European and International Standards and other documents in the field of GPS **28. 1**

(K. Kiszka)

28.1 Published standards of ISO/TC 213 and CEN/TC 290 28. 1
28.2 Other selected ISO standards connected with textbook scope 28. 3
28.3 Other normative documents referred in textbook 28. 6
28.4 Withdrawn standards of ISO/TC 213 (replaced) 28. 8
28.5 Withdrawn standards of ISO/TC 213 (without replacement) 28. 8

试读结束，需要全本PDF请购买 www.ertongbook.com

1 INTRODUCTION

S. Białas

When a machine part is being designed, the designer imagines it as an ideal, perfect object. According to designer's intent all dimensions and the shape (geometry) of the part are without geometrical error and the surface is smooth.

However, during machining an actual workpiece is created that is far from perfect. Its shape is distorted, dimensions are different from those imagined by the designer and the surface is rough. If many workpieces are manufactured according to the same technical drawing, each of them generally differs from others.

After machining the parts are assembled. This process is also not ideal and additional errors may occur. So the result of a manufacturing process is a real, not perfect product – a machine or a mechanical device. Despite manufacturing errors, the product may be regarded as acceptable if the errors are properly controlled.

A set of requirements concerning the geometry of a workpiece (or of an assembly of some workpieces) is known as the *Geometrical Product Specifications (GPS)* covering requirements of size and dimension, geometrical tolerance and geometrical properties of the surface (Fig. 1.1).

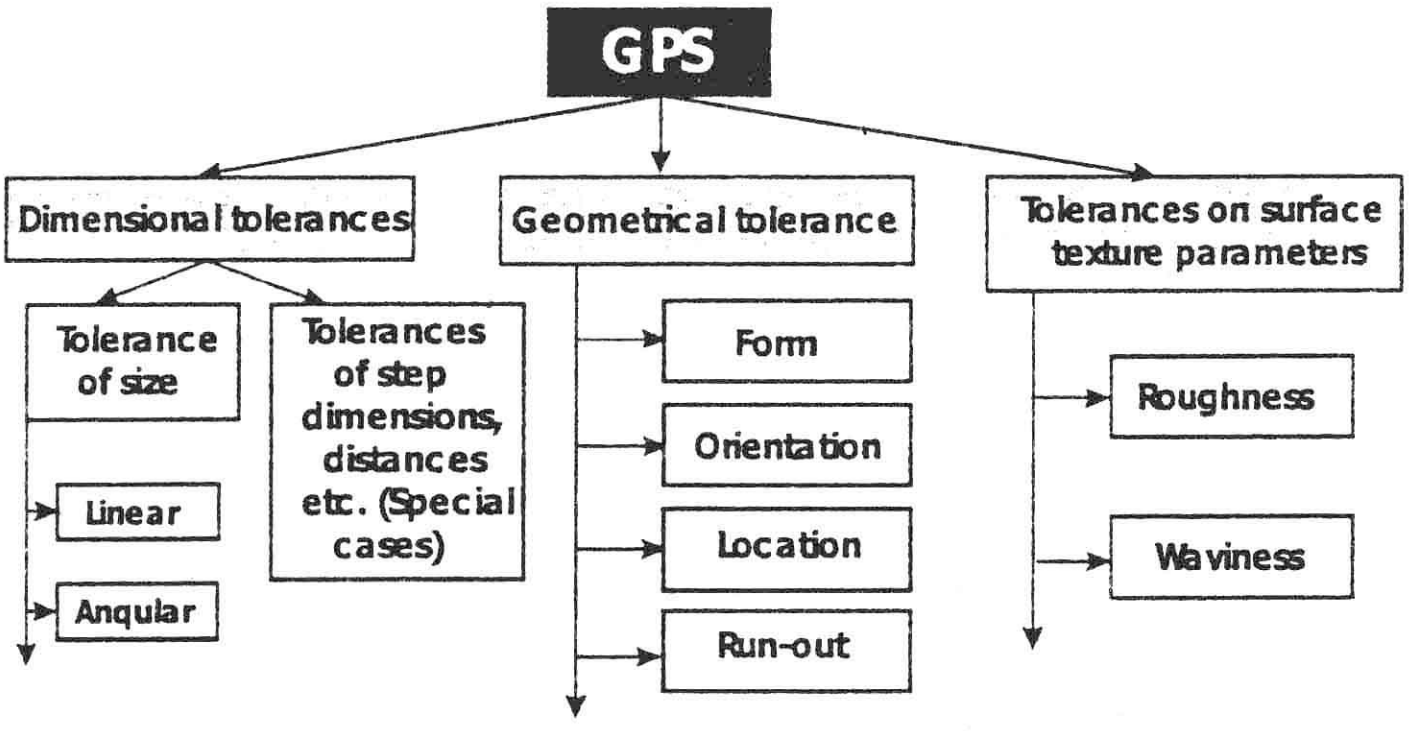

Fig. 1.1. General concept of *Geometrical Product Specifications.*

GPS are applied for various reasons. Generally – GPS give an assurance for obtaining some essential properties of the product:

- *Functionality*. A well-known example may be a machine tool – if its elements meet certain geometrical tolerances (e.g. straightness of bedways), the machine works well.
- *Safety*. If for example the crankshaft pin is ground according to specifications concerning roughness, there is no danger of a fatigue crack destroying the engine.
- *Dependability*. Properly selected geometrical tolerances, for instance roundness of compressor cylinders, guarantee long work life of the machine.
- *Interchangeability*. This is perhaps the oldest aspect applying GPS. Interchangeability is advantageous in assembly of a new machine and in repair as well.

It should be noted that GPS express different requirements in a language of geometry. The properties that are to be obtained using GPS are not necessary of a geometrical nature – the link between GPS and the desired parameters of a machine is indirect. It is down to the skill of the designer to "translate" the various mechanical requirements into the geometrical language of GPS. As an example a slide bearing may be considered – the relation of maximum and minimum clearances (that result from specified tolerances) to lubricating process is very complicated and difficult to foresee.

International organisations for standardization are deeply interested in developing the fundamentals of GPS. Technical Committee ISO/TC 213 *Dimensional and Geometrical Product Specifications and Verification* was established in 1996 and works in close collaboration with a similar committee in the European organisation CEN/TC 290. According to *Vienna agreement* all projects are processed in parallel by these two technical committees – so documents on GPS prepared by ISO and CEN are identical.

The ISO/TC 213 runs the web site http://www.ds.dk/isotc213. This web site with partly open access gives the overview of the scope and activity of Technical Committee ISO/TC 213.

Most countries adopt international standards (ISO/CEN) on GPS by just issuing national standards which are identical to international standards; therefore ISO(CEN) standards obtain the status of their national standards. For countries that are members of CEN, implementation of European Standards through giving them status of national standards is obligatory.

The bases of GPS should be a part of mechanical engineering education. Each engineer that is involved in designing or manufacturing processes (even indirectly) must have some knowledge of specifications concerning the geometry of a product. Without such competence neither creating new technical documentation nor its reading and construction is possible.

In this textbook the contemporary idea of GPS has been presented in a concise form. First three chapters cover general information on GPS – standardisation and application in quality management. Chapters 4 – 19 may be regarded as the main part of the book – they contain a systematic review of different cases of tolerancing (based chiefly on *General GPS Matrix* – see Chapter 2) including their theoretical background. In Chapters 20 and 21 some specific methods of tolerancing (vectorial, statistical) are presented. The subject of Chapter 22 is calculation of tolerances applied in design and manufacturing. Chapters 23 and 24 cover inspection problems. Last chapters (25 – 28) concern selected questions related to standardisation, terminology and computer aided tolerancing.

The book contains many excerpts from standards, e.g. tables, examples of drawing indications etc. that can be applied in teaching process. It is strongly recommended in practical applications to use only full, original copies of the standards. The possibility of applying the most recent editions should be always investigated.

2 CHAINS OF GPS STANDARDS MATRIX MODEL

S. Białas

Before establishment of Technical Committee ISO/TC 213 *Dimensional and Geometrical Product Specifications and Verification* the need for classification of GPS standards was recognised. This was necessary for reviewing the many standards on GPS that were published before 1995, and for programming and monitoring future work in the field of GPS standardisation.

The Joint Harmonisation Group ISO/TC 3-10-57/JHG (working in years 1993 – 1996) prepared a Technical Report ISO/TR 14638:1995 concerning classification system of GPS standards, known as the *Masterplan*. In this document all GPS standards have been divided into 4 groups:

- Fundamental GPS standards;
- Global GPS standards;
- General GPS standards;
- Complementary GPS standards.

A special graphical presentation of these groups has been adopted (Fig. 2.1).

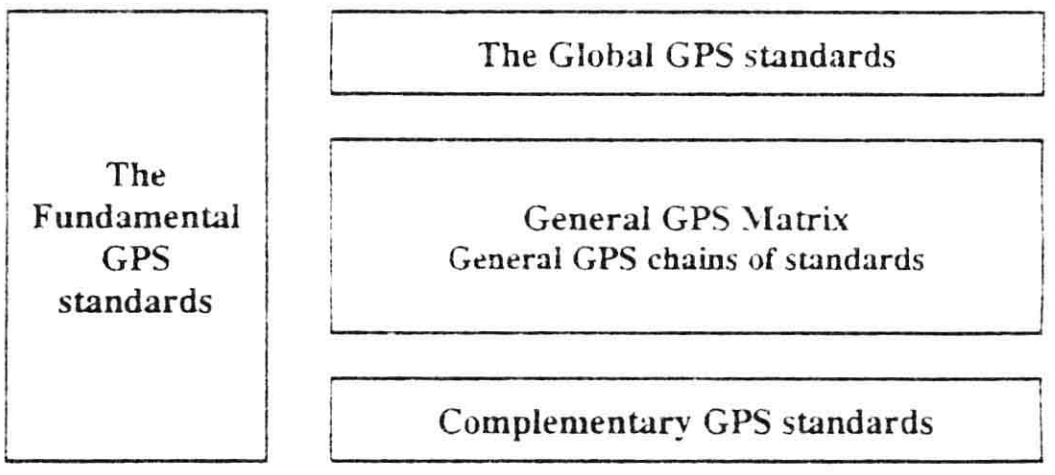

Fig. 2.1. Overview of GPS Masterplan structure.

According to the original idea, the group of *Fundamental GPS standards* should consist of such standards that establish very fundamental rules for dimensioning and tolerancing. However, in this group there are only two documents – ISO 8015:1985 (which, in fact, now is not regarded as really "fundamental") and ISO/TR 14638 which contains the outline of the *Masterplan*.

Global GPS standards are closely related to many other GPS standards – first of all those contained in the General GPS Matrix. Global standards influence general GPS chains of standards directly (being referenced to) or as default documents. The most important global GPS

standard is ISO 1 on the standard reference temperature. Another global GPS standard is for example ISO 14660-1 which establishes terms and definitions of geometrical features. Several global GPS standards are under preparation. There are two metrological documents – VIM [2.1] and GUM [2.2] – that play an important role in GPS and for this reason may be found among the Global GPS Standards despite the fact that they are not standards.

Complementary GPS standards contain technical rules for drawing indications, definitions and verification principles for specific categories of features or elements. Some of the rules depend on the type of manufacturing process (machining, casting, welding, forming ...); other may concern the geometry of certain machine elements like screw threads, splines, or gears. Most of the numerous Complementary GPS standards have been prepared by various ISO Technical Committees; only a few are the results of TC 213 activity. Some complementary GPS standards are presented in Chapters 8, 18 and 19.

General GPS standards are the kernel of the *Masterplan*. They are ordered in a matrix in which rows constitute *chains* of standards, and columns concern various characteristics of geometrical features (Tab. 2.1). Due to the structure of this part of *Masterplan*, the whole system is known as the *GPS matrix model*.

Tab. 2.1. General GPS matrix – layout.

Chain link number / **Geometrical characteristic of feature**		**1**	**2**	**3**	**4**	**5**	**6**
1	Size						
2	Distance						
3	Radius						
4	Angle						
5	Form of line independent of datum						
6	Form of line dependent on datum						
7	Form of surface independent of datum						
8	Form of surface dependent on datum						
9	Orientation						
10	Location						
11	Circular run-out						
12	Total run-out						
13	Datums						
14	Roughness profile						
15	Waviness profile						
16	Primary profile						
17	Surface imperfections						
18	Edges						

A chain of standards consists of a set of standards related to a given characteristic. The standards are collected in a few groups – "links" of the chain. There are 6 chain links associated with different geometrical characteristics of features. There are explained as follows.

1. ***Product documentation indication – codification***. The standards placed in this link define drawing symbols (specific codes) and designations, establish rules of their application and explain how to read and generally understand specifications.
2. ***Definition of tolerances***. The standards contain theoretical definitions of tolerances and their numerical values as well (as translated from code symbols). By means of these standards theoretical exact features with associated tolerances can be defined.
3. ***Definitions of characteristics of actual (real) feature***. Basing on these standards, the geometry of a non-ideal, real workpiece can be unambiguously defined in relation to tolerance code symbols on the drawing. The definitions are based on a set of data points of considered features.
4. ***Assessment of the workpiece deviations – comparison with specified limits***. The main task of these standards is to state how to prove conformance or non-conformance of a real workpiece with specifications, taking into account the uncertainty of inspection procedures.
5. ***Measurement equipment requirements***. The standards in this link describe characteristics (particularly – metrological ones) of measurement instruments in a general approach or related to specific types of equipment.
6. ***Calibration requirements – measurement standards***. These standards establish the characteristics of calibration standards used in calibration procedures of the equipment described in link no. 5. The traceability to SI length unit (meter) shall always be assured.

It is clear then that each chain of standards is related to the complete process of designing (setting up unambiguous specifications), manufacturing (interpreting specifications) and verification (measuring).

Table 2.2 presents, as an example, the first row (chain of standards No 1) of the General GPS Matrix, concerning *size* – perhaps the most important characteristic of geometrical feature. (see Chapters 5 and 6). Some of the listed standards are in the course of preparation or revision.

Tab. 2.2. The chain of standards related to *size* – 1st row of General GPS Matrix.

1	2	3	4	5	6
ISO 129 ISO 286-1	ISO 286-1 ISO 286-2	ISO 286-1 ISO 8015 ISO 14660-2	ISO 14253-1	ISO 463 ISO 9121 ISO 9493 ISO 10360-1 ISO 10360-2 ISO 13225 ISO 13385 ISO 14253-1	ISO 3650 ISO 14253-1
Titles of the standards – see Chapter 28.					

The General GPS matrix is composed of a total of 6×18 = 108 cells (links of chains); each cell should contain at least one standard. The chain concerning *size* (Tab. 2.2) fulfils this

requirement. However, many cells of other chains (e.g. the *distance* chain) are still empty because of the lack of corresponding standards. It is probable that after some years of activity of ISO/TC 213 all the chain links will contain related standards.

Global GPS Standards

General GPS matrix

Chain link number	**1**	**2**	**3**	**4**	**5**	**6**
Size						
Distance						
Radius						
Angle						
Form of line independent of datum						
Form of line dependent on datum						
Form of surface independent of datum						
Form of surface dependent on datum						
Orientation						
Location						
Circular run-out						
Total run-out						
Datums						
Roughness profile						
Waviness profile						
Primary profile						
Surface imperfections						
Edges						

Fundamental GPS Standards

Fig. 2.2. An example scheme explaining the indication of matrix cells in GPS Matrix model (ISO 5458).

The *Masterplan* applied as a tool in standardisation work helps to observe the following basic rules:

1. The *rule of unambiguity*; it means that each chain of standards in the General GPS Matrix shall contain all necessary, unambiguous regulations existing between the drawing indication and the geometrical characteristic of the workpiece, and that the assessed value representing the characteristic is traceable to international calibration standards. Each measurand in the chain shall be measurable.
2. The *rule of totality* – the standards contained in all chains (rows) of the General GPS Matrix shall ensure the possibility of indicating on the drawing all the required

试读结束，需要全本PDF请购买 www.ertongbook.com