# Specification of the standard for the standard standard for the standard st

河南理工大学

2004年9月

# **ACKNOWLEDGMENTS**

The authoring team is extremely grateful to the Commission of the European Communities for support for the creation of this textbook and the attached multimedia CD received within the framework of the European Community vocational training action programme Leonardo da Vinci. The project Geometrical Product Specifications – course for Technical Universities was accepted in the 1999 call for proposals for Leonardo da Vinci Programme Pilot Projects as the project PL/99/1/86613/PI/I.1.1a/FPI.

This textbook would not have been possible without understanding and cosponsoring from the authorities of the project partner universities.

The need for a textbook that provides the fundamentals of dimensional and geometrical tolerancing was identified by the editor and his colleagues from other European universities during the International Conference on Coordinate Measuring Technique that is organised by Łódź Technical University the Bielsko-Biała Branch every two years. We furthermore discussed demands for such a textbook for students and lecturers in mechanical and production engineering faculties during the IMEKO World Congresses in 1999 in Osaka and in 2000 in Vienna.

I would also like to acknowledge the numerous colleagues from Technical Committee ISO/TC 213 Dimensional and Geometrical Product Specifications and Verification and the national standards committees who have contributed much to our understanding of the current state of the art in dimensional and geometrical tolerancing.

I am also deeply indebted to:

- Prof. Peter Herbert Osanna, Department of Interchangeable Manufacturing and Industrial Metrology, Vienna University of Technology (Austria);
- Prof. Mart Tamre, Chair of Engineering Design and Mechatronics, Tallinn Technical University (Estonia);
- Prof. Albert Weckenmann, Chair Quality Management and Manufacturing Metrology, Friedrich-Alexander University Erlangen-Nuremberg (Germany);
- Dr Eng. Liam Blunt, School of Engineering, University of Huddersfield (United Kingdom);
- Dr Eng. Władysław Jakubiec, Department of Manufacturing Technology and Automation, Łodź Technical University the Bielsko-Biała Branch (Poland)
   who excellently managed their university authors' teams, as well as for smooth cooperation, advisable comments and suggestions.

Special thanks to **Prof. Slawomir Bialas** of the Institute of Machine Design Fundamentals, Warsaw University of Technology, who encouraged me to discover and explore the intriguing field of dimensional and geometrical specifications. **Prof. Slawomir Bialas** is truly one of the most knowledgeable people I have ever met.

Finally particular thanks are due to **Prof. Albert Weckenmann** who persuaded me to become this project promotor and to apply to the *Commission of the European Communities* for the grant for this project. **Prof. Albert Weckenmann** provided numerous valuable advices as well as gave me a great deal of support during the project execution.

I would like to express my gratitude to all coauthors for the sharing of valuable ideas and mutual help in their development.

Zbigniew Humienny Warsaw, July 2001

## PREFACE

In this textbook we present the science of dimensioning, geometrical tolerancing and measurement of geometrical characteristics in a carefully structured manner which emphasises their foundations as well as their application. Most of the material covered in this textbook is regarded as appropriate for core bachelor and master student courses in mechanical and production engineering disciplines.

It is not intended that basic course lectures cover every point made in the textbook. Some topics are discussed more in details and it is believed that the parts of textbook are also highly suitable for more advanced courses.

The content of this textbook is based on the authors discussions, years of teaching experience and the curricula that are offered to students at:

- Institute of Machine Design Fundamentals, Warsaw University of Technology (Poland);
- Department of Interchangeable Manufacturing and Industrial Metrology, Vienna University of Technology (Austria);
- Department of Mechatronics, Tallinn Technical University (Estonia);
- Chair of Quality Management and Manufacturing Metrology,
   Friedrich-Alexander University Erlangen-Nuremberg (Germany);
- School of Engineering, University of Huddersfield (United Kingdom);
- Department of Manufacturing Technology and Automation,
   Łodź Technical University the Bielsko-Biała Branch (Poland).

All of the chapters' contributors are active researchers in the area and many are well known scholars whose research results have guided progress in their particular research field. Other contributors are young and promising scholars.

The objective of the authoring team has throughout, remained that of developing a model course for geometrical product specification that may be regarded as the basic textbook for teaching/learning at technical universities in Europe.

The authors have attempted to highlight the latest achievements and standards developed by ISO/TC 213 Dimensional and Geometrical Product Specifications and Verification as well as by other ISO technical committees.

A novel feature of this textbook is the interactive CD that employs new information technology for teaching/learning and allows readers further study.

The text book is accompanied by the web page:

http://leonardo.simr.pw.edu.pl.

We encourage you to browse this web page to get the latest information in the GPS field as well as to send questions, comments and remarks to the autors.

Zbigniew Humienny (editor)
Peter Herbert Osanna
Mart Tamre
Albert Weckenmann
Liam Blunt
Władysław Jakubiec

# **CONTENTS**

# Acknowledgments

-			
	-		na
		<b>a</b> .	

1	Introduction	0	1.	1
		(S. Białas)		
2	Chains of GPS standards. Matrix model		2.	1
=		(S. Białas)		
17-41	6	,		
3	Business environment. Quality management		3.	1
	(D. Geus, T. Killmaier, A. W	(eckenmann)		
	3.1 Introduction.		3.	
	3.2 Quality and costs.		3.	1
	3.3 Standards		3.	4
	3.3.1 EN ISO 9000-9004:1994	3 - 2	3.	4
	3.3.2 VDA 6.1		3.	5
	3.3.3 QS 9000	217 g fl	3.	6
	3.3.4 ISO 9000:2000 and family - Differences from the 1994 version	K, r = 10	3.	7
	3.4 References	C**-30	3.	8
4	Skin model	, 1675 - 1404 T. (C)	4.	
7		Inches man	٦.	•
	(D. Geus, T. Killmaier, A. W. 4.1 Introduction	eckenmann)	1 4	
	4.2 Geometrical features	seg or 6 o	4.	1
		eş.,	4.	4
	4.3 Expanded feature definitions	on the second	4.	7
	4.3.1 Motivation	and the contract	4.	7
	4.3.2 Geometrical features – general terms and definitions	way a self	4.	
	4.4 Operators	e t <sub>an</sub> (4)	4.	9
	4.4.1 Perfect operator			10
	4.4.2 Optimal operator			10
	4.4.3 Simplified operator	and the second second		10
	4.5 References		4.	10
5	Size general principles		5.	1
	(D. Geus, T. Killmaier, A. W	'eckenmann)	13	120
	5.1 Definitions of size		5.	ì
	5.1.1 Groups of sizes and dimensions		5.	
	5.1.2 Maximum and least material limit	xc,	5.	4
	5.2 Principle of independency		5.	4
	5.3 Envelope requirement	sec s u <sub>p</sub>	5. 5,	7
		267	5.	
	5.4.1 Maximum material virtual limit	5 1 520 °	5.	
	5.4.2 Everagle for maximum material condition	· (***)		10
	5.4.3 Least material requirement	FAT The ME + X . g		10
	5.4.4 Reciprocity requirement	* , * . **	5	12
	5.5-References	F 65 ' ya, 2"		13

6	ISO system of limits and fits	6.	1
	(I. Märtson, M. Tamre)		
	6.1 Brief history	6.	1
	6.2 Tolerance grades	6.	1
	6.2.1 Tolerance of a size as function of nominal size and tolerance grade	6.	1
	6.2.2 Functions for various tolerance grades	6.	3
	6.2.3 Rounding of calculated values of tolerances	6.	4
	6.3 Fundamental deviations	6.	5
	6.3.1 Layout of fundamental deviations	6.	5
	6.3.2 Designation of toleranced sizes	6.	7
	6.3.3 Recommended tolerance classes	6.	7
	6.4 Fits and their characteristics	6.	7
	6.4.1 The term of fit	6.	7
	6.4.2 Types of fits	6.	9
	6.4.3 Hole-basis and shaft-basis systems of fits		11
	6.4.4 General rules of designing fits		12
	6.4.5 Corrections of fundamental deviations due to the fit structure		13
	6.4.6 Recommended fits		15
	6.5 References		16
	U.S Actorences	U.	10
7	Introduction to Geometrical Tolerancing	7.	1
•	(W. Jakubiec, J. Malinowski, M. Starczak)		•
	7.1 Classification	7	1
	7.2 Indication		2
	7.3 References	1.	7
8	Tolerances of form	8.	1
•	(D. Geus, T. Killmaier, A. Weckenmann)		o.,
	8.1 Introduction	8.	1
	8.2 General concepts	8.	
	8.3 Straightness	8.	6
	8.3.1 Definition	8.	6
	8.3.2 Transmission band	8.	
		8.	
	8.3.3 Probing system and probing force 8.4 Roundness		
		8.	
	8.5 Flatness		11
	8.5.1 Definition		11
	8.5.2 Measurements		12
	8.6 Cylindricity	-	12
	8.7 Line and surface profile		14
	8.8 Rules for form tolerancing		15
	8.9 References	8.	16
0	Datuma	•	
9	Datums (W. Jahahian M. Standah)	9.	1
	(W. Jakubiec, M. Starczak)		
	9.1 Datums, datum features and simulated datum features	9.	
	9.2 Establishing datums	9.	
	9.2.1 Points as a datum	9.	
	9.2.2 Straight line or a plane as datum	9.	
	9.2.3 Axis of the cylinder or median plane as datum	Q	5
	7.2.5 That of the Cylinder of median plane as datain		341
	9.3 Datum targets	9.	
	· · · · · · · · · · · · · · · · · · ·		6

	9.4.2 Plane and axis of a cylinder perpendicular to a plane as a datum	9.	8
	9.4.3 Three-plane datum-system	9.	8
	9.5 Groups of feature nominated as datums (pattern datums)		11
	9.6 Datums on CMM		12
	9.7 Datums for threads, gears and splines		14
	9.8 Datums for flexible parts		15
	9.9 References		15
10	Tolerances of orientation	10.	1
	(W. Jakubiec, J. Malinowski)		
	10.1 Introduction	10.	1
	10.2 Parallelism	10.	1
	10.2.1 Parallelism tolerance of a straight line related to a datum system (straight		
	line and plane)	10.	1
	10.2.2 Parallelism tolerance of a straight line related to a datum straight line	10.	4
	10.2.3 Parallelism tolerance of a straight line related to a datum plane	10.	4
	10.2.4 Parallelism tolerance of a straight line related to a datum system (two		
	planes)	10.	5
	10.2.5 Parallelism tolerance of a plane related to a datum straight line	10.	5
	10.2.6 Parallelism tolerance of a plane related to a datum plane	10.	6
	10.3 Perpendicularity	10.	6
	10.3.1 Perpendicularity tolerance of a straight line related to a datum straight line	10.	7
	10.3.2 Perpendicularity tolerance of a straight line related to a datum system (two		
	planes)	10.	7
	10.3.3 Perpendicularity tolerance of a straight line related to a datum plane	10.	8
	10.3.4 Perpendicularity tolerance of a plane related to a datum straight line	10.	
	10.3.5 Perpendicularity tolerance of a plane related to a datum plane	10.	
	10.4 Angularity	10.	
	10.4.1 Angularity tolerance of a straight line related to a datum straight line		10
	10.4.2 Angularity tolerance of a straight line related to a datum plane	10.	
	10.4.3 Angularity tolerance of a line related to a datum system (two planes)	10.	
	10.4.4 Angularity tolerance of a plane related to a datum straight line	10.	12
	10.4.5 Angularity tolerance of a plane related to a datum system	10.	
	10.5 References	10.	NEW PARTY
11	Tolerances of location	11.	1
	(W. Jakubiec, W. Płowucha)		-
	11.1 Introduction	11.	1
	11.2 Position	11.	
	11.2.1 Position tolerance of a point	11.	
	11.2.2 Position tolerance of a line	11.	
	11.2.3 Position tolerance of a flat plane or a median plane	11.	
	11.2.4 The position of cylindrical surface related to an axis	11.	
	11.2.5. Position tolerance as an equivalent of any other location tolerance.	11.	
	11.2.5. Position tolerance as an equivalent of any other location tolerance.  11.3. Concentricity and coaxiality	11.	
		11.	
	11.3.1 Concentricity tolerance of a point	11.	
	11.3.2 Coaxiality tolerance of an axis	11.	
	11.4 Symmetry 11.5. References	11.	
	11.J. Neidelikes	44.	10

160			
12	Tolerances of line or surface with or without datum (P.H. Osanna, N.M. Durakbasa, A. Afjehi-Sada)t	12.	1
		12.	1
	12.1 Introduction 12.2 Profile any line	12.	
	12.3 Profile any surface	12.	4
13	Tolerances of runout	13.	1
	(P.H. Osanna, N.M. Durakbasa, A. Afjehi-Sada)t		
	13. 1 Introduction	13.	
	13.2 Circular run-out	13.	
	13.2.1 Circular run-out in the radial direction	13.	
	13.2.2 Circular run-out in the axial direction	13.	
	13.2.3 Circular run-out in any direction	13. 13.	
	13.3 Total runout	13.	,
14	Tolerances of angles and cones	14.	1
	(M. Tamre)		
	14.1 Angle and angle dimension	14.	
	14.2 Tolerancing of angles	14.	-
	14.2.1 Tolerancing method by linear size	14.	
	14.2.2 Tolerancing method by angular deviation	14.	
	14.3 Tolerances for cones	14.	
	14.4 References	14.	9
15	General tolerances	15.	1
13	(M. Tamre)		
	15.1 Principle of general tolerance	15.	1
	15.2 Customary workshop accuracy	15.	2
	15.3 Use of general tolerances	15.	3
	15.4 General tolerances for dimensions	15.	4
	15.4.1 General tolerances for linear dimensions	15.	
	15.4.2 General tolerances for angular dimensions	15.	
	15.5 General geometrical tolerances	15.	
	15.6 Indications on drawings	15.	
	15.7 References	15.	11
16	Roughness, waviness and primary profile	16.	1
	(L. Blunt, X. Jiang)		
	16.1 Introduction	16.	
	16.2 Surface profile parameters	16.	
	16.2.1 Surface mean line	16.	
	16.2.2 Amplitude parameters	16.	
	16.2.3 Spatial parameters	16.	
	16.2.4 Hybrid parameters		9
	16.2.5 Curves and related parameters		10
	16.2.6 Surface texture comparison rules		11
	16.3 Surface measurement		12
	16.3.1 Basic contact measurement		12
	16.3.2 Sources of error		13
	16.4 Filtering		14
	16.5 Limitations of 2D surface measurement		18
	16.6 Development of the areal approach	16.	20

	16.7 Areal roughness parameters 16.7.1 The field parameters 16.7.2 Feature parameters	16. 16. 16.	
	16.8 Near future		23
	16.9 References	16.	24
17	Designation and interpretation of geometrical tolerances	17.	1
	(D. Geus, T. Killmaier, A. Weckenmann)		
	17.1 Introduction	17.	-
	17.2 Geometrical tolerances	17.	
	17.3 Principle of tolerancing	17.	
	17.4 Practical examples for application of geometrical tolerances	17.	
	17.4.1 Principle of independency	17.	
	17.4.2 Envelope requirement	17.	
30	17.4.3 Maximum material requirement	17.	
	17.4.4 Projected tolerance zone		10
	17.4.5 Free state tolerancing	17.	
	17.5 Checklist for the interpretation of specified tolerances	17.	12
14	17.6 References	17.	13
18	Tolerances for specific manufacturing processes	18.	1
10	(S. Białas)	20.	•
	18.1 Introduction	18.	1
		18.	
	18.2 Tolerances for castings		1.0
	18.3 Tolerances for welded constructions	18.	•
19	Tolerances for selected complex geometrical features	19.	1
	(S. Białas, W. Jakubiec)		
	19.1 Introduction	19.	1
	19.2 Screw threads	19.	1
*	- 19.3 Splines	19.	8
	19.4 Cylindrical gears	19.	10
	19.4.1 Deviations relevant to corresponding flanks of gear teeth	19.	
	19.4.2 Radial composite deviations and runout	19.	17
	19.4.3 Deviations of tooth thickness		19
	19.5 References	11770-310-5	23
20	Was del Was advantage and Asharantage	20	
20	Vectorial dimensioning and tolerancing (Z. Humienny)	20.	1
		20.	1
	20.1 Vectorial dimensioning and tolerancing state of art and perspectives	20.	
	20.2 Vectorial dimensioning and tolerancing concept	20.	
	20.3 Substitute elements		
	20.4 Substitute datum system	20.	
	20.5 Substitute location	20.	
	20.6 Substitute orientation	20.	
	20.7 Substitute rotation	20.	
	20.8 Form, roughness and further requirements	20.	
	20.9 A case study - VDT of a car engine connecting rod	20.	
	20.9.1 Connecting rod – main sizes and tolerances	20.	
	20.9.2 Algorithm of the VDT	20.	
	20.10 Feedback from measurement to control manufacturing process provided by VDT	20.	18
	20.11 References	20.	18

	21	Statistical tolerancing of mechanical assemblies	21.	1
*		(P.H. Osanna, N.M. Durakbasa, A. Afjehi-Sadat)		
		21.1 Introduction	-	1
		21.2 Background	21.	
1		21.2.1 Elementary statistics	21.	
		21.2.2 Example	21.	
	7	21.3 Tolerance indications	21.	
		21.3.1 Workpiece drawings	21.	
		21.3.1 Process capability indices	21.	
		21.4 Assembly example	21.	
		21.4.1 Problem definition	21.	
		21.4.2 Analysis	21. 21.	
	÷	21.5 References	21.	11
	22	Dimensional chains. Accumulation of tolerances	22.	1
		(K. Kiszka, A. Leśniewicz)		
		22.1 Operation on toleranced dimensions	22.	1
		22.1.1 Tolerance calculations based on deterministic model	22.	1
		22.2.1. Tolerance calculation based on stochastic model	22.	4
		22.2 Types of dimensional chains	22.	7
÷		22.3 Graphical presentation of dimensional chains	22.	
		22.4 Dimensional chain analysis		11
	3 7	22.5 Dimensional chain synthesis		13
	1.	22.5.1 Equivalent tolerances method		14
$\mathcal{L}_{\mathcal{L}}$		22.5.2 Equivalent standard tolerance grade method		15
	20	22.5.3 Equivalent influence method		15
	200	22.5.4 Optimisation method		17
		22.6 Computer aided tolerance analysis/synthesis		19
	3	22.7 References	22.	23
	23	Inspection of dimensional and geometrical deviations - overview	23.	1
	23	(D. Geus, T. Killmaier, A. Weckenmann)		
1	9.	23.1 Introduction	23.	1
		23.2 Testing of sizes and distances	23.	3
		23.2.1 Calliper	23.	3
		23.2.2 Micrometer gauges	23.	5
		22.2.2 Dial gauges	23.	6
1	$= t _{Y,y}$	23.2.3 Dial gauges 23.3 Testing of angles	23.	8
		23.4 Gauging	23.	9
		23.5 Measuring of form deviations	23.	9
	1	23.6 Coordinate measurements		12
	91	23.7 Measurement uncertainty		14
		23.7.1 Measuring instrument		16
	14	23.7.2 Environment		16
		23.7.3 Workpiece		16
		23.7.4 Operator and measurement strategy		17
	***	23.7.5 Reasons for result differences from coordinate measurements		17
		23.8. Consequences for inspection of workpieces		17
7	¥	23.9 References	23.	18
	(a)	to the state of th		
317		The second secon		

24	Measurement uncertainty and statistical process control in manufacturing processes	24.	1
	(D. Geus, T. Killmaier, A. Weckenmann)		
	24.1 Introduction	24.	1
	24.2 Characterization of production processes	24.	
	24.3 Characterization of measuring processes	24.	
	24.4 Observation of production processes with measuring instruments	24.	
	24.5 Determination of the real process capability	24.	
	24.5 Statistical process control	24.	
	24.7 Conclusions	24.	
	24.8 References	24.	
	24.8 References	27.	U
25	Differences between EN-ISO standards and others standards	25.	1
	(S. Białas, T. Killmaier, K. Kiszka)		
	25.1 Differences between EN-ISO and DIN standards	25.	1
	25.2 Differences between EN-ISO and ASME standardS	25.	2
	25.3 Geometrical tolerances according to EN-ISO and SEV	25.	5
	25.4 References	25.	7
	,		
26	Computer aided tolerancing and verification	26.	1
	(Z. Humienny, W Jakubiec)		
	26.1 Introduction	26.	ì
	26.2. Software implementation of ISO system of limits and fits	26.	2
	26.3 Packages for computer aided dimensional analysis/synthesis	26.	2
	26.4. Packages for geometrical tolerancing in CAD environment	26.	3
	26.5 Educational packages	26.	4
	26.6 Measurement systems software	26.	5
	26.6.1 CMM software	26.	6
×	26.6.2 From CAD drawing to executable measurement programme	26.	10
	26.7 References	26.	1
			-
27	Glossary – terms and definitions	27.	1
	(K. Kiszka)		
28	List of published European and International Standards and other	28.	1
	documents in the field of GPS		
	(K. Kiszka)		
2	28.1 Published standards of ISO/TC 213 and CEN/TC 290	28.	1
	28.2 Other selected ISO standards connected with textbook scope	28.	3
	28.3 Other normative documents referred in textbook	28.	6
	28.4 Withdrawn standards of ISO/TC 213 (replaced)	28.	8
4 /	28.5 Withdrawn standards of ISO/TC 213 (without replacement)	28.	8

# 1 INTRODUCTION

S. Biglas

When a machine part is being designed, the designer imagines it as an ideal, perfect object. According to designer's intent all dimensions and the shape (geometry) of the part are without geometrical error and the surface is smooth.

However, during machining an actual workpiece is created that is far from perfect. Its shape is distorted, dimensions are different from those imagined by the designer and the surface is rough. If many workpieces are manufactured according to the same technical drawing, each of them generally differs from others.

After machining the parts are assembled. This process is also not ideal and additional errors may occur. So the result of a manufacturing process is a real, not perfect product – a machine or a mechanical device. Despite manufacturing errors, the product may be regarded as acceptable if the errors are properly controlled.

A set of requirements concerning the geometry of a workpiece (or of an assembly of some workpieces) is known as the Geometrical Product Specifications (GPS) covering requirements of size and dimension, geometrical tolerance and geometrical properties of the surface (Fig. 1.1).

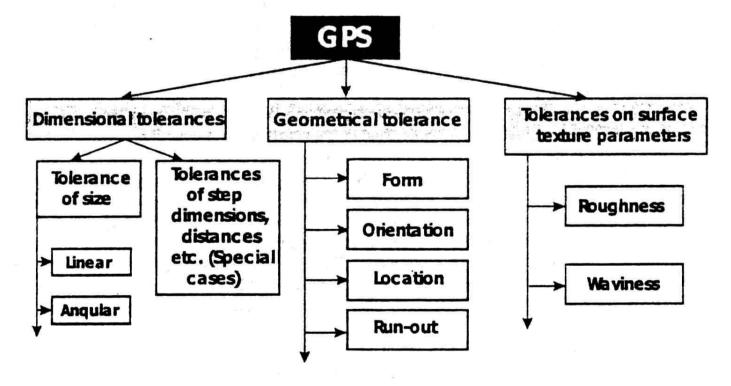


Fig. 1.1. General concept of Geometrical Product Specifications.

GPS are applied for various reasons. Generally – GPS give an assurance for obtaining some essential properties of the product:

### GEOMETRICAL PRODUCT SPECIFICATIONS - COURSE FOR TECHNICAL UNIVERSITIES

- Functionality. A well-known example may be a machine tool if its elements meet certain geometrical tolerances (e.g. straightness of bedways), the machine works well.
- Safety. If for example the crankshaft pin is ground according to specifications concerning roughness, there is no danger of a fatigue crack destroying the engine.
- Dependability. Properly selected geometrical tolerances, for instance roundness of compressor cylinders, guarantee long work life of the machine.
- Interchangeability. This is perhaps the oldest aspect applying GPS. Interchangeability is advantageous in assembly of a new machine and in repair as well.

It should be noted that GPS express different requirements in a language of geometry. The properties that are to be obtained using GPS are not necessary of a geometrical nature – the link between GPS and the desired parameters of a machine is indirect. It is down to the skill of the designer to "translate" the various mechanical requirements into the geometrical language of GPS. As an example a slide bearing may be considered – the relation of maximum and minimum clearances (that result from specified tolerances) to lubricating process is very complicated and difficult to foresee.

International organisations for standardization are deeply interested in developing the fundamentals of GPS. Technical Committee ISO/TC 213 Dimensional and Geometrical Product Specifications and Verification was established in 1996 and works in close collaboration with a similar committee in the European organisation CEN/TC 290. According to Vienna agreement all projects are processed in parallel by these two technical committees – so documents on GPS prepared by ISO and CEN are identical.

The ISO/TC 213 runs the web site http://www.ds.dk/isotc213. This web site with partly open access gives the overview of the scope and activity of Technical Committee ISO/TC 213.

Most countries adopt international standards (ISO/CEN) on GPS by just issuing national standards which are identical to international standards; therefore ISO(CEN) standards obtain the status of their national standards. For countries that are members of CEN, implementation of European Standards through giving them status of national standards is obligatory.

The bases of GPS should be a part of mechanical engineering education. Each engineer that is involved in designing or manufacturing processes (even indirectly) must have some knowledge of specifications concerning the geometry of a product. Without such competence neither creating new technical documentation nor its reading and construction is possible.

In this textbook the contemporary idea of GPS has been presented in a concise form. First three chapters cover general information on GPS – standardisation and application in quality management. Chapters 4 - 19 may be regarded as the main part of the book – they contain a systematic review of different cases of tolerancing (based chiefly on General GPS Matrix – see Chapter 2) including their theoretical background. In Chapters 20 and 21 some specific methods of tolerancing (vectorial, statistical) are presented. The subject of Chapter 22 is calculation of tolerances applied in design and manufacturing. Chapters 23 and 24 cover inspection problems. Last chapters (25 - 28) concern selected questions related to standardisation, terminology and computer aided tolerancing.

The book contains many excerpts from standards, e.g. tables, examples of drawing indications etc. that can be applied in teaching process. It is strongly recommended in practical applications to use only full, original copies of the standards. The possibility of applying the most recent editions should be always investigated.

# 2 CHAINS OF GPS STANDARDS MATRIX MODEL

S. Białas

Before establishment of Technical Committee ISO/TC 213 Dimensional and Geometrical Product Specifications and Verification the need for classification of GPS standards was recognised. This was necessary for reviewing the many standards on GPS that were published before 1995, and for programming and monitoring future work in the field of GPS standardisation.

The Joint Harmonisation Group ISO/TC 3-10-57/JHG (working in years 1993 – 1996) prepared a Technical Report ISO/TR 14638:1995 concerning classification system of GPS standards, known as the *Masterplan*. In this document all GPS standards have been divided into 4 groups:

- Fundamental GPS standards:
- Global GPS standards:
- General GPS standards:
- Complementary GPS standards.

A special graphical presentation of these groups has been adopted (Fig. 2.1).

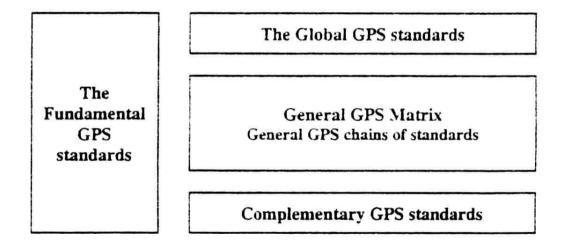


Fig. 2.1. Overview of GPS Masterplan structure.

According to the original idea, the group of Fundamental GPS standards should consist of such standards that establish very fundamental rules for dimensioning and tolerancing. However, in this group there are only two documents – ISO 8015:1985 (which, in fact, now is not regarded as really "fundamental") and ISO/TR 14638 which contains the outline of the Masterplan.

Global GPS standards are closely related to many other GPS standards – first of all those contained in the General GPS Matrix. Global standards influence general GPS chains of standards directly (being referenced to) or as default documents. The most important global GPS

### GEOMETRICAL PRODUCT SPECIFICATIONS - COURSE FOR TECHNICAL UNIVERSITIES

standard is ISO 1 on the standard reference temperature. Another global GPS standard is for example ISO 14660-1 which establishes terms and definitions of geometrical features. Several global GPS standards are under preparation. There are two metrological documents – VIM [2.1] and GUM [2.2] – that play an important role in GPS and for this reason may be found among the Global GPS Standards despite the fact that they are not standards.

Complementary GPS standards contain technical rules for drawing indications, definitions and verification principles for specific categories of features or elements. Some of the rules depend on the type of manufacturing process (machining, casting, welding, forming ...); other may concern the geometry of certain machine elements like screw threads, splines, or gears. Most of the numerous Complementary GPS standards have been prepared by various ISO Technical Committees; only a few are the results of TC 213 activity. Some complementary GPS standards are presented in Chapters 8, 18 and 19.

General GPS standards are the kernel of the Masterplan. They are ordered in a matrix in which rows constitute chains of standards, and columns concern various characteristics of geometrical features (Tab. 2.1). Due to the structure of this part of Masterplan, the whole system is known as the GPS matrix model.

Tab. 2.1. General GPS matrix - layout.

	Chain link number	1	2	3	4	5	6
G	eometrical characteristic of feature	1		3	•	3	U
1	Size						
2	Distance						
3	Radius	/					
4	Angle						
5	Form of line independent of datum						
6	Form of line dependent on datum						
7	Form of surface independent of datum						
8	Form of surface dependent on datum						
9	Orientation						
10	Location						
11	Circular run-out			11			
12	Total run-out						
13	Datums						
14	Roughness profile						
15	Waviness profile						1
16	Primary profile						
17	Surface imperfections						
18	Edges						

A chain of standards consists of a set of standards related to a given characteristic. The standards are collected in a few groups – "links" of the chain. There are 6 chain links associated with different geometrical characteristics of features. There are explained as follows.

- Product documentation indication codification. The standards placed in this link define
  drawing symbols (specific codes) and designations, establish rules of their application and
  explain how to read and generally understand specifications.
- 2. Definition of tolerances. The standards contain theoretical definitions of tolerances and their numerical values as well (as translated from code symbols). By means of these standards theoretical exact features with associated tolerances can be defined.
- 3. Definitions of characteristics of actual (real) feature. Basing on these standards, the geometry of a non-ideal, real workpiece can be unambiguously defined in relation to tolerance code symbols on the drawing. The definitions are based on a set of data points of considered features.
- 4. Assessment of the workpiece deviations comparison with specified limits. The main task of these standards is to state how to prove conformance or non-conformance of a real workpiece with specifications, taking into account the uncertainty of inspection procedures.
- Measurement equipment requirements. The standards in this link describe characteristics (particularly - metrological ones) of measurement instruments in a general approach or related to specific types of equipment.
- 6. Calibration requirements measurement standards. These standards establish the characteristics of calibration standards used in calibration procedures of the equipment described in link no. 5. The traceability to SI length unit (meter) shall always be assured.

It is clear then that each chain of standards is related to the complete process of designing (setting up unambiguous specifications), manufacturing (interpreting specifications) and verification (measuring).

Table 2.2 presents, as an example, the first row (chain of standards No 1) of the General GPS Matrix, concerning size – perhaps the most important characteristic of geometrical feature. (see Chapters 5 and 6). Some of the listed standards are in the course of preparation or revision.

Tab. 2.2. The	chain of	standards i	related t	to size – 1	st row	of General	GPS Matrix.

1	2	3	4	5	6
ISO 129	ISO 286-1	ISO 286-1	ISO 14253-1	ISO 463	ISO 3650
ISO 286-1	ISO 286-2	ISO 8015		ISO 9121	ISO 14253-1
×		ISO 14660-2		ISO 9493	
				ISO 10360-1	
				ISO 10360-2	÷
		Į		ISO 13225	
				ISO 13385	
				ISO 14253-1	
Titles of the	standards - see	Chapter 28.			

The General GPS matrix is composed of a total of  $6\times18 = 108$  cells (links of chains); each cell should contain at least one standard. The chain concerning size (Tab. 2.2) fulfils this

requirement. However, many cells of other chains (e.g. the distance chain) are still empty because of the lack of corresponding standards. It is probable that after some years of activity of ISO/TC 213 all the chain links will contain related standards.

	Global GP	S Stan	dards				
	. ",			gr <sup>th</sup> s			
	General C	PS m	atrix			MI COLONIA	
	Chain link number	1	2	3	4	5	6
	Size						
Della II	Distance			-			
	Radius						
2	Angle				=		
lard	Form of line independent of datum					a:	-
tand	Form of line dependent on datum						
GPS St	Form of surface independent of datum				II _		
Fundamental GPS Standards	Form of surface dependent on datum			ST	,		
dan	Orientation						
, m	Location		色点		-		
-	Circular run-out				¥.	R	
1	Total run-out						
Ì	Datums						
	Roughness profile						
l	Waviness profile						
Ì	Primary profile						
	Surface imperfections						
	Edges						

Fig. 2.2. An example scheme explaining the indication of matrix cells in GPS Matrix model (ISO 5458).

The Masterplan applied as a tool in standardisation work helps to observe the following basic rules:

- The rule of unambiguity; it means that each chain of standards in the General GPS Matrix shall contain all necessary, unambiguous regulations existing between the drawing indication and the geometrical characteristic of the workpiece, and that the assessed value representing the characteristic is traceable to international calibration standards. Each measurand in the chain shall be measurable.
- 2. The rule of totality the standards contained in all chains (rows) of the General GPS Matrix shall ensure the possibility of indicating on the drawing all the required

characteristics. This rule influences the number of chains of standards in the General GPS Matrix. Up to now in the matrix there are enough chains of standard – but perhaps in the future some new chains will have to be added to the matrix, according to possible future needs.

3. The rule of complementarity – each of the individual chains of standards in the General GPS Matrix shall be complementary to the other. This means that individual requirements specified on a workpiece drawing are independent of each other and no interference occurs between them (e.g. between tolerances of size and of form).

Each GPS standard prepared by ISO/TC 213 contains an annex with the specific scheme that explains the position of the standard in the matrix model; the respective cell is marked (e.g. shadowed) on the scheme. In many cases the standard influences more than one chain link or even more chains of the matrix – therefore several cells may be marked. Fig. 2.2 presents an example of the GPS Matrix scheme concerning ISO 5458 (Positional tolerancing).

### REFERENCES

- 2.1 Białas S., Partyka Z.: From "Joint Harmonisation Group" to the new Technical Committee ISO/TC 213. Normalizacja, 1/1997 (in Polish).
- 2.2 International vocabulary of basic and general terms in metrology (VIM). International Organisation for Standardisation, 1993.
- 2.3 Guide to the expression of uncertainty in measurement (GUM). International Organisation for Standardisation, 1993.