

S 555 E.3.

# **INTRODUCTION TO APPLIED STATISTICAL** SIGNAL ANALYSIS: GUIDE TO BIOMEDICAL AND **ELECTRICAL ENGINEERING APPLICATIONS**

### **Richard Shiavi**

Vanderbilt University Nashville, TN





AMSTERDAM • BOSTON • HEIDELBERG • LONDON NEW YORK • OXFORD • PARIS • SAN DIEGO SAN FRANCISCO • SINGAPORE • SYDNEY • TOKYO





Academic Press is an imprint of Elsevier

Academic Press is an imprint of Elsevier 30 Corporate Drive, Suite 400, Burlington, MA 01803, USA 525 B Street, Suite 1900, San Diego, California 92101-4495, USA 84 Theobald's Road, London WC1X 8RR, UK

This book is printed on acid-free paper. ⊚

Copyright © 2007, Elsevier Inc. All rights reserved.

No part of this publication may be reproduced or transmitted in any form or by any means, electronic or mechanical, including photocopy, recording, or any information storage and retrieval system, without permission in writing from the publisher.

Permissions may be sought directly from Elsevier's Science & Technology Rights Department in Oxford, UK: phone: (+44) 1865 843830, fax: (+44) 1865 853333, E-mail: permissions@elsevier.com. You may also complete your request on-line via the Elsevier homepage (http://elsevier.com), by selecting "Support & Contact" then "Copyright and Permission" and then "Obtaining Permissions."

#### Library of Congress Cataloging-in-Publication Data Application Submitted

#### **British Library Cataloguing-in-Publication Data**

A catalogue record for this book is available from the British Library.

ISBN 13: 978-0-12-088581-7 ISBN 10: 0-12-088581-6

For information on all Academic Press publications visit our Web site at www.books.elsevier.com

Printed in the United States of America
06 07 08 09 10 9 8 7 6 5 4 3 2 1

# Working together to grow libraries in developing countries

www.elsevier.com | www.bookaid.org | www.sabre.org

**ELSEVIER** 

BOOK AID

Sabre Foundation

# **PREFACE**

his book presents a practical introduction to signal analysis techniques that are commonly used in a broad range of engineering areas such as biomedical engineering, communications, geophysics, speech, etc. In order to emphasize the analytic approaches, a certain background is necessary. The book is designed for an individual who has a basic background in mathematics, science, and computer programming that is required in an undergraduate engineering curriculum. In addition one needs to have an introductory-level background in probability and statistics and discrete time systems.

The sequence of material begins with definitions of terms and symbols used for representing discrete data measurements and time series/signals and a presentation of techniques for polynomial modeling and data interpolation. Chapter 3 focuses on the windowing and the discrete Fourier transform. It is introduced by presenting first the various definitions of the Fourier transform and harmonic modeling using the Fourier series. The remainder of the book deals with signals having some random signal component and Chapter 4 reviews the aspects of probability theory and statistics needed for subsequent topics. In addition, histogram fitting, correlation, regression, and maximum likelihood estimation are presented. In the next chapter these concepts are extended to define random signals and introduce the estimation of correlation functions and tests of stationarity. Chapter 6 reviews linear systems and defines power spectra. Chapter 7 presents classical spectral analysis and its estimators. The periodogram and Blackman-Tukey methods are covered in detail. Chapter 8 covers autoregressive modeling of signals and parametric spectral estimation. Chapter 9 presents the classical uses of cross correlation and coherence functions. In particular, the practical techniques for estimating coherence function are presented in detail. Chapter 10 is a new chapter for the third edition and covers envelope estimation and kernel functions. Presentation of these topics is motivated by the growth in usage of these techniques. Envelope estimation is important not only for signals such as electromyograms but also when using high frequency carrier signals such as in ultrasound applications. The fundamentals of Hilbert transforms, analytic signals, and their estimation are

**XİV** PREFACE

presented. Kernel functions appear in the neuromuscular literature dealing with point processes such as action potentials. The main purpose is to create a continuous amplitude function from a point process. A summary of kernel functions and their implementation is presented.

The material in Chapter 10 is drawn with permission from the doctoral dissertation work of Robert Brychta and Melanie Bernard. They are both graduate students in Biomedical Engineering at Vanderbilt University. Robert's research is being done in the General Clinical Research Center and Melanie's is being done in the Visual System's laboratory.

The presentation style is designed for the individual who wants a theoretical introduction to the basic principles and then the knowledge necessary to implement them practically. The mode of presentation is to: define a theoretical concept, show areas of engineering in which these concepts are useful, define the algorithms and assumptions needed to implement them, and then present detailed examples that have been implemented using FORTRAN and more recently MATLAB. The exposure to engineering applications will hopefully develop an appreciation for the utility and necessity of signal processing methodologies.

The exercises at the end of the chapters are designed with several goals. Some focus directly on the material presented and some extend the material for applications that are less often encountered. The degree of difficulty ranges from simple pencil and paper problems to computer implementation of simulations and algorithms for analysis. For an introductory course, the environment and software recommended are those that are not overly sophisticated and complex so that the student cannot comprehend the code or script. When used as a course textbook, most of the material can be studied in one semester in a senior undergraduate or first year graduate course. The topic selection is obviously the instructor's choice.

Most of the examples and many of the exercises use measured signals, many from the biomedical domain. Copies of these are available from the publisher's Website.<sup>3</sup> Also available, for interactive learning, are a series of MATLAB notebooks that have been designed for interactive learning.<sup>1,2</sup> These notebooks are written in the integrated environment of Microsoft Word and MATLAB. Each notebook presents a principle and demonstrates its implementation via script in MATLAB. The student is then asked to exercise other aspects of the principle interactively by making simple changes in the script. The student then receives immediate feedback concerning what is happening and can relate theoretical concepts to real effects upon a signal. The final one or two questions in the notebooks are more comprehensive and ask the student to make a full implementation of the technique or principle being studied. This requires understanding all of the previous material and selecting, altering, and then integrating parts of the MATLAB script previously used.

<sup>&</sup>lt;sup>1</sup> Shiavi, R., Learning Signal Processing Using Interactive Notebooks. *IEEE Transactions on Education*; 42:355-CD, 1999.

<sup>&</sup>lt;sup>2</sup> Shiavi, R. "Teaching Signal Processing Using Notebooks". ASEE Annual Conference; Charlotte NC, June, 1999.

This book is dedicated to my wife, Gloria, and to my parents who encouraged me and gave me the opportunity to be where I am today.

# **ACKNOWLEDGMENTS**

The author of a textbook is usually helped significantly by the institution by which he is employed and through surrounding circumstances. In particular I am indebted to the Department of Biomedical Engineering and the School of Engineering at Vanderbilt University for giving me some released time and for placing a high priority on writing this book for academic purposes. This being the third edition, There have been three sets of reviewers. I would like to thank them because they have contributed to the book through suggestions of new topics and constructive criticism of the initial drafts. In addition, I am very grateful to Robert Brychta and Melanie Bernard, both graduate students in Biomedical Engineering at Vanderbilt University. Their doctoral research provided the basis for the topics in Chapter 10.

# **LIST OF SYMBOLS**

#### **ENGLISH**

a(i), b(i)	parameters of AR, MA, and ARMA models
$A_m$	polynomial coefficient
$B^{'''}$	bandwidth
$B_{\rho}$	equivalent bandwidth
$c_x(k)$	sample covariance function
$c_{yx}(k)$	sample cross covariance function
$C_n$	coefficients of trigonometric Fourier series
$C_{x}(k)$	autocovariance function
$C_{xy}(k)$	cross covariance function
Cov[]	covariance operator
d(n)	data window
D(f)	data spectral window
$e_i$	error in polynomial curve fitting
E[ ]	expectation operator
$E_{M}$	sum of squared errors
$E_{\mathrm{tot}}$	total signal energy
f	cyclic frequency
$f_d$	frequency spacing
$f_N$	folding frequency, highest frequency component
$f_s$	sampling frequency
f(t)	scaler function of variable t

XX LIST OF SYMBOLS

$f_x(\alpha), f(x)$	probability density function
$f_{xy}(\alpha,\beta), f(x,y)$	bivariate probability density function
$F_{x}(\alpha), F(x)$	probability distribution function
$F_{xy}(\alpha,\beta), F(x,y)$	bivariate probability distribution function
g	loss coefficient
$g_1$	sample coefficient of skewness
h(t), h(n)	impulse response
$H(f), H(\omega)$	transfer function
I(f), I(m)	periodogram
Im()	imaginary part of a complex function
3[]	imaginary operator
$K^{2}(f), K^{2}(m)$	magnitude squared coherence function
$L_i(x)$	Lagrange coefficient function
m	mean
N	number of points in a discrete time signal
p, q	order of AR, MA, and ARMA processes
P	signal power, or signal duration
$P[\ ]$	probability of [ ]
$P_m(x)$	polynomial function
q- $q$	quantile-quantile
$r_Q$	correlation coefficient for q-q plot
Re()	real part of a complex function
$R_{x}(k)$	autocorrelation function
$R_{yx}(k)$	cross correlation function
R[]	real operator
$S_p^2$	variance of linear prediction error
S(f), S(m)	power spectral density function
$S_{yx}(f), S_{yx}(m)$	cross spectral density function
T	sampling interval
U(t)	unit step function
Var[]	variance operator
w(k)	lag window
W(f)	lag spectral window
x(t), x(n)	time function
$X(f), X(m), X(\omega)$	Fourier transform
$z_m$	coefficients of complex Fourier series

#### **GREEK**

$\alpha$	significance level
$\gamma_x(t_0,t_1), \ \gamma_{x(K)}$	ensemble autocovariance function
$\gamma_1$	coefficient of skewness
$\delta(t)$	impulse function, dirac delta function

$\delta(n)$	unit impulse, Kronecker delta function
$\varepsilon(n)$	linear prediction error
$\lambda_i$	energy in a function
$\Lambda_{yx}(f)$	co-spectrum
$\mu_k$	kth central moment
$\eta(n)$	white noise process
$\xi( au)$	ensemble normalized autocovariance function
Ħ	Gaussian probability distribution function
ρ	correlation coefficient
$\rho_x(k)$	normalized autocovariance function
$\rho_{yx}(k)$	normalized cross covariance function
$\sigma^2$	variance
$\sigma_{e}$	standard error of estimate
$\sigma_e \ \sigma_{xy}^2$	covariance
$\phi(f)$	phase response
$\phi_{yx}(f), \phi_{yx}(m)$	cross phase spectrum
$\Phi_{n(t)}$	orthogonal function set
$\varphi_x(t_0,t_1), \ \varphi_x(k)$	ensemble autocorrelation function
$\Psi_{vx}(f)$	quadrature spectrum
ω	radian frequency

radian frequency spacing

autocorrelation function

#### **ACRONYMS**

 $\boldsymbol{\omega}_d$ 

ACF

FS

ACVF	autocovariance function
AIC	Akaike's information criterion
AR	autoregressive
ARMA	autoregressive-moving average
BT	Blackman-Tukey
CCF	cross correlation function
CCVF	cross covariance function
cdf	cumulative distribution function
CF	correlation function
CSD	cross spectral density
CTFT	continuous time Fourier transform
DFT	discrete Fourier transform
DTFT	discrete time Fourier transform
E	energy
erf	error function
FPE	final prediction error

Fourier series

xxii

LIST OF SYMBOLS

**IDFT** inverse discrete Fourier transform **IDTFT** inverse discrete time Fourier transform

LPC linear prediction coefficient

MA moving average

**MEM** maximum entropy method **MLE** maximum likelihood estimator MSC magnitude squared coherence

MSE mean square error

NACF normalized autocovariance function **NCCF** normalized cross covariance function

pdf probability density function

PLprocess loss

**PSD** power spectral density

PW power

**TSE** total square error VR variance reduction

WN white noise YW Yule-Walker

#### **OPERATORS**

 $X(f)^*$ conjugation x(n) \* y(n)convolution  $\hat{S}(m)$ sample estimate  $\tilde{S}(m)$ smoothing

 $\overline{x}(n)$ periodic repetition

#### **FUNCTIONS**

sgn(x)signum(x) = 1, x > 0=-1, x<0

# **CONTENTS**

#### \* = new section

PREFACE xiii

DEDICATION xv

ACKNOWLEDGMENTS xvii

LIST OF SYMBOLS xix

### INTRODUCTION AND TERMINOLOGY

1.1	Introduction	
1 2	Signal To	in

- **1.2** Signal Terminology 3
  - **I.2.1** Domain Types 3
  - **1.2.2** Amplitude Types 5
  - **1.2.3** Basic Signal Forms 6
  - **1.2.4** The Transformed Domain—The Frequency Domain 8
  - **1.2.5** General Amplitude Properties 9
- **1.3** Analog to Digital Conversion 10
- 1.4 Measures of Signal Properties 11
  - I.4.1 Time Domain 11
  - **1.4.2** Frequency Domain 12

References 13

# 2 EMPIRICAL MODELING AND APPROXIMATION

- 2.1 Introduction 15
- **2.2** Model Development 16
- 2.3 Generalized Least Squares 21
- **2.4** Generalities 23
- **2.5** Models from Linearization 24
- 2.6 Orthogonal Polynomials 28
- **2.7** Interpolation and Extrapolation 33
  - **2.7.1** Lagrange Polynomials 34
  - **2.7.2** Spline Interpolation 38
- **2.8** Overview 43

References 43

Exercises 44

# 3 FOURIER ANALYSIS

- 3.1 Introduction 51
- **3.2** Review of Fourier Series 53
  - **3.2.1** Definition 53
  - **3.2.2** Convergence 60
- **3.3** Overview of Fourier Transform Relationships 61
  - 3.3.1 Continuous versus Discrete Time 61
  - **3.3.2** Discrete Time and Frequency 63
- **3.4** Discrete Fourier Transform 64
  - **3.4.1** Definition Continued 64
  - **3.4.2** Partial Summary of DFT Properties and Theorems 65
- **3.5** Fourier Analysis 68
  - **3.5.1** Frequency Range and Scaling 69
  - **3.5.2** The Effect of Discretizing Frequency 70
  - **3.5.3** The Effect of Truncation 73
  - **3.5.4** Windowing 77
  - **3.5.5** Resolution 79
  - **3.5.6** Detrending 82
- **3.6** Procedural Summary 82
- **3.7** Selected Applications 82

References 86

Exercises 87

Appendix 3.1: DFT of Ionosphere Data 92

**Appendix 3.2:** Review of Properties of Orthogonal Functions 93

CONTENTS

**Appendix 3.3:** The Fourier Transform 94

Appendix 3.4: Data and Spectral Windows 98

# 4

### PROBABILITY CONCEPTS AND SIGNAL CHARACTERISTICS

- **4.1** Introduction 101
- **4.2** Introduction to Random Variables 102
  - **4.2.1** Probability Descriptors 102
  - **4.2.2** Moments of Random Variables 108
  - **4.2.3** Gaussian Random Variable 110
- **4.3** Joint Probability 112
  - **4.3.1** Bivariate Distributions 112
  - **4.3.2** Moments of Bivariate Distributions 113
- **4.4** Concept of Sampling and Estimation 115
  - 4.4.1 Sample Moments 115
  - **4.4.2** Significance of the Estimate 119
- **4.5** Density Function Estimation 122
  - **4.5.1** General Principle for  $\chi^2$  Approach 122
  - **4.5.2** Detailed Procedure for  $\chi^2$  Approach 124
  - \*4.5.3 Quantile-Quantile Approach 127
- **4.6** Correlation and Regression 130
  - \*4.6.1 Estimate of Correlation 130
  - \*4.6.2 Simple Regression Model 132
- **4.7** General Properties of Estimators 136
  - **4.7.1** Convergence 136
  - **4.7.2** Recursion 137
  - \*4.7.3 Maximum Likelihood Estimation 138
- 4.8 Random Numbers and Signal Characteristics 139
  - **4.8.1** Random Number Generation 140
  - 4.8.2 Change of Mean and Variance 141
  - 4.8.3 Density Shaping 142

References 145

Exercises 146

Appendix 4.1: Plots and Formulas for Five Probability Density Functions 154

### 5

# INTRODUCTION TO RANDOM PROCESSES AND SIGNAL PROPERTIES

- **5.1** Introduction 155
- **5.2** Definition of Stationarity 156

viii CONTENTS

<b>5</b> 2	Definition of Moment Functions 159
3.3	<b>5.3.1</b> General Definitions 159
	<b>5.3.2</b> Moments of Stationary Processes 160
5.4	Time Averages and Ergodicity 162
5.5	Estimating Correlation Functions 166
	<b>5.5.1</b> Estimator Definition 166
	<b>5.5.2</b> Estimator Bias 168
	<b>5.5.3</b> Consistency and Ergodicity 168
	<b>5.5.4</b> Sampling Properties 170
	<b>5.5.5</b> Asymptotic Distributions 171
5.6	Correlation and Signal Structure 176
	<b>5.6.1</b> General Moving Average 176
	<b>5.6.2</b> First-Order MA 177
	<b>5.6.3</b> Second-Order MA 181
	<b>5.6.4</b> Overview 181
5.7	Assessing Stationarity of Signals 182
	*5.7.1 Multiple Segments—Parametric 184
	<b>*5.7.2</b> Multiple Segments—Nonparametric 189
Refe	rences 193
Exe	rcises 194
Арр	pendix 5.1: Variance of Autocovariance Estimate 197
Appendix 5.2: Stationarity Tests 198	

# 6

# RANDOM SIGNALS, LINEAR SYSTEMS, AND POWER SPECTRA

	AND TOWER SI ECTIV
6. I	Introduction 201
6.2	Power Spectra 201
	*6.2.1 Empirical Approach 201
	*6.2.2 Theoretical Approach 203
6.3	System Definition Review 205
	<b>6.3.1</b> Basic Definitions 205
	<b>6.3.2</b> Relationships between Input and Output 208
6.4	Systems and Signal Structure 210
	<b>6.4.1</b> Moving Average Process 210
	<b>6.4.2</b> Structure with Autoregressive Systems 211
	<b>6.4.3</b> Higher-Order AR Systems 215
6.5	Time Series Models for Spectral Density 219
Refe	erences 225

Exercises 226

CONTENTS

ix

# 7

# SPECTRAL ANALYSIS FOR RANDOM SIGNALS: NONPARAMETRIC METHODS

- **7.1** Spectral Estimation Concepts 229
  - **7.1.1** Developing Procedures 233
  - **7.1.2** Sampling Moments of Estimators 234
- **7.2** Sampling Distribution for Spectral Estimators 239
  - **7.2.1** Spectral Estimate for White Noise 239
  - **7.2.2** Sampling Properties for General Random Processes 242
- **7.3** Consistent Estimators—Direct Methods 244
  - **7.3.1** Spectral Averaging 224
  - **7.3.2** Confidence Limits 248
  - **7.3.3** Summary of Procedure for Spectral Averaging 258
  - **7.3.4** Welch Method 259
  - **7.3.5** Spectral Smoothing 259
  - **7.3.6** Additional Applications 263
- **7.4** Consistent Estimators—Indirect Methods 264
  - **7.4.1** Spectral and Lag Windows 264
  - **7.4.2** Important Details for Using FFT Algorithms 266
  - **7.4.3** Statistical Characteristics of BT Approach 267
- **7.5** Autocorrelation Estimation 275

References 277

Exercises 278

Appendix 7.1: Variance of Periodogram 281

Appendix 7.2: Proof of Variance of BT Spectral Smoothing 283

**Appendix 7.3:** Window Characteristics 284

Appendix 7.4: Lag Window Functions 285

Appendix 7.5: Spectral Estimates from Smoothing 286

### 8

# RANDOM SIGNAL MODELING AND PARAMETRIC SPECTRAL ESTIMATION

- **8.1** Introduction 287
- **8.2** Model Development 288
- **8.3** Random Data Modeling Approach 293
  - 8.3.1 Basic Concepts 293
  - **8.3.2** Solution of General Model 296

X CONTENTS

	8.3.3	Model Order 300	
	8.3.4	Levinson-Durbin Algorithm 305	
	8.3.5	Burg Method 309	
	8.3.6	Summary of Signal Modeling 313	
8.4	Power	Spectral Density Estimation 314	
	8.4.I	Definition and Properties 314	
	8.4.2	Statistical Properties 318	
	8.4.3	Other Spectral Estimation Methods 320	
	8.4.4	Comparison of Nonparametric and Parametric Methods	322
Refe	rences	323	
Exer	cises	324	
Арр	endix 8	<b>B.I:</b> Matrix Form of Levinson-Durbin Recursion 327	

### 9

# THEORY AND APPLICATION OF CROSS CORRELATION AND COHERENCE

9. I	Introduction 331	
9.2	Properties of Cross Correlation Functions 333	
	<b>9.2.1</b> Theoretical Function 333	
	<b>9.2.2</b> Estimators 334	
9.3	Detection of Time-Limited Signals 339	
	<b>9.3.1</b> Basic Concepts 340	
	<b>9.3.2</b> Application of Pulse Detection 342	
	<b>9.3.3</b> Random Signals 343	
	<b>9.3.4</b> Time Difference of Arrival 345	
	<b>9.3.5</b> Marine Seismic Signal Analysis 347	
	<b>9.3.6</b> Procedure for Estimation 347	
9.4	Cross Spectral Density Functions 349	
	<b>9.4.1</b> Definition and Properties 349	
	<b>9.4.2</b> Properties of Cross Spectral Estimators 351	
9.5	Applications 354	
9.6	Tests for Correlation between Time Series 355	
	<b>9.6.1</b> Coherence Estimators 355	
	<b>9.6.2</b> Statistical Properties of Estimators 358	
	<b>9.6.3</b> Confidence Limits 359	
	<b>9.6.4</b> Procedure for Estimation 362	
	<b>9.6.5</b> Application 362	

References 364 Exercises 365