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THEORY OF ALGEBRAIC EQUATIONS.



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THEORY OF ALGEBRAIC EQUATIONS.



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PREFACE.

The solution of the general quadratic equation was known as early as the ninth century; that of the general cubic and quartic equations was discovered in the sixteenth century. During the succeeding two centuries many unsuccessful attempts were made to solve the general equations of the fifth and higher degrees. In 1770 Lagrange analyzed the methods of his predecessors and traced all their results to one principle, that of rational resolvents, and proved that the general quintic equation cannot be solved by rational resolvents. The impossibility of the algebraic solution of the general equation of degree n(n>4), whether by rational or irrational resolvents, was then proved by Abel, Wantzel, and Galois. Out of these algebraic investigations grew the theory of substitutions and groups. The first systematic study of substitutions was made by Cauchy (Journal de l'école polytechnique, 1815).

The subject is here presented in the historical order of its development. The First Part (pp. 1-41) is devoted to the Lagrange-Cauchy-Abel theory of general algebraic equations. The Second Part (pp. 42-98) is devoted to Galois' theory of algebraic equations, whether with arbitrary or special coefficients. The aim has been to make the presentation strictly elementary, with practically no dependence upon any branch of mathematics beyond elementary algebra. There occur numerous illustrative examples, as well as sets of elementary exercises.

In the preparation of this book, the author has consulted, in addition to various articles in the journals, the following treatises:

Lagrange, Réflexions sur la résolution algébrique des équations; Jordan, Traité des substitutions et des équations algébriques; Serret, Cours d'Algèbre supérieure; Netto-Cole, Theory of Substitutions and its Applications to Algebra; Weber, Lehrbuch der Algebra; Burnside, The Theory of Groups Pierpont, Galois' Theory of Algebraic Equations, Annals of Math., 2d ser., vols. 1 and 2; Bolza, On the Theory of Substitution-Groups and its Applications to Algebraic Equations, Amer. Journ. Math., vol. XIII.

The author takes this opportunity to express his indebtedness to the following lecturers whose courses in group theory he has attended: Oscar Bolza in 1894. E. H. Moore in 1895, Sophus Lie in 1896. Camille Jordan in 1897.

But, of all the sources, the lectures and publications of Professor Bolza have been of the greatest aid to the author. In particular, the examples (§ 65) of the group of an equation have been borrowed with his permission from his lectures.

The present elementary presentation of the theory is the outcome of lectures delivered by the author in 1897 at the University of California, in 1899 at the University of Texas, and twice in 1902 at the University of Chicago.

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THEORY OF ALGEBRAIC EQUATIONS.

FIRST PART.

THE LAGRANGE-ABEL-CAUCHY THECRY OF GENERAL ALGEBRAIC EQUATIONS.

CHAPTER I.

SOLUTION OF THE GENERAL QUADRATIC, CUBIC, AND QUARTIC EQUATIONS. LAGRANGE'S THEOREM* ON THE IRRATIONALITIES ENTERING THE ROOTS.

1. Quadratic equation. The roots of $x^2 + px + q = 0$ are

$$x_1 = \frac{1}{2}(-p + \sqrt{p^2 - 4q}), \quad x_2 = \frac{1}{2}(-p - \sqrt{p^2 - 4q}).$$

By addition, subtraction, and multiplication, we get

$$x_1 + x_2 = -p$$
, $x_1 - x_2 = \sqrt{p^2 - 4q}$, $x_1 x_2 = q$.

Hence the irrationality $\sqrt{p^2-4q}$, which occurs in the expressions for the roots, is rationally expressible in terms of the roots, being equal to x_1-x_2 . Unlike the last function, the functions x_1+x_2 and x_1x_2 are symmetric in the roots and are rational functions of the coefficients.

2. Cubic equation. The general cubic equation may be written

(1)
$$x^3 - c_1 x^2 + c_2 x - c_3 = 0.$$

Setting $x=y+\frac{1}{3}c_1$, the equation (1) takes the simpler form

(2)
$$y^3 + py + q = 0$$
,

^{*} Réflexions sur la résolution algébrique des équations, Œuvres de Lagrange, Paris, 1869, vol. 3; first printed by the Berlin Academy, 1770-71

if we make use of the abbreviations

(3)
$$p = c_2 - \frac{1}{3}c_1^2$$
, $q = -c_3 + \frac{1}{3}c_1c_2 - \frac{2}{37}c_1^3$.

The cubic (2), lacking the square of the unknown quantity, is called the *reduced cubic equation*. When it is solved, the roots of (1) are found by the relation $x=y+\frac{1}{3}c_1$.

The cubic (2) was first solved by Scipio Ferreo before 1505. The solution was rediscovered by Tartaglia and imparted to Cardan under promises of secrecy. But Cardan broke his promises and published the rules in 1545 in his Ars Magna, so that the formulæ bear the name of Cardan. The following method of deriving them is essentially that given by Hudde in 1650. By the transformation

$$(4) y = z - \frac{p}{3z},$$

the cubic (2) becomes $z^3 - \frac{p^3}{27z^3} + q = 0$, whence

(5)
$$z^6 + qz^3 - \frac{p^3}{27} = 0.$$

Solving the latter as a quadratic equation for z3, we get

$$z^3 = -\frac{1}{2}q \pm \sqrt{R}, \quad R = \frac{1}{2}q^2 + \frac{1}{27}p^3.$$

Denote a definite one of the cube roots of $-\frac{1}{2}q + \sqrt{R}$ by

$$\sqrt[3]{-\frac{1}{2}q+\sqrt{R}}$$
.

The other two cube roots are then

$$\omega \sqrt[3]{-\frac{1}{2}q+\sqrt{R}}, \quad \omega^2 \sqrt[3]{-\frac{1}{2}q+\sqrt{R}},$$

where ω is an imaginary cube root of unity found as follows. The three cube roots of unity are the roots of the equation

$$r^3-1=0$$
, or $(r-1)(r^2+r+1)=0$.

The roots of $r^2+r+1=0$ are $-\frac{1}{2}+\frac{1}{2}\sqrt{-3}=\omega$ and $-\frac{1}{2}-\frac{1}{2}\sqrt{-3}=\omega^2$. Then

(6)
$$\omega^2 + \omega + 1 = 0 \quad \omega^3 = 1.$$

In view of the relation

$$(-\frac{1}{2}q+\sqrt{R})(-\frac{1}{2}q-\sqrt{R})=\frac{1}{4}q^2-R=-\frac{1}{27}p^3$$

a particular cube root $\sqrt[3]{-\frac{1}{2}q-\sqrt{R}}$ may be chosen so that

$$\sqrt[3]{-\frac{1}{2}q + \sqrt{R}} \cdot \sqrt[3]{-\frac{1}{2}q - \sqrt{R}} = -\frac{1}{3}p.$$

$$\therefore \omega \sqrt[3]{-\frac{1}{2}q + \sqrt{R}} \cdot \omega^2 \sqrt[3]{-\frac{1}{2}q - \sqrt{R}} = -\frac{1}{3}p,$$

$$\omega^2 \sqrt[3]{-\frac{1}{2}q + \sqrt{R}} \cdot \omega \sqrt[3]{-\frac{1}{2}q - \sqrt{R}} = -\frac{1}{3}p.$$

Hence the six roots of equation (5) may be separated into pairs in such a way that the product of two in any pair is $-\frac{1}{3}p$. The root paired with z is therefore $-\frac{p}{3z}$, and their sum $z-\frac{p}{3z}$ is, in view of (4), a root y of the cubic (2). In particular, the two roots of a pair lead to the same value of y, so that the six roots of (5) lead to only three roots of the cubic, thereby explaining an apparent difficulty. Since the sum of the two roots of any pair of roots of (5) leads to a root of the cubic (2), we obtain Cardan's formulæ for the roots y_1, y_2, y_3 of (2):

(7)
$$\begin{cases} y_1 = \sqrt[3]{-\frac{1}{2}q + \sqrt{R}} + \sqrt[3]{-\frac{1}{2}q - \sqrt{R}}, \\ y_2 = \omega \sqrt[3]{-\frac{1}{2}q + \sqrt{R}} + \omega^2 \sqrt[3]{-\frac{1}{2}q - \sqrt{R}}, \\ y_3 = \omega^2 \sqrt[3]{-\frac{1}{2}q + \sqrt{R}} + \omega \sqrt[3]{-\frac{1}{2}q - \sqrt{R}}. \end{cases}$$

Multiplying these expressions by 1, ω^2 , ω and adding, we get, by (6),

$$\sqrt[3]{-\frac{1}{2}q+\sqrt{R}} = \frac{1}{3}(y_1+\omega^2y_2+\omega y_3).$$

Using the multipliers 1, ω , ω^2 , we get, similarly,

$$\sqrt[3]{-\frac{1}{2}q-\sqrt{R}} = \frac{1}{3}(y_1+\omega y_2+\omega^2 y_3).$$

Cubing these two expressions and subtracting the results, we get

$$\sqrt{R} = \frac{1}{54} \{ (y_1 + \omega^2 y_2 + \omega y_3)^8 - (y_1 + \omega y_2 + \omega^2 y_3)^8 \}
= \frac{\sqrt{-3}}{10} (y_1 - y_2) (y_2 - y_3) (y_3 - y_1),$$

upon applying the Factor Theorem and the identity $\omega - \omega^2 = \sqrt{-3}$. Hence all the irrationalities occurring in the roots (7) are rationally expressible in terms of the roots, a result first shown by Lagrange.

The function

$$(y_1-y_2)^2(y_2-y_3)^2(y_3-y_1)^2 = -27q^2-4p^3$$

is called the discriminant of the cubic (2).

The roots of the general cubic (1) are

$$= y_1 + \frac{1}{3}c_1, \quad x_2 = y_2 + \frac{1}{3}c_1, \quad x_3 = y_3 + \frac{1}{3}c_1.$$

$$x_1 - x_2 = y_1 - y_2, \quad x_2 - x_3 = y_2 - y_3, \quad x_3 - x_1 = y_3 - y_1,$$

$$(x_1 - x_2)(x_2 - x_3)(x_3 - x_1) = (y_1 - y_2)(y_2 - y_3)(y_3 - y_1)$$

$$= \frac{18}{\sqrt{-3}}\sqrt{R} = -6\sqrt{-3}\sqrt{\frac{1}{4}q^2 + \frac{1}{3}\sqrt{p^3}}.$$

EXERCISES.

1. Show that $x_1 + \omega^2 x_2 + \omega x_3 = y_1 + \omega^2 y_2 + \omega y_3$, $x_1 + \omega x_2 + \omega^2 x_3 = y_1 + \omega y_2 + \omega^2 y_3$.

2. The cubic (2) has one real root and two imaginary roots if R > 0; three real roots, two of which are equal, if R = 0; three real and distinct roots if R < 0 (the so-called irreducible case).

3. Show that the discriminant $(x_1-x_2)^2(x_2-x_3)^2(x_3-x_1)^2$ of the cubic (1) equals

$$c_1^2c_2^2+18c_1c_2c_3-4c_2^3-4c_1^2c_3-27c_3^2$$
.

Hint: Use formula (8) in connection with (3).

4. Show that the nine expressions $\sqrt[3]{-\frac{1}{2}q+\sqrt{R}}+\sqrt[3]{-\frac{1}{2}q}-\sqrt{R}$, where all combinations of the cube roots are taken, are the roots of the cubics

$$y^3 + py + q = 0$$
, $y^3 + \omega py + q = 0$, $y^3 + \omega^2 py + q = 0$.

5. Show that $y_1 + y_2 + y_3 = 0$, $y_1y_2 + y_1y_3 + y_2y_3 = p$, $y_1y_2y_3 = -q$.

6 Show that $x_1+x_2+x_3=c_1$, $x_1x_2+x_3+x_2+x_2+x_3=c_2$, $x_1x_2x_3=c_3$, using Ex. 5. How may these results be derived directly from equation (1)?

3. Aside from the factor $\frac{1}{3}$, the roots of the sextic (5) are

$$\begin{array}{ll} \psi_1\!=\!x_1\!+\!\omega x_2\!+\!\omega^2 x_3, & \psi_4\!=\!x_1\!+\!\omega x_3\!+\!\omega^2 x_2, \\ \psi_2\!=\!\omega^2 \psi_1\!=\!x_2\!+\!\omega x_3\!+\!\omega^2 x_1, & \psi_5\!=\!\omega^2 \psi_4\!=\!x_3\!+\!\omega x_2\!+\!\omega^2 x_1, \\ \psi_3\!=\!\omega \psi_1\!=\!x_3\!+\!\omega x_1\!+\!\omega^2 x_2, & \psi_6\!=\!\omega \psi_4\!=\!x_2\!+\!\omega x_1\!+\!\omega^2 x_3. \end{array}$$

These functions differ only in the permutations of x_1 , x_2 , x_3 . As there are just six permutations of three letters, these functions

give all that can be obtained from ψ_1 by permuting x_1 , x_2 , x_3 . For this reason, ψ_1 is called a six-valued function.

Lagrange's à priori solution of the general cubic (1) consists in determining these six functions ψ_1, \ldots, ψ_6 directly. They are the roots of the sextic equation $(t-\psi_1)\ldots(t-\psi_6)=0$, whose coefficients are symmetric functions of ψ_1, \ldots, ψ_6 and consequently symmetric functions of x_1, x_2, x_3 and hence * are rationally expressible in terms of c_1, c_2, c_3 . Since $\psi_2 = \omega^2 \psi_1, \psi_3 = \omega \psi_1$, etc., we have by (6)

$$\begin{split} &(t-\psi_1)(t-\psi_2)(t-\psi_3) = t^3 - {\psi_1}^3,\\ &(t-\psi_4)(t-\psi_5)(t-\psi_6) = t^3 - {\psi_4}^3. \end{split}$$

Hence the resolvent sextic becomes

(9)
$$t^{6} - (\psi_{1}^{8} + \psi_{4}^{8})t^{8} + \psi_{1}^{8}\psi_{4}^{8} = 0.$$
But
$$\psi_{1}\psi_{4} = x_{1}^{2} + x_{2}^{2} + x_{3}^{2} + (\omega + \omega^{2})(x_{1}x_{2} + x_{1}x_{3} + x_{2}x_{3})$$

$$= (x_{1} + x_{2} + x_{3})^{2} - 3(x_{1}x_{2} + x_{1}x_{3} + x_{2}x_{3}) = c_{1}^{2} - 3c_{2},$$

in view of Ex. 6, page 4. Also, $\psi_1^3 + \psi_4^3$ equals

$$\begin{array}{l} 2({x_{1}}^{3}+{x_{2}}^{3}+{x_{3}}^{3})-3({x_{1}}^{2}{x_{2}}+{x_{1}}{x_{2}}^{2}+{x_{1}}^{2}{x_{3}}+{x_{1}}{x_{3}}^{2}+{x_{2}}^{2}{x_{3}}+{x_{2}}{x_{3}}^{2})+12{x_{1}}{x_{2}}{x_{3}}\\ =3({x_{1}}^{3}+{x_{2}}^{3}+{x_{3}}^{3})-({x_{1}}+{x_{2}}+{x_{3}})^{3}+18{x_{1}}{x_{2}}{x_{3}}\\ =2{c_{1}}^{3}-9{c_{1}}{c_{2}}+27{c_{3}}. \end{array}$$

Hence equation (9) becomes

$$t^{\mathfrak{a}} - (2c_{1}^{3} - 9c_{1}c_{2} + 27c_{3})t^{\mathfrak{a}} + (c_{1}^{2} - 3c_{2})^{\mathfrak{a}} = 0.$$

Solving it as a quadratic equation for t^3 , we obtain two roots θ and θ' , and then obtain

$$\psi_1 = \sqrt[3]{\theta}, \quad \psi_4 = \sqrt[3]{\theta'}.$$

Here $\sqrt[3]{\theta}$ may be chosen to be an arbitrary one of the cube roots of θ , but $\sqrt[3]{\theta'}$ is then that definite cube root of θ' for which

(10)
$$\sqrt[3]{\overline{\theta}} \cdot \sqrt[3]{\overline{\theta}}' = c_1^2 - 3c_2.$$

We have therefore the following known expressions:

$$x_1 + \omega x_2 + \omega^2 x_3 = \sqrt[3]{\theta}, \qquad x_1 + \omega^2 x_2 + \omega x_3 = \sqrt[3]{\theta'}, \qquad x_1 + x_2 + x_3 = c_{1^*}$$

^{*}The fundamental theorem on symmetric functions is proved in the Appendix.

Multiplying them by 1, 1, 1; then by ω^3 , ω , 1; and finally by ω , ω^3 , 1; and adding the resulting equations in each case, we get

(11)
$$\begin{cases} x_1 = \frac{1}{3}(c_1 + \sqrt[3]{\theta} + \sqrt[3]{\theta'}), \\ x_2 = \frac{1}{3}(c_1 + \omega^2\sqrt[3]{\theta} + \omega\sqrt[3]{\theta'}), \\ x_3 = \frac{1}{3}(c_1 + \omega\sqrt[3]{\theta} + \omega^2\sqrt[3]{\theta'}). \end{cases}$$

4. Quartic equation. The general equation of degree four,

(12)
$$x^4 + ax^3 + bx^3 + cx + d = 0,$$

may be written in the form

$$(x^2 + \frac{1}{2}ax)^2 = (\frac{1}{4}a^2 - b)x^2 - cx - d.$$

With Ferrari, we add $(x^2 + \frac{1}{2}ax)y + \frac{1}{2}y^2$ to each member. Then

$$(13) (x^2 + \frac{1}{2}ax + \frac{1}{2}y)^2 = (\frac{1}{4}a^2 - b + y)x^2 + (\frac{1}{2}ay - c)x + \frac{1}{4}y^2 - d.$$

We seek a value y_i of y such that the second member of (13) shall be a perfect square. Set

$$(14) a^2 - 4b + 4y_1 = t^2.$$

The condition for a perfect square requires that

(15)
$$\frac{1}{4}t^2x^2 + (\frac{1}{2}ay_1 - c)x + \frac{1}{4}y_1^2 - d = \left(\frac{1}{2}tx + \frac{\frac{1}{2}ay_1 - c}{t}\right)^2.$$

$$\therefore \frac{1}{4}y_1^2 - d = \left(\frac{\frac{1}{2}ay_1 - c}{t}\right)^2 - \frac{(\frac{1}{2}ay_1 - c)^2}{a^2 - 4h + 4y_1}.$$

Hence y, must be a root of the cubic, called the resolvent,

(16)
$$y^3 - by^2 + (ac - 4d)y - a^2d + 4bd - c^2 = 0.$$

In view of (15), equation (13) leads to the two quadratic equations

(17)
$$x^2 + (\frac{1}{2}a - \frac{1}{2}t)x + \frac{1}{2}y_1 - (\frac{1}{2}ay_1 - c)/t = 0,$$

(18)
$$x^2 + (\frac{1}{2}a + \frac{1}{2}t)x + \frac{1}{2}y_1 + (\frac{1}{2}ay_1 - c)/t = 0.$$

Let x_1 and x_2 be the roots of (17), x_3 and x_4 the roots of (18). Then

$$x_1 + x_2 = -\frac{1}{2}a + \frac{1}{2}t, \quad x_1 x_2 = \frac{1}{2}y_1 - (\frac{1}{2}ay_1 - c)/t,$$

$$x_2 + x_4 = -\frac{1}{2}a - \frac{1}{2}t, \quad x_3 x_4 = \frac{1}{2}y_1 + (\frac{1}{2}ay_1 - c)/t.$$

By addition and subtraction, we get

(19)
$$x_1 + x_2 - x_3 - x_4 = t, \quad x_1 x_2 + x_3 x_4 = y_1.$$

La solving (17) and (18), two radicals are introduced, one equal to x_1-x_2 and the other equal to x_3-x_4 (see § 1). Hence all the irrationalities entering the expressions for the roots of the general quartic are rational functions of its roots.

If, instead of y_1 , another root of the resolvent cubic (16) be employed, quadratic equations different from (17) and (18) are obtained, such, however, that their four roots are x_1 , x_2 , x_3 , x_4 , but paired differently. It is therefore natural to expect that the three roots of (16) are

$$(20) y_1 = x_1 x_2 + x_2 x_4, y_2 = x_1 x_3 + x_2 x_4, y_3 = x_1 x_4 + x_2 x_3.$$

It is shown in the next section that this inference is correct.

5. Without having recourse to Ferrari's device, the two quadratic equations whose roots are the four roots of the general quartic equation (12) may be obtained by an à priori study of the rational functions $x_1x_3+x_3x_4$ and $x_1+x_2-x_3-x_4=t$. The three quantities (20) are the roots of $(-y_1)(y-y_2)(y-y_3)=0$, or

(21)
$$y^3 - (y_1 + y_2 + y_3)y^2 + (y_1y_2 + y_1y_3 + y_2y_3)y - y_1y_2y_3 = 0.$$

Its coefficients may be expressed * as rational functions of a, b, c, d:

$$\begin{aligned} y_1 + y_2 + y_3 &= x_1 x_2 + x_3 x_4 + x_1 x_3 + x_2 x_4 + x_1 x_4 + x_3 x_4 = b, \\ y_1 y_2 + y_1 y_3 + y_2 y_3 &= -4 x_1 x_2 x_2 x_4 \\ &\quad + (x_1 + x_2 + x_3 + x_4)(x_1 x_2 x_3 + x_1 x_2 x_4 + x_1 x_3 x_4 + x_2 x_3 x_4) \\ &= a c - 4 d, \\ y_1 y_2 y_3 &= (x_1 x_2 x_3 + x_1 x_2 x_4 + x_1 x_3 x_4 + x_2 x_2 x_4)^2 \\ &\quad + x_1 x_2 x_3 x_4 \{(x_1 + x_2 + x_3 + x_4)^2 - 4(x_1 x_2 + x_1 x_3 + \dots + x_3 x_4)\} \\ &= c^2 + d(a^2 - 4b). \end{aligned}$$

^{*}This is due to the fact (shown in § 29 Ex. 2, and § 30) that any permutation of x_1 , x_2 , x_3 , x_4 merely permutes y_1 , y_2 , y_3 , so that any symmetric function of y_1 , y_2 , y_3 is a symmetric function of x_1 , x_2 , x_3 , x_4 and hence rationally expressible in terms of a, b, c, d.

Hence equation (21) is identical with the resolvent (16). Next,

$$\begin{split} t^2 &= (x_1 + x_2 + x_3 + x_4)^2 - 4(x_1 + x_2)(x_3 + x_4) \\ &= a^2 - 4(x_1x_2 + x_1x_3 + \ldots + x_3x_4) + 4x_1x_2 + 4x_3x_4 \\ &= a^2 - 4b + 4y_1. \end{split}$$

Again, $x_1 + x_2 + x_3 + x_4 = -a$. Hence $x_1 + x_2 = \frac{1}{2}(t-a), \quad x_3 + x_4 = \frac{1}{2}(-t-a).$

To find x_1x_2 and x_3x_4 , we note that their sum is y_1 , while

$$-c = x_1 x_2 (x_3 + x_4) + x_3 x_4 (x_1 + x_2) = x_1 x_2 \left(\frac{-t - a}{2}\right) + x_3 x_4 \left(\frac{t - a}{2}\right).$$

$$\therefore x_1 x_2 = (c - \frac{1}{2}ay_1 + \frac{1}{2}ty_1)/t, \quad x_2 x_4 = (-c + \frac{1}{2}ay_1 + \frac{1}{2}ty_1)/t.$$

Hence x_1 and x_2 are the roots of (17), x_3 and x_4 are the roots of (18).

6. Lagrange's à priori solution of the quartic (12) is quite similar to the preceding. A root $y_1 = x_1x_2 + x_3x_4$ of the cubic (16) is first obtained. Then $x_1x_2 \equiv z_1$ and $x_3x_4 \equiv z_2$ are the roots of

$$z^2 - y_1 z + d = 0$$
.

Then $x_1 + x_2$ and $x_3 + x_4$ are found from the relations

$$(x_1 + x_2) + (x_3 + x_4) = -a,$$

$$z_2(x_1 + x_2) + z_1(x_3 + x_4) = x_3x_4x_1 + x_3x_4x_2 + x_1x_2x_3 + x_1x_2x_4 = -c.$$

$$\therefore x_1 + x_2 = \frac{-az_1 + c}{z_1 - z_2}, \quad x_3 + x_4 = \frac{az_2 - c}{z_1 - z_2}.$$

Hence x_1 and x_2 are given by a quadratic, as also x_3 and x_4 .

7. In solving the auxiliary cubic (16), the first irrationality entering (see § 2) is

$$\Delta \equiv (y_1 - y_2)(y_2 - y_3)(y_1 - y_3).$$

But
$$y_1 - y_2 = (x_1 - x_4)(x_2 - x_3)$$
,

$$y_2-y_3=(x_1-x_2)(x_3-x_4), \quad y_1-y_3=(x_1-x_3)(x_2-x_4),$$

in view of (20). Hence

(22)
$$\Delta = (x_1 - x_2)(x_1 - x_3)(x_1 - x_4)(x_2 - x_3)(x_2 - x_4)(x_2 - x_4).$$

By § 2, the reduced form of (16) is $\eta^{3}+P\eta+Q=0$, where

(23)
$$\begin{cases} P = ac - 4d - \frac{1}{3}b^2, \\ Q = -a^2d + \frac{1}{3}abc + \frac{8}{3}bd - c^2 - \frac{2}{27}b^3. \end{cases}$$

Applying (8), with a change of sign, we get

CHAPTER II.

SUBSTITUTIONS; RATIONAL FUNCTIONS.

8. The operation which replaces x_1 by x_a , x_2 by x_β , x_3 by x_7 , ..., x_n by x_ν , where a, β , ..., ν form a permutation of 1, 2, ..., n, is called a substitution on x_1 , x_2 , x_3 , ..., x_n . It is usually designated

$$\begin{pmatrix} x_1 & x_2 & x_3 & \dots & x_n \\ x_a & x_B & x_T & \dots & x_\nu \end{pmatrix}.$$

But the order of the columns is immaterial; the substitution may also be written

$$\begin{pmatrix} x_2 & x_1 & x_3 & \dots & x_n \\ x_{\beta} & x_a & x_7 & \dots & x_{\nu} \end{pmatrix}$$
, or $\begin{pmatrix} x_n & x_1 & x_2 & x_3 & \dots \\ x_{\nu} & x_a & x_{\beta} & x_7 & \dots \end{pmatrix}$, ...

The substitution which leaves every letter unaltered.

$$\begin{pmatrix} x_1 & x_2 & x_3 & \dots & x_n \\ x_1 & x_2 & x_3 & \dots & x_n \end{pmatrix},$$

is called the identical substitution and is designated I.

9. Theorem. The number of distinct substitutions on n letters is $n! \equiv n(n-1) \dots 3 \cdot 2 \cdot 1$.

For, to every permutation of the n letters there corresponds a substitution.

Example. The 31-6 substitutions on n=3 letters are:

$$\begin{split} I &= \begin{pmatrix} x_1 & x_2 & x_3 \\ x_1 & x_2 & x_3 \end{pmatrix}, \quad a = \begin{pmatrix} x_1 & x_2 & x_3 \\ x_2 & x_3 & x_1 \end{pmatrix}, \quad b = \begin{pmatrix} x_1 & x_2 & x_3 \\ x_2 & x_1 & x_2 \end{pmatrix}, \\ c &= \begin{pmatrix} x_1 & x_2 & x_3 \\ x_1 & x_3 & x_2 \end{pmatrix}, \quad d = \begin{pmatrix} x_1 & x_2 & x_3 \\ x_2 & x_1 & x_2 \end{pmatrix}, \quad e = \begin{pmatrix} x_1 & x_2 & x_3 \\ x_2 & x_1 & x_2 \end{pmatrix}. \end{split}$$

Applying these substitutions to the function $\psi = x_1 + \omega x_2 + \omega^2 x_3$, we obtain the following six distinct functions (cf. § 3):

$$\begin{aligned} \phi_I = x_1 + \omega x_2 + \omega^2 x_3 &\equiv \psi, & \psi_a = x_2 + \omega x_3 + \omega^2 x_1 &= \omega^2 \psi, & \psi_b = x_3 + \omega x_1 + \omega^2 x_2 &= \omega \psi, \\ \psi_c = x_1 + \omega x_3 + \omega^2 x_2, & \psi_d = x_2 + \omega x_2 + \omega^2 x_1 &= \omega^2 \psi_c, & \psi_e = x_2 + \omega x_1 + \omega^2 x_2 &= \omega \psi_c. \end{aligned}$$

Applying them to the function $\phi = (x_1 - x_2)(x_2 - x_3)(x_3 - x_1)$, we obtain

$$\phi_I = \phi_a = \phi_b = \phi, \qquad \phi_c = \phi_d = \phi_e = -\phi.$$

Hence ϕ remains unaltered by I, a, b, but is changed by c, d, e.

10. Product. Apply first a substitution s and afterwards a substitution t, where

$$s = \begin{pmatrix} x_1 & x_2 & \dots & x_n \\ x_a & x_{\beta} & \dots & x_{\nu} \end{pmatrix}, \quad t = \begin{pmatrix} x_a & x_{\beta} & \dots & x_{\nu} \\ x_{a'} & x_{\beta'} & \dots & x_{\nu} \end{pmatrix}.$$

The resulting permutation $x_{\alpha'}, x_{\beta'}, \ldots, x_{\nu'}$ can be obtained directly from the original permutation x_1, x_2, \ldots, x_n by applying a single substitution, namely,

 $u = \begin{pmatrix} x_1 & x_2 & \dots & x_n \\ x_{a'} & x_{\beta'} & \dots & x_{\nu'} \end{pmatrix}.$

We say that u is the product of s by t and write u=st.

Similarly, stv denotes the substitution w which arises by applying first s, then t, and finally v, so that stv = uv = w. The order of applying the factors is from left to right.*

EXAMPLES. For the substitutions on three letters (§ 9),

$$ab = ba = I$$
, $ac = d$, $ca = e$, $ad = e$, $da = c$, $aa = b$, $bb = a$, $abc = Ic = c$, $aca = da = c$.

Applying the substitution a to the function ϕ , we get ϕ_a ; applying the substitution c to ϕ_a , we get ϕ_d . Hence $\phi_{ac} = \phi_d$. Likewise $\phi_{ab} = \phi_I = \phi$, $\phi_{ba} = \phi$.

11. Multiplication of substitutions is not commutative in general.

Thus, in the preceding example, $ac \neq ca$, $ad \neq da$. But ab = ba, so that a and b are said to be **commutative**.

12. Multiplication of substitutions is associative: $st \cdot v = s \cdot tv$. Let s, t, and their product st = u have the notations of § 10.

$$v = \begin{pmatrix} x_{a'} & x_{\beta'} & \dots & x_{v'} \\ x_{a''} & x_{\beta''} & \dots & x_{v''} \end{pmatrix}, \quad \text{then } tv = \begin{pmatrix} x_a & x_{\beta} & \dots & x_v \\ x_{a''} & x_{\beta''} & \dots & x_{v''} \end{pmatrix}.$$

$$\therefore st \cdot v = uv = \begin{pmatrix} x_1 & x_2 & \dots & x_n \\ x_{a''} & x_{\beta''} & \dots & x_{v''} \end{pmatrix} = \begin{pmatrix} x_1 & x_2 & \dots & x_n \\ x_a & x_{\beta} & \dots & x_n \end{pmatrix} \begin{pmatrix} x_a & \dots & x_v \\ x_{a''} & \dots & x_{v''} \end{pmatrix} = s \cdot tv.$$
Example. For 3 letters, $ac \cdot a = da = c$, $a \cdot ca = ae = c$.

This is the modern use. The inverse order ts, vts was used by Cayley and Serret.

18 Powers. We write s2 for ss, s3 for sss, etc. Then

(25)
$$s^m s^n = s^{m+n}$$
 (m and n positive integers).

For, by the associative law $s^m s^n = s^m \cdot s s^{n-1} = s^{m+1} s^{n-1} = \dots$

14. Period. Since there is only a finite number n! of distinct substitutions on n letters, some of the powers

$$3, s^2, s^3, \ldots$$
 ad infinitum

must be equal, say $s^m = s^{m+n}$, where m and n are positive integers. Then $s^m = s^m s^n$, in view of (25). Hence s^n leaves unaltered each of the n letters, so that $s^n = I$.

The least positive integer σ such that $s^{\sigma} = I$ is called the period of s. It follows that

$$(26) s, s2, ... ss-1, ss \equiv I$$

are all distinct; while $s^{\sigma+1}$, $s^{\sigma+2}$,..., $s^{2\sigma-1}$, $s^{2\sigma}$ are repetitions of the substitutions (26). Hence the first σ powers are repeated periodically in the infinite series of powers.

Examples. From the example in § 10, we get

 $a^2=b$, $a^3=a^2a=ba=I$, whence a is of period 3; $b^2=a$, $b^3=b^2b=ab=I$, whence b is of period 3; c, d, e are of period 2; I is of period 1.

15. Inverse substitution. To every substitution s there corresponds one and only one substitution s' such that ss'=I. If

$$s = \begin{pmatrix} x_1 & x_2 & \dots & x_n \\ x_{\sigma} & x_{\rho} & \dots & x_{\nu} \end{pmatrix}, \text{ then } s' = \begin{pmatrix} x_{\sigma} & x_{\rho} & \dots & x_{\nu} \\ x_1 & x_2 & \dots & x_n \end{pmatrix}.$$

Evidently s's = I. We call s' the inverse of s and denote it henceforth by s^{-1} . Hence

$$8s^{-1} = 8^{-1}8 = I$$
, $(s^{-1})^{-1} = 8$.

If s is of period σ , then $s^{-1}=s^{\sigma-1}$. Since s replaces a rational function $j=j(x_1,\ldots,x_n)$ by $j_s=j(x_a,\ldots,x_\nu)$, s^{-1} replaces j, by j.

EXAMPLES For the substitutions on 3 letters (§ 9),

$$a = \begin{pmatrix} x_1 & x_2 & x_3 \\ x_2 & x_3 & x_1 \end{pmatrix}, \quad a^{-1} = \begin{pmatrix} x_2 & x_3 & x_1 \\ x_1 & x_2 & x_2 \end{pmatrix} = \begin{pmatrix} x_1 & x_2 & x_2 \\ x_3 & x_1 & x_2 \end{pmatrix} = b,$$

$$b^{-1} = a, \quad c^{-1} = c, \quad d^{-1} = d, \quad e^{-1} = e, \quad I^{-1} = I.$$