

Progress in Systems  
and Control Theory

# Systems and Control in the Twenty-First Century

Christopher I. Byrnes  
David S. Gilliam  
Editors

Biswa N. Datta  
Clyde F. Martin

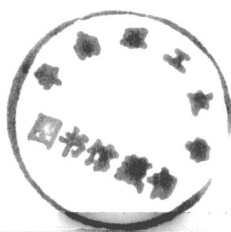
**Birkhäuser**

0231-53  
M426  
1996

9761960

# Systems and Control in the Twenty-First Century

Christopher I. Byrnes  
Biswa N. Datta  
Clyde F. Martin  
David S. Gilliam  
Editors



E9761960

Birkhäuser  
Boston • Basel • Berlin

Christopher I. Byrnes  
School of Engineering and  
Applied Science  
Washington University  
St. Louis, MO 63130-4899

Biswa N. Datta  
Dept. of Mathematical Sciences  
Northern Illinois University  
DeKalb, IL 60115

David S. Gilliam  
Clyde F. Martin  
Dept. of Mathematics  
Texas Tech University  
Lubbock, TX 79409

### Library of Congress Cataloging-in-Publication Data

Systems and control in the twenty-first century / [edited by]

Christopher Byrnes . . . [et al.].

p. cm. -- (Progress in systems and control theory ; v. 22)

"[Papers] presented at the 12th International Symposium on the  
Mathematical Theory of Networks and Systems, held in St. Louis,  
Missouri, from June 24-28, 1996" -- Pref.

Includes bibliographical references and index.

ISBN 0-8176-3881-4 (alk. paper) ISBN 3-7643-3881-4 (alk. paper)

1. System analysis--Congresses. 2. Control Theory--Congresses.

I. Byrnes, Christopher I., 1949- . II. International Symposium on  
the Mathematical Theory of Networks and Systems (12th : 1996 : Saint  
Louis, Mo.) III. Series.

QA402.S9694 1997

003--dc21

96-45612

CIP

Printed on acid-free paper  
© 1997 Birkhäuser Boston

*Birkhäuser* 

Copyright is not claimed for works of U.S. Government employees.

All rights reserved. No part of this publication may be reproduced, stored in a retrieval system, or transmitted, in any form or by any means, electronic, mechanical, photocopying, recording, or otherwise, without prior permission of the copyright owner.

Permission to photocopy for internal or personal use of specific clients is granted by Birkhäuser Boston for libraries and other users registered with the Copyright Clearance Center (CCC), provided that the base fee of \$6.00 per copy, plus \$0.20 per page is paid directly to CCC, 222 Rosewood Drive, Danvers, MA 01923, U.S.A. Special requests should be addressed directly to Birkhäuser Boston, 675 Massachusetts Avenue, Cambridge, MA 02139, U.S.A.

ISBN 0-8176-3881-4

ISBN 3-7643-3881-4

Camera-ready copy prepared by the editors in L<sup>A</sup>T<sub>E</sub>X.

Printed and bound by Quinn-Woodbine, Woodbine, NJ.

Printed in the U.S.A.

9 8 7 6 5 4 3 2 1

# **Systems & Control: Foundations & Applications**

Founding Editor

Christopher I. Byrnes, Washington University

## Preface

The mathematical theory of networks and systems has a long, and rich history, with antecedents in circuit synthesis and the analysis, design and synthesis of actuators, sensors and active elements in both electrical and mechanical systems. Fundamental paradigms such as the state-space realization of an input/output system, or the use of feedback to prescribe the behavior of a closed-loop system have proved to be as resilient to change as were the practitioners who used them.

This volume celebrates the resiliency to change of the fundamental concepts underlying the mathematical theory of networks and systems. The articles presented here are among those presented as plenary addresses, invited addresses and minisymposia presented at the 12th International Symposium on the Mathematical Theory of Networks and Systems, held in St. Louis, Missouri from June 24 - 28, 1996. Incorporating models and methods drawn from biology, computing, materials science and mathematics, these articles have been written by leading researchers who are on the vanguard of the development of systems, control and estimation for the next century, as evidenced by the application of new methodologies in distributed parameter systems, linear nonlinear systems and stochastic systems for solving problems in areas such as aircraft design, circuit simulation, imaging, speech synthesis and visionics.

We wish to thank these authors, and all the contributors to MTNS-96, for making this conference an outstanding intellectual celebration of this area and its ability to embrace and lead paradigm shifts, a celebration which will continue to grow in importance as we enter the next century. We also take great pleasure in thanking Rose Brower, Bijoy Ghosh, Michalina Karina, Susan McLaughlin, Giorgio Picci, Beth Scnettlar, Elizabeth SoRelle and Sue Schenker for years of outstanding service to MTNS-96. This endeavor could not have succeeded without their dedication.

Chris Byrnes	Biswa Datta	David Gilliam	Clyde Martin
St. Louis, MO	Dekalb, Il	Lubbock, TX	Lubbock, TX

## Contributors List

*D. Alpay* Department of Mathematics, Ben-Gurion University of the Negev, Israel

*B.D.O. Anderson* Department of Systems Engineering and Cooperative Research, Australian National University, Canberra, Australia

*H.T. Banks* Center for Research in Scientific Computation, North Carolina State University, USA

*D. Boley* Dept. of Computer Science, University of Minnesota

*R. Brockett* Division of Engineering and Applied Sciences, Harvard University, USA

*C.I. Byrnes* Department of Systems Science and Mathematics, Washington University, USA

*S. Coraluppi* Electrical Engineering Department and Institute for Systems Research, University of Maryland, USA

*B.N. Datta* Dept. of Mathematical Sciences, Northern Illinois University, USA

*P. Fard* Electrical Engineering Department and Institute for Systems Research, University of Maryland, USA

*E. Fernández-Gaucherand* Systems and Industrial Engineering Department, University of Arizona, USA

*M. Fliess* Laboratoire des Signaux et Systèmes, CNRS-Supélec, Plateau de Moulon, France

*H. Frankowska* CNRS URA 749, CEREMADE, Université Paris-Dauphine, France

*R.W. Freund* Bell Laboratories, Lucent Technologies, USA

*B.K. Ghosh* Department of Systems Science and Mathematics, Washington University, St. Louis, USA

*I. Gohberg* School of Mathematical Sciences, Tel-Aviv University, Tel-Aviv, Israel

*U. Grenander* Division of Applied Mathematics, Brown University, USA

*U. Helmke* Department of Mathematics, University of Würzburg, Germany

*D. Hernández-Hernández* Department of Mathematics, CINVESTAV-IPN, Mexico

*K. Hüper* Department of Mathematics, University of Würzburg, Germany

*M. Janković* Ford Motor Company, Scientific Research Laboratories, USA

*Petar V. Kokotović* Center for Control Engineering and Computation, Dept. of Electrical and Computer Engineering, University of California, USA

*A.B. Kurzhanski* Moscow State University, Russia

*I. Lasiecka* Department of Applied Mathematics, University of Virginia, USA

*J. Levine* Centre Automatique et Systèmes, École des Mines de Paris, France

*A. Lindquist* Department of Optimization and Systems Theory, Royal Institute of Technology, Sweden

*E.P. Loucks* Chiron Corporation, St. Louis, Missouri, USA

*N. Lybeck* Center for Research in Scientific Computation, North Carolina State University, USA

*C.F. Martin* Department of Mathematics, Texas Tech University, USA

*P. Martin* Centre Automatique et Systèmes, École des Mines de Paris, France

*S.I. Marcus* Electrical Engineering Department and Institute for Systems Research, University of Maryland, USA

*M.I. Miller* Department of Electrical Engineering, Washington University, St. Louis, USA

*F. Ollivier* GAGE-CNRS, Centre de Mathématiques, École polytechnique, France

*Y.M. Ram* Department of Mechanical Engineering, University of Adelaide, Australia

*J. Rosenthal* Department of Mathematics, University of Notre Dame, Notre Dame, USA

*P. Rouchon* Centre Automatique et Systèmes, École des Mines de Paris, France

*L. Schovanec* Department of Mathematics, Texas Tech University, USA

*R. Sepulchre* Center for Systems Engineering and Applied Mechanics, Université Catholique de Louvain, Belgium

*A. Srivastava* Department of Electrical Engineering, Washington University, St. Louis, USA

*H.J. Sussmann* Department of Mathematics, Rutgers University, USA

*A.R. Teel* Electrical Engineering Department, University of Minnesota, USA

*X.A. Wang* Department of Mathematics, Texas Tech University, USA

*G. Weiss* Center for Systems and Control Engineering, School of Engineering, University of Exeter, United Kingdom

*Jan C. Willems* University of Groningen, The Netherlands

*K.A. Wise* McDonnell Douglas Aerospace, St. Louis, USA



# Systems & Control: Foundations & Applications

## *Founding Editor*

Christopher I. Byrnes  
School of Engineering and Applied Science  
Washington University  
Campus P.O. 1040  
One Brookings Drive  
St. Louis, MO 63130-4899  
U.S.A.

*Systems & Control: Foundations & Applications* publishes research monographs and advanced graduate texts dealing with areas of current research in all areas of systems and control theory and its applications to a wide variety of scientific disciplines.

We encourage the preparation of manuscripts in TEX, preferably in Plain or AMS TEX—LaTeX is also acceptable—for delivery as camera-ready hard copy which leads to rapid publication, or on a diskette that can interface with laser printers or typesetters.

Proposals should be sent directly to the editor or to: Birkhäuser Boston,  
675 Massachusetts Avenue, Cambridge, MA 02139, U.S.A.

Estimation Techniques for Distributed Parameter Systems  
*H.T. Banks and K. Kunisch*

Set-Valued Analysis  
*Jean-Pierre Aubin and Hélène Frankowska*

Weak Convergence Methods and Singularly Perturbed  
Stochastic Control and Filtering Problems  
*Harold J. Kushner*

Methods of Algebraic Geometry in Control Theory: Part I  
Scalar Linear Systems and Affine Algebraic Geometry  
*Peter Falb*

$H^\infty$ -Optimal Control and Related Minimax Design Problems  
*Tamer Başar and Pierre Bernhard*

Identification and Stochastic Adaptive Control  
*Han-Fu Chen and Lei Guo*

Viability Theory  
*Jean-Pierre Aubin*

Representation and Control of Infinite Dimensional Systems, Vol. I  
*A. Bensoussan, G. Da Prato, M. C. Delfour and S. K. Mitter*

Representation and Control of Infinite Dimensional Systems, Vol. II  
*A. Bensoussan, G. Da Prato, M. C. Delfour and S. K. Mitter*

Mathematical Control Theory: An Introduction  
*Jerzy Zabczyk*

$H_\infty$ -Control for Distributed Parameter Systems: A State-Space Approach  
*Bert van Keulen*

Disease Dynamics  
*Alexander Asachenkov, Guri Marchuk, Ronald Mohler, Serge Zuev*

Theory of Chattering Control with Applications to Astronautics,  
Robotics, Economics, and Engineering  
*Michail I. Zelikin and Vladimir F. Borisov*

Modeling, Analysis and Control of Dynamic Elastic  
Multi-Link Structures  
*J. E. Lagnese, Günter Leugering, E. J. P. G. Schmidt*

First Order Representations of Linear Systems  
*Margreet Kuijper*

Hierarchical Decision Making in Stochastic Manufacturing Systems  
*Suresh P. Sethi and Qing Zhang*

Optimal Control Theory for Infinite Dimensional Systems  
*Xunjing Li and Jiongmin Yong*

Generalized Solutions of First-Order PDEs: The Dynamical  
Optimization Process  
*Andreï I. Subbotin*

Finite Horizon  $H_\infty$  and Related Control Problems  
*M. B. Subrahmanyam*

Control Under Lack of Information  
*A. N. Krasovskii and N. N. Krasovskii*

$H^\infty$ -Optimal Control and Related Minimax Design Problems  
A Dynamic Game Approach  
*Tamer Başar and Pierre Bernhard*

Control of Uncertain Sampled-Data Systems  
*Geir E. Dullerud*

Robust Nonlinear Control Design: State-Space and  
Lyapunov Techniques  
*Randy A. Freeman and Petar V. Kokotović*

Adaptive Systems: An Introduction  
*Iven Mareels and Jan Willem Polderman*

Sampling in Digital Signal Processing and Control  
*Arie Feuer and Graham C. Goodwin*

Ellipsoidal Calculus for Estimation and Control  
*Alexander Kurzhanski and István Vályi*

Minimum Entropy Control for Time-Varying Systems  
*Marc A. Peters and Pablo A. Iglesias*

Chain-Scattering Approach to  $H^\infty$ -Control  
*Hidenori Kimura*

Systems and Control in the Twenty-First Century  
*Christopher I. Byrnes, Biswa N. Datta, Clyde F. Martin,  
and David S. Gilliam*

# Contents

Preface .....	vii
Contributors List .....	ix
State Space Method for Inverse Spectral Problems <i>D. Alpay and I. Gohberg</i> .....	1
New Developments in the Theory of Positive Systems <i>B.D.O. Anderson</i> .....	17
Modeling Methodology for Elastomer Dynamics <i>H.T. Banks and N. Lybeck</i> .....	37
Numerical Methods for Linear Control Systems <i>D. Boley and B.N. Datta</i> .....	51
Notes on Stochastic Processes on Manifolds <i>R. Brockett</i> .....	75
On Duality between Filtering and Interpolation <i>C.I. Byrnes and A. Lindquist</i> .....	101
Controlling Nonlinear Systems by Flatness <i>M. Fliess, J. Levine, P. Martin, F. Ollivier, and P. Rouchon</i> ...	137
How Set-Valued Maps Pop Up in Control Theory <i>H. Frankowska</i> .....	155
Circuit Simulation Techniques Based on Lanczos-Type Algorithms <i>R.W. Freund</i> .....	171
Dynamical Systems Approach to Target Motion Perception and Ocular Motion Control <i>B.K. Ghosh, E.P. Loucks, C.F. Martin and L. Schovanec</i> .....	185
The Jacobi Method: A Tool for Computation and Control <i>U. Helmke and K. Hüper</i> .....	205
Ellipsoidal Calculus for Estimation and Feedback Control <i>A.B. Kurzhanski</i> .....	229
Control and Stabilization of Interactive Structures <i>I. Lasiecka</i> .....	245
Risk Sensitive Markov Decision Processes <i>S.I. Marcus, E. Fernández-Gaucherand, D. Hernández-Hernández, S. Coraluppi, and P. Fard</i> .....	263

On Inverse Spectral Problems and Pole-Zero Assignment <i>Y.M. Ram</i> .....	281
Inverse Eigenvalue Problems for Multivariable Linear Systems <i>J. Rosenthal and X.A. Wang</i> .....	289
Recursive Designs and Feedback Passivation <i>Rodolphe Sepulchre, Mrdjan Janković, Petar V. Kokotović</i> .....	313
Ergodic Algorithms on Special Euclidean Groups for ATR <i>A. Srivastava, M.I. Miller, and U. Grenander</i> .....	327
Some Recent Results on the Maximum Principle of Optimal Control Theory <i>H.J. Sussmann</i> .....	351
Nonlinear Input-output Stability and Stabilization <i>A.R. Teel</i> .....	373
Repetitive Control Systems: Old and New Ideas <i>G. Weiss</i> .....	389
Fitting Data Sequences to Linear Systems <i>Jan C. Willems</i> .....	405
Fighter Aircraft Control Challenges and Technology Transition <i>K.A. Wise</i> .....	417

# State Space Method for Inverse Spectral Problems

D. Alpay and I. Gohberg

## 1 Introduction

Let  $H$  denote a differential operator of the form

$$(Hf)(t) = -iJ \frac{d}{dt} f(t) - V(t)f(t), \quad t \geq 0, \quad (1.1)$$

where

$$J = \begin{pmatrix} I_m & 0 \\ 0 & -I_m \end{pmatrix} \quad \text{and} \quad V(t) = \begin{pmatrix} 0 & k(t) \\ k(t)^* & 0 \end{pmatrix}. \quad (1.2)$$

Here,  $k(t)$  is a  $\mathbb{C}^{m \times m}$ -valued function with entries in  $L_1(0, \infty)$ . It is sometimes called the potential of the differential operator, or the local reflexivity coefficient function (see [10] for this latter interpretation). Associated to the operator  $H$  are two important functions: the scattering function and the spectral function.

To define the scattering function, consider for real  $\lambda$  the  $\mathbb{C}^{2m \times m}$ -valued solution of the equation

$$-iJ \frac{d}{dt} X(t, \lambda) - V(t)X(t, \lambda) = \lambda X(t, \lambda), \quad (1.3)$$

subject to the boundary conditions

$$(I_m - I_m)X(0, \lambda) = 0, \quad (I_m \ 0)X(t, \lambda) = e^{-i\lambda t} I_m + o(1) \quad (t \rightarrow \infty).$$

Such a solution exists and is unique (see [20], [11]). It has the further property that there exists a  $\mathbb{C}^{m \times m}$  matrix  $S(\lambda)$  such that

$$(0 \ I_m)X(t, \lambda) = S(\lambda)e^{i\lambda t} + o(1) \quad (t \rightarrow \infty).$$

The function  $\lambda \mapsto S(\lambda)$  is called the scattering matrix function and it belongs to the Wiener algebra  $\mathcal{W}^{m \times m}$ . Recall that this algebra  $\mathcal{W}^{m \times m}$  consists of the matrix-valued functions of the form

$$Z(\lambda) = D - \int_{-\infty}^{\infty} z(t)e^{i\lambda t} dt \quad (1.4)$$

where  $D \in \mathbb{C}^{m \times m}$  and  $z \in L_1^{m \times m}(\mathbb{R})$ . Note that  $D = \lim_{\lambda \rightarrow \pm\infty} Z(\lambda)$ ; we will use the notation  $D = Z(\infty)$ .

The scattering function  $S$  has the following properties: it takes unitary values, belongs to  $\mathcal{W}^{m \times m}$ ,  $S(\infty) = I_m$  and it admits a Wiener–Hopf factorization:

$$S(\lambda) = S_-(\lambda)S_+(\lambda), \quad (1.5)$$

where  $S_-$  and its inverse are in  $\mathcal{W}_-^{m \times m}$ , and  $S_+$  and its inverse are in  $\mathcal{W}_+^{m \times m}$ . Here the subalgebra  $\mathcal{W}_-^{m \times m}$  consists of the elements of the form (1.4) for which the support of  $z(t)$  is in  $\mathbb{R}_-$ , and  $\mathcal{W}_+^{m \times m}$  consists of the elements of the form (1.4) for which the support of  $z(t)$  is in  $\mathbb{R}_+$ .

The inverse scattering problem consists in recovering the function  $k$  (and hence the potential) from the scattering function  $S$ . There is a rich literature about this problem. We follow the approach suggested in [18], [19], [20].

We now turn to the spectral function. The operator  $H$  defined by (1.1) is selfadjoint when restricted to the space  $D_H$  of  $\mathbb{C}^{2m}$ -valued functions  $f$  which are absolutely continuous and which satisfy the initial value  $(I_m - I_m)f(0) = 0$ . Let  $W$  be a  $\mathbb{C}^{m \times m}$ -valued function which is continuous on the real line and for which  $W(\lambda) > 0$  for all real  $\lambda$ . It is called a spectral function for the operator  $H$  if there is a unitary mapping  $U : L_2^m(0, \infty) \rightarrow L_2^m(W)$  such that  $(UHf)(\lambda) = \lambda(Uf)(\lambda)$  for  $f \in D_H$ , where  $L_2^m(W)$  is the Hilbert space of  $\mathbb{C}^m$ -valued measurable functions  $g$  such that  $\int_{-\infty}^{\infty} g(t)^* W(t) g(t) dt < \infty$ . If  $S$  given by (1.5) is the scattering function of the operator (1.1), then the function

$$W(\lambda) = S_-(\lambda)^{-1} S_-(\lambda)^{-*} \quad (1.6)$$

is a spectral function of  $H$ , and the map  $U$  is given in terms of the continuous orthogonal polynomials of M.G. Krein (see [17], [11]). The definitions of these functions and of the map  $U$  are given in the next section. We will call this function the spectral function of the operator  $H$ ; it is uniquely determined from the scattering function  $S$  and the condition  $W(\infty) = I_m$ . Let  $W \in \mathcal{W}^{m \times m}$ , with  $W(\infty) = I_m$ . The function  $W$  admits Wiener–Hopf factorizations  $W = W_+ W_+^* = W_- W_-^*$ , where  $W_+$  and its inverse are in  $\mathcal{W}_+^{m \times m}$  and  $W_-$  and its inverse are in  $\mathcal{W}_-^{m \times m}$ . The function  $W$  is the spectral function of the differential operator (1.1) with scattering matrix-function  $S = W_-^{-1} W_+$ . The inverse spectral problem consists of recovering the function  $k$  from the spectral function  $W$ .

We will also consider the case where the reflection coefficient matrix function  $R(\lambda)$  is known and rational. We recall that  $R(\lambda) = X_{21}(0, \lambda) X_{11}(0, \lambda)^{-1}$  where  $X = (X_{ij})$  is the (unique)  $\mathbb{C}^{2m \times 2m}$  solution of equation (1.3) subject to the asymptotic property

$$X(t, \lambda) = \begin{pmatrix} e^{-i\lambda t} I_m & 0 \\ 0 & -e^{i\lambda t} I_m \end{pmatrix} + o(1) \quad (t \rightarrow \infty).$$

In this paper we present explicit formulas for  $k$  when the spectral matrix function (or equivalently the scattering matrix function or the reflection coefficient function) is rational, and give applications of these formulas to the

equivalence between Kreĭn's and Marchenko's approach to inverse problems in the rational case. This leads us to a new relationship between the coefficient matrix functions of the Carathéodory–Toeplitz and Nehari extension problems. We also discuss a solution of the direct scattering problem in the rational case which turns out to be related to a problem of partial realization considered in [14]. In general, the results of this paper are obtained by a method which is based on the state space method from system theory. The main results with complete proofs can be found in the papers [2], [1], [3], [5], [4] and [6]. A topic not discussed here is the discrete case (see [1]).

Some words on notation: we denote by  $\mathbb{C}^{m \times n}$  the space of  $m$ -rows and  $n$ -columns matrices with complex entries, and  $\mathbb{C}^m$  is short for  $\mathbb{C}^{m \times 1}$ ; the identity matrix of  $\mathbb{C}^{m \times m}$  is denoted by  $I_m$ , or simply by  $I$ . The adjoint of a matrix  $A$  is denoted by  $A^*$ .

## 2 The Approaches of Kreĭn and Marchenko

The approach of M.G. Kreĭn's to the inverse spectral problem is as follows: let

$$W(\lambda) = I_m - \int_{-\infty}^{\infty} h(u) e^{i\lambda u} du$$

with  $h \in L_1^{m \times m}(\mathbb{R})$  be the spectral function. Since  $W(\lambda) > 0$  for all real  $\lambda$ , the integral equation

$$\gamma_\tau(t, s) - \int_0^\tau h(y - u) \gamma_\tau(u, s) du = h(t - s), \quad t, s \in [0, \tau] \quad (2.1)$$

has a unique solution  $\gamma_\tau(t, s)$  for every  $\tau > 0$ . Then, the potential  $k(t)$  is given by the formula

$$k(t) = -2i\gamma_{2t}(0, 2t). \quad (2.2)$$

Let

$$P(t, \lambda) = e^{i\lambda t} \left( I_m + \int_0^{2t} \gamma_{2t}(u, 0) e^{-i\lambda u} du \right) \quad (2.3)$$

and

$$R(t, \lambda) = e^{i\lambda t} \left( I_m + \int_0^{2t} \gamma_{2t}(2t - u, 2t) e^{-i\lambda u} du \right). \quad (2.4)$$

The unitary map  $U$  between the spaces  $L_2^{2m}[0, \infty)$  and  $L_2^m(W)$  alluded to in the introduction is given by

$$(Uf)(\lambda) = \sqrt{2\pi} \int_0^\infty (P(t, -\lambda) \quad R(t, \lambda)) f(t) dt. \quad (2.5)$$

Marchenko's approach is concerned with inverse scattering. Let

$$S(\lambda) = I_n - \int_{-\infty}^{\infty} \sigma(u) e^{-i\lambda u} du \quad \lambda \in \mathbb{R}$$



be the scattering matrix function where  $\sigma \in L_1^{m \times m}(\mathbb{R})$ , and set

$$\xi(u) = \begin{pmatrix} 0 & \sigma(u)^* \\ \sigma(u) & 0 \end{pmatrix}. \quad (2.6)$$

Marchenko's approach consists in solving the equation

$$M(t, s) - \xi(t + s) - \int_t^\infty M(t, u) \xi(u + s) du = 0 \quad (2.7)$$

for  $0 \leq t \leq s < \infty$  (see [20, equation (1.10)]) with the unknown matrix  $M(t, s) = (m_{ij}(t, s))_{i,j=1,2}$  (where the block  $m_{ij}$  are  $\mathbb{C}^{n \times n}$ -valued).

The potential is then given by  $k(t) = -2im_{21}(t, t)$ .

### 3 Review of the State Space Technique

We recall a number of facts from the theory of realization of matrix-valued rational functions. Any  $\mathbb{C}^{m \times m}$ -valued rational function  $W$ , analytic on the real line and at infinity with  $W(\infty) = I_m$ , can be written as

$$W(\lambda) = I_m + C(\lambda I_n - A)^{-1} B, \quad (3.1)$$

where  $A \in \mathbb{C}^{n \times n}$ ,  $B \in \mathbb{C}^{n \times m}$  and  $C \in \mathbb{C}^{m \times n}$ .

Such an expression (3.1) is called a realization of  $W$ . The realization is called minimal if the number  $n$  in (3.1) is as small as possible and the minimal such  $n$  is called the McMillan degree of  $W$ . Two minimal realizations of  $W$  are similar: namely, if  $W(\lambda) = I_m + C_i(\lambda I_n - A_i)^{-1} B_i$ ,  $i = 1, 2$  are two minimal realizations of  $W$ , there exists a (uniquely defined and invertible) matrix  $S \in \mathbb{C}^{n \times n}$  such that

$$A_2 = S A_1 S^{-1} \quad B_2 = S B_1 \quad C_2 = C_1 S^{-1}. \quad (3.2)$$

For these facts and more information on the theory of realization of matrix-valued functions, we refer to [8] and [21].

If  $W$  is a  $\mathbb{C}^{m \times m}$ -valued function analytic on the real line and at infinity with  $Z(\infty) = I_m$ , with minimal realization (3.1), it is of the form (1.4) with

$$z(u) = \begin{cases} i C e^{-iuA} (I_m - P) B & u > 0 \\ -i C e^{-iuA} P B & u < 0 \end{cases} \quad (3.3)$$

where  $P$  is the Riesz projection corresponding to the eigenvalues of  $A$  in  $\mathbb{C}_+$ . The function  $z$  has absolutely summable entries and thus  $Z$  is in the Wiener algebra and it is therefore meaningful to consider the case of rational scattering and spectral functions.

A factorization  $R = R_- R_+$  of  $R$  into two  $\mathbb{C}^{n \times n}$ -valued functions analytic at infinity is called a (right) canonical (Wiener-Hopf or spectral) factorization if  $R_-$  and its inverse are analytic in the closed lower half plane