

MICRO AND NANO MANIPULATIONS FOR BIOMEDICAL APPLICATIONS

R318 M626

Micro and Nano Manipulations for Biomedical Applications

Tachung C. Yih Ilie Talpasanu

Editors







artechhouse.com

Library of Congress Cataloging-in-Publication Data

A catalog record for this book is available from the U.S. Library of Congress.

British Library Cataloguing in Publication Data

A catalogue record for this book is available from the British Library.

ISBN-13: 978-1-59693-254-8

Cover design by Igor Valdman

Chapter 3 permissions: Sections of text from pages 59–67 have been reprinted in large part with permission from [84]. Copyright 1997 American Chemical Society. Sections of text from pages 82–83 have been reprinted in large part with permissions from [160]. Copyright 2006 American Chemical Society. Sections of text from pages 72, 74, and 75 have been reprinted in large part with permission from [119]. Copyright 2006 American Chemical Society. Sections of text from pages 52–54 have been reprinted in large part with permission from [53] Copyright 1999 WILEY-VCH verlag GmbH.

© 2008 ARTECH HOUSE, INC. 685 Canton Street Norwood, MA 02062

All rights reserved. Printed and bound in the United States of America. No part of this book may be reproduced or utilized in any form or by any means, electronic or mechanical, including photocopying, recording, or by any information storage and retrieval system, without permission in writing from the publisher.

All terms mentioned in this book that are known to be trademarks or service marks have been appropriately capitalized. Artech House cannot attest to the accuracy of this information. Use of a term in this book should not be regarded as affecting the validity of any trademark or service mark.

10987654321

Micro and Nano Manipulations for Biomedical Applications

For a listing of recent related Artech House titles turn to the back of this book.

此为试读,需要完整PDF请访问: www.ertongbook.com

To our familes

To my wife Debbie and my daughter Jessica
—Tachung C. Yih

To my wife Lucretia-Dalia and my son Alexandru —Ilie Talpasanu

List of Contributors

Chapter 1 Tachung C. Yih Oakland University, Rochester, Michigan, United States Ilie Talpasanu Wentworth Institute of Technology, Boston, Massachusetts, United States Chapter 2 Nicosor V. Iftmia Physical Sciences, Inc., Andover, Massachusetts, United States Mansoor M. Amiji Northeastern University, Boston, Massachusetts, United States Ileana N. Iftimia Lahey Clinic, Burlington, Massachusetts, United States and Tufts University, Medford, Massachusetts, United States Tianzhong Yang, Chengmin Shen, Hongjun Gao, and Congwen Xiao Chapter 3 Beijing National Laboratory for Condensed Matter Physics, Institute of Physics, Chinese Academy of Sciences, Beijing, China Anca Mocofanescu Brigham and Women's Hospital, Boston, Massachusetts, United States Chapter 4 I. C. Chiao University of Texas at Arlington, Arlington, Texas, United States Mu Chiao University of British Columbia, Vancouver, British Columbia, Canada Chapter 5 I. C. Chiao University of Texas at Arlington, Arlington, Texas, United States Mu Chiao University of British Columbia, Vancouver, British Columbia, Canada Leonardo Sacconi and Francesco Saverio Pavone, Chapter 6 LENS European Laboratory for Non Linear Spectroscopy, University of Florence, Firenze, Italy Alessio Masi University of Florence, Firenze, Italy Chapter 7 Iody Vykoukal and Davene Mannering Vykoukal University of Texas M. D. Anderson Cancer Center, Houston, Texas, United States Chapter 8 Florin Ionescu University of Applied Sciences, Konstanz, Germany Kostadin Kostadinov Institute of Mechanics and Biomechanics, Bulgarian Academy of Sciences, Sofia, Bulgaria Ilie Talpasanu Wentworth Institute of Technology, Boston, Massachusetts, United States Dragos Arotaritei University of Medicine and Pharmacy "Gr. T. Popa," Iasi, Romania George Constantin Polytechnic University of Bucharest, Bucharest, Romania Chapter 9 Brooks Automation, Inc., San Jose, California, United States Mingjun Zhang Agilent Technologies, Inc., Santa Clara, California, United States

Preface

In the next decade, nanotechnology is expected to have a large impact on diseases such as cancer, neurodegeneration, and diabetes and those of the blood, lungs, cardiovascular system, and skeleton. The design of novel nanoparticles, capable of sensing and drug delivery, will increase. Chapter 2 presents an overview of technologies for cancer diagnosis and therapy. The fabrication and properties of metallic nanoparticles, as well as quantum dots, nanocrystals based on semiconductors, also are presented in this chapter.

Chapter 3 outlines the fundamentals of MEMS/NEMS actuator design and fabrication. A description of thermal, magnetic, electrostatic, piezoelectric microactuators is detailed in Chapter 4, which also focuses on the micromanipulators for minimally invasive procedures. Chapter 5 discusses end effector tools and electron microscopy for biomedical nanomanipulations.

Cell viability and behavior following nanoparticle injection are observed through imaging techniques. Chapter 6 presents current applications and trends in imaging manipulations such as 3-D imaging and optical dissection by nonlinear optical microscopy, laser-induced microdissection, nanosurgery characterization, optical trapping, and optical tweezers.

Chapter 7 discusses dielectrophoretic methods for cell and biomolecule manipulations. The design, modeling, and control of a piezo-actuated robotic system with microaccuracy and nanoaccuracy, as required in cell manipulations, are presented in Chapter 8. The main physical methods of gene manipulations and delivery such as electroporation, hydroporation, sonoporation, microneedle and microinjection, optoinjection and optoporation, magnetofection, and the gene gun method are described in Chapter 9. The performances and limitations of the gene delivery methods are also analyzed in this chapter.

The book covers basic principles and applications of micromanipulation and nanomanipulation for biomedicine and will provide the reader with the facts he or she needs to know about the manipulation, control, modeling, and simulation at the microscale and nanoscale levels. Microprecision and nanoprecision robotic systems are used by manufacturers or researchers involved in biorobotics projects, and by practitioners involved in applications from the emerging area of micro and nano bio devices. Presenting the most recent applications of biomanipulation of cells and genes, the book is suitable also for undergraduate and graduate students in biomedical applications.

We wish to thank Dr. Frank Caserta from the Wentworth Institute of Technology for his suggestions during the preparation of the manuscript. We would like to thank the reviewers, Dr. Jane Wang from the Northwestern University and Dr. Pak Kin Wong from the Systematic Bioengineering Lab at the University of Arizona, for

their critical reviews. We also would like to thank Wayne Yuhasz, Barbara Lovenvirth, Judi Stone, and Rebecca Allendorf from Artech House for their efforts during the preparation of this book.

Recent Related Titles from Artech House

Biomolecular Computation for Bionanotechnology, Jian-Qin Liu and Katsunori Shimohara

Fundamentals and Applications of Microfluidics, Second Edition, Nam-Trung Nguyen and Steven T. Wereley

Genome Sequencing Technology and Algorithms, Sun Kim, Haixu Tang, and Elaine R. Mardis, editors

Intelligent Systems Modeling and Decision Support in Bioengineering, Mahdi Mahfouf

Introduction to Microelectromechanical Systems Engineering, Second Edition, Nadim Maluf and Kirt Williams

Life Science Automation Fundamentals and Applications, Mingjun Zhang, Bradley Nelson, and Robin Felder, editors

Microfluidics for Biotechnology, Jean Berthier and Pascal Silberzan

Nanoelectronics Principles and Devices, Mercea Dragoman and Daniela Dragoman

Nanotechnology Applications and Markets, Lawrence D. Gasman

Nanotechnology Regulation and Policy Worldwide, Jeffrey H. Matsuura

Organic and Inorganic Nanostructures, Alexei Nabok

Pressure-Driven Microfluidics, Václav Tesar

Text Mining for Biology and Biomedicine, Sophia Ananiadou and John McNaught

Translational Approaches in Tissue Engineering and Regenerative Medicine, Jeremy J. Mao, Antonios Mikos, Gordana Vunjak-Novakovic, and Anthony Antala, editors

For further information on these and other Artech House titles, including previously considered out-of-print books now available through our In-Print-Forever[®] (IPF[®]) program, contact:

Artech House Artech House

685 Canton Street 46 Gillingham Street
Norwood, MA 02062 London SW1V 1AH UK

Phone: 781-769-9750 Phone: +44 (0)20 7596-8750 Fax: 781-769-6334 Fax: +44 (0)20 7630-0166

e-mail: artech@artechhouse.com e-mail: artech-uk@artechhouse.com

Find us on the World Wide Web at: www.artechhouse.com

Contents

Prefa	eface		
	APTER 1	1	
	oduction	1	
1.1	The Third Industrial Revolution?	1	
	1.1.1 The First Industrial Revolution—	4	
	Manufacturing and Transportation	1	
	1.1.2 The Second Industrial Revolution—	2	
	Computer and Communication	3 5	
	1.1.3 The Third Industrial Revolution—Health and Environment?	6	
1.2	Microtechnologies and Nanotechnologies	7	
	1.2.1 Challenges and Opportunities in Nanotechnology	9	
1 2	1.2.2 Micromanipulations and Nanomanipulations	9	
1.3	Applications and Trends	9	
	1.3.1 Biomedical Science and Engineering1.3.2 Health Care and Environmental Applications	10	
	References	10	
	References	10	
СН	APTER 2		
000000000000000000000000000000000000000	otechnology Applications in Cancer Imaging and Therapy	13	
2.1	Introduction	13	
2.1	Nanotechnology Approaches for In Vivo Diagnostics	15	
2.2	2.2.1 Molecular Imaging Approaches for In Vivo Diagnostics	16	
	2.2.1 Notectial imaging reproducts for in Vivo Biagnostics 2.2.2 Nanotechnology-Based Contrast Agents for In Vivo Imaging	18	
2.3	Nanotechnology-Based Drug Delivery Systems for Cancer Therapy	24	
2.5	2.3.1 Fundamental Requirements for Drug Delivery Systems	25	
	2.3.2 Cancer Therapy Approaches Using Nanotechnologies	30	
2.4	Conclusions	36	
	References	37	
CH	APTER 3		
Nan	noparticles for Biomedical Applications	43	
3.1	Introduction	43	
3.2	Synthesis of Metallic Nanoparticles	45	
	3.2.1 Synthesis Approaches to Noble Metal Nanoparticles	45	
	3.2.2 Synthesis of Magnetic Metal Nanoparticles	49	
3.3	Novel Properties of Metal Nanoparticles	57	
	3.3.1 Unique Properties of Noble Metal Nanoparticles	57	
	3.3.2 Magnetic Properties of Metallic Nanoparticles	67	

viii Contents

3.4	Application of Metal Nanoparticles in Biomedicine	71
	3.4.1 Biomedical Detection Using Novel Metal Nanoparticles	71
	3.4.2 Drug Delivery and Biosensing with Magnetic Nanoparticles	78
3.5	Specific Properties of Quantum Dots	83
3.6	Quantum Dots as Fluorescent Biological Labels	86
	3.6.1 Disadvantages of Organic Dyes, Traditional Biological Labels	86
	3.6.2 Beneficial Quantum Dot Optical and Spectral Properties	87
3.7	Quantum Dots in Biomedical Applications	88
	References	91
***************************************	APTER 4	
	roactuators for In Vivo Imaging and Micromanipulators in	
Min	imally Invasive Procedures	101
4.1	Minimally Invasive Procedure Applications	101
4.2	Endoscopic and In Vivo Imaging Applications	102
	4.2.1 In Vivo Scanning Microscope	103
	4.2.2 In Vivo Optical Coherent Tomography Imaging	104
4.3	Micromanipulators for Minimally Invasive Procedures	108
	4.3.1 Microtools	109
	4.3.2 Sensors in Micromanipulators	111
	4.3.3 Navigation	112
4.5	Conclusions	113
	References	114
MANUSCON STORY	APTER 5	
Mici	roactuators	119
5.1	Introduction	119
5.2	Electrostatic Actuators	119
5.3	Thermal Actuators	122
5.4	Piezoelectric Actuators	126
5.5	Shape Memory Alloy Actuators	128
5.6	Magnetic Actuators	132
5.7	Conclusions	135
	References	135
CH	APTER 6	
Opti	cal Nanomanipulation in a Living Cell	143
6.1	Two-Photon Fluorescence Microscopy	143
	6.1.1 Introduction	143
	6.1.2 A Brief Analytical Description	145
6.2	Second-Harmonic-Generation Microscopy	146
	6.2.1 Introduction	146
	6.2.2 Nonlinear Optical Processes	147
	6.2.3 Single-Molecule Cross Section	148
	6.2.4 Biological Membrane Imaging	149
6.3	Laser-Induced Microdissection	151
	6.3.1 Summary	151

Contents

	6.3.2	Introduction to Optical Dissection	151
	6.3.3		13
	by No	onlinear Optical Microscopy	151
	6.3.4		153
	6.3.5		154
	6.3.6		156
6.4	Optic	al Trapping	157
	6.4.1	Summary	157
	6.4.2	Introduction to Optical Tweezers	157
	6.4.3	Optical Trapping Inside Yeast Cells	158
	6.4.4	Laser-Induced Nucleus Displacement	162
	6.4.5	Motion of a Displaced Interphase Nucleus Back	102
	to the	Cell Center by Microtubule Pushing	163
	6.4.6	Asymmetric Cell Division as a Result of Nucleus	100
	Displa	acement During Interphase	164
		Division Plane Determination in Early Prophase	165
6.5	Optic	al Knockout	166
	6.5.1	Introduction	166
	6.5.2	One-Photon CALI	167
	6.5.3	Micro-CALI	168
	6.5.4	Multiphoton CALI	171
6.6	Concl	usions	172
Ack	nowled	gments	173
	Refere	ences	173
***************************************	APTER		
Diel	ectroph	oretic Methods for Biomedical Applications	179
7.1	Introd	uction	179
7.2	Theor	y	181
	7.2.1	Dielectrophoresis	181
		Dielectric Properties of Bioparticles and Biomolecules	185
7.3	Dielec	trophoretic Approaches to Bioparticle Manipulation	103
and	Charact	terization	191
	7.3.1	Differential Manipulation of Bioparticles	191
	7.3.2	Filtration and Concentration of Bioparticles	193
	7.3.3	Manipulating Cells for Subsequent Analysis	195
	7.3.4	Cell Patterning and Tissue Engineering	198
	7.3.5	Characterizing Cell Physiology by Dielectrophoresis	200
7.4	Dielect	crophoretic Approaches to Molecular Assays	202
	7.4.1	Microparticle-Based Systems	202
	7.4.2	Droplet-Based Systems: Digital Microfluidics	203
7 . 5	Conclu	isions and Perspectives	204
Ackr	owledg	ments	205
	Referen	nces	205

CHAPTER 8

Desi	gn, An	alysis, Modeling, Simulation, and Control of Microscale and	
Nan	oscale	Cell Manipulations	215
8.1	Introd	luction	215
	8.1.1	Overview of Micropositioning and Nanopositioning	210
		ns Based on Piezoactuators	216
	8.1.2	Applications of Piezoactuated Micropositioning and	_10
	Nano	positioning Systems	217
8.2		ruction of the Micro-Nano Robot as a Mechatronic System	218
	8.2.1	Conceptual Design of Piezo-Actuated Microrobot	
	Development		
	8.2.2	Robot RoTeMiNa for Cell Micromanipulation and	218
	Nano	manipulation	221
	8.2.3	Design of the Micro Stage Robot	222
	8.2.4	Design of the Nano Stage Robot	223
	8.2.5	Teleoperated Control	223
8.3	Differ	ential Kinematics of a Hybrid Robot for Cell	
Mici	omanij	oulations and Nanomanipulations	225
	8.3.1	Link and Joint Numbering	225
	8.3.2	Oriented Graph Attached to the Mechanism	225
	8.3.3	Matrix Description of Graph	226
		Geometric Jacobean	227
		Degrees of Freedom	232
	8.3.6	Independent Equations for the Inverse Kinematics	232
8.4	Hardy	vare and Software for the Development of Micropositioning and	
Nan	opositio	oning Systems	234
	8.4.1	Guidelines for Development	234
	8.4.2	Sensors for Feedback	235
	8.4.3	Unified Approach for Functional Task Formulation	235
8.5	Intellig	gent Control of Piezoactuated Robot Using an Approximated	
Hyst	eresis N	Model in Micromanipulations and Nanomanipulations	238
	8.5.1	Introduction	238
	8.5.2	The Mathematical Model of Hysteresis	238
	8.5.3	The Neuro-Fuzzy Inverse Model	241
	8.5.4	The Control System Structure	242
	8.5.5	Multiobjective Optimal PI/PID Controller Design Using Genetic	
	Algori	thms	244
8.6		mental Results	246
8.7		ion of the Method and Limitations	247
8.8		sion and Conclusions	247
Ackn	owledg	,	250
	Refere	nces	250

Index

287

CH	APTER	9	
Dyna	amics I	Modeling and Analysis for Gene Manipulations	253
9.1	Introduction		253
	9.1.1	Current Status	254
	9.1.2	Requirements for Gene Delivery	254
	9.1.3	•	256
9.2	Electroporation		257
	9.2.1		258
	9.2.2	Electric Pulse	259
	9.2.3	Tissue Damage	260
	9.2.4		260
	9.2.5		261
9.3	Hydro	oporation	261
9.4	Sonop	poration	262
	9.4.1	Impact of Ultrasound Frequency	263
	9.4.2		263
	9.4.3	Impact of Ultrasound Exposure Time	264
	9.4.4	Cell Damage with Sonoporation	264
	9.4.5	Dynamic Modeling	264
9.5	Micro	oneedle and Microinjection	266
	9.5.1	Microneedle	266
	9.5.2	Microinjection	266
9.6	Optoi	njection and Optoporation	267
9.7		etofection	268
9.8	Gene	Gun	269
	9.8.1	Introduction	269
	9.8.2	Dynamic Modeling	272
9.9		nary and Comparison of the Physical Methods	275
9.10	Summary and Future Challenges		275
	Refere	ences	277
Aboı	ıt the A	Authors	281
1 1000			201

CHAPTER 1

Introduction

Tachung C. Yih and Ilie Talpasanu

1.1 The Third Industrial Revolution?

In 2000, then-President William J. Clinton launched the National Nanotechnology Initiative (NNI) as a top science and technology priority [1]. The President's Council of Advisors on Science and Technology (PCAST) described NNI as an excellent multiagency framework to ensure U.S. leadership in this emerging field that will be essential for economic and national security leadership in the first half of the next century [2]. The speech by President Clinton given at the California Institute of Technology on January 21, 2000, was titled "National Nanotechnology Initiative: Leading to the Next Industrial Revolution." Is nanotechnology leading us into our third Industrial Revolution? To answer this question, we must understand what happened in previous industrial revolutions [3–12].

Humans walked through the Stone Age, Bronze Age, and Iron Age, periods covering thousands of years, with a dawdling speed of technology advancement. The common cause of the Industrial Revolution is the advancement of new technology, triggered by scientific innovations. The Industrial Revolution transformed countries from agricultural to industrial, communities from rural to urban, and people from farmers to factory workers. The significant impacts resulting from the Industrial Revolution cover a broad range such as productivity growth, culture, and the daily lives of the populace. The long-term effects brought about by the industrial revolutions remain debatable. However, many believe that, on the whole, the benefits that came with the Industrial Revolution outweigh the problems.

1.1.1 The First Industrial Revolution—Manufacturing and Transportation

The first Industrial Revolution occurred in Great Britain between 1750 and 1850, followed by those of the United States and other countries in Europe during the nineteenth century as well as those of Russia and Japan in the first half of the twentieth century.

The earliest factories appeared in 1740, producing textile merchandise. Eli Whitney, an American, changed the textile industry from using wool to using cotton as its raw material with his invention of the cotton gin (1792). Other important English inventions included the flying shuttle (John Kay, 1733), the hand-powered cotton-spinning jenny (James Hargreaves, 1765) [13], the water frame spinning

device (Richard Arkwright, 1766), and the improvements in weaving powered by a steam engine (Samuel Crompton, 1790). Samuel Slater, known as the father of the American Industrial Revolution, emigrated from England to America in 1789 and built the first successful water-powered textile mill in Pawtucket, Rhode Island, in 1793 [14, 15]. The first sewing machine was designed by Elias Howe in 1843. Sewing machines were the first major consumer appliance. In 1851, Isaac Singer invented the first practical, domestic sewing machine and widely marketed his machines.

The early steam engines were developed in England by Thomas Savery (1698) and Thomas Newcomen (1705) to pump water out of coal mines, but they could not generate power. Henry Cort (1780) developed the steam-powered rolling mills that revitalized the iron industry. James Watt (1782) developed power-generating steam engines to drive rotary shafts in other machinery. Watt's engines were widely used during the period of the Industrial Revolution. Richard Trevithick (1805) built several full-size, high-pressure steam carriages, known as locomotives, which were used to haul coal and ore out of the mines. George Stephenson opened the first public railway in the world in 1825, which was worked by a Stephenson Rocket locomotive. During the nineteenth century, steam locomotives were exported from England to many other countries. The steam-powered locomotive and iron railway system revolutionized the means of transportation in human history; people and goods could be transported in mass quantities at lower cost, which enabled the market economy.

In the United States [16, 17], Oliver Evans pioneered and invented the high-pressure steam engine. He built the first automatic mill in Delaware in 1782, and in 1789, the first U.S. patent for a steam-powered land vehicle was granted to him. John Fitch designed and tested a steam-powered boat on the Delaware River in 1786. The first practical steamboat was built by William Symington in Scotland in 1801. Robert Fulton constructed the *Clermont* to carry fare-paying passengers on the Hudson River in 1807.

To construct the steam engines and machines, the growing need for machine tools was inevitable. The oldest known machine tool was the wood-working lathe. Jasse Ramsden, an English instrument maker, developed the first screw-cutting lathes in 1770. Henry Maudslay, in 1800, produced the first large, high-accuracy (1/10,000 of an inch) screw-cutting lathe. Maudslay's assistants introduced the first gear-cutting machine (Richard Roberts, 1818), a punching machine for making rivet holes (Richard Roberts, 1847), a measuring machine with an accuracy of one-millionth of an inch (Joseph Whitworth, 1856; he also standardized the screw threads in English), and the milling machine and shaper (James Nasmyth, 1854). One of the most important inventions, which made Watt's steam engine a practical power source, was John Wilkinson's cylinder boring machine (1775).

The post–Industrial Revolution (1850–1950) mainly carried on in the United States. One of the most important landmarks in the history of engine design was the invention of the internal combustion engine (Nikolaus A. Otto, 1876) [18]. He constructed the first practical gas-motor, four-stroke piston cycle internal combustion engine, named the Otto Cycle Engine. Otto's invention was the first practical alternative to the steam engine and the foundation of the modern engine. By applying Otto's engine, Gottlieb Daimler built a motorcycle (1885) and the first four-wheeled automobile (1886) in the world. Karl Benz also constructed his first three-wheel