

Progress in Systems
and Control Theory



Robust Control of Linear Systems and Nonlinear Control

Proceedings of the International
Symposium MTNS-89, Volume II

M.A. Kaashoek J.H. van Schuppen
A.C.M. Ran Editors



Birkhäuser

9162032

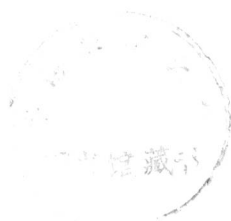
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1990

Birkhäuser
Boston · Basel · Berlin

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Library of Congress Cataloging-in-Publication Data

Proceedings of the International Symposium MTNS-89 / M.A. Kaashoek,

J.H. van Schuppen, A.C.N. Ran, editors.

p. cm. — (Perspectives in control theory ; v. 3-5)

"The 1989 International Symposium on the Mathematical Theory of
Networks and Systems (MTNS) . . . held in Amsterdam, The Netherlands,
June 19-23, 1989"—Pref.

Contents : v. 1. Realization and modelling in system theory — v.

2. Robust control of linear systems and nonlinear control — v.

3. Signal processing, scattering and operator theory, and numerical
methods.

1. System analysis—Congresses. 2. Control theory—Congresses.

I. Kaashoek, M. A. II. Schuppen, J. H. van. III. Ran, A. C. M.

IV. International Symposium on the Mathematical Theory of Networks
and Systems (9th : 1989 : Amsterdam, Netherlands) V. Series.

QA402.P766 1990

003—dc20

90-1003

CIP

Printed on acid-free paper.

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ISBN 0-8176-3470-3

ISBN 3-7643-3470-3

For three-volume set:

ISBN 0-8176-3468-1

ISBN 3-7643-3468-1

Camera-ready text provided by the individual authors.

Printed and bound by Edwards Brothers, Inc., Ann Arbor, Michigan.

Printed in the U.S.A.

9 8 7 6 5 4 3 2 1

Progress in Systems and Control Theory

Volume 4

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Preface

This volume is the second of the three volume publication containing the proceedings of the *1989 International Symposium on the Mathematical Theory of Networks and Systems (MTNS-89)*, which was held in Amsterdam, The Netherlands, June 19-23, 1989.

The International Symposia MTNS focus attention on problems from system and control theory, circuit theory and signal processing, which, in general, require application of sophisticated mathematical tools, such as from function and operator theory, linear algebra and matrix theory, differential and algebraic geometry. The interaction between advanced mathematical methods and practical engineering problems of circuits, systems and control, which is typical for MTNS, turns out to be most effective and is, as these proceedings show, a continuing source of exciting advances.

The second volume contains invited papers and a large selection of other symposium presentations in the vast area of robust and nonlinear control. Modern developments in robust control and H-infinity theory, for finite as well as for infinite dimensional systems, are presented. A large part of the volume is devoted to nonlinear control. Special attention is paid to problems in robotics. Also the general theory of nonlinear and infinite dimensional systems is discussed. A couple of papers deal with problems of stochastic control and filtering.

The titles of the two other volumes are: *Realization and Modelling in System Theory* (volume 1) and *Signal Processing, Scattering and Operator Theory, and Numerical Methods* (volume 3).

The Editors are most grateful to the about 300 reviewers for their help in the refereeing process. The Editors thank Ms. G. Bijleveld and Ms. L.M. Schultze for their professional secretarial assistance, and Mr. K. van 't Hoff for his programming support.

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Amsterdam
February 1990

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