BIPOLAR TRANSISTOR RADIO FREQUENCY INTEGRATED CIRCUITS

TN432 5974

Designing Bipolar Transistor Radio Frequency Integrated Circuits

Allen A. Sweet







Library of Congress Cataloging-in-Publication Data

A catalog record of this book is available from the Library of Congress.

British Library Cataloguing in Publication Data

A catalogue record of this book is available from the British Library.

ISBN 13: 978-1-59693-128-2 ISBN 10: 1-59693-128-0

Cover design by Yekaterina Ratner

© 2008 ARTECH HOUSE, INC. 685 Canton Street Norwood, MA 02062

All rights reserved. Printed and bound in the United States of America. No part of this book may be reproduced or utilized in any form or by any means, electronic or mechanical, including photocopying, recording, or by any information storage and retrieval system, without permission in writing from the publisher.

All terms mentioned in this book that are known to be trademarks or service marks have been appropriately capitalized. Artech House cannot attest to the accuracy of this information. Use of a term in this book should not be regarded as affecting the validity of any trademark or service mark.

10987654321

Designing Bipolar Transistor Radio Frequency Integrated Circuits

For a listing of recent titles in the *Artech House Microwave Library*, turn to the back of this book.

FUNDAMENTAL PHYSICAL CONSTANTS

- 1. Speed of light in a vacuum: $c=3x10^{10}$ cm/s
- 2. Permittivity of a vacuum: $\varepsilon_0 = 8.89 \times 10^{-14}$ F/cm
- 3. Permeability of a vacuum: $\mu_0 = 1260$ nH/meter
- 4. Planck's constant: h=6.63x10⁻³⁴ J-seconds
- 5. Boltzmann's constant: k=1.38x10⁻²³ J/degrees Kelvin
- 6. Charge of an electron: $q=1.6\times10^{-19}$ C
- 7. Rest mass of an electron: $m_a = 9.11 \times 10^{-31} \text{ Kg}$
- 8. Thermal voltage: VT=kT/q=0.0259 volts at T=300 degrees Kelvin
- 9. Bandgap energy of Silicon= 1.12 eV
- 10. Bandgap energy of GaAs = 1.42 eV
- 11. Dielectric constant of Silicon: 11.7
- 12. Dielectric constant of GaAs: 12.5

IMPORTANT UNIT CONVERSIONS

- 1. Angstrom (Å): $1\text{Å}=1\text{x}10^{-8}$ cm
- 2. Nanometer (nm): $1 \text{ nm} = 1 \times 10^{-7} \text{ cm}$
- 3. Micron (μ m): 1μ m= 1×10^{-4} cm
- 4. Electron-Volt (eV): $1 \text{ eV} = 1.6 \times 10^{-19} \text{ J}$

Acknowledgments

I wish to acknowledge all of my ELEN 351, ELEN 354, and ELEM359 graduate students at Santa Clara University. Your probing questions, your well-executed class projects, and your sense of excitement about the material has helped me greatly to clarify many of the design concepts that are discussed in this book. In this regard, my special thanks go to Amer Droubi and Calvin Chien for contributing excellent design material, based on their class projects, to this book. I wish all of you much success in your design careers. I would also like to thank my faithful teaching assistant Yiching Chen, who has added so much to these classes.

I am deeply indebted to Professor Shoba Krishnan and Professor Samiha Mourad of the Electrical Engineering Department of Santa Clara University, for making possible the creation of a sequence of RFIC graduate design classes at Santa Clara University. It is out of these classes that this book has grown.

To Barbara Lovenvirth of Artech House Publishing, goes my heartfelt thanks for your constant encouragement and support (especially when I needed it the most) during the creation process of this book.

My special thanks to Agilent Corporation for making their ADS simulation tool set available to the students and facility of Santa Clara University.

I wish to give my special thanks to Ron Parrott and his staff at Vida Products Inc., for supplying design material for this book, and making time available for our many interesting discussion about the operation of Vida Product's YIG tuned ring oscillators.

Many thanks to Taka Shinomiya with whom I have enjoyed many lively discussions on power amplifer design.

Finally, I want most especially to thank my wife Fran Sweet, for her patience and support during our many discussions about the book's preparation; for her word-processing talents and editing skills, and for her "advanced wordsmithing" magic acts. Everything that you have done on behalf of the book has helped in so many ways to bring us to this successful conclusion of our 18-month book-writing project. With all my love I thank you Fran for being my faithful and constant partner and companion in this endeavor.

Lastly, I wish to thank my father, Norman A. Sweet, for giving me a crystal radio kit as a present on my 10th Christmas. It was this crystal radio that started me on a life long odyssey of discovery into the joys and wonder of radio electronics, which lives in this book and continues on.

Contents

Ackı	nowledgments	X
***************************************	APTER 1	
Intro	oduction	1
	References	11
CH	APTER 2	
App	lications	13
2.1	Cellular/PCS Handsets	13
2.2	Cellular/PCS Infrastructure	15
2.3	WLANs	16
2.4	Bluetooth	17
2.5	UWB	18
2.6	WiMax	19
2.7	Digital TV and Set-Top Boxes	20
2.8	Cognitive Radio	20
2.9	Spectrum Allocation in the United States (All Frequencies	
2.40	in Megahertz)	21
2.10		22
	References	24
CH/	APTER 3	
RFIC	Architectures	25
3.1	I/Q Receivers	25
3.2	I/Q Modulators	30
3.3	Nonzero IF Receivers	32
3.4	Zero IF Receivers	37
3.5	Differential versus Single-Ended Topologies	41
	References	41
CHA	APTER 4	
InGa	P/GaAs HBT Fabrication Technology	43
4. 1	Transistor Structures	43
4.2	Device Models	45
4.3	Passive Structures, Their Electrical Models, and Layout Design Rules	48
	4.3.1 Microstrip Lines	53
	4.3.2 TFR Resistors	55

⁄iii	Contents
· III	Contents

	4.3.3 M1-to-M2 Vias	57
	4.3.4 MIM Capacitors	57
	4.3.5 Substrate Vias	58
	4.3.6 Bonding Pads	60
	4.3.7 Crossover Capacitances	61
	4.3.8 Spiral Inductors4.3.9 Transistor Dummy Cells	62
	The state of the s	64
	4.3.10 Significant Layout Parasitic Elements4.3.11 Simple Layout Example	65
4.4	1 , 1	65 67
4.5	CAD Layout Tools	70
1.0	References	70
СН	APTER 5	
SiG	e HBT Fabrication Technology	71
5.1	SiGe HBT Transistor Structures	71
5.2	Transistor Device Models	79
5.3	Passive Device Structures and Models	81
5.4	Design Rules	86
5.5	CAD Layout	86
	References	87
	APTER 6	
Pass	ive Circuit Design	89
6.1	Low-Pass Filters	89
6.2	High-Pass Filters	93
6.3	Band-Pass Filters	93
6.4	Differential Filters	95
6.5	Technology and Substrates	99
6.6	Splitters/Dividers	99
6.7	Phase Shifters and Baluns	102
	References	104
	APTER 7	
Amp	olifier Design Basics	105
7.1	Matching Techniques	105
7.2	Gain Compensation	106
7.3	Fano's Limit	106
7.4	Stability	107
7.5	Noise Match	109
7.6	Differential Amplifiers	109
7.7	Cascode Amplifiers	111
	References	113
CHA	APTER 8	
Low	-Noise Amplifier Design	115
8.1	Noise Figure Concepts	115

Contents ix

8.2	Noise Temperature	116
8.3	Front-end Attenuation and LNAs	117
8.4	Multistage Noise Figure Contributions	117
8.5	Circuit Topologies for Low Noise	118
8.6	Design Example 1: Single-Ended PCS LNA	126
8.7	Design Example 2: Three-Transistor Hybrid Darlington	
	Differential LNA Using SiGe Technology	127
	References	132
an	ADTER O	
	APTER 9 er Amplifier Design	133
9.1 9.2	Loadline Concepts Maximum Power and Efficiency	134
9.3	Maximum Power and Efficiency	136
9.4	Class AB Power Amplifiers Definitions of Nonlinear Performance Metrics	139
9.5	Adjacent Channel Power Ratio	141 145
9.6	Error Vector Magnitude	143
9.7	Circuit Topologies for PAs	146
9.8	Matching Circuit Options	149
9.9	Stability Stability	150
9.10	Bias Circuits	150
9.11	Design Example 3: Wideband Gain Block Darlington Amplifier	154
9.12	Design Example 4: Feedback Power Amplifier Design	164
	References	171
CUA	DTER 10	
OCCUPATION OF PERSONS ASSESSED.	IPTER 10 gning Multistage Amplifiers	173
10.1	Multistage LNAs	173
10.2	Multistage Power Amplifiers	175
10.3	Gain and Power Allocations	177
10.4	Active Device Sizing	177
10.5	Design Example 5: A Differential PCS PA References	181
	References	194
CHA	PTER 11	
Mixe	r/Modulator Design	195
11.1	Mixer Basics	195
11.2	Diode Mixers	197
11.3	Single-Balanced Active Multiplying Mixers	200
11.4	Fully Balanced Active Multiplying Mixers (Gilbert Cell)	205
11.5	I/Q Mixers	217
11.6	I/Q Modulators	219
11.7	Design Example 6: Cellular/PCS Downconverting Mixer RFIC	221
	References	230
CHA	PTER 12	
account annual account to the same	jency Multiplier Design	221

_		cono:			
	$\hat{}$	n	te	m	1

12.1 12.2 12.3	Frequency Triplers	231 233 235
	References	239
СЫ	APTER 13	
	age-Controlled Oscillator Design	241
13.1	3	
13.1		242
13.3	S. C.	248 252
13.4	7 1 000 000 5 000 000 000 000 000 000 000	252
10.1	13.4.1 Negative-Resistance Oscillator Circuits	252
	13.4.2 The Colpitts Oscillator Circuit	258
13.5	•	261
13.6	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	263
13.7	Quadrature Phase-Shifting Networks	266
13.8		267
13.9	Design Example 7: 802.11a (Wi-Fi A) Differential VCO	272
13.1		278
13.1	0	279
	References	281
CH/	APTER 14	
	ut Design Strategies	283
14.1	Minimum Area	
14.2	"On-Chip" versus "Off-Chip" Component Decisions	283 283
14.3	Minimizing Parasitics	284
14.4	Testability	285
14.5	Types of CAD Systems	286
14.6	Foundry Comparison	287
14.7	Reticle Assembly	289
CHA	DTED 15	
	APTER 15 Economics	202
		293
15.1 15.2	Levels of Integration	293
15.2	Single-Ended versus Differential Topologies Process Took role and Chairman	294
15.4	Process Technology Choices Area versus Performance Trade-offs	295
15.5	Electrical Yield	296
15.6	Prototype Costs	297
15.7	Production Costs	298
10.7	2704401011 00010	298
Acror	nyms	301
	t the Author	305
Index		
	•	307

CHAPTER 1

Introduction

Over the past three decades, radio frequency (RF) and microwave circuits have come through a period of rapid evolution and growth. Until the early 1960s, most RF and microwave circuits made use of vacuum tubes such as "lighthouse" tubes, klystrons, magnetrons, backward wave oscillators (BWOs), and traveling-wave tubes (TWTs) [1]. By the mid-1960s, all this was beginning to change as even more dramatic changes were rapidly approaching on the horizon in the form of new solid-state devices capable of working at RF and microwave frequency ranges. The first of these new technologies to present itself was the silicon (Si) bipolar transistor, which had been scaled to operate up to a frequency of about 1 GHz. And that was only the beginning of a wave of development during which time such unique solid-state devices as Gunn diodes, Impatt diodes, PIN diodes, and varactor diodes became available [2]. These two-terminal solid-state devices had the ability to push the upper frequency limit of solid-state electronics from under 1 GHz to well over 10 GHz. The rush was on. All eyes were watching to see whose efforts would deliver the next highest operating frequency, the highest power output, the lowest noise, and the best temperature stability. As the Vietnam War came to an end, this process accelerated even more because of the availability of federal research money. Because much of the basic RF and microwave research was funded by the federal government, a sharp focus was placed on military applications. RF and microwave technology had become a very important element in the cold war strategy of the time.

Since then, the RF and microwave field has evolved over four distinct periods. Figure 1.1 provides a map of the way these developing technologies emerged over time. The first period, from the mid-1960s to the mid-1970s, is characterized by the use of diode-active devices and waveguide transmission lines and resonators. The great technology push during this period provided a replacement for vacuum tubes in both military and commercial communications systems. Reliability was a major motivating factor. Vacuum tube systems were famous for failing at the worst possible time, and it was widely felt in the 1960s that a switch to solid state, even with reduced performance, would significantly improve system reliability [3]. The question of the day became, what vacuum tubes can realistically be replaced by solid-state devices? Since solid-state devices could not generate the RF power of the magnitude that vacuum tubes were capable of, the first targets were applications not requiring high RF power levels. Examples of these include receiver local oscillators and low power transmitters. Most mixers in this period were already using solid-state designs employing point contact diodes, or Schottky diodes, as the active devices. It was therefore very natural to include a solid-state local oscillator as an

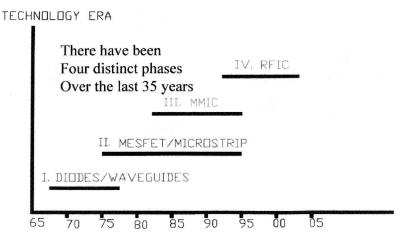


Figure 1.1 A timeline showing how the RF and microwave electronics field has evolved through four distinct phases during the last forty years.

integral part of these mixers, forming a nearly complete solid-state receiver. This need was filled by replacing klystron vacuum tubes with Gunn diode oscillators. The exception to the trend toward solid state within receiver systems was the low-noise amplifier, which remained a TWT until gallium arsenide (GaAs) metal-semiconductor field-effect transistors (MESFETs) became more widely available. Low- and medium-power transmitters evolved into solid-state designs; Impatt diode oscillators were used as replacements for klystron, TWT, and magnetron vacuum tubes in these applications. Along with reliability, the new solid-state hardware offered the systems designer further advantages of lower power dissipation (no vacuum tube filaments needing heater power) and lower operating voltages, eliminating complex high-voltage power supplies. The RF/microwave industry very rapidly became sold on the virtues of solid-state hardware. We were ready for the next important period of development.

The second major period is characterized by the availability of GaAs MESFET devices [4]. With the arrival of GaAs MESFET devices, three terminal devices were at long last available to the RF/microwave circuit designer. Microstrip transmission lines were introduced during this period [5]. Microstrip transmission lines are usually patterned on thin film ceramic substrates. Using photolithographic techniques [4], the circuit designer can fabricate an entire network of microstrip transmission lines on a single thin film ceramic substrate, and using so-called hybrid assembly techniques, circuits may be assembled by connecting active devices such as GaAs MESFETs and diodes to the patterned ceramic substrates using wire-bonding techniques. The field was revolutionized with the development of these RF/microwave thin film hybrid circuits. It was now possible to construct an entire subsystem within a single small mechanical housing. When compared to the old technologies using vacuum tube equipment or even the diode/waveguide solid-state equipment from the recent past, the savings in terms of size, weight, and power consumption were dramatic.

During the cold war military buildup following the end of the Vietnam War, considerable research and development funding for this type of work became avail-

able from the U.S. government. For this reason, many of the applications addressed by the emerging solid-state RF/microwave technology were military in nature. In fact, RF/microwave technology development coincided with a major cold war arms buildup in both the United States and the Soviet Union. The compact hardware, made possible by the use of ceramic microstrip circuits and GaAs transistors and diodes, found ready application in newly designed radar, electronic warfare, and missile systems. This period extended from the mid-1970s to the mid-1990s. It was a very intense and exciting two decades of design progress. The domain of solid-state circuits was growing by leaps and bounds. With the advent of GaAs MESFET devices, both low-noise and medium-power TWTs were at last replaced by solid-state transistor amplifiers [7]. These ceramic microstrip hybrid circuits were capable of extremely wide bandwidth operation. This was a great advance for electronic warfare systems, which depend on the ability to acquire random signals over a wide range of possible input frequencies. TWT amplifiers were no longer needed in such systems. The elimination of TWTs created an opportunity for tremendous savings in terms of cost, power, and weight in many airborne systems. All of these technological advances worked in combination with advances in other areas, such as engine design, new materials, and life support, to make possible the high-performance military aircraft that became available toward the end of the cold war period.

The third significant period of RF/microwave technological development grew out of the desire to reduce the cost, size, and weight of RF/microwave solid-state circuits. The path to cost and size reduction followed the same route as that followed by both digital and low-frequency analog circuits: the implementation of integrated circuit (IC) techniques. Since GaAs MESFET devices had very quickly become the most important solid-state active device at these frequencies, an integrated circuit technology was needed that would build on GaAs MESFETs. Fabrication technology for GaAs integrated circuits became available in the mid-1980s [8].

At first, these so-called microwave monolithic integrated circuits (MMICs) were limited to perhaps two transistors and some matching elements, but over time MMICs grew to include enough components to make up entire amplifiers and even simple subsystems. MMICs made use of a particular property of undoped GaAs substrates: their high natural resistance. In fact, undoped GaAs, unlike undoped silicon, is an excellent insulator. This means that the undoped GaAs substrates used in MMIC circuits are excellent media for microstrip lines. Furthermore, since the dielectric constant of GaAs is 12.5, such transmission lines are physically short, reducing size, weight, and total cost. As cost depends heavily on total die area, this unique new MMIC technology held the promise of replacing much of the then existing ceramic microstrip hybrid hardware with low-cost, fully monolithic, MMIC-integrated circuits.

This promise has been only partially fulfilled because of two factors: First, there is the issue of tuning (or tweaking). Hybrid ceramic circuits had always required a moderate amount of expensive hand alignment. This alignment, known in the industry as "tweaking," accounted for much of the hardware's cost. However, in the case of MMIC circuits, it was no longer possible to tweak the circuit because it is an integrated circuit and too small for any hands-on alignment (even if the insulating passivation layer were to be left off in processing) to be practical. This means

that either MMICs work or they don't. However, it's not quite that simple. Variations in the fabrication process occur from wafer to wafer, which can significantly affect the performance of an MMIC circuit. Wafer-to-wafer variations reduce the overall yield of MMIC devices, and depending on the degree of difficulty of the electrical specifications, the yield may be quite low, which tends to cancel out the cost advantages of using an MMIC approach in the first place.

Two possible solutions to these problems were attempted. The first was more exact modeling, and the second was improved process uniformity. The first solution made use of models that allowed the simulation of a wide range of electrical parameters, not just the small-signal S-parameters, which were customarily used in hybrid ceramic circuit simulations. The new models created for MMIC applications had to be able to function over a large range of signal levels, including dc behavior. These models, generically called large-signal models, were far more complex than the small-signal S-parameter models that preceded them. Considerable effort and expense went into the development of these large-signal models, with the hope that if the new MMIC circuits could be modeled accurately and completely, their yields would increase. The effort was only partially successful because of a second major issue: wafer-to-wafer variations during fabrication. All the modeling precision in the world won't increase yield if the model parameters keep changing in unpredictable ways. To improve this situation, the foundries (fabrication facilities) attempted to use more repeatable processes. The most significant change was a switch from wet etch processing (involving placing the wafers into chemical baths) to a dry etch process (which makes use of a plasma that impinges very uniformly onto the wafer in a specially designed vacuum chamber). However, not all etching processes could be switched to dry etch. In particular, the gate recess etch step in fabricating the MESFET device's gates could not be done by dry etch and had to remain a wet etch process step. A lot of device variation is experienced in this one step, and it is a challenge to model developers and circuit designers alike to deal with this variation. This situation has never been totally resolved. MESFET circuits today still experience significant process variations that affect yield, sometimes profoundly. By necessity, designers have developed ways of optimizing their circuits for process variations so that yield number can be increased. However, to date no universal solution to this problem has been identified.

History intervened at this point to create a shift in emphasis and application. In 1991, the Soviet Union ceased to exist, and the cold war ended. As a result, the ongoing demand for improved military hardware came to an abrupt end, and government-sponsored research and development funding sharply declined. This global political change created temporary hard times for companies and individuals working in RF and microwaves throughout the 1990s. However, just as the RF/microwave electronics field descended into decline with the end of the cold war, the technology quickly came back to life with the arrival of the wireless revolution, which began gaining energy in the second part of the 1990s.

The emergence of wireless technology signaled the beginning of a fourth period of technology development, and work in wireless research and development continues today. This period signaled the emergence of radio frequency integrated circuits (RFICs) as a major driver of progress in RF and microwaves. The timeline presented in Figure 1.2 focuses on the applications in each time period. Wireless applications

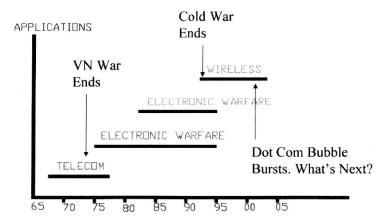


Figure 1.2 A timeline showing the most important application associated with each phase in the development of the RF and microwave electronics field.

are the latest period. In many ways, wireless applications feel like "back to the future." The focus is changing to narrowband applications at relatively low frequencies (1 to 4 GHz). This is a dramatic shift from ceramic/hybrid and MMIC technologies, where the focus was on very broadband applications at high frequencies (up to 25 GHz). However, the concept of RFIC was born out of the need to serve these applications.

New high-frequency fabrication technologies began to appear. All during the purely microwave–millimeter-wave period (late 1960s to mid-1990s), the dominant high-frequency fabrication technology was GaAs MESFET. However, by the late 1990s, GaAs MESFET was joined by the GaAs heterojunction bipolar transistor (HBT) [9] whose advantages relative to GaAs MESFET are discussed throughout the present book. MMIC designers were quick to perceive the advantages of GaAs HBT, and many designers changed technologies, especially for cellular infrastructure applications. Within a short period, designers began designing PAs for mobile handsets using GaAs HBT. During this largely III–V compound semiconductor design period of the late 1980s, MMIC designers gave considerable attention to cellular applications. Due to the low-frequency (0.80 to 1.9 GHz) operations associated with cellular applications, these new integrated circuits came to be called RFICs, rather than MMICs. RFICs have operating frequencies more in keeping with traditional RF frequencies than with the higher microwave frequencies associated with MMICs.

Then, the world changed again, in many ways, all at once. First, new silicon-based fabrication technologies [silicon germanium (SiGe), BiCMOS, and RFCMOS] became available [10]. Second, in order to reduce cost and size, there was a major push toward higher levels of integration. This trend toward high IC integration was the key ingredient responsible for morphing the "brick" cellular telephone of the 1990s into the palm-sized "clam shell" phone of today. Today, everyone, young children included, uses cell phones. This is true not only in the United States but worldwide. In terms of availability, cell phones are to this decade what personal computers were to the 1980s and 1990s. Mobile cellular phones have indeed changed the world, and these emerging IC technologies had a lot to do with

it. These new product trends were driven by the availability of new and highly integrated RFICs. Transceiver designs moved away from realizations involving separate components attached to a common PCB, to one (or a few) RF chips based on one of the new silicon technologies. Currently, many low-frequency analog designers are entering the field in order to apply their craft of designing very large integrated circuits to the RF frequency range. Most of the GaAs technologies have been ignored by these analog designers (because of cost) when designing the new, highly integrated transceiver chips.

There are two exceptions to this trend. The first is infrastructure amplifiers and mixers, which remain mostly in GaAs. The second exception includes handset PAs and T/R switches, which also remain in GaAs. The scope of this book is chiefly those designs made in support of cellular infrastructure and instrument applications. So, the question remains, are these cellular infrastructure (and instrument) amplifiers, mixers, voltage-controlled oscillators (VCOs), and switches, strictly speaking, RFICs or MMICs? Good question. It all depends on how one defines MMIC and RFIC technologies.

In many ways, RFIC devices are replacements for discrete circuits. Their frequencies are low enough and their bandwidth is narrow enough that, in general, transmission line parasitic elements do not greatly affect performance. This is a big relief to the designer, who is not facing the difficult goals of wide-bandwidth, high-frequency operation where designs require modeling every transmission line like parasitic elements in order to succeed.

RFICs have always relied on the same circuit elements used in MMICs use, such as spiral inductors and metal insulator metal (MIM) capacitors. These elements naturally have complicated models, each of which must be carefully analyzed in a top-notch simulator in order to predict performance accurately. Like the MMIC before it, the RFIC cannot be tuned, or "tweaked." Once it is fabricated, "what you see is what you get." To avoid a costly series of design "spins," it is very important to model and simulate an RFIC accurately. However, these concerns can be mitigated to some degree by using feedback (both digital and analog) to control performance parameters. Some examples are variable bias circuits and automatic gain-control circuits.

Concurrent with the wireless revolution of the late 1980s and early 1990s, a similar revolution was happening in device and fabrication technology. For many years, the only transistor technologies available to the RFIC/MMIC designer had been silicon bipolar or GaAs MESFET. That situation changed drastically during this period for two important reasons. The first was the exploration and exploitation of heterojunctions, and the second was the availability of CMOS devices operating at RF/microwave frequencies. Heterojunction devices were first proposed in the late 1950s by Herb Kromer, who ultimately won a Nobel Prize for this work [11].

Heterojunctions significantly increase the degrees of freedom available to the device designer. No longer are device parameters adjustable only with doping gradients; with heterojunctions, the dissimilar material's energy band gap becomes a controlling aspect for determining performance. The Ft performance of nonheterojunction transistors (i.e., homojunction transistors) is dependent on the ratio of the donor concentrated in the emitter to the acceptor concentration in the