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DETERMINISTIC SYSTEMS
OF DIFFERENTIAL EQUATIONS***

G. S. LADDE

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PREFACE

The classical random flow and Newtonian mechanics approaches are the most extensively studied stochastic modeling methods for dynamic processes in biological, engineering, physical and social sciences. Both of these approaches lead to differential equations.

In the classical stochastic modeling approach, the state of a dynamic process is considered to be a random flow or process satisfying a certain probabilistic law such as Markov or diffusion. From these types of probabilistic assumptions, one then needs to determine the state transition probability distribution and density functions (STPDF). The determination of the unknown STPDF leads to the study of deterministic problems in the theory of ordinary, partial or integro-differential equations. These types of equations are referred to as master equations in the literature. The solution processes of such systems of differential equations are used to find the higher moments and other statistical properties of dynamic processes described by random flows.

On the other hand, the classical Newtonian mechanics type of stochastic modeling approach deals with a stochastic calculus to formulate stochastic mathematical models of dynamic processes. This approach leads directly to a system of stochastic differential equations, and its solution processes provide the description of the states of the dynamic processes as stochastic or random processes. This method of stochastic modeling generates three basic problems:

- (i) Concepts of solution processes depending on modes of convergence and the fundamental properties of solutions: existence, uniqueness, measurability, continuous dependence on system parameters.

- (ii) Probabilistic and statistical properties of solution process: probability distribution and density function, variance, and moments of solution processes and the qualitative/quantitative behavior of solutions.
- (iii) Deterministic versus stochastic modeling of dynamic processes: If the deterministic mathematical model is available, then why do we need a stochastic mathematical model? If a stochastic mathematical model provides a better description of a dynamic process than the deterministic model, then the second question is to what extent the stochastic mathematical model differs from the corresponding deterministic model in the absence of random disturbances or fluctuations and uncertainties.

Most of the work on the theory of systems of stochastic differential equations is centered around problems (i) and (ii). This is because the theory of deterministic systems of differential equations provides many mathematical tools and ideas. It is problem (iii) that deserves more attention. Since 1970, some serious efforts have been made to address this issue in the context of stochastic modeling of dynamic processes by means of systems of stochastic differential equations. In the light of this interest, now is an appropriate time to present an account of stochastic versus deterministic issues in a systematic and unified way.

Two of the most powerful methods for studying systems of nonlinear differential equations are nonlinear variation of parameters and Lyapunov's second method. About a quarter century ago a hybrid of these two methods evolved. This hybrid method is called variational comparison method. In addition, a generalized variation of constants method has also developed in the same period of time. These new

techniques are very suitable and effective tools to investigate problems concerning stochastic systems of differential equations, in particular, stochastic versus deterministic issues.

This book offers a systematic and unified treatment for systems of stochastic differential equations in the framework of three methods: a) variational comparison method, b) generalized variation of constants method, and c) probability distribution method. The book is divided into five chapters. The first chapter deals with random algebraic polynomials. Chapter 2 is devoted to the initial value problem (IVP) for ordinary differential systems with random parameters. Stochastic boundary value problems (SBVP) with random parameters are treated in Chapter 3. Chapters 4 and 5 cover IVP and SBVP for systems of stochastic differential equations of Itô type, respectively.

A few important features of the monograph are as follows:

- (i) This is the first book that offers a systematic study of the well-known problem of stochastic mathematical modeling in the context of systems of stochastic differential equations, namely, “stochastic versus deterministic;”
- (ii) It complements the existing books in stochastic differential equations;
- (iii) It provides a unified treatment of stability, relative stability and error estimate analysis;
- (iv) It exhibits the role of randomness as well as rate functions in explicit form;
- (v) It provides several illustrative analytic examples to demonstrate the scope of methods in stochastic analysis;
- (vi) The methods developed in the book are applied to the existing stochastic mathematical models described by stochastic dif-

ferential equations in population dynamics, hydrodynamics, and physics;

- (vii) Last but not least, it provides several numerical examples and figures to illustrate and compare the analytic techniques that are outlined in the book.

The monograph can be used as a textbook for graduate students. It can also be used as a reference book for both experimental and applied scientists working in the mathematical modeling of dynamic processes.

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NOTATION AND ABBREVIATIONS

For the convenience of readers we list below the various notations and abbreviations employed in the monograph.

Vectors (column vectors) of dimension n are basically treated as $n \times 1$ matrices. All relations such as equations, inequalities, belonging to, and limits involving random variables or functions are valid with probability one. Sometimes the symbols $x(t)$ and $x(t, \omega)$ are used interchangeably as a random function.

R^n	As n -dimensional Euclidean space with a convenient norm $\ \bullet\ $
$\ \bullet\ $	The norm of a vector or matrix
R	The set of all deterministic real numbers or a real line
R_+	The set of all $t \in R$ such that $t \geq 0$
I	An arbitrary index set, in particular, a finite, countable set, or any interval in R
$I(1, n)$	$\{1, 2, \dots, n\}$, that is, the set of first n positive integers
J	$[t_0, t_0 + a]$, where $t_0 \in R$ and a is a positive real number
$B(z, \rho)$	The set of all $x \in R^n$ such that $\ x - z\ < \rho$ for given $z \in R^n$ and positive real number ρ
$\overline{B}(z, \rho)$	The closure of $B(z, \rho)$
$B(\rho)$	The set $B(z, \rho)$ with $z = 0 \in R^n$
\mathcal{F}^n	The σ -algebra of Borel sets in R^n
\mathcal{B}	The σ -algebra of Borel sets in a metric space (X, d) , where d is a metric induced by the norm $\ \bullet\ $ and X is a separable Banach space

$(\Omega, \mathcal{F}, P) \equiv \Omega$	A complete probability space, where Ω is a sample space, \mathcal{F} is a σ -algebra of Ω , and P is a probability measure defined on \mathcal{F}
\mathcal{F}_t	A sub- σ -algebra of \mathcal{F} for $t \in R_+$
\mathcal{L}_t	The smallest sub- σ -algebra of \mathcal{F} generated by a k -dimensional normalized Wiener process $z(t)$ for $t \in R_+$
$R[\Omega, R^n]$	The collection of all random vectors defined on complete probability space (Ω, \mathcal{F}, P) into R^n
$R[\Omega, R^{nm}] \equiv [\Omega, \mathcal{M}_{n \times m}]$	A collection of all $n \times m$ random matrices $A(\omega) = (a_{ij}(\omega))$ such that $a_{ij} \in R[\Omega, R]$
$\ x\ _p$	$\ x\ _p = \left(E[\ x(\omega)\ ^p] \right)^{1/p} = \left(\int_{\Omega} \ x(\omega)\ ^p P(d\omega) \right)^{1/p}$ for $p \geq 1$
\mathcal{L}^p	The collection of all n -dimensional random vectors x such that $E[\ x(\omega)\ ^p] < \infty$ for $p \geq 1$
$L^p[\Omega, R^n]$	A collection of all equivalence classes of n -dimensional random vectors such that an element of an equivalence class belongs to \mathcal{L}^p
$R[[a, b], R[\Omega, R^n]] \equiv R[[a, b] \times \Omega, R^n]$	A collection of all R^n -valued separable random functions defined on $[a, b]$ with a state space (R^n, \mathcal{F}^n) , $a, b \in R$
$M[[a, b], R[\Omega, R^n]] \equiv M[[a, b] \times \Omega, R^n]$	A collection of all random functions in $R[[a, b], R[\Omega, R^n]]$ which are product-measurable on $([a, b] \times \Omega, \mathcal{F}^1 \times \mathcal{F}, m \times P)$, where $(\Omega, \mathcal{F}, P) \equiv \Omega$ and $([a, b], \mathcal{F}^1, m)$ are complete probability and Lebesgue-measurable spaces, respectively
$M[R_+ \times R^n, R[\Omega, R^n]] \equiv M[R_+ \times R^n \times \Omega, R^n]$	A class of R^n -valued

- random functions $F(t, x, \omega)$ such that $F(t, x(t, \omega), \omega)$ is product measurable whenever $x(t, \omega)$ product is measurable
- $M[[0, 1] \times R^n \times R^n, R[\Omega, R^n]] \equiv M[[0, 1] \times R^n \times R^n \times \Omega, R^n]$ A class of R^n -valued random functions $F(t, x, y, \omega)$ such that $F(t, x(t, \omega), y(t, \omega), \omega)$ is product measurable whenever $x(t, \omega)$ and $y(t, \omega)$ are product measurables
- $C[D, R^n]$ The class of all deterministic continuous functions defined on an open (t, x) subset D of R^{n+1} into R^n
- $C[R_+ \times R^n, R^m]$ The class of all deterministic continuous functions defined on $R_+ \times R^n$ into R^m
- $C[[0, 1] \times R^n \times R^n, R^m]$ The collection of all deterministic continuous functions $[0, 1] \times R^n \times R^n$ into R^m
- $C[[a, b], R[\Omega, R^n]] \equiv C[R_+ \times R^n, R[\Omega, R^n]]$ A collection of all sample continuous R^n -valued random functions $x(t, \omega)$
- $C[R_+ \times R^n, R[\Omega, R^n]] \equiv C[R_+ \times R^n \times \Omega, R^n]$ A class of sample continuous R^n -valued random functions $F(t, x, \omega)$ defined on $R_+ \times R^n \times \Omega$ into R^n
- $C[[0, 1] \times R^n \times R^n, R[\Omega, R^n]] \equiv C[[0, 1] \times R^n \times R^n \times \Omega, R^n]$ A class of sample continuous R^n -valued random functions $F(t, x, y, \omega)$ defined on $[0, 1] \times R^n \times R^n \times \Omega$ into R^n
- A^T The transpose of a vector or matrix A
- A^{-1} The inverse of a square matrix A
- $tr(A)$ The trace of a square matrix A
- $\det(A)$ The determinant of a square matrix A