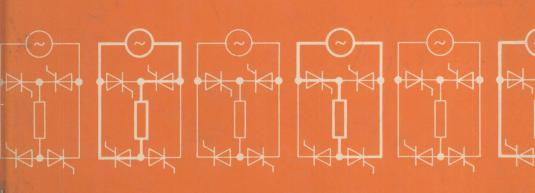
A Basic Guide to Power Electronics



Albert Kloss

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A BASIC GUIDE TO POWER ELECTRONICS

Albert Kloss

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A BASIC GUIDE TO POWER ELECTRONICS

List of Symbols

CURRENTS

Instantaneous values

Alternating current, transformer current, valve current Alternating current, supply (source) current i ~ Phase currents IR.S.T Short-circuit current, commutating current $i_{\mathbf{k}}$ Thyristor current i_{Th} Valve currents $i_{1,2,...}$ Fundamental current i_1 Triggering (gate) pulse i_g D.C. voltage-source current $i_{\rm E}$ Direct current

ia Current in resistor iR Current in capacitor $i_{\rm C}$ Maximum value $i_{\rm m}$

 I_{m} Amplitude

Foward current, maximum value $I_{\rm F}$ Reverse current peak

Relative values

 i_{rr}

Direct current $i_{\rm d}$

Mean values

Direct current I_d

Direct current with $\alpha = 0^{\circ}$ I_{do} I_{dN} Rated (nominal) direct current Short-circuit direct current I_{dk}

Valve current I_{VAV} IThAV Thyristor current

R.M.S. values

I Alternating current, transformer current IN Rated (nominal) transformer current

Short-circuit current $I_{\mathbf{k}}$

 I_{Vrms} Valve current I_{Thrms} Thyristor current

I₁ Fundamental component

 I_n Harmonic current I_s Supply current

VOLTAGES

Instantaneous values

v Alternating voltage, line voltage, valve voltage

 $\begin{array}{lll}
\nu_{R,S,T} & \text{Phase voltages} \\
\nu_{ph} & \text{Phase voltage} \\
\nu_{n} & \text{Harmonic voltage} \\
\nu_{s} & \text{Supply voltage} \\
\nu_{sec} & \text{Secondary voltage} \\
\nu_{V} & \text{Valve voltage} \\
\nu_{1,2,...} & \text{Valve voltage}
\end{array}$

ν_{Th} Thyristor voltage

VL, Lk Voltage across inductance

ν_C Capacitor voltage
 ν_d Direct voltage
 ν_D Diode voltage

 $v_{\rm rr}$ Reverse recovery voltage peak $V_{\rm vm}$ Valve voltage, maximum value

Relative values

v_d Direct voltage

dx Inductive d.c. voltage drop dr Ohmic d.c. voltage drop e_k Total short-circuit voltage

ekt Transformer short-circuit voltage

Mean values

V_d Direct voltage

 $V_{\rm dio}$ Ideal no-load direct voltage, $\alpha = 0^{\circ}$

 V_{do} Direct voltage with $\alpha = 0^{\circ}$

D.C. voltage source

A Voltage-time integral (area)

R.M.S. values

V Line voltage

V_i Fundamental component

 V_{Vrms} Valve voltage V_{ph} Phase voltage

$V_{ m sec}$	Secondary voltage
$V_{\rm p}$	Primary voltage
V_0	Source voltage, no-load voltage

POWERS

Active power (mean)
Total apparent power
Fundamental frequency apparent power
Transformer rated power (VA)
Total non-active power (reactive power)
Fundamental frequency reactive power
Harmonic non-active power, distortion power
Transformer short-circuit volt-amperes
Supply short-circuit capacity
Relative active power, instantaneous power
Relative fundamental frequency reactive power
Relative capacitive reactive power
Relative fundamental frequency apparent power
Energy

	PARAMETERS, ABBREVIATIONS
L	Inductance in d.c. circuit
$L_{\mathbf{k}}$	Commutating inductance
C	Capacitance
R	Resistance
$R_{\rm i}$	Equivalent resistance
$\chi_{\mathbf{k}}$	Commutating reactance
V	Valve
D	Diode
$L_{ m F}$	Filter inductance
L_{μ}	Transformer no-load (magnetising) inductance
K	Cathode
A	Anode
p,n	Semiconductor conductivity types
REC	Rectifier
INV	Inverter
G	Generator
M	Motor
ASM	Asynchronous (induction) motor
SM	Synchronous machine
HVDC	High-voltage d.c. (transmission)
Hg	Mercury
Si	Silicon

Harmonic order, rotational speed

Se

n

Selenium

ANGLES, ANGULAR INTERVALS, FACTORS

α	Delay angle
α'	Natural delay angle
ϕ	Phase angle
ϕ_1	Phase angle of fundamental component
ωt	Angular interval at supply frequency
ω	Angular frequency of alternating (supply) voltage
ω_0	Natural angular frequency of oscillatory circuit
λ	Conduction angle, power factor
μ	Overlap (commutation) angle
f	Frequency
T	Period
au	Time constant

HEAT

$R_{\rm th}$	Thermal resistance (steady state)
$r_{ m th}$	Transient thermal resistance
P	Loss in valve
ν_0	Threshold voltage
r	Equivalent (incremental) resistance
θ	Temperature
$k_{\rm f}$	Current form factor

Preface

This book is directed both to students and to practising engineers and technicians.

The pillars of the book are the diagrams. They carry the most important information and it is possible as a first step to use the work as a picture book.

The main emphasis is placed upon a physical understanding of the problems considered. Practically oriented mathematical relationships are associated with, but separated from, individual sections of text. The reader can study the book in its essentials without having to become involved with mathematics.

The book is intended to serve as a textbook, with systematically structured material, and also as a practical work of reference.

The discussion concerns the most important aspect of power electronics—converter circuits for three-phase systems—and is centred on the three-phase bridge circuits with natural commutation which are the most widely used. Systematic treatment of the fundamentals is supported by the latest findings from industry and research. Many of the diagrams are based upon computer calculations.

The author has drawn upon long experience as an engineer with Brown Boveri and Co. at Baden, Switzerland, since 1969, and as delegate laecture at the Winterthur Technical and Engineering College (1971–1983).

The author would like to thank Mrs. M. Lochner for the painstakingly drawn diagrams and Mr. G. Lochner (Dipl. Ing.) for his critical checking of the manuscript.

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The Structure of Power Electronics

FUNDAMENTALS

The principles of power electronics cover electrical circuits and apparatus which achieve the control or conversion of electrical energy by means of electronic valves.*

Power electronic equipments are generally referred to as 'converters', and the valves are accordingly termed 'converter valves'.

Valve action takes place in solid-state semiconductors. Because power electronic apparatus contains no moving parts, it is often referred to as 'static' equipment. The term 'power electronics' stems from the development of high-power semiconductor valves during the nineteen-sixties. The expressions converter or rectifier technology were previously used.

CONVERTERS

Converters constitute the hardware of power electronics. According to their basic functions, converters can be divided into the following groups:

Rectifiers (a.c.-d.c. converters) Inverters (d.c.-a.c. converters) A.C.-a.c. converters

D.C.-d.c. converters

Rectifiers convert alternating current (a.c.) into direct current (d.c.). Conversely, inverters convert direct to alternating current.

With converters that convert from a.c. to a.c. or from d.c. to d.c. it is possible to change voltage, frequency, phase number, or polarity.

Circuits that can function as rectifiers or inverters, according to the way in which they are controlled, are often referred to simply as 'converters'.

With the exception of rectifiers, which can operate in an uncontrolled mode, all converters embody controllable valves.

A.C.-a.c. and D.C.-d.c. CONVERTERS

This group includes the following subgroups:

Direct a.c. converters (direct frequency changers, cycloconverters)

^{*} As often in continental usage, and in accordance with the *IEC International Electrotechnical Vocabulary*, Chapter 551, the term 'valve' is applied generally in this book to the class of rectifying and switching devices which includes solid-state diodes and thyristors as well as vacuum, gas, or vapour-filled tubes.

Indirect a.c. converters (d.c.-link frequency changers)

D.C. regulators (d.c. choppers)

A.C. regulators

The direct frequency changer converts alternating current of one voltage, frequency, and phase number into a different voltage, frequency, and phase number directly, without a means of energy storage. The output frequency is usually lower than the input frequency.

The d.c.-link frequency changer serves basically the same purpose as the direct frequency changer, but includes in addition a means of energy storage in a direct current or direct voltage intermediate circuit. The output frequency is consequently independent of the input frequency.

In both d.c.—link and direct frequency changers energy can be translated in either direction. The d.c.—link frequency changer feeding a synchronous machine constitutes the so-called converter motor; connected in the rotor circuit of an asynchronous machine it forms a subsynchronous converter

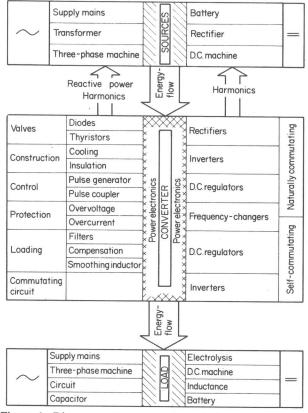


Figure 1. Diagrammatic presentation of the role of converters in energy conversion and control. The converters lie in the path of energy flowing between the source and the load. On the left are listed the components and the problem areas, on the right the classification of converter systems

cascade (the static Kraemer system), and in electricity supply systems it is used for high-voltage d.c. transmission.

The d.c. regulator facilitates the variation of d.c. voltage, without any intermediate circuit, but normally by dint of a forced commutation circuit (or valves with a turn-off facility).

The a.c. regulator affords a variation of a.c. voltage, at an unchanged frequency, again without an intermediate circuit.

The two regulators are not always counted as 'converters' but may be regarded as a distinct group. Figures 1 and 2 illustrate the classification of converters in terms of power flow, components, and grouping.

INTERNAL OPERATION OF CONVERTERS

Converter circuits are assemblies of converter valves, which function as controlled switching devices. The required conversion and control of voltage

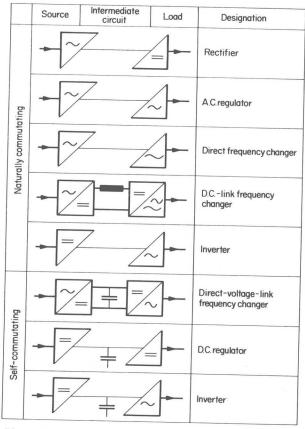


Figure 2. Systematic classification and simplified symbols of converter types. Converter circuits fall into two main groups: converters with natural (external) commutation and converters with forced commutation (self-commutating)