# SIMULATION MODELING AND ANALYSIS

# SIMULATION MODELING AND ANALYSIS

#### Averill M. Law

Professor of Industrial Engineering University of Wisconsin, Madison

#### W. David Kelton

Professor of Administrative Sciences Kent State University

## McGraw-Hill Book Company

New York St. Louis San Francisco Auckland Bogotá Hamburg Johannesburg London Madrid Mexico Montreal New Delhi Panama Paris São Paulo Singapore Sydney Tokyo Toronto

This book was set in Times Roman by University Graphics, Inc. The editors were Julienne V. Brown and Madelaine Eichberg; the production supervisor was Joe Campanella. The drawings were done by Fine Line Illustrations, Inc. The cover was designed by Carla Bauer.

R. R. Donnelley & Sons Company was printer and binder.

#### SIMULATION MODELING AND ANALYSIS

Copyright © 1982 by McGraw-Hill, Inc. All rights reserved.

Printed in the United States of America. No part of this publication may be reproduced, stored in a retrieval system, or transmitted, in any form or by any means, electronic, mechanical, photocopying, recording, or otherwise, without the prior written permission of the publisher.

1234567890 DODO 8987654321

## Library of Congress Cataloging in Publication Data

Law, Averill M.

Simulation modeling and analysis.

(McGraw-Hill series in industrial engineering and management science)

Includes bibliographical references and index.

Digital computer simulation. I. Kelton,
 W. David. II. Title. III. Series.

QA76.9.C65L38 001.4'34 81-5777

ISBN 0-07-036696-9 AACR2

# SIMULATION MODELING AND ANALYSIS

# McGraw-Hill Series in Industrial Engineering and Management Science

#### **Consulting Editor**

James L. Riggs, Department of Industrial Engineering, Oregon State University

Barish and Kaplan: Economic Analysis: For Engineering and Managerial Decision Making

Blank: Statistical Procedures for Engineering, Management, and Science

Cleland and Kocaoglu: Engineering Management

Denton: Safety Management: Improving Performance

**Dervitsiotis:** Operations Management

Gillett: Introduction to Operations Research: A Computer-Oriented Algorithmic Approach

Hicks: Introduction to Industrial Engineering and Management Science

**Huchingson:** New Horizons for Human Factors in Design Law and Kelton: Simulation Modeling and Analysis

Love: Inventory Control
Riggs: Engineering Economics

Riggs: Essentials of Engineering Economics

Wu and Coppins: Linear Programming and Extensions

To my wife, Steffi, and children, Heather and Adam, for their encouragement and understanding during the writing of this book.

AVERILL M. LAW

For Christie, who understood and helped more than I could tell her.

W. DAVID KELTON

## **PREFACE**

The goal of Simulation Modeling and Analysis is to give an up-to-date treatment of all the important aspects of a simulation study, including modeling, simulation languages, validation, and output data analysis. In addition, we have tried to present the material in a manner understandable to a person having only a basic familiarity with probability, statistics, and computer programming. The book does not sacrifice statistical correctness for expository convenience, but contains virtually no theorems or proofs. Technically difficult topics are placed in starred (\*) sections or in an appendix to an appropriate chapter, and left for the advanced reader. (More difficult problems are also starred.) The book strives to motivate intuition about difficult topics and contains a large number of examples, figures, problems, and references for further study. There is also a solutions manual for instructors.

We feel that two of the book's major strengths are its treatment of modeling and of output data analysis. Chapters 1 and 2 show in complete detail how to build simulation models in FORTRAN of a simple queueing system, an inventory system, a time-shared computer model, a multiteller bank with jockeying, and a job-shop model. Chapter 8 contains what we believe is a complete and practical treatment of statistical analysis of simulation output data. Since lack of definitive output data analyses appears to have been a major shortcoming of most simulation studies, we feel that this chapter should enhance the practice of simulation.

We believe that Simulation Modeling and Analysis could serve as a textbook for the following types of courses:

- 1. A beginning course in simulation at the junior, senior, or first-year graduate level for engineering, business, or computer science students (Chaps. 1 through 4 and parts of Chaps. 5 through 8, 10, and 11).
- 2. A second, advanced course in simulation (most of Chaps. 7 through 12).
- 3. An introduction to simulation as part of a general course on operations research or management science (Chaps. 1 through 3).

The book should also be of interest to simulation practitioners. As a matter of fact, a large number of such practitioners from industry, government, and the military have used preliminary drafts of the manuscript while attending a seminar on simulation which has been given by the first author for the last four years.

There are a number of people and organizations that have contributed considerably to the writing of this book. Foremost among them are Dr. Thomas Varley and the Office of Naval Research, without whose research support during the past five years this book simply would not have been possible. We would also like to thank the Army Research Office for its research funding to the Mathematics Research Center at the University of Wisconsin. This support in 1980 allowed for the expeditious completion of the book. Most of the development of the simulation language SIM-LIB which is discussed in Chap. 2, and almost all of the research of the statistical methods in Chap. 5 was done by Stephen Vincent, a graduate student at Wisconsin. The organization and content of Chap. 7 benefitted greatly from our having in-depth discussions with Professor Bruce Schmeiser of Purdue University. In addition, conversations with the following people positively influenced our thinking on particular chapters of the book: William Biles (Penn State), Edward Dudewicz (Ohio State), James Henriksen (Wolverine Software), Stephen Lavenberg (IBM), Richard Nance (Virginia Tech), Alan Pritsker (Purdue), Edward Russell (CACI), Robert Sargent (Syracuse), Thomas Schriber (Michigan), Edward Silver (Waterloo), and Glenn Thomas (Kent State). Finally, we acknowledge the following graduate students at Wisconsin who read the entire manuscript and made many valuable suggestions: Steven Kimbrough, Lloyd Koenig, Insup Lee, and Muslim Yildiz.

> Averill M. Law W. David Kelton

# CONTENTS

	Preface	xiii
Chapter 1	Basic Simulation Modeling	1
1.1	The Nature of Simulation	1
1.2	Systems, Models, and Simulation	2
1.3	Discrete-Event Simulation	4
	1.3.1 Time-Advance Mechanisms	4
	1.3.2 Components and Organization of a Discrete-Event	t
	Simulation Model	6
	1.3.3 Advantages and Disadvantages of Simulation	8
1.4	Simulation of a Single-Server Queueing System	9
	1.4.1 Statement of the Problem	9
	1.4.2 Intuitive Explanation	1.1
	1.4.3 FORTRAN Program	15
	1.4.4 Simulation Output and Discussion	25
	1.4.5 Alternative Stopping Rules	27
1.5	Simulation of an Inventory System	28
	1.5.1 Statement of the Problem	28
	1.5.2 FORTRAN Program	32
	1.5.3 Simulation Output and Discussion	42
1.6	Steps in a Discrete-Event Simulation Study	43
1.7	Other Types of Simulation	46
	1.7.1 Continuous Simulation	46
	1.7.2 Combined Discrete-Continuous Simulation	47
	1.7.3 Monte Carlo Simulation	49
	Appendix 1A: Fixed-Increment Time Advance	50
	Appendix 1B: A Primer on Queueing Systems	51
	1B.1 Components of a Queueing System	52
	1B.2 Notation for Queueing Systems	53
	1B.3 Measures of Performance for Queueing Systems	54
	Problems	5.5
	References	57

Chapter 2	Modeling Complex Systems	59
2.1	Introduction	59
	2.1.1 Approaches to Storing Lists in a Computer	60
2.2	Linked Storage Allocation	60
2.3	A Simple Simulation Language, SIMLIB	65
2.4	A Time-Shared Computer Model	70
	2.4.1 Statement of the Problem	70
	2.4.2 SIMLIB Program	71
	2.4.3 Simulation Output and Discussion	79
2.5	A Multiteller Bank with Jockeying	79
	2.5.1 Statement of the Problem	79
	2.5.2 SIMLIB Program	80
	2.5.3 Simulation Output and Discussion	85
2.6	A Job-Shop Model	85
	2.6.1 Statement of the Problem	85
	2.6.2 SIMLIB Program	90
2.7	2.6.3 Simulation Output and Discussion	99
2.7	Efficient Event-List Manipulation	100
	Appendix 2A: FORTRAN Listings for SIMLIB Problems	101
	References	102
	References	113
Chapter 3	Simulation Languages	114
3.1	Introduction	114
3.2	Comparison of Simulation Languages with	
	General-Purpose Languages	115
3.3	Approaches to Discrete-Event Simulation Modeling	116
3.4	GASP IV and Related Languages	118
	3.4.1 Simulation of the $M/M/1$ Queue	119
	3.4.2 SLAM	123
3.5	SIMSCRIPT II.5	124
	3.5.1 Simulation of the $M/M/1$ Queue	125
	3.5.2 The Process-Interaction Approach in	
	SIMSCRIPT II.5	128
3.6	GPSS	129
2.7	3.6.1 Simulation of the $M/M/1$ Queue	130
3.7	Criteria for Selecting a Simulation Language	133
	Problems	135
	References	136
Chapter 4	Review of Basic Probability and Statistics	137
4.1	Introduction	137
4.2	Random Variables and Their Properties	137
4.3	Simulation Output Data and Stochastic Processes	142
4.4	Estimation of Means, Variances, and Correlations	145
4.5	Confidence Intervals and Hypothesis Tests for the Mean	148
4.6	The Strong Law of Large Numbers	151

	Appendix 4A: Comments on Covariance Stationary Processes	152
	Problems	153
	References	154
Chapter 5	Selecting Input Probability Distributions	155
5.1	Introduction	155
5.2	Useful Probability Distributions	157
	5.2.1 Parameterization of Distributions	157
	5.2.2 Continuous Distributions	158
	5.2.3 Discrete Distributions	170
	5.2.4 Empirical Distributions	176
5.3	Hypothesizing a Family of Distributions	177
	5.3.1 Continuous Distributions	178
	5.3.2 Discrete Distributions	187
5.4	Estimation of Parameters	188
5.5	Goodness-of-Fit Tests	192
	<ul><li>5.5.1 Informal Visual Assessment</li><li>5.5.2 Chi-Square Tests</li></ul>	193
		194 199
	5.5.3 Kolmogorov-Smirnov Tests 5.5.4 Poisson Process Test	203
	5.5.5 Other Tests	203
5.6	Selecting a Distribution in the Absence of Data	204
5.7	Models of Arrival Processes	206
	5.7.1 Poisson Process	206
	5.7.2 Nonstationary Poisson Process	207
	5.7.3 Batch Arrivals	209
	Appendix 5A: Shifted and Truncated Distributions	210
	Appendix 5B: Tables of MLEs for the Gamma and	
	Beta Distributions	212
	Problems	214
	References	216
Chapter 6	Random-Number Generators	219
6.1	Introduction	219
6.2	Linear Congruential Generators	222
0.2	6.2.1 Mixed Generators	224
	6.2.2 Multiplicative Generators	225
6.3	Other Kinds of Generators	228
	6.3.1 More General Congruences	228
	6.3.2 Composite Generators	229
	6.3.3 Tausworthe Generators	230
6.4	Testing Random-Number Generators	231
	6.4.1 Empirical Tests	231
	6.4.2 Theoretical Tests	235
	6.4.3 Some General Observations on Testing	236
	Problems	236
	References	238

Chapter 7	Generating Random Variables	240
7.1	Introduction	240
7.2	General Approaches to Generating Random Variables	242
	7.2.1 Inverse Transform	242
	7.2.2 Composition	247
	7.2.3 Convolution	249
	7.2.4 Acceptance-Rejection	250
	7.2.5 Special Properties	252
7.3	Generating Continuous Random Variables	253
	7.3.1 Uniform	253
	7.3.2 Exponential	254
	7.3.3 <i>m</i> -Erlang	254
	7.3.4 Gamma	255
	7.3.5 Weibull	260
	7.3.6 Normal	260
	7.3.7 Lognormal	259
	7.3.8 Beta	260
	7.3.9 Triangular	261
= :	7.3.10 Empirical Distributions	261
7.4	Generating Discrete Random Variables	262
	7.4.1 Bernoulli	263
	7.4.2 Discrete Uniform	263
	7.4.3 Arbitrary Discrete Distribution	263
	7.4.4 Binomial	266
	7.4.5 Geometric	266
	7.4.6 Negative Binomial	266
7.5	7.4.7 Poisson	267
7.5	Generating Correlated Random Variables	267
	7.5.1 Using Conditional Distributions 7.5.2 Multivariate Normal and Multivariate Lognormal	268
	7.5.2 Multivariate Normal and Multivariate Lognormal 7.5.3 Correlated Gamma Random Variables	269 269
7.6	Generating Arrival Processes	270
7.0	7.6.1 Poisson Process	270
	7.6.2 Nonstationary Poisson Process	270
	7.6.3 Batch Arrivals	271
	Appendix 7A: Validity of the Acceptance-Rejection Method	273
	Problems	274
	References	277
Chapter 8	Output Data Analysis for a Single System	279
8.1	Introduction	279
8.2	Types of Simulations with Regard to Analysis of the Output	280
8.3	Measures of System Performance	283
	8.3.1 Contrast of Measures of Performance	283
	8.3.2 The Meaning of Steady State	284
2: 4	8.3.3 Measures of Performance Other than Averages	285
8.4	The Need for Confidence Intervals	287

8.5	Confidence Intervals for Terminating Simulations	287
	8.5.1 Fixed-Sample-Size Procedure	288
	8.5.2 Obtaining Confidence Intervals with a Specified	
	Precision	291
	8.5.3 Recommended Use of the Procedures	293
	8.5.4 Approaches to Choosing Appropriate Initial Conditions	294
8.6	Confidence Intervals for Steady-State Simulations	295
	8.6.1 Fixed-Sample-Size Procedures	295
	8.6.2 Sequential Procedures	302
	8.6.3 A Replication-Deletion Approach	307
8.7	Multiple Measures of Performance	308
8.8	Concluding Thoughts on the Chapter	310
	Appendix 8A: The Memoryless Property	311
	Appendix 8B: Ratios of Expectations and Jackknife Estimators	311
	Problems	313
	References	314
Chapter 9	Statistical Techniques for Comparing	
Chapter	Alternative Systems	316
9.1	Introduction	316
9.2	Confidence Intervals for the Difference between Measures of	210
	Performance of Two Systems	319
9.3	Selecting the Best of k Systems	322
9.4	Selecting a Subset of Size m Containing the Best of k Systems	325
9.5	Selecting the m Best of k Systems	326
9.6	Validity of the Selection Procedures	327 329
	Appendix 9A: Constants for the Selection Procedures	
	Problems References	331 331
	References	331
Chapter 10	Validation of Simulation Models	333
10.1	Introduction	333
10.1	Verification of Simulation Models	334
10.3	General Perspectives on Validation	337
10.4	A Three-Step Approach to Validation	338
10.4	10.4.1 Develop a Model with High Face Validity	338
	10.4.2 Test the Assumptions of the Model Empirically	339
	10.4.3 Determine How Representative the Simulation Output	337
	Data Are	340
10.5		342
10.6	Statistical Procedures for Comparing Real-World Observations	3 12
1010	and Simulation Output Data	343
	10.6.1 An Inspection Approach	343
	10.6.2 A Confidence-Interval Approach	345
	10.6.3 Time-Series Approaches	347
	Problems	347
	References	348

#### xii CONTENTS

Chapter 11	Variance-Reduction Techniques	349
11.1	Introduction	349
11.2	Common Random Numbers	350
11.3	Antithetic Variates	354
11.4	Control Variates	357
11.5	Indirect Estimation	361
11.6	Conditional Expectations	363
	Problems	366
	References	368
Chapter 12	Experimental Design and Optimization	370
12.1	Introduction	370
12.2	2 <sup>k</sup> Factorial Designs	372
12.3	2 <sup>k-p</sup> Fractional Factorial Designs	376
12.4	Response-Surface Methodology	379
	Problems	381
	References	382
	A : P	
	Appendix	385
	Index	389

CHAPTER

# ONE

## **BASIC SIMULATION MODELING**

#### 1.1 THE NATURE OF SIMULATION

This is a book about techniques for using computers to imitate, or *simulate*, the operations of various kinds of real-world facilities or processes. The facility or process of interest is usually called a *system*, and in order to study it scientifically we often have to make a set of assumptions about how it works. These assumptions, which usually take the form of mathematical or logical relationships, constitute a *model* which is used to try and gain some understanding of how the corresponding system behaves.

If the relationships which compose the model are simple enough, it may be possible to use mathematical methods (such as algebra, calculus, or probability theory) to obtain *exact* information on questions of interest; this is called an *analytic* solution. However, most real-world systems are too complex to allow realistic models to be evaluated analytically, and these models must be studied by means of simulation. In a *simulation* we use a computer to evaluate a model *numerically* over a time period of interest, and data are gathered to *estimate* the desired true characteristics of the model.

As an example of the use of simulation, consider a manufacturing firm that is contemplating building a large extension onto one of its plants but is not sure whether the potential gain in productivity would justify the construction cost. It certainly would not be cost-effective to build the extension and then remove it later if it does not work out. However, a careful simulation study could shed some light on the question by simulating the operation of the plant as it currently exists and as it would be if the plant were expanded.

Simulation is one of the most widely used techniques in operations research and management science, and by all indications its popularity is on the increase. There have been several impediments to its even wider acceptance and usefulness, however. First, models used to study large-scale systems tend to be very complex, and writing computer programs to execute them can be an arduous task indeed. This task has been eased in recent years by the development of several special-purpose computer languages that automatically provide many of the features needed to code a simulation model. A second problem with simulation of complex systems is that a large amount of computer time is often required. We anticipate, however, that this difficulty will become less severe as the cost of computing continues to fall. Finally, there appears to be an unfortunate impression that simulation is just an exercise in computer programming, albeit a complicated one. Consequently, many simulation "studies" have been composed of heuristic model building, coding, and a single run of the program to obtain "the answer." We fear that this attitude, which neglects the important issue of how a properly coded model should be used to draw inferences about the system of interest, has led to erroneous conclusions being drawn from many simulation studies. These questions of simulation methodology, which are largely independent of the programming language and computer hardware used, form an integral part of the latter chapters of this book.

In the remainder of this chapter (as well as in Chap. 2) we discuss systems and models in considerably more detail and then show how to write computer programs to simulate systems of varying degrees of complexity.

#### 1.2 SYSTEMS, MODELS, AND SIMULATION

A system is defined to be a collection of entities, e.g., people or machines, which act and interact together toward the accomplishment of some logical end. (This definition was proposed by Schmidt and Taylor [14].†) In practice, what is meant by the system depends on the objectives of a particular study. The collection of entities which compose a system for one study might only be a subset of the overall system for another. For example, if one wants to study a bank to determine the number of tellers needed to provide adequate service for customers who only want to cash a check or make a savings deposit, the system can be defined to be that portion of the bank consisting of the tellers and the customers waiting in line or being served. If, on the other hand, the loan officer and the safety deposit boxes are to be included, the definition of the system must be expanded in an obvious way. We define the state of a system to be that collection of variables necessary to describe a system at a particular time, relative to the objectives of a study. In a study of a bank, examples of possible state variables are the number of busy tellers, the number of customers in the bank, and the time of arrival of each customer in the bank. We categorize systems to be of two types, discrete and continuous. A discrete system is one for which the state variables change only at a countable (or finite) number of points in time. A bank is an example of a discrete system since state variables, e.g., the number

<sup>†</sup>Numbers in brackets correspond to references at the end of the chapter.

of customers in the bank, change only when a customer arrives or when a customer finishes being served and departs. A continuous system is one for which the state variables change continuously with respect to time. An airplane moving through the air is an example of a continuous system since such state variables as position or velocity change continuously with respect to time. Few systems in practice are wholly discrete or continuous, but since one type of change predominates for most systems, it will usually be possible to classify a system as being either discrete or continuous.

Sometimes it is desired to study a system to understand the relationships between its various components or to predict its performance under a new operating policy. However, actual experimentation with the system may be infeasible, costineffective, or disruptive of the present system's operation. This is particularly true when, as is often the case in practice, the system of interest does not yet exist. For example, suppose that it is desired to study (as a possible cost-saving measure) the effect of reducing the number of tellers in a bank. If the number of tellers in the bank were actually reduced temporarily, it might cause a significant increase in customers' delays and alienate them from doing future business with the bank. Because of the infeasibility of experimenting with many systems, a systems analyst often uses a model of a system to draw inferences about the operations of the actual system. We define a *model* to be a representation of a system developed for the purpose of studying that system. The model should be sufficiently detailed or "valid" to permit an analyst or decision maker to use it to make the same decisions about the system that would be made if it were feasible to experiment with the system itself.

In this book we restrict our attention to a particular type of mathematical model of a system which we call a simulation model. (Some models of systems are physical rather than mathematical, e.g., a scale model of an airplane tested in a wind tunnel.) Although we shall not explicitly define a simulation model in general, we distinguish between simulation models which are static or dynamic, deterministic or stochastic, and discrete or continuous. A static simulation model is a representation of a system at a particular time. Monte Carlo simulation models (Sec. 1.7.3) are typically of this type. A dynamic simulation model is a representation of a system as it evolves over time, e.g., a simulation model of a bank's activities over an 8-hour day. A simulation model is said to be *deterministic* if it contains no random variables. For a deterministic model, there is a unique set of model output data for a given set of inputs. On the other hand, a simulation model is stochastic if it contains one or more random variables. The output data for a stochastic model are themselves random and thus only estimates of the true characteristics of the model. A simulation model of a bank would normally treat the interarrival times and the service times of customers as random variables, each with their own probability distribution. Loosely speaking, we define discrete and continuous simulation models analogously to the way discrete and continuous systems were defined above. More precise definitions of discrete (event) simulation and continuous simulation are given in Secs. 1.3 and 1.7, respectively. It should be mentioned that a discrete model is not always used to model a discrete system and vice versa. The decision whether to use a discrete or continuous model for a particular system depends on the specific objectives of the study. For example, a model of traffic flow on a freeway would be discrete if the characteristics and movement of individual cars were important. Alternatively, if the cars can be