## Structural Mechanics

## Bao Shihua

Tsinghua University

## Gong Yaoqing

Henan Polytechnic University



## 内容简介

本书是根据中国高等学校土木工程专业的教学计划、结构力学课程的教学大纲和课程基本要求,为中国高等学校土木工程专业结构力学课程"双语教学"编写的英文结构力学教材。全书共分 14 章,包括:绪论,结构的几何组成分析,静定梁,静定刚架,三铰拱,静定桁架和组合结构,静定结构总论,影响线,虚功原理和结构的位移,力法,位移法,渐进法和超静定结构的影响线,矩阵位移法和超静定结构总论。除第一章外,每章均有提要、小结、思考题和习题,书后附有答案。

本书与第一作者主编的中文结构力学(参考文献 1)在章节次序和内容上基本上是对应的,便于中文与英文教学中交互使用。

本书可作为土木工程专业,即"大土木"的房建、路桥、水利等各类专门化方向的"双语"教材及参考用书, 也可供工程技术人员学习专业外语之用。

### Brief Introduction of the Book

The textbook, written in terms of the national education program, syllabus and requirement of the course—Structural Mechanics—for the undergraduates majoring in civil engineering in China, is intend to be a sort of bilingually teaching material. It includes 14 chapters, which are: introduction, geometric construction analysis of structures, statically determinate beams, plane statically determinate rigid frames, three-hinged arches, plane statically determinate trusses and composite structures, general remarks on statically determinate structures, influence lines, principle of virtual work and displacement of structures, force method, displacement method, method of successive approximations and influence lines for indeterminate structures, matrix displacement method, and general remarks on statically indeterminate structures. All chapters except for chapter 1 are arranged by abstract, text, summary, problems for reflecting, and problems for solution; the answers to selected problems are attached to the back as well.

It should be pointed out that the arrangement of the content and the order of the chapters for the book is almost the same as its Chinese counterpart (bibliography 1), so as to give an alternant usage for Chinese readers and teachers.

The book can be not only used as a textbook and/or reference book for the students majoring in civil engineering structures, but also employed as a specialized English book for the engineer and technicians interested in civil engineering and English.

## 图书在版编目(CIP)数据

Structural Mechanics/包世华,龚耀清编著.—武汉:武汉理工大学出版社,2006 ISBN 7-5629-2407-4

Ⅰ. 结 … Ⅱ.①包… ②龚 Ⅲ. 结构力学-双语教学-研究生-教材 Ⅳ. 0342

出版者:武汉理工大学出版社(武汉市武昌珞狮路 122 号 邮编:430070)

印刷者:

发行者:各地新华书店

开 本:787×1092 1/16

印 张:35.75

字 数:900 千字

版 次:2006年6月第1版 2006年6月第1次印刷

印 数:1-2000 册

定 价:59.00

(本书如有印装质量问题,请向承印厂调换)

## **Contents**

Introduction 1

CHAPTER 1

CHAPTER 4	Plane Statically Determinate Rigid Frames 67
Summary 61	• Problems for Reflecting 62 • Problems for Solution 62
	terminate Multispan Beams 57
	3.5 The Construction of Internal Force Diagrams of Statically De-
	Statically Determinate Multispan Beams 55
	3.4 The Restraint Force Calculation and Geometric Construction of
	3.3 The Analysis of Simply Supported Inclined Beams 51
	position for Straight Members 48
	3.2 Construction of Bending Moment Diagram By Principle of Super-
	3.1 The Analysis of Single Span Beams 35
CHAPTER 3	Statically Determinate Beams 35
Summary 31	• Problems for Reflecting 31 • Problems for Solution 32
0 01	Construction of Structures 30
	2.5 The Relationship between Static Determinacy and Geometric
	2.4 Illustration of Geometric Construction Analysis 28
	Without Redundant Restraints 24
	2.3 Geometric Construction Rules of Planar Stable Framed Systems
	2.2 The Concept of Degrees of Freedomand Restraints 19
	Stable and Unstable Structural Systems 18
	2.1 Purpose of Analyzing Geometric Construction of Structures,
CHAPTER 2	Geometric Construction Analysis of Structures 18
Summary 16	• Problems for Reflecting 17
	1.5 The Classification of Loads 15
	1.4 Classification of Framed Structures 12
	1.3 Analytical Models of Structures 5
	1.2 Objective and Learning Method of Structural Mechanics 3
	1.1 Structures and metric assistication 1

4.1 Geometric Construction and Characteristics of Plane Stati-

- cally Determinate Rigid Frames 68
- 4.2 The Analyzing of Reactions for Statically Determinate Rigid Frames 70
- 4.3 Determination of Internal Forces of Member Ends by Using the Method of Sections 73
- 4.4 The Construction of Internal Force Diagrams of Statically Determinate Frames 76
- 4.5 Internal Force Diagrams of Statically Determinate Threehinged Frames, Multispan and Multistory Frames 80
- Summary 84 Problems for Reflecting 85 Problems for Solution 87

## CHAPTER 5 Three Hinged Arches 91

- 5.1 The Constitution and Type of Three Hinged Arches 91
- 5.2 The Reactions of Three Hinged Arches Under the Action of Vertical Loads 92
- 5. 3 The Formula for Calculating Internal Forces of Three Hinged Arches Under Action of Vertical Loads 94
- 5.4 Stressing Performance of Three Hinged Arches 99
- 5.5 Rational Axial Lines of Three Hinged Arches 100
- Summary 104 Problems for Reflecting 105 Problems for Solution 106

## CHAPTER 6 Plane Statically Determinate Trusses and Composite Structures 108

- 6.1 Characteristics and Classification of Trusses 108
- 6.2 The Method of Joints 114
- 6.3 The Method of Sections 119
- 6.4 The Combination of the Method of Joints and the Method of Sections 123
- 6.5 Formand Stressing Characteristics of Grder Trusses 125
- 6.6 Composite Structures 128
- Summary 132 Problems for Reflecting 133 Problems for Solution 134

## CHAPTER 7 General Remarks on Statically Determinate Structures 139

- 7.1 Analytical Methods for Statically Determinate Structures
  139
- 7.2 General Property of Statically Determinate Structures 144
- 7.3 Stressing Characteristics of Various Types of Structures

## CHAPTER 8 Influence Lines 153

- 8.1 Concept of influence lines 153
- 8.2 Influence Lines for Statically Determinate Single Span Beams by Static Method 156
- 8.3 Influence Lines for Girders with Floor Systems 163
- 8.4 Influence Lines for Trusses by Using Static Method 166
- 8.5 Virtual Displacement Method for Constructing Influence Lines for Statically Determinate Beams 170
- 8.6 Application of Influence Lines 179
- Summary 192 Problems for Reflecting 193 Problems for Solution 194

## CHAPTER 9 Principle of Virtual Work and Displacement of Structures 199

- 9.1 Introduction for Calculation of Structural Displacement 199
- 9.2 Virtual Work and Principle of Virtual Work 201
- 9.3 General Equation and Unit Load Method for Computing Displacements 212
- 9.4 Calculation of Displacements Caused by Loads 213
- 9.5 Graph-Multiplication Method 221
- 9.6 Calculation of Displacements Caused by Temperature Changes 233
- 9.7 Calculation of Displacements Caused by Support Movement 236
- 9.8 Reciprocal Laws for Linear Elastic System 238

Problems for Reflecting 243 • Problems for Solution 246

## CHAPTER 10 Force Method 251

- 10. 1 Statically Indeterminate Structures and Degrees of Indeterminacy 251
- 10.2 Basic Concept of Force Method 254
- 10.3 Canonical Equations of Force Method 258
- 10. 4 Statically Indeterminate Beams, Rigid Frames and Bent Frames 262
- 此为试读, 需10.5 Statically Indeterminate Trusses and Composite Structures

272

- 10.6 Analysis of Symmetric Structures 277
- 10.7 Statically Indeterminate Arches 291
- 10. 8 Internal Forces due to Support Settlements and Temperature Changes 303
- 10.9 Computation of Displacements of Statically Indeterminate Structures 309
- 10.10 Verification of Calculation of Statically Indeterminate
  Structures 313
- Summary 317
- Problems for Reflecting 320 Problems for Solution 323

## CHAPTER 11 Displacement Method 329

- 11.1 Fundamental Concepts of Displacement Method 329
- 11. 2 Member End Forces of Various Single-Span Indeterminate Prismatic Beams Due to Their End Displacements and External Loadings 332
- 11.3 Primary Unknowns and Primary Systems in Displacement Method 340
- 11.4 Displacement-Method Equations 345
- 11.5 Analysis of Statically Indeterminate Beams and Rigid Frames with No Sidesway 350
- 11.6 Analysis of Statically Indeterminate Rigid and Bent Frames with Sidesway 357
- 11.7 Analysis of Statically Indeterminate Symmetric Structures 365
- 11.8 Development of Displacement-Method Equations by Direct Stiffness Method 370

Summary 374

Problems for Reflecting 376
 Problems for Solution 377

## CHAPTER 12

Method of Successive Approximations and Influence Lines for Indeterminate Structures 383

- 12.1 General Remarks for Method of Successive Approximations 383
- 12.2 Concepts and Terminology in Moment Distribution Method 384
- 12.3 Moment Distribution at a Single Joint—Moment-Distribution Process 389
- 12.4 Moment Distribution at Multi-Joints—Successive Approximations 395

- 12.5 No-Shear Moment Distribution Method 408
- 12.6 Shear Distribution Method 414
- 12.7 Influence Lines for Forces of Statically Indeterminate Structures 420
- 12.8 Most Unfavorable Arrangement of Live Loads and Envelops for Internal Forces of Continuous Beams 426

Summary 430

• Problems for Reflecting 431 • Problems for Solution 432

## CHAPTER 13 Matrix Displacement Method 436

- 13.1 Introduction 436
- 13.2 Member Stiffness Matrix in Local Coordinate System 441
- 13.3 Member Stiffness Matrix in Gobal Coordinate System 446
- 13.4 Global Stiffness Matrixes of Continuous Beams 451
- 13.5 Global Stiffness Matrixes of Rigid Frames 460
- 13.6 Equivalent Nodal Loads 466
- 13.7 Procedure for Analysis and Examples 471
- 13.8 Global Analysis of Rigid Frames without Considering Axial Deformation 480
- 13. 9 Block Diagram and Computer Programs for Plane Framed Structures 485

Summary 509

• Problems for Reflecting 510 • Problems for Solution 511

## CHAPTER 14 General Remarks on Statically Indeterminate Structures 513

- 14. 1 Classification and Comparison of Fundamental Method used to Analyze Statically Indeterminate Structures 513
- 14.2 Combined Method—Simultaneously Applying Moment Distribution and Displacement Methods to Frames with Sides way 513
- 14.3 Approximate Analysis of Statically Indeterminate Structures 515
- 14.4 Properties of Statically Indeterminate Structures 520
- 14. 5 Complementary Discussion about Computing Models of Structures 527
- Summary 533 Problems for Reflecting 539 Problems for Solution 540

Answers to selected problems 541 Bibliography 554

# CHAPTER 1

## Abstract of the chapter

The chapter will introduce four questions such as the objective and learning method of structural mechanics, the analytical models of structures, the classification of framed structures and their loads. Among the four questions, the analytical models are the most significant since they will lay the foundations of the other chapters of the book.

## 1.1 Structures and Their Classification

In civil engineering project, the generic term an engineering structure or briefly named a structure is referred to as a frame or skeleton used to carry loads applied on it and composed by members of buildings or other constructions made of construction materials. The following figures show some photographs of engineering structures. Figure 1.1 is a tall building suspended structure, Fig. 1.2 is a bridge structure, Fig. 1.3 is the structure of a hydraulic power station, Fig. 1.4 is the structure of an industrial premises. Speaking in detail, the roof panel, the roof truss, the beams, the columns, the foundation and their combination of the one-storey workshop of a plant shown in Fig. 1.18 are all structures.



Fig. 1.1 Tall building suspended structure

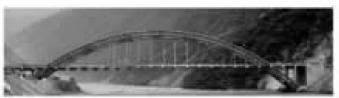


Fig. 1. 2 Bridge structure



Fig. 1. 3 Hydraulic power station



Fig. 1. 4 Industrial premises

## 2 Chapter 1 Introduction

Structures can be classified into three categories by their geometric characteristics.

### (1) Framed structure

A framed structure is comprised of members whose cross-sectional dimension (e.g. the width b and depth h of a rectangular cross section, the radius of a circular cross section, etc.) is much smaller than the length l as shown in Fig. 1.5. The most commonly used types of structures in the structural engineering are framed structures which will be the main attention the book focuses on.



Fig. 1. 5 Bar

Fig. 1. 6 Plate

## (2) Plate, slab and shell (or thin-walled structure)

When the thickness of the structure is very small in comparison with its other two dimensions (length and width), the structure is referred to as a thin-walled structure. The geometric characteristic of a thin-walled structure is that its thickness h is much smaller than its length l and width b. The plate shown in Fig. 1. 6 is one of instances of thin-walled structures. The combination of finite number of plates would develop a floded plate shown as in Fig. 1. 7 (a). Figure 1. 7 (b) shows a building with a roof structure composed of floded plates. If a structure has a curved middle surface, it is called a shell, as shown in Fig. 1. 8. In that context, a plate or a slab can be considered as a thin-walled structure with a plane middle surface.

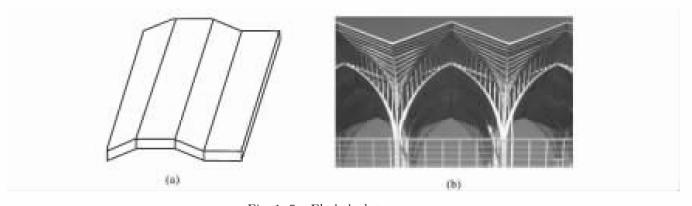


Fig. 1. 7 Floded plate structure
(a) floded plate; (b) floded plate roof



Fig. 1. 8 Shell structure

(a) shell; (b) shell roof

## (3) Massive structure

The three dimensions (length l, width b and depth h) of a massive structure have the same order of magnitude. Consider, for example, the retaining wall shown in Fig. 1.9 and the dam shown in Fig. 1. 10 are two of projects applying massive structures.





Fig. 1. 9 Retaining wall

Fig. 1. 10 Dam

#### 1.2 Objective and Learning Method of Structural Mechanics

#### 1, 2, 1 The relationship between Structural Mechanics and other curricula

In Structural Mechanics, the primary focus will be on the analysis of the structure. In this context, you can name the course as Mechanics of Framed Structure. For simplicity, Structural Mechanics is adopted.

Structural Mechanics belongs to one of technically fundamental courses, plays a very important role and is a connecting link between the preceding courses and the following (or subsequent) courses learned by the undergraduates majoring in the specialty pertinent to civil engineering.

Structural Mechanics is the following course of Theoretical Mechanics and Strength of Materials. The objective of Theoretical Mechanics is the investigation of essential rules and analysis of mechanical motion (including static state and equilibrium) of rigid bodies. The attention paid by Strength of Materials is the strength, stiffness and stability of a single member (or a bar). While the contents treated of in Structural Mechanics are the strength, stiffness and stability of framed structures, which are composed of many members. Therefore, Theoretical Mechanics and Strength of Materials would provide primary principles and basement of mechanical analysis for the studying of Structural Mechanics.

Structural Mechanics is meanwhile the preceding course of Theory of Elasticity (focusing on the strength, stiffness and stability of plate, shell and massive structures), Reinforced Concrete Design, Masonry Structure, Steel Structure and other specialized curricula associated with building construction, structural engineering, highway engineering, bridge engineering, water conservancy engineering and underground engineering. By this token, Structural Mechanics will provide basic mechanical knowledge for the studying of the subsequent courses and play a very important role in the specialty pertinent to civil engineering.

## 1.2.2 Objective and learning method of Structural Mechanics

The objective of Structural Mechanics comprises following aspects:

- (1) Discuss principles for constructing structures, rational configurations of structures and selections of computing models for analyzing structures;
- (2) Investigate the methods for analyzing internal forces and displacements of structures so as to check their strength and stiffness;
  - (3) Study structural stability and structural response induced by dynamic loading.

The analyzing problems involved in Structural Mechanics can be classified into two categories: the first category is statically determinate problems, which can be solved by means of force equilibrium conditions, the first fundamental condition listed in next paragraph; the second category is statically indeterminate problems, which can be figured out only by satisfying all of the following three types of fundamental conditions. The three types of fundamental conditions are:

- (1) **Force equilibrium conditions** The entire structure or part of it must be balanced under the action of a system of forces.
- (2) Compatibility conditions or geometrical conditions of displacements The continuity of a structure must be maintained after the structure has deformed under the action of the loadings applied on it. That is, there are no overlap and gap existing in the materials composing the structure, and meanwhile the deformation and displacement of the structure should satisfy the restraint conditions provided by the supports and the connecting joints.
- (3) **Physical conditions** This is the physical performance condition linking stress and strain or forces and displacements yielding in a structure, i. e. physical or constitutive equation.

The all analyzing methods formulated in Structural Mechanics are permeated by aforementioned three types of fundamental conditions, i. e. every analyzing method discussed in the course has to utilize the three conditions in some kinds of degree and order.

During studying the course, we should focus our attention on the relationship between Structural Mechanics and other curricula. A necessary review about the knowledge associated with Theoretical Mechanics and Strength of Materials should be taken and the knowledge also should be consolidated and advanced during the study.

In the process of studying the course, we have to pay attention to the learning method and clue of solving problems. All of the analyzing methods discussed in the book are the concrete application of above-mentioned three types of fundamental conditions. How the three types of conditions are applied to the computing process of every analyzing method is the point we should focus on. During studying the course, the clues of solving problems must be mastered, especially the general method of analyzing problems should be held. For instance, the method of passing through known field to unknown field; the method of partitioning the entire structure into elements then integrating them into the very beginning structure; the method of contrasting pertinent problems between which some sort of relationship exist in

some extent, etc.

Study should associate with practice. Doing exercises is a very important approach for learning Structural Mechanics. We will not predominate the primary concept, principle and method of Structural Mechanics without doing some amount of exercises. However, doing exercises should avoid silliness. The first silliness is only doing exercises without reading and reviewing the book. The second silliness is doing exercises fast and more without understanding them completely. The third silliness is doing exercises with referring to the answers but being not able to verify the exercises by self. The fourth silliness is doing exercises without rectifying fault happened in doing exercises and extracting lesson from them.

#### **Analytical Models of Structures** 1.3

#### 1.3.1 The rules of developing analytical model

Real structures are usually too complex to perform a rational analysis in their real practical states. They have to be simplified or idealized, by throwing away some unimportant details, as analyzing models prior to computation. An analytical model is a simplified representation of sketch, or an ideal sketch, of a real structure for the purpose of analysis. The simplified representation of sketch of a structure is referred to as its analytical model. All the analysis of structures is performed in their analytical models. Therefore, the development of analytical model is the basement of structural analysis. Establishment of an analytical model is one of the most important steps of the analysis process; it requires experience and knowledge of design practices in addition to a thorough understanding of the behavior of structures. Remember that the structural response predicted from the analysis of the model is valid only to the extent that the model represents the actual structure.

Development of the analytical model should generally obey the following rules:

- (1) The analytical model should reflect, as accurately as practically possible, the main stressed and strained characteristics of the structure of interest to the analyst;
- (2) In order to facilitate the analysis, the analytical model should maintain principal factors and discard much of the detail about the members, connections, and so on, that is expected to have little effect on the desired characteristics.

It should be pointed out that the development of analytical model should meet the site and time conditions under the above rules. It should have alternative ways. For instance, a more precise analytical model should be developed for an important structure; while a less precise analytical model should be used for an unimportant structure. Furthermore, in schematic design stage we can develop a rough analytical model for a structure; while in technical design stage we can select a more precise analytical model for the same structure. For handoriented method, the simplest analytical models of structures should be used; while for computer-oriented method, complex models of structures might be selected.

## 1.3.2 Simplifying points of analytical model

## (1) The simplification of structural system

Generally, the actual structures are space, or three-dimensional, structures, whose members are connected as a space frame to undergo the loadings likely acting on it in various sense. Fortunately, many actual three-dimensional structures can be subdivided, by discarding some subsidiary space restraints, into plane structures for simplifying analysis. If all the members of a structure as well as the applied loads lie in a single plane, the structure is called a plane structure. The book will mainly discuss the calculation problems of plane structures.

## (2) The simplification of members

The main attention the book focuses on is the framed structures. A framed structure is comprised of members (or bars), whose cross-sectional dimensions (e. g. the width b and depth h of a rectangular cross section, the radius of a circular cross section, etc.) is much smaller than the length l. Also cross-sectional deformation of the members satisfies plane-section assumption, and stress acting on the cross sections of members can be determined by the stress resultants (i. e. internal forces, bending moment, shear force and axial force). The cross-sectional deformation can be also evaluated by the strain components of the centroidal axes of the members. In the circumstances, the analytical model of a two- or three-dimensional structure selected for analysis is represented by a line diagram. On this diagram, each member of the structure is represented by a kind of joint; the length of each member is represented by the distance between joints to which the member be attached; the position of the loads acting upon members is also transmitted to their centroidal axes. However, the simplifying approach is only suitable for the members whose ratios between their longitudinal and lateral dimensions are greater than 4.

## (3) The simplification of connections

The connections between members of a structure are commonly simplified into joints. Two types of joints are commonly used to join members of structures:

## ① Flexible, or hinged joint

A hinged joint prevents only relative translations of member ends connected to it; that is, all member ends connected to a hinged joint have the same translation but may have different rotations. Such joints are thus capable of transmitting forces but not moments between the connected members. Figure 1.11 (a) shows a roof structure, the relative translations of each member are restrained by the gussets, but slight rotation between members will exist. So the gussets or connections of the roof structure are idealized into hinges. Hinged joints are usually depicted by small circles at the intersections of members on the line diagram of the structure, as shown in Fig. 1.11(b).

## 2 Rigid joint

A rigid joint prevents relative translations and rotations of the member ends connected

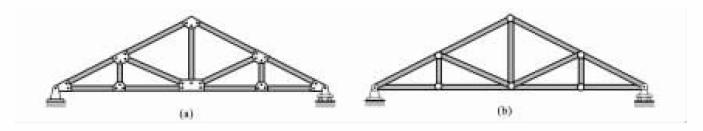


Fig. 1.11 Roof structure and its computing model

to it; that is, all member ends connected to a rigid joint have the same translations and rotation. In other words, the original angles between the members intersecting at a rigid joint are maintained after the structure has deformed under the action of loads. Such joints are, therefore, capable of transmitting forces as well as moments between the connected members. Figure 1.12 (a) shows a connection of a reinforced concrete side column and beam, the relative translations and rotation of the column and beam are restricted by the arrangement of the reinforcements which are cast into the whole body by the concrete. So the connection is simplified into a rigid joint. Rigid joints are usually represented by monolithic point at the intersections of members on the line diagram of the structure, as shown in Fig. 1.12 (b).

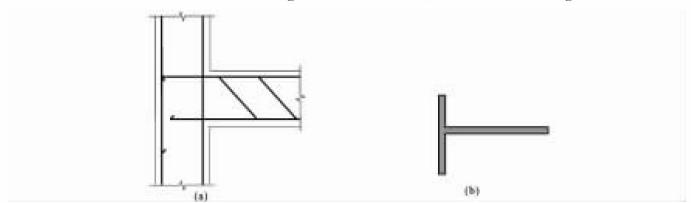


Fig. 1. 12 Connection of reinforced concrete bars and its computing model

### (4) The simplification of connections between structure and its foundation

Supports are used to attach structures to their foundations or other bodies, thereby restricting their movements under the action of applied loads. The loads tend to move the structures; but supports prevent the movements by exerting opposing forces, or reactions, to neutralize the effects of loads, thusly keeping the structures in equilibrium. The type of reaction depends on the type of supporting device used and the type of movement it prevents. A support that prevents translation of the structure in a particular direction exerts a reaction force on the structure in that direction. Similarly, a support that prevents rotation of the structure about a particular axis exerts a reaction couple on the structure about that axis.

The types of supports commonly used for plane structures are grouped into four categories, depending on the number of reactions (1, 2 or 3) they exert on the structures.

## ① Roller support

Figure 1. 13 (a) shows a photo of the roller support of a bridge structure; Fig. 1. 13 (b) and (c) depict the roller and rocker supports used in bridge structures. The supports only prevent translation perpendicular to the supporting surface. So the reaction force  $R_A$  acts

## 8 Chapter 1 Introduction

perpendicular to the supporting surface and may be directed either into or away from the structure. The magnitude of  $R_A$  is the unknown. The support is thusly idealized, in according with its behavioral characteristics, as a roller-liked symbol shown as in Fig. 1. 13 (d) or a link shown as in Fig. 1. 13 (e).

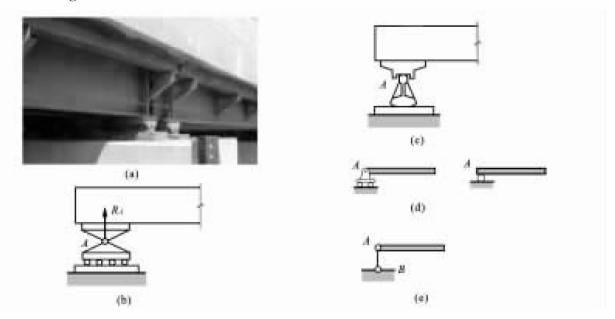


Fig. 1. 13 Roller support

(a) photo of the roller support of a bridge;(b) the roller support of a bridge;(c) the rocker support of a bridge;(d) computing models of roller support;(e) computing model of roller support

## ② Hinged support

The conformations of this kind of supports are depicted in Fig. 1.14 (a) and (b), they are simply referred to as hinge. The supports are able to prevent translations in any direction. So the reaction force  $R_A$  may act in any direction. It is usually convenient to represent  $R_A$  by its rectangular components,  $X_A$  and  $Y_A$ . The magnitudes of  $X_A$  and  $Y_A$  are the two unknowns. The support is thusly idealized, in according with its behavioral characteristics, as a hinge-liked symbol shown as in Fig. 1.14 (c) or two concurrent links shown as in Fig. 1.14 (d) and (e).

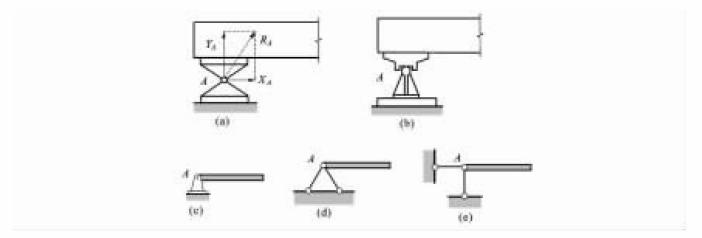


Fig. 1. 14 Hinged support

(a) and (b) conformations of hinged support; (c), (d) and (e) computing models of hinged support

Figure 1. 15 (a) shows a precast reinforced concrete column embedded in cup-liked foundation and the interspace around the column bottom end is filled by asphaltum with jute fiber. In practice, there is slight rotation between the column and the foundation but no translations. So the attachment can be simplified as a hinge. Figure 1.15 (b) shows another example of hinged support, an arc-shaped sluice, there is a rotation about pin A when the sluice is being opened.

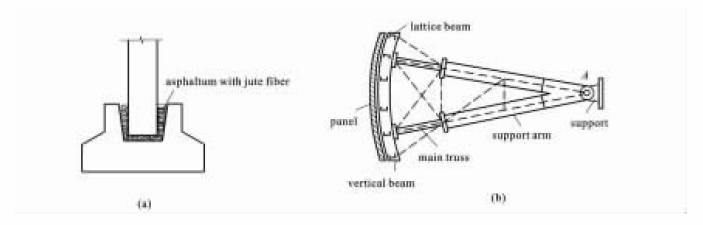


Fig. 1. 15 Practical hinged supports

(a) precast reinforced concrete column embedded in cup-liked foundation; (b) arc-shaped sluice with hinged support

## ③ Fixed support

The fixed support can prevent both relative translations and rotation between structure and its foundation. So the reactions consist of two force components  $X_A$ ,  $Y_A$  and a couple of moment  $M_A$ . The magnitude of  $X_A$ ,  $Y_A$  and  $M_A$  are the three unknowns. The support is thusly idealized, in according with its behavioral characteristics, as a symbol shown as in Fig. 1. 16 (b).

Figure 1.16 (c) shows a precast reinforced concrete column embedded in cup-liked foundation and the interspace around the column bottom end is filled by crushed stone concrete. In practice, there is no movement between the column and the foundation when the depth of embedment reaches some kind of degree. So the attachment generally is simplified as a fixed support.

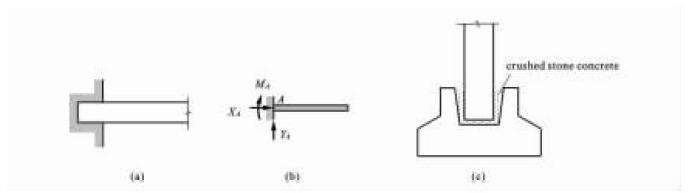


Fig. 1. 16 Fixed support

(a) conformation of fixed support; (b) computing model of fixed support;

(c) precast reinforced concrete cup-liked foundation

4 Directional support

## 10 Chapter 1 Introduction

The directional support (or double-link support) restricts all relative movement between structure and its foundation but slides along its supporting surface. So the reactions consist of a force  $Y_A$  perpendicular to the supporting surface and a couple of moment  $M_A$ . The magnitudes of  $Y_A$  and  $M_A$  are the two unknowns. The support is thusly idealized, by its behavioral characteristics, as a symbol shown as in Fig. 1.17 (b) or two parallel links shown as in Fig. 1.17 (c).

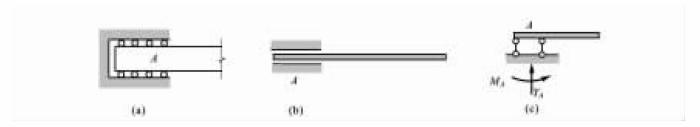


Fig. 1. 17 Directional support

(a) conformation of directional support;(b) schematic symbol of directional support;(c) computing model of directional support

## (5) The simplification of property of material

Generally, the structures constructed in civil engineering are made of materials such as steel, concrete, bricks, stone, timber, and so on. However, in order to simplify the structural analysis, all materials composing structures are assumed to be continuous, homogeneous, isotropic, perfectly elastic or plastic.

Above assumption is suitable for metal within some stressing extent, but for concrete, reinforced concrete, bricks, stone and the like, the assumption will have some degree of approximation. As far as timber, because the property along the timber grain is quite different from that cross the timber grain, the attention should be paid when applying the assumption.

## (6) The simplification of load

The loads applied on structures may be divided into two categories such as body force and surface force. The body force indicates the gravities and inertial forces of structures and the like; the surface force means the action upon structures transmitted by other bodies attached to them, for instance, the compression of soil and vehicular wheels and so on. In framed structures, the members are represented by lines coinciding with their centroidal axes, so both body force and surface force can be simplified as the forces acting on the lines. The loads can be simplified into concentrated loads and distributed loads according to their distribution. The simplification and determination of loads are of complexity. The special discussion about them will be given in latter section.

### 1.3.3 Illustration of analytical models of structures

Figure 1.18 (a) shows an illustrative diagram of a workshop of a factory. Now its analytical models will be discussed.

## (1) The simplification of structural system of the workshop

The structure of the workshop is, like clockwork along its longitudinal direction, collocated by a series of planar elements, composed by roof structure, columns and foundation