



Fluid Transport

Jean-Paul Duroudier

Pipes

ISTE
PRESS



Industrial Equipment for Chemical Engineering Set

coordinated by
Jean-Paul Duroudier

Fluid Transport

Pipes

Jean-Paul Duroudier



First published 2016 in Great Britain and the United States by ISTE Press Ltd and Elsevier Ltd

Apart from any fair dealing for the purposes of research or private study, or criticism or review, as permitted under the Copyright, Designs and Patents Act 1988, this publication may only be reproduced, stored or transmitted, in any form or by any means, with the prior permission in writing of the publishers, or in the case of reprographic reproduction in accordance with the terms and licenses issued by the CLA. Enquiries concerning reproduction outside these terms should be sent to the publishers at the undermentioned address:

ISTE Press Ltd
27-37 St George's Road
London SW19 4EU
UK

www.iste.co.uk

Elsevier Ltd
The Boulevard, Langford Lane
Kidlington, Oxford, OX5 1GB
UK

www.elsevier.com

Notices

Knowledge and best practice in this field are constantly changing. As new research and experience broaden our understanding, changes in research methods, professional practices, or medical treatment may become necessary.

Practitioners and researchers must always rely on their own experience and knowledge in evaluating and using any information, methods, compounds, or experiments described herein. In using such information or methods they should be mindful of their own safety and the safety of others, including parties for whom they have a professional responsibility.

To the fullest extent of the law, neither the Publisher nor the authors, contributors, or editors, assume any liability for any injury and/or damage to persons or property as a matter of products liability, negligence or otherwise, or from any use or operation of any methods, products, instructions, or ideas contained in the material herein.

For information on all our publications visit our website at <http://store.elsevier.com/>

© ISTE Press Ltd 2016

The rights of Jean-Paul Duroudier to be identified as the author of this work have been asserted by him in accordance with the Copyright, Designs and Patents Act 1988.

British Library Cataloguing-in-Publication Data

A CIP record for this book is available from the British Library

Library of Congress Cataloging in Publication Data

A catalog record for this book is available from the Library of Congress

ISBN 978-1-78548-184-0

Fluid Transport

There are no such things as applied sciences,
only applications of science.
Louis Pasteur (11 September 1871)

Dedicated to my wife, Anne, without whose unwavering support, none of this
would have been possible.

Preface

The observation is often made that, in creating a chemical installation, the time spent on the recipient where the reaction takes place (the reactor) accounts for no more than 5% of the total time spent on the project. This series of books deals with the remaining 95% (with the exception of oil-fired furnaces).

It is conceivable that humans will never understand all the truths of the world. What is certain, though, is that we can and indeed must understand what we and other humans have done and created, and, in particular, the tools we have designed.

Even two thousand years ago, the saying existed: “*faber fit fabricando*”, which, loosely translated, means: “*c'est en forgeant que l'on devient forgeron*” (a popular French adage: *one becomes a smith by smithing*), or, still more freely translated into English, “practice makes perfect”. The “artisan” (faber) of the 21st Century is really the engineer who devises or describes models of thought. It is precisely that which this series of books investigates, the author having long combined industrial practice and reflection about world research.

Scientific and technical research in the 20th century was characterized by a veritable explosion of results. Undeniably, some of the techniques discussed herein date back a very long way (for instance, the mixture of water and ethanol has been being distilled for over a millennium). Today, though, computers are needed to simulate the operation of the atmospheric distillation column of an oil refinery. The laws used may be simple statistical

correlations but, sometimes, simple reasoning is enough to account for a phenomenon.

Since our very beginnings on this planet, humans have had to deal with the four primordial “elements” as they were known in the ancient world: earth, water, air and fire (and a fifth: aether). Today, we speak of gases, liquids, minerals and vegetables, and finally energy.

The unit operation expressing the behavior of matter are described in thirteen volumes.

It would be pointless, as popular wisdom has it, to try to “reinvent the wheel” – i.e. go through prior results. Indeed, we well know that all human reflection is based on memory, and it has been said for centuries that every generation is standing on the shoulders of the previous one.

Therefore, exploiting numerous references taken from all over the world, this series of books describes the operation, the advantages, the drawbacks and, especially, the choices needing to be made for the various pieces of equipment used in tens of elementary operations in industry. It presents simple calculations but also sophisticated logics which will help businesses avoid lengthy and costly testing and trial-and-error.

Herein, readers will find the methods needed for the understanding the machinery, even if, sometimes, we must not shy away from complicated calculations. Fortunately, engineers are trained in computer science, and highly-accurate machines are available on the market, which enables the operator or designer to, themselves, build the programs they need. Indeed, we have to be careful in using commercial programs with obscure internal logic which are not necessarily well suited to the problem at hand.

The copies of all the publications used in this book were provided by the *Institut National d'Information Scientifique et Technique* at Vandœuvre-lès-Nancy.

The books published in France can be consulted at the *Bibliothèque Nationale de France*; those from elsewhere are available at the British Library in London.

In the in-chapter bibliographies, the name of the author is specified so as to give each researcher his/her due. By consulting these works, readers may

gain more in-depth knowledge about each subject if he/she so desires. In a reflection of today's multilingual world, the references to which this series points are in German, French and English.

The problems of optimization of costs have not been touched upon. However, when armed with a good knowledge of the devices' operating parameters, there is no problem with using the method of steepest descent so as to minimize the sum of the investment and operating expenditure.

Contents

Preface	xv
Chapter 1. Fluid Ejectors and Gas Ejectors	1
1.1. General	1
1.1.1. Principle of an ejector	1
1.2. Liquid–liquid or gas–gas ejectors.	2
1.2.1. Parameters of the problem.	2
1.2.2. Finding the characteristic equation.	3
1.3. Gas ejectors and thermocompressors.	7
1.3.1. Parameters of the problem.	7
1.3.2. Flow and velocity of driving fluid	8
1.3.3. Flow and velocity of the suction fluid.	9
1.3.4. Specific consumption σ	10
1.3.5. Study of the mixing of two gases	10
1.3.6. Global compression ratio	14
1.4. Practical applications of ejectors and thermocompressors	17
1.4.1. Value of these devices	17
1.4.2. Compression ratio and mounting ejectors	18
1.4.3. Similarity between suction gases.	18
1.4.4. Stability and stall point	19
1.4.5. Ice formation at the exit of the ejection nozzle.	20
1.4.6. Regulation of ejectors	20
1.4.7. Simplified calculation of specific consumption of an ejector.	21
1.4.8. Conclusion	23

Chapter 2. Pipe Dimensions, Non-Newtonian Fluids, Liquid Hammer	25
2.1. Establishing pipe diameter	25
2.1.1. Exterior diameter of metallic piping	25
2.1.2. Choice of pipe velocity	26
2.1.3. Available pressure drop	29
2.1.4. Pressure drop calculation	30
2.1.5. Expression in practical units (fluids)	31
2.1.6. Gas	32
2.1.7. Newtonian viscous fluids	33
2.1.8. Non-Newtonian fluids	35
2.2. Establishing pipe thickness	36
2.2.1. Mechanical calculation conditions	36
2.2.2. Pressure resistance	38
2.2.3. Vacuum resistance	39
2.2.4. Corrosion allowance and final thickness	40
2.3. Flanges, seals and accessories	41
2.3.1. Flanges and mounting	41
2.3.2. The choice of flanges and seals	41
2.3.3. Two types of pipe accessory	43
2.4. Sound waves in pipes	45
2.4.1. Wave celerity	45
2.4.2. Natural damping of sound waves	47
2.5. Mechanism of liquid hammer	51
2.5.1. Closure of a valve, pressure equation	51
2.5.2. Integrated pressure equation	53
2.5.3. The complete equations of the problem	54
2.6. Approximate simulation method for simple pipes (without intermediate accessories and fittings)	57
2.6.1. Assumption of mean values	57
2.6.2. Physical interpretation	59
2.6.3. Boundary conditions	60
2.6.4. Propagation diagram	62
2.6.5. Calculation procedure	64
2.7. Simplified graphic method	66
2.7.1. Preliminary	66
2.7.2. Practical procedure	67
2.8. Anti-liquid hammer chambers	71
2.8.1. Definition	71
2.8.2. Influence of the chamber on over-pressure	71

2.8.3. Fluid-level oscillations inside the tank	72
2.8.4. Pipe friction equations	75
2.8.5. Resolution of the damping equation	76
2.8.6. Weakening of a sound wave along a pipe for a single trip	78
Chapter 3. Block or Stop Valves and Control Valves	79
3.1. On valves in general.	79
3.1.1. Terminology	79
3.1.2. The essential parts of a valve	80
3.1.3. Sealing	81
3.1.4. Protection against corrosion and abrasion	82
3.1.5. Protection against pressure and temperature	82
3.2. Different types of valves	83
3.2.1. Valve categorization and study design	83
3.2.2. Plug valves.	84
3.2.3. Angle valves	85
3.2.4. Other plug valves	86
3.2.5. Eccentric shut-off control valve	87
3.2.6. Ball valve	87
3.2.7. Membrane valve	90
3.2.8. Pinch valve.	91
3.2.9. Butterfly valve	92
3.2.10. Gate valve	93
3.2.11. Knife valve	93
3.2.12. Cage valve	94
3.2.13. Multipath valves.	95
3.3. Control valve choice and calculation.	98
3.3.1. Purpose of control valves	98
3.3.2. Flow in a valve	99
3.3.3. Thermodynamic approach and calculation principle	100
3.3.4. Calculation of C_V with flow in volume	100
3.3.5. The K_V in the international system of units.	101
3.3.6. Calculation of C_V with flow in mass.	103
3.3.7. Laminar flow of a liquid.	104
3.3.8. The meaning of C_V	105
3.3.9. Cavitation of a fluid in a liquid.	106
3.3.10. Limiting flowrate of a liquid entering at its boiling point	107

3.3.11. Conclusion for liquids	109
3.3.12. Relaxation coefficient for gases.	109
3.3.13. Sonic regime for gases	110
3.3.14. Flow characteristic of a control valve	111
3.3.15. Operating range	113
3.3.16. Installation of a control valve	114
3.4. The process parameters of a control valve.	116
3.4.1. Variation in line pressure	116
3.4.2. Disturbances on a line	118
3.4.3. Definition of control valves (principles)	119
Chapter 4. Electric Motors: Performance and Choice of Pumps and Fans	125
4.1. Choice of motor	125
4.1.1. General	125
4.1.2. Installed power	125
4.1.3. Supply voltage	126
4.1.4. Rotation velocity	126
4.2. Utilization of motors	127
4.2.1. Starting	127
4.2.2. Power consumption of an installation	129
4.3. Turbopumps	130
4.3.1. The main types of turbopump.	130
4.3.2. Centrifugal pumps	130
4.3.3. Centrifugal pump yield	135
4.3.4. Normal-emergency centrifugal pump systems	138
4.3.5. Liquid flow criteria	139
4.3.6. Safety	140
4.3.7. Drive shaft outlet seal	140
4.3.8. Cooling requirement	141
4.3.9. Dry running centrifugal pumps	141
4.3.10. Hermetically sealed centrifugal pump	142
4.3.11. Propeller pumps	143
4.3.12. Turbopump shaft power	143
4.3.13. Cavitation.	144
4.4. Volumetric pumps	146
4.4.1. Need for volumetric pumps	146
4.4.2. Piston pumps	147
4.4.3. Gear pumps	149
4.4.4. Moyno pumps	149

4.4.5. Double-screw pump	150
4.4.6. Sealed volumetric pumps (membrane)	150
4.4.7. Volumetric pumps and net suction pressure	150
4.4.8. Flow regulation of volumetric pumps	151
4.4.9. Shaft power	151
4.5. Special cases	152
4.5.1. Pumps for liquid–gas mixes.	152
4.5.2. Self-priming pumps	152
4.5.3. Slurry pumping	153
4.5.4. Sludge pumping.	153
4.5.5. The water screw.	154
4.6. Fans	156
4.6.1. Similarity laws and electrical power consumed by a fan	156
4.6.2. Fan flow calibration	157
4.6.3. Uses of fans outside of pneumatic transport	158
4.6.4. Ventilator start time	159
4.6.5. Noise caused by a ventilator	160
Chapter 5. Polymer Extruder Screw	163
5.1. Introduction of extrusion screw	163
5.1.1. Extruder principle.	163
5.1.2. Geometrical description of a screw	164
5.1.3. Screw rotation direction	167
5.1.4. Movement of fluid particles.	167
5.1.5. Preliminary studies	170
5.2. Movement of the polymer in the screw channel	171
5.2.1. Introduction	171
5.2.2. The viscosity of extruded polymers	172
5.2.3. Movement equation between two parallel plates: velocity and flowrate	173
5.2.4. Polymer friction on a solid lining	178
5.2.5. Cord movement and simulation of screw operation	180
5.2.6. Effect on the cord of the orthoaxial component of relative velocity V_R	183
5.2.7. Leak flowrate between the flight and the barrel	184
5.2.8. Friction of the barrel on the flight edge	185
5.3. Heat for polymer melting.	186
5.3.1. Melting of polymer particles	186
5.3.2. Heat dissipated by viscous friction between two parallel plates in relative movement	187

5.3.3. Thermal dissipation due to the liquid cord rotating by itself	188
5.3.4. Preliminary waiting time before fusion as described by Tadmor <i>et al.</i>	189
5.3.5. Thermal exchange in the fusion zone	190
5.4. Shaft electrical power	191
5.4.1. Shaft power of the screw	191
5.4.2. Extrapolation of power from diameter d to diameter D	191
5.5. Practical considerations and screw use	192
5.5.1. Operating variables and dimensioning variables	192
5.5.2. Choosing of certain extruder screws	193
5.5.3. Uses of extruders	194
5.6. Mixing and thermal transfer in the screw	194
Chapter 6. Choice and Performance of Compressors	197
6.1. About compressors	197
6.1.1. Energy loss and yields	197
6.1.2. Gas exit temperature	200
6.1.3. Energetic losses to the environment	200
6.1.4. Ideal compression power	201
6.1.5. Real gases	203
6.1.6. Protecting the machines	206
6.2. Reciprocating compressors	206
6.2.1. Use	206
6.2.2. Dead space in reciprocating compressors	207
6.2.3. Energy and yield	208
6.3. Open volumetric compression – screw compressors and lobe compressors	211
6.3.1. Description	211
6.3.2. Use	211
6.3.3. Yields	212
6.3.4. Internal leak and volumetric yield	213
6.4. Turbo compressors	220
6.4.1. Description and use	220
6.4.2. Flowrate regulation	221
6.4.3. Energy equation	221
6.4.4. Ideal gases	222
6.4.5. Real gases	224

6.5. Fans	227
6.5.1. Use	227
6.5.2. Compression power	227
6.6. Liquid ring pumps	229
6.6.1. Principle and use	229
6.6.2. Shaft power	229
6.6.3. Liquid consumption	231
Chapter 7. Free Gas Expansion	233
7.1. Types of expansion: one-dimensional flow equations	233
7.1.1. Types of expansion and starting hypotheses	233
7.1.2. Free expansion and energy	233
7.1.3. Mach number	237
7.1.4. Pipe friction	237
7.1.5. General equations of adiabatic flow	238
7.1.6. Flow without friction but with variable cross-section	240
7.1.7. Isentropic flow and critical values	243
7.1.8. Flow at constant cross-section with friction (gas pipelines)	245
7.1.9. Equation of the stationary shock wave	248
7.1.10. Singular pressure drop	250
7.2. Theoretical study of control valves, safety valves and gas pipelines	253
7.2.1. Modeling control valves	253
7.2.2. Modeling valves	256
7.2.3. Conclusions	260
7.2.4. Pressure drop in a gas pipeline	261
7.2.5. Overall conclusions	263
Chapter 8. Safety Valves and Rupture Disks	265
8.1. Pressure around a safety valve	265
8.1.1. Operating pressure of a protected device	265
8.1.2. Maximum operating pressure	265
8.1.3. Pressure calculation	266
8.1.4. Set pressure	266
8.1.5. Pressure upstream of the safety valve	267
8.1.6. Closing differential (drop)	268
8.1.7. Counter-pressure downstream of the valve	268

8.2. Choice between two types of safety valves	269
8.2.1. Usual valves	269
8.2.2. Balanced plugs	270
8.2.3. Choosing a safety valve type	271
8.2.4. Inlet cross-section norms	271
8.3. Relationship between flowrate and pressure	271
8.3.1. Gases	271
8.3.2. Liquids	274
8.3.3. Viscous liquids	275
8.3.4. Flow through valves	277
8.4. Upstream and downstream connections	279
8.4.1. Connection between valve and protected device	279
8.4.2. Exhaust pipe	279
8.4.3. Reaction force on the structure	283
8.5. Various applications	284
8.5.1. Vacuum-breaking valves	284
8.5.2. Breathing of reservoirs under atmospheric pressure	286
8.5.3. Liquid escaping without free surface (low vapor pressure)	286
8.6. Rupture disks	287
8.6.1. Rupture pressure	287
8.6.2. Operating ratio	288
8.6.3. Relationship between pressure and flow	289
8.6.4. Conventional disks	290
8.6.5. Composite disks	291
8.6.6. Thick disks	291
8.6.7. Graphite disks	292
8.6.8. Rupture indicators	292
8.6.9. Association of a disk with a safety valve	293

Chapter 9. Breathing, Inerting, Gas Losses and Circulation between Reservoirs, Tanks and Vats

9.1. Breather valve specifications: reservoir filling ratio limitations	295
9.1.1. Types of temperature fluctuations	295
9.1.2. Set pressure of exhalation valve	296
9.1.3. Range of filling ratio for operations	298