



普通高等教育“十一五”国家级规划教材

# 自动化专业英语教程

王宏文 主编

第2版



机械工业出版社  
CHINA MACHINE PRESS



普通高等教育“十一五”国家级规划教材

# 自动化专业英语教程

## Specified English for Automation

### 第2版

主 编	王宏文		
副主编	李练兵	刘作军	
参 编	王 萍	孙进生	陈志军
	林 燕	耿 昕	薛忠辉
	暴永辉	蔡 建	江春冬
	孙 昊	岳大为	孙曙光
	梁 涛	雷兆明	郭 欣
主 审	杨 鹏	李彦平	



机械工业出版社

本书是普通高等教育“十一五”国家级规划教材，是针对高等工科院校自动化专业“科技英语阅读”课程的需要而编写的，内容包括电气与电子工程基础、控制理论、计算机控制技术、过程控制、网络化与信息化控制及自动化技术的综合应用 6 部分，涵盖了自动化专业各个发展方向，内容新颖、全面、系统、精炼。每篇文章后都附有词汇表和注解，并配有 30 篇英语翻译及应用文知识，专业、学科介绍，自动化学科相关的期刊、会议、科技前沿等诸多内容，使读者在学习并掌握专业词汇和翻译技能的同时开阔眼界。本书可作为自动化专业本科生及研究生专业英语课程的教材，也可供有关工程技术人员参考。

#### 图书在版编目 (CIP) 数据

自动化专业英语教程/王宏文主编. —2 版. —北京: 机械工业出版社, 2007.3

普通高等教育“十一五”国家级规划教材

ISBN 978-7-111-06753-5

I. 自… II. 王… III. 自动化-英语-高等学校-教材  
IV. H31

中国版本图书馆 CIP 数据核字 (2007) 第 093226 号

机械工业出版社 (北京市百万庄大街 22 号 邮政编码 100037)

策划编辑: 韩雪消 苏颖杰 责任编辑: 苏颖杰

责任校对: 王宏文

封面设计: 张 静

责任印制: 洪汉军

北京振兴源印务有限公司印刷厂印刷

2007 年 7 月第 2 版第 1 次印刷

184mm × 260mm · 17.75 印张 · 437 千字

标准书号: ISBN 978-7-111-06753-5

定价: 26.00 元

凡购本书, 如有缺页、倒页、脱页, 由本社发行部调换

销售服务热线电话: (010) 68326294

购书热线电话: (010) 88379639 88379641 88379643

编辑热线电话: (010) 88379727

封面防伪标均为盗版

# 序

随着我国经济发展逐渐被纳入全球经济发展轨道,特别是在我国加入 WTO 以后,我国与世界的政治、经济、文化交往越来越频繁,各行各业与国际接轨的步伐逐步加快,我国迫切需要既掌握专业知识又掌握专业外语的高素质、复合型人才。培养这种人才是现阶段中国高等教育发展的重要目标之一。教育部于 2001 年 9 月颁布了 4 号文件《关于加强高等学校本科教学工作提高教学质量的若干意见》,要求全国各高等院校积极推广使用英语等外语进行专业课教学,实现我国高等教育的可持续发展。

在我国加入 WTO 的新形势下,教育现代化、国际化已成为高校办学水平的重要体现。双语教学在我国悄然兴起,并逐渐成为教育国际化的重要标志。英语教学作为一种全新的教学方式,承接了中西文化的碰撞与融合,涉及到教学理念的更新、教学内容的重审、授课形式的改革、教学手段的改进、教材的创新。亟待探索的高校英语教学新模式,在实现英语教学提高学生英语语言素养和能力的同时,发挥各学科的学科育人功能,激发学生各方面的潜能,促进学生全方面的发展,培养国际型、复合型人才。

语言的本质是工具,但随着人类的进步、时代的发展、社会的前进,语言已从一种工具变为一种思想、一种知识库。从学习者的认知角度来看,语言是人类思维的工具、认识世界的工具,掌握一种语言也即掌握了一种观察和认识世界的方法和习惯,而学习另外一种语言就意味着学习另外一种观察和认识世界的方法和习惯。这不仅会增加学生浸入在外语中的机会,提高学生的第二语言能力,而且能从不同的侧面和角度,让学生接触世界最先进的文化成果,开发各方面的能力,从而促进他们的全面发展。

《自动化专业英语教程》一书是作者根据多年“专业英语”课程的教学实践,参照国家教育部制定的有关专业英语教学要求编写的。第 1 版于 1998 年出版,在选材上重视先进性,书中内容大部分选自欧美国家相关专业的教学参考书;在编排上力求系统性,较好地贯穿了自动化专业的全部专业课程。选编了许多新知识,使这门课程不仅是对专业课程的总结,而且是一种有益的补充。本书另一特色是增加了专业英语知识,以加强对专业英语技能的培养,并选编和介绍了科技写作、广告、说明书、信函、合同与协议等内容,使得本书内容更加丰富。这有助于培养学生的综合能力,提高全面素质。该书出版后受到了广大师生的欢迎,被 100 余所高等院校所选用。这次修订除了保留原有的特色之外,又增加了许多最新学科知识,如智能控制、嵌入式系统、现场总线、虚拟制造、CIMS and ERP、机器人与模式识别、电动车与新能源技术等,使本书较第 1 版内容更加丰富。本书既是一本专业教材,又是一本专业参考书。

目前,许多高校自动化专业相继开设了“专业英语”课程,该教材是一本适应我国高校自动化专业教学的专业英语教材。这次被列为国家“十一五”规划教材,无疑为自动化专业英语教学提供了一本好教材。再一次由衷地感谢本书的作者,对他们的努力和杰出工作表示钦佩。同时感谢使用这本教材的学校和读者,你们的支持是这本教材再版的动力。专业英语教学作为一种手段,不仅着眼于它能够有效地提高学生的英语语言的工具作用,更为重要的是在实践中培养出全面发展的复合型、国际型人才,为全球化中开放的祖国建设服务。希望这次再版能够对此起到积极作用。

孙鹤旭

# 前 言

高等学校教材《自动化专业英语教程》自 1998 年问世以来,得到了许多学校师生的喜爱。经过 9 年多的教学实践,在广泛采纳兄弟院校师生建议的基础上,并遵循教育部“自动化专业教学指导委员会”的教改精神,我们组织大量在教学、科研一线工作的教师对本书进行了修订。

编写本书的指导思想是:“内容新颖、全面、系统、精炼,既重视学科基础知识又反映学科发展前沿动态”。同时新增了专业介绍、学科相关科技文献网站、自动化专业的科技前沿、学术会议等辅助内容。“见多才能识广”,希望本书对培养有开拓精神、综合素质强的科技创新型人才有所帮助。

全书共包括电气与电子工程基础、控制理论、计算机控制技术、过程控制系统、网络化与信息化控制、自动化技术的综合应用 6 部分共 30 个单元。新增了智能控制综述、DSP、嵌入式系统、电力系统自动化、电动车与新能源技术等诸多内容,覆盖 9 万余字的专业词汇量。

本书由河北工业大学王宏文教授担任主编,河北工业大学李练兵副教授、刘作军副教授担任副主编。书中 Part 1 的 Unit 1 由天津工业大学基建副教授编写;Part 1 的 Unit 2、Unit 3 和 Part 2 的 Unit 6 由天津工业大学王萍教授编写;Part 2 的 Unit 1-5 由河北工业大学李练兵副教授编写;Part 3 的 Unit 1A、Unit 2A 由河北工业大学李练兵副教授和河北科技大学陈志军副教授编写;Part 3 的 Unit 1B、Unit 2B、Unit 4A 由河北科技大学陈志军副教授和薛忠辉副教授编写;Part 1 的 Unit 5B、Unit 6B、Part 6 的 Unit 1A 由河北理工大学孙进生教授编写;Part 1 的 Unit 4、Unit 5A、Unit 6A 由河北工业大学江春冬讲师编写;Part 2 的 Unit 7 由河北工业大学孙昊硕士编写;Part 3 的 Unit 3、Unit 5, Part 6 的 Unit 3 由河北工业大学岳大为博士编写;Part 3 的 Unit 4B 由河北工业大学孙曙光博士编写;Part 4 由河北工业大学耿欣硕士编写;Part 5 的 Unit 1、Unit 2 由河北工业大学梁涛博士编写;Part 5 的 Unit 3、Unit 4 由河北工业大学雷兆明博士编写;Part 6 的 Unit 1B 由河北工业大学王宏文教授编写;Part 6 的 Unit 2 由河北工业大学刘作军副教授、郭欣副教授编写。Part 4 中 Unit 4C 由河北工业大学林燕研究馆员、刘作军副教授编写;Part 5 中 Unit 1C、Unit 2C 由河北工业大学林燕研究馆员编写;Part 4 中 Unit 1C、Unit 3C 由河北工业大学暴永辉硕士编写;其余章节的 C 部分均由河北工业大学刘作军副教授编写。河北工业大学王宏文教授对全书进行总编和修改更正,河北工业大学杨鹏教授、沈阳大学李彦平教授担任主审,河北工业大学孙鹤旭教授为本书题写序言。

在此对参加本书第 1 版编写工作的天津理工大学陈在平教授,以及为本书第 1 版的出版提供大力帮助的孙鹤旭教授、杨鹏教授表示由衷的感谢!河北工业大学 04 级硕士研究生陈悦,05 级硕士研究生刘通学、黄伟杰、王艳霞、刘丽参加了本书部分章节的计算机绘图与文字校对工作,在此一并表示感谢。

本书有完备的参考译文供任课教师使用,欢迎大家对本书提出宝贵意见,通信地址:天津河北工业大学东院 358 信箱 (300130),联系人:王宏文、李练兵、刘作军。传真:(022) 60204686, E-mail: wanghongwen@hebut.edu.cn

编者

# 目 录

序  
前言

<b>PART 1</b>	<b>Electrical and Electronic Engineering Basics</b>	<b>1</b>
UNIT 1	A Electrical Networks	1
	B Three-phase Circuits	4
	C 专业英语 (Specified English) 概述	7
UNIT 2	A The Operational Amplifier	9
	B Transistors	12
	C 专业简介	15
UNIT 3	A Logical Variables and Flip-flop	17
	B Binary Number System	20
	C 专业英语的翻译标准	24
UNIT 4	A Power Semiconductor Devices	25
	B Power Electronic Converters	31
	C 专业英语的词汇特点	34
UNIT 5	A Types of DC Motors	36
	B Closed-loop Control of DC Drivers	40
	C 理解与表达	43
UNIT 6	A AC Machines	45
	B Induction Motor Drive	49
	C 长句的翻译	53
UNIT 7	A Electric Power System	55
	B Power System Automation	59
	C 被动句的翻译	64
<b>PART 2</b>	<b>Control Theory</b>	<b>66</b>
UNIT 1	A The World of Control	66
	B The Transfer Function and the Laplace Transformation	70
	C 否定句的翻译	74
UNIT 2	A Stability and the Time Response	76
	B Steady State	81
	C 名词的翻译	84
UNIT 3	A The Root Locus	86
	B The Frequency Response Methods: Nyquist Diagrams	90
	C 动词的翻译	95
UNIT 4	A The Frequency Response Methods: Bode Plots	97

	B	Nonlinear Control System	100
	C	形容词的翻译	105
UNIT 5	A	Introduction to Modern Control Theory	107
	B	State Equations	110
	C	词性的转换	114
UNIT 6	A	Controllability, Observability, and Stability	115
	B	Optimum Control Systems	118
	C	语法成分的转换	121
UNIT 7	A	Conventional and Intelligent Control	123
	B	Artificial Neural Network	127
	C	增词译法	131
<b>PART 3</b>		<b>Computer Control Technology</b>	<b>133</b>
UNIT 1	A	Computer Structure and Function	133
	B	Fundamentals of Computer and Networks	138
	C	减词译法	141
UNIT 2	A	Interfaces to External Signals and Devices	143
	B	The Applications of Computers	147
	C	常用数学符号和公式的读法	151
UNIT 3	A	PLC Overview	153
	B	PACs for Industrial Control, the Future of Control	156
	C	科技论文的结构与写作	161
UNIT 4	A	Fundamentals of Single-chip Microcomputer	163
	B	Understanding DSP and Its Uses	166
	C	论文的标题和摘要	171
UNIT 5	A	A First Look at Embedded Systems	172
	B	Embedded Systems Design	175
	C	信函	178
<b>PART 4</b>		<b>Process Control</b>	<b>180</b>
UNIT 1	A	A Process Control System	180
	B	Fundamentals of Process Control	182
	C	便笺和通知	184
UNIT 2	A	Sensors and Transmitters	186
	B	Final Control Elements and Controllers	188
	C	简历	190
UNIT 3	A	P Controllers and PI Controllers	192
	B	PID Controllers and Other Controllers	195
	C	面试	199
UNIT 4	A	Indicating Instruments	201
	B	Control Panels	203

C	自动化专业信息检索 .....	206
<b>PART 5</b>	<b>Control Based on Network and Information .....</b>	<b>210</b>
UNIT 1	A Automation Networking Application Areas .....	210
	B Evolution of Control System Architecture .....	215
	C 国内自动化专业主要期刊 .....	219
UNIT 2	A Fundamental Issues in Networked Control Systems .....	221
	B Stability of NCSs with Network-induced Delay .....	225
	C 国外自动化专业主要期刊 .....	228
UNIT 3	A Fundamentals of the Database System .....	231
	B Virtual Manufacturing—A Growing Trend in Automation .....	233
	C 自动化专业的科技前沿 .....	236
UNIT 4	A Concepts of Computer Integrated Manufacturing .....	239
	B Enterprise Resources Planning and Beyond .....	243
	C 自动化专业的学术会议 .....	246
<b>PART 6</b>	<b>Synthetic Applications of Automatic Technology .....</b>	<b>249</b>
UNIT 1	A Recent Advances and Future Trends in Electrical Machine Drivers .....	249
	B System Evolution in Intelligent Buildings .....	252
	C 说明书常用术语 .....	255
UNIT 2	A Industrial Robot .....	256
	B A General Introduction to Pattern Recognition .....	259
	C 合同与协议书常用术语和句型 .....	262
UNIT 3	A Renewable Energy .....	266
	B Electric Vehicles .....	270
	C 广告 .....	273
<b>参考文献</b> .....		<b>274</b>



# PART 1

## Electrical and Electronic Engineering Basics

### UNIT 1

#### A Electrical Networks

An *electrical circuit or network* is composed of elements such as resistors, inductors, and capacitors connected together in some manner. If the network contains no energy sources, such as batteries or electrical generators, it is known as a *passive network*. On the other hand, if one or more energy sources are present, the resultant combination is an *active network*. In studying the behavior of an electrical network, we are interested in determining the voltages and currents that exist within the circuit. Since a network is composed of passive circuit elements, we must first define the electrical characteristics of these elements.

In the case of a resistor, the voltage-current relationship is given by Ohm's law, which states that the voltage across the resistor is equal to the current through the resistor multiplied by the value of the resistance.<sup>[1]</sup> Mathematically, this is expressed as

$$u = iR \quad (1-1A-1)$$

where  $u$  = voltage, V;  $i$  = current, A;  $R$  = resistance,  $\Omega$ .

The voltage across a pure inductor is defined by Faraday's law, which states that the voltage across the inductor is proportional to the rate of change with time of the current through the inductor. Thus we have

$$u = L \frac{di}{dt} \quad (1-1A-2)$$

where  $di/dt$  = rate of change of current, A/s;  $L$  = inductance, H.

The voltage developed across a capacitor is proportional to the electric charge  $q$  accumulating on the plates of the capacitor. Since the accumulation of charge may be expressed as the summation, or integral, of the charge increments  $dq$ , we have the equation

$$u = \frac{1}{C} \int dq \quad (1-1A-3)$$

where the capacitance  $C$  is the proportionality constant relating voltage and charge. By definition, current equals the rate of change of charge with time and is expressed as  $i = dq/dt$ . Thus an increment of charge  $dq$  is equal to the current multiplied by the corresponding time increment, or  $dq = i dt$ . Eq.

(1-1A-3) may then be written as

$$u = \frac{1}{C} \int i dt \quad (1-1A-4)$$

where  $C$  = capacitance, F.

A summary of Eqs. (1-1A-1), (1-1A-2) and (1-1A-4) for the three forms of passive circuit elements is given in Fig. 1-1A-1. Note that conventional current flow is used; hence the current in each element is shown in the direction of decreasing voltage.

Active electrical devices involve the conversion of energy to electrical form. For example, the electrical energy in a battery is derived from its stored chemical energy. The electrical energy of a generator is a result of the mechanical energy of the rotating armature.

Active electrical elements occur in two basic forms: *voltage sources* and *current sources*. In their ideal form, voltage sources generate a constant voltage independent of the current drawn from the source. The aforementioned battery and generator are regarded as voltage sources since their voltage is essentially constant with load. On the other hand, current sources produce a current whose magnitude is independent of the load connected to the source. Although current sources are not as familiar in practice, the concept does find wide use in representing an amplifying device, such as the transistor, by means of an equivalent electrical circuit. Symbolic representations of voltage and current sources are shown in Fig. 1-1A-2.

A common method of analyzing an electrical network is mesh or loop analysis. The fundamental law that is applied in this method is Kirchhoff's first law, which states that the algebraic sum of the voltages around a closed loop is 0, or, in any closed loop, the sum of the voltage rises must equal the sum of the voltage drops. Mesh analysis consists of assuming that currents—termed loop currents—flow in each loop of a network, algebraically summing the voltage drops around each loop, and setting each sum equal to 0.

Consider the circuit shown in Fig. 1-1A-3a, which consists of an inductor and resistor connected in series to a voltage source  $e$ . Assuming a loop current  $i$ , the voltage drops summed around the loop are

$$-e + u_R + u_L = 0 \quad (1-1A-5)$$

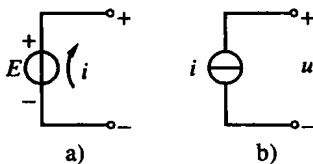


Fig. 1-1A-2 Voltage source and current source

a) Voltage source      b) Current source

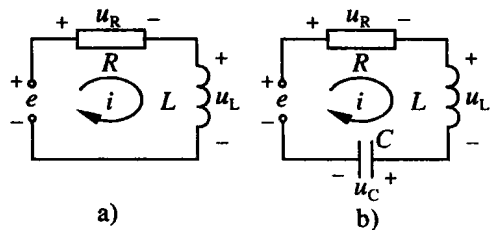


Fig. 1-1A-3 Series circuits containing  $R$ ,  $L$  and  $C$

The input voltage is summed negatively since, in the direction of assumed current, it represents

an increase in voltage. The drop across each passive element is positive since the current is in the direction of the developed voltage.

Using the equations for the voltage drops in a resistor and inductor, we have

$$L \frac{di}{dt} + Ri = e \quad (1-1A-6)$$

Eq. (1-1A-6) is the differential equation for the current in the circuit.

It may be that the inductor voltage rather than the current is the variable of interest in the circuit.<sup>[2]</sup> As noted in Fig. 1-1A-1,  $i = \frac{1}{L} \int u_L dt$ . Substituting this integral for  $i$  in Eq. (1-1A-6) gives

$$u_L + \frac{R}{L} \int u_L dt = e \quad (1-1A-7)$$

After differentiation with respect to time, Eq. (1-1A-7) becomes

$$\frac{du_L}{dt} + \frac{R}{L} u_L = \frac{de}{dt} \quad (1-1A-8)$$

which is the differential equation for the inductor voltage.

Fig. 1-1A-3b shows a series circuit containing a resistor, inductor, and capacitor. Following the mesh-analysis method outlined above, the circuit equation is

$$L \frac{di}{dt} + Ri + \frac{1}{C} \int i dt = e \quad (1-1A-9)$$

Recalling that current  $i = dq/dt$ , a substitution of this variable may be made to eliminate the integral from the equation. The result is the second-order differential equation

$$L \frac{d^2 q}{dt^2} + R \frac{dq}{dt} + \frac{q}{C} = e$$

## WORDS AND TERMS

network *n.* 网络, 电路

resistor *n.* 电阻器

inductor *n.* 电感器

capacitor *n.* 电容器

passive network 无源网络

active network 有源网络

characteristic *adj.* 特性(的); *n.* 特性曲线

Ohm *n.* 欧姆

Faraday *n.* 法拉第

electric charge 电荷

integral *n.* 积分

increment *n.* 增量

armature *n.* 电枢, 衔铁, 加固

aforementioned *adj.* 上述的, 前面提到的

represent *v.* 代表, 表示, 阐明

amplify *v.* 放大

symbolic *adj.* 符号的, 记号的

mesh *n.* 网孔

Kirchhoff's first law 基尔霍夫第一定律

loop current 回路电流

voltage drop 电压降

in series 串联

differential *adj.* 微分的; *n.* 微分

variable *n.* 变量

outline *n.* 轮廓; *v.* 提出……的要点

eliminate *v.* 消除, 对消

## NOTES

[1] In the case of a resistor, the voltage-current relationship is given by Ohm's law, which states that the voltage across the resistor is equal to the current through the resistor multiplied by the value of the resistance.

就电阻来说，电压—电流的关系由欧姆定律决定。欧姆定律指出：电阻两端的电压等于电阻上流过的电流乘以电阻值。

in the case of: 就……来说，就……而论

in case (of): 假如；万一；在……的情况下

in that case: 那么，既然是那样

in this case: 既然是这样

in any case: 无论如何，总之

in all case: 就一切情况而论

[2] It may be that the inductor voltage rather than the current is the variable of interest in the circuit.

或许在电路中，人们感兴趣的变量是电感电压而不是电感电流。

M rather than N: 是 M 而不是 N

of interest: 有价值的；使人感兴趣的；有意义的

## B Three-phase Circuits

A three-phase circuit is merely a combination of three single-phase circuits. Because of this fact, current, voltage, and power relations of balanced three-phase circuits may be studied by the application of single-phase rules to the component parts of the three-phase circuit. Viewed in this light, it will be found that the analysis of three-phase circuits is little more difficult than that of single-phase circuits.<sup>[1]</sup>

### Reasons for Use of Three-phase Circuits

In a single-phase circuit, the power is of a pulsating nature. At unity power factor, the power in a single-phase circuit is zero twice each cycle.<sup>[2]</sup> When the power factor is less than unity, the power is negative during parts of each cycle. Although the power supplied to each of the three phases of a three-phase circuit is pulsating, it may be proved that the total three-phase power supplied a balanced three-phase circuit is constant. Because of this, the characteristics of three-phase apparatus, in general, are superior to those of similar single-phase apparatus.

Three-phase machinery and control equipment are smaller, lighter in weight, and more efficient than single-phase equipment of the same rated capacity. In addition to the above-mentioned advantages offered by a three-phase system, the distribution of three-phase power requires only three fourths as much line copper as does the single-phase distribution of the same

amount of power.

### Generation of Three-phase Voltages

A three-phase electric circuit is energized by three alternating emfs of the same frequency and differing in time phase by 120 electrical degrees. Three such sine-wave emfs are shown in Fig. 1-1B-1. These emfs are generated in three separate sets of armature coils in an AC generator. These three sets of coils are mounted 120 electrical degrees apart on the generator armature. The coil ends may all be brought out of the generator to form three separate single-phase circuits. However, the coils are ordinarily interconnected either internally or externally to form a three-wire or four-wire three-phase system.

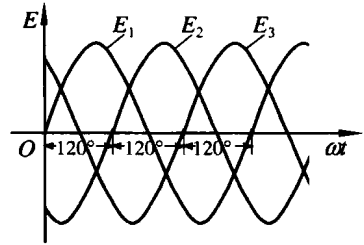


Fig. 1-1B-1 Three sine-wave emfs differing in phase by 120 electrical degrees are used for energizing a three-phase circuit

There are two ways of connecting the coils of three-phase generators, and in general, there are two ways of connecting devices of any sort to a three-phase circuit. These are the *wye-connection* and the *delta-connection*. Most generators are wye-connected, but loads may be either wye-connected or delta-connected.

### Voltage Relations in a Wye-connected Generator

Fig. 1-1B-2a represents the three coils or phase windings of a generator. These windings are so spaced on the armature surface that the emfs generated in them are 120° apart in time phase. Each coil ends lettered S and F (start and finish). In Fig. 1-1B-2a, all the coil ends marked S are connected to a common point N, called the neutral, and the three coil ends marked F are brought

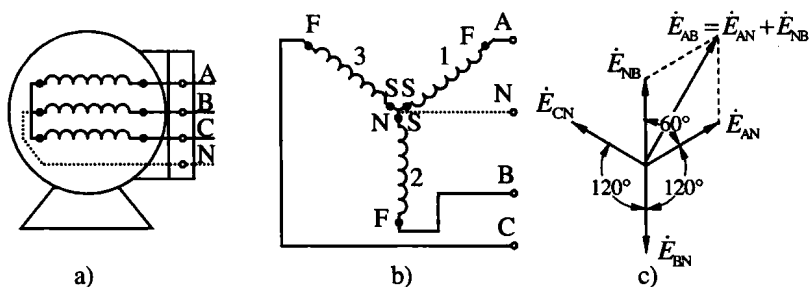


Fig. 1-1B-2 a) Connection of the phase windings in a wye-connection generator  
b) Conventional diagram of a wye connection  
c) Phasor diagram showing the relation between phase and line voltages

out to the line terminals A, B, and C to form a three-wire three-phase supply. This type of connection is called the wye-connection. Often the neutral connection is brought out to the terminal board, as shown by the dotted line in Fig. 1-1B-2a, to form a four-wire three-phase system.

The voltages generated in each phase of an AC generator are called the *phase voltages* (symbol  $E_p$ ). If the neutral connection is brought out of the generator, the voltage from any one of the line terminals A, B, or C to the neutral connection N is a phase voltage. The voltage between any two of the three line terminals A, B, or C is called line-to-line voltage or, simply, a *line voltage* (symbol  $E_L$ ).

The order in which the three voltages of a three-phase system succeed one another is called the phase sequence or the phase rotation of the voltages. This is determined by the direction of rotation of the generator but maybe reversed outside the generator by interchanging any two of the three line wires (not a line wire and a neutral wire).

It is helpful when drawing circuit diagrams of wye connection to arrange the three phases in the shape of a Y as shown in Fig. 1-1B-2b. Note that the circuit of Fig. 1-1B-2b is exactly the same as that of Fig. 1-1B-2a, with the S end of each coil connected to the neutral point and the F end brought out to the terminal in each case. After a circuit diagram has been drawn with all intersections lettered, a phasor diagram may be drawn as in Fig. 1-1B-2c. The phasor diagram shows the three phase voltages  $\dot{E}_{AN}$ ,  $\dot{E}_{BN}$ , and  $\dot{E}_{CN}$  which are  $120^\circ$  apart.

It should be noted in Fig. 1-1B-2 that each phasor is lettered with two subscripts. The two letters indicate the two points between which the voltage exists, and the order of the letters indicates the relative polarity of the voltage during its positive half-cycle. For example, the symbol  $\dot{E}_{AN}$  indicates a voltage between the points A and N with the point A being positive with respect to point N during its positive half-cycle. In the phasor diagram shown, it has been assumed that the generator terminals were positive with respect to the neutral during the positive half-cycle. Since the voltage reverses every half-cycle, either polarity may be assumed if this polarity is assumed consistently for all three phases. It should be noted that if the polarity of point A with respect to N ( $\dot{E}_{AN}$ ) is assumed for the positive half-cycle, then  $\dot{E}_{NA}$  when used in the same phasor diagram should be drawn opposite to, or  $180^\circ$  out of phase with,  $\dot{E}_{AN}$ .<sup>[3]</sup>

The voltage between any two line terminals of wye-connected generator is the difference between the potentials of these two terminals with respect to the neutral. For example, the line voltage  $\dot{E}_{AB}$  is equal to the voltage A with respect to neutral ( $\dot{E}_{AN}$ ) minus the voltage B with respect to neutral ( $\dot{E}_{BN}$ ). To subtract  $\dot{E}_{BN}$  from  $\dot{E}_{AN}$ , it is necessary to reverse  $\dot{E}_{BN}$  and add this phase to  $\dot{E}_{AN}$ . The two phasors  $\dot{E}_{AN}$  and  $\dot{E}_{NB}$  are equal in length and are  $60^\circ$  apart, as shown in Fig. 1-1B-2c. It may be shown graphically or proved by geometry that  $\dot{E}_{AB}$  is equal to 1.73, multiplied by the value of either  $\dot{E}_{AN}$  or  $\dot{E}_{NB}$ . The graphical construction is shown in the phasor diagram. Therefore, in a balanced wye connection

$$E_L = 1.73E_p$$

### Current Relations in a Wye-connected Generator

The current flowing out to the line wires from the generator terminals A, B, and C (Fig. 1-1B-2) must flow from the neutral point N, out through the generator coils. Thus, the current each line wire ( $I_L$ ) must equal the current in the phase ( $I_p$ ) to which it is connected. In a wye connection

$$I_L = I_P$$

## WORDS AND TERMS

Pulsate *v.* 脉动, 跳动, 振动  
 apparatus *n.* 一套仪器, 装置  
 rated *adj.* 额定的, 设计的, 适用的  
 coil *n.* 绕组, 线圈; *v.* 盘绕  
 distribution *n.* 分配, 分布, 配电  
 generator *n.* 发生器, 发电机  
 emf (electromotive force) 电动势  
 interconnect *v.* 互相连接  
 wye *n.* Y 形联结, 星形联结, 三通  
 delta *n.* 希腊字母  $\Delta$  ( $\delta$ ), 三角形 (物)

geometry *n.* 几何学, 几何形状  
 winding *adj.* 缠绕的; *n.* 线圈, 绕组  
 polarity *n.* 极性  
 neutral *adj.* 中性的; *n.* 中性线  
 subscript *n.* 下标, 角注, 索引  
 succeed *v.* 继……之后, 接替  
 intersection *n.* 相交, 逻辑乘法  
 phase sequence 相序  
 reverse *v., n.* 反转; *adj.* 变换极性的

## NOTES

[1] Viewed in this light, it will be found that the analysis of three-phase circuits is little more difficult than that of single-phase circuits.

这样看来, 三相电路的分析比单相电路的分析难不了多少。

viewed in this light: 从这个意义上来看

that: 指代 analysis

[2] At unity power factor, the power in a single-phase circuit is zero twice each cycle.

在功率因数为 1 时, 单相电路里的功率值每个周波有两次为零。

twice each cycle: 每个周波有两次 (为零)。twice 和 each cycle 都做状语。

[3] It should be noted that if the polarity of point A with respect to N ( $\dot{E}_{AN}$ ) is assumed for the positive half-cycle, then  $\dot{E}_{NA}$  when used in the same phasor diagram should be drawn opposite to, or  $180^\circ$  out of phase with,  $\dot{E}_{AN}$ .

应该注意, 如果把 A 点相对于 N 的极性 ( $\dot{E}_{AN}$ ) 定为正半周, 那么  $\dot{E}_{NA}$  在用于同一相量图中时就应该画得同  $\dot{E}_{AN}$  相反, 即相位差为  $180^\circ$ 。

with respect to: 相对于; 关于

## C 专业英语(Specified English)概述

大学生在经过基础英语的学习后, 基本上已掌握了英语的常用语法, 并具有 4000 以上的词汇量, 具备了较扎实的英语基础。进入三年级后, 随着专业课的进一步学习, 学生的专业知识技能也开始逐步加强。具备了以上两个条件后, 应进行专业英语的训练, 在保证 30 万词以上阅读量的基础上, 对本专业英文资料的阅读达到基本的要求。换言之, 掌握专业外语技能是大学基础英语学习的主要目的之一, 是一种素质上的提高, 直接关系到学生的求职和毕

业后的工作能力。

专业英语的重要性体现在很多方面：大到日益广泛的国际间的科学技术交流，小到对产品说明书的翻译。而近几年普及的 Internet 网为工程技术人员提供了更为巨大的专业信息量，作为主要网络语言的英语则对资料查询者提出了更高的要求。

尽管很多人在此之前已经进行了至少 8 年的基础英语学习，但专业英语的学习仍是很必要的。首先，专业英语在词义上具有不同于基础英语的特点和含义，如下例：

**Connect the black pigtail with the dog-house.**

错误译法：把黑色的猪尾巴系在狗窝上。

专业译法：将黑色的引出线接在高频高压电源屏蔽罩上。

通过以上的例子，我们不难认识到专业词汇的一些特点，即同一个词在日常生活中，在不同的专业中可能会有截然不同的含义。例如 bus 这个词，在日常生活中是“公共汽车”的意思，但在计算机中是指“总线”，在电力系统中是指“母线”。单靠日常用语进行望文生义的判断不仅会闹笑话，还有可能出事故。

其次，外文科技文章在结构上也具有很多自身的特点，如长句多、被动语态多、大量的名词化结构等，这都给对原文的理解和翻译带来了基础英语中所难以解决的困难。

再者，专业英语对听、说、读、写、译的侧重点不同，其最主要的要求在于“读”和“译”，也就是通过大量的阅读对外文资料进行正确的理解和翻译(interpretation & translation)；在读和译的基础上，对听、说、写进行必要的训练。此外，专业外文资料由于涉及许多科技内容，而往往极为复杂而难以理解，加之这类文章的篇幅通常很长，所以只有经过一定的专业外语训练，才能完成从基础英语到专业英语的过渡，达到英语学以致用最终的目的。

专业翻译是指把科技文章由原作语言(source language)用译文语言(target language)忠实、准确、严谨、通顺、完整地再现出来的一种语言活动。它要求翻译者在具有一定专业基础知识和英语技能的前提下，借助于合适的英汉科技字典来完成整个翻译过程。专业翻译直接应用于科技和工程，因而对翻译的质量具有极高的要求。翻译上的失之毫厘，工程中就有可能差之千里，造成巨大的损失。例如，这样一个标志牌：

**Control Center. Smoking Free.**

它的意思是“控制中心，严禁吸烟”，free 在这里作“免除……的”讲；而如果理解为“随便的，自由的”，就会产生完全相反的意义。



# UNIT 2

## A The Operational Amplifier

One problem with electronic devices corresponding to the generalized amplifiers is that the gains,  $A_U$  or  $A_I$ , depend upon internal properties of the two-port system ( $\mu$ ,  $\beta$ ,  $R_i$ ,  $R_o$ , etc.).<sup>[1]</sup> This makes design difficult since these parameters usually vary from device to device, as well as with temperature. The operational amplifier, or Op-Amp, is designed to minimize this dependence and to maximize the ease of design. An Op-Amp is an integrated circuit that has many component parts such as resistors and transistors built into the device. At this point we will make no attempt to describe these inner workings.

A totally general analysis of the Op-Amp is beyond the scope of some texts. We will instead study one example in detail, then present the two Op-Amp laws and show how they can be used for analysis in many practical circuit applications. These two principles allow one to design many circuits without a detailed understanding of the device physics. Hence, Op-Amps are quite useful for researchers in a variety of technical fields who need to build simple amplifiers but do not want to design at the transistor level. In the texts of electrical circuits and electronics they will also show how to build simple filter circuits using Op-Amps. The transistor amplifiers, which are the building blocks from which Op-Amp integrated circuits are constructed, will be discussed.

The symbol used for an ideal Op-Amp is shown in Fig.1-2A-1. Only three connections are shown: the positive and negative inputs, and the output. Not shown are other connections necessary to run the Op-Amp such as its attachments to power supplies and to ground potential. The latter connections are necessary to use the Op-Amp in a practical circuit but are not necessary when considering the ideal Op-Amp applications we study in this unit. The voltages at the two inputs and the output will be represented by the symbols  $U^+$ ,  $U^-$ , and  $U_o$ . Each is measured with respect to ground potential. Operational amplifiers are differential devices. By this we mean that the output voltage with respect to ground is given by the expression

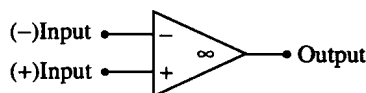


Fig. 1-2A-1 Operational amplifier

$$U_o = A(U^+ - U^-) \quad (1-2A-1)$$

where  $A$  is the gain of the Op-Amp and  $U^+$  and  $U^-$  the voltages at inputs. In other words, the output voltage is  $A$  times the difference in potential between the two inputs.

Integrated circuit technology allows construction of many amplifier circuits on a single composite “chip” of semiconductor material. One key to the success of an operational amplifier is the “cascading” of a number of transistor amplifiers to create a very large total gain. That is, the number  $A$  in Eq. (1-2A-1) can be on the order of 100,000 or more. (For example, cascading of five transistor amplifiers, each with a gain of 10, would yield this value for  $A$ .) A second important