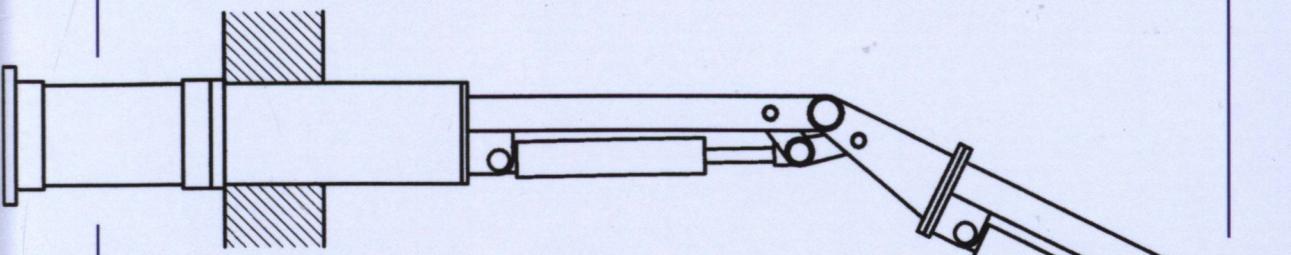


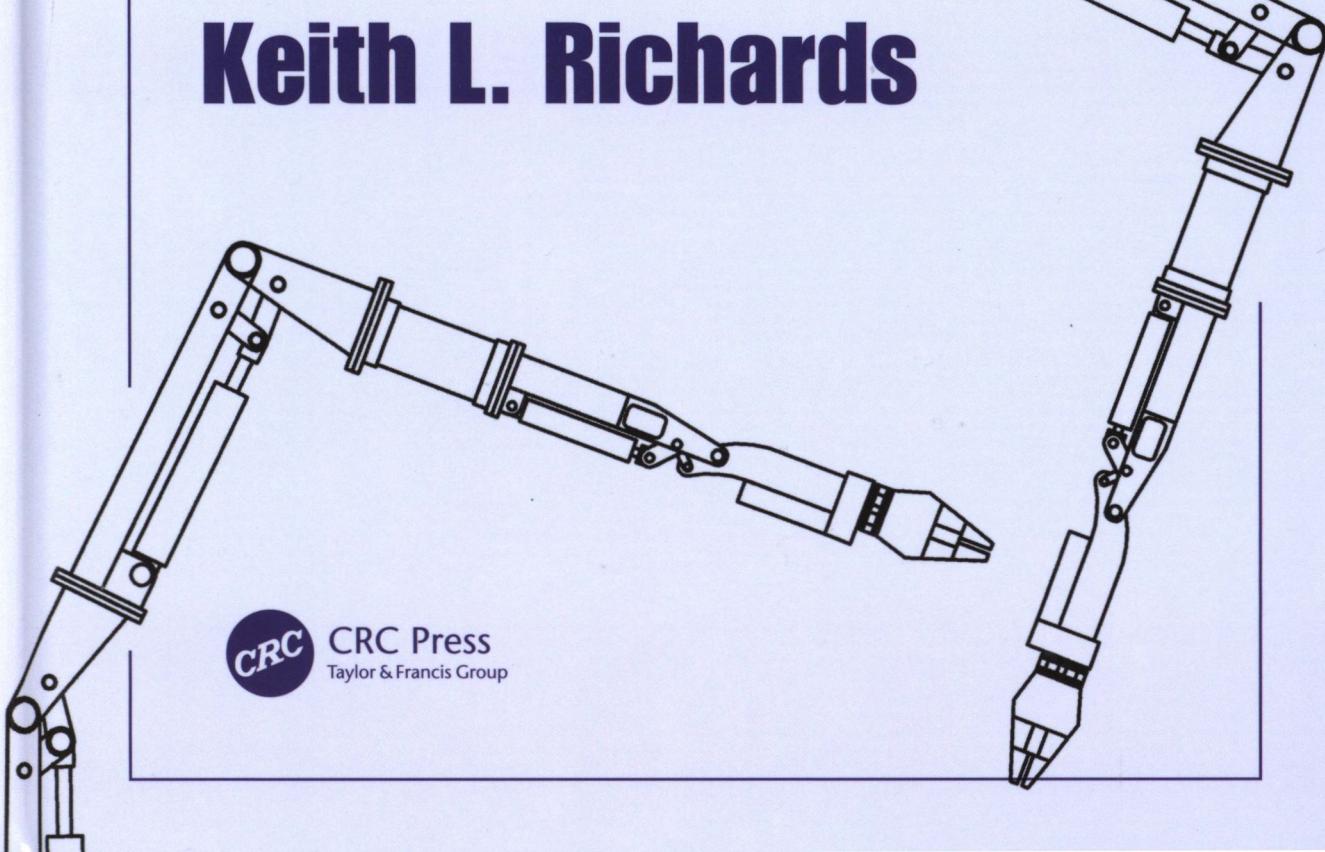
Design Engineer's Sourcebook



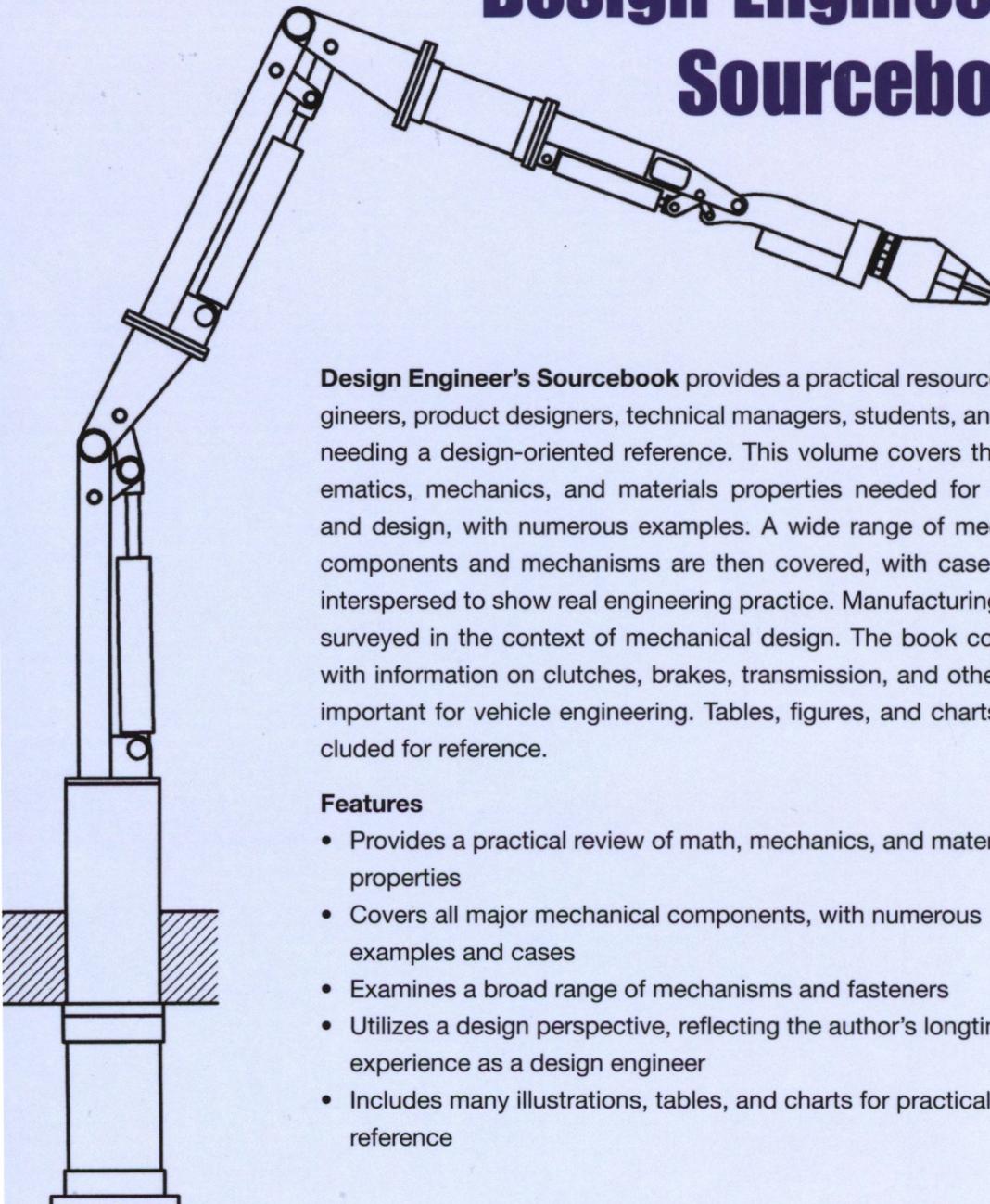
Keith L. Richards



CRC Press
Taylor & Francis Group



Design Engineer's Sourcebook



Design Engineer's Sourcebook provides a practical resource for engineers, product designers, technical managers, students, and others needing a design-oriented reference. This volume covers the mathematics, mechanics, and materials properties needed for analysis and design, with numerous examples. A wide range of mechanical components and mechanisms are then covered, with case studies interspersed to show real engineering practice. Manufacturing is then surveyed in the context of mechanical design. The book concludes with information on clutches, brakes, transmission, and other topics important for vehicle engineering. Tables, figures, and charts are included for reference.

Features

- Provides a practical review of math, mechanics, and materials properties
- Covers all major mechanical components, with numerous examples and cases
- Examines a broad range of mechanisms and fasteners
- Utilizes a design perspective, reflecting the author's longtime experience as a design engineer
- Includes many illustrations, tables, and charts for practical reference

K28968



CRC Press
Taylor & Francis Group
an informa business

6000 Broken Sound Parkway, NW
Suite 300, Boca Raton, FL 33487
711 Third Avenue
New York, NY 10017
2 Park Square, Milton Park
Abingdon, Oxon OX14 4RN, UK

ISBN: 978-1-4987-6341-7

90000
9781498763417

www.crcpress.com

Information about the
protection of personal data
is available at
www.etsi.org

THE S E G I T S C O M P A N Y



Design Engineer's Sourcebook

Keith L. Richards



CRC Press

Taylor & Francis Group

Boca Raton London New York

CRC Press is an imprint of the
Taylor & Francis Group, an **informa** business

CRC Press
Taylor & Francis Group
6000 Broken Sound Parkway NW, Suite 300
Boca Raton, FL 33487-2742

© 2018 by Taylor & Francis Group, LLC
CRC Press is an imprint of Taylor & Francis Group, an Informa business

No claim to original U.S. Government works
Printed on acid-free paper

International Standard Book Number-13: 978-1-4987-6341-7 (Hardback)

This book contains information obtained from authentic and highly regarded sources. Reasonable efforts have been made to publish reliable data and information, but the author and publisher cannot assume responsibility for the validity of all materials or the consequences of their use. The authors and publishers have attempted to trace the copyright holders of all material reproduced in this publication and apologize to copyright holders if permission to publish in this form has not been obtained. If any copyright material has not been acknowledged please write and let us know so we may rectify in any future reprint.

Except as permitted under U.S. Copyright Law, no part of this book may be reprinted, reproduced, transmitted, or utilized in any form by any electronic, mechanical, or other means, now known or hereafter invented, including photocopying, microfilming, and recording, or in any information storage or retrieval system, without written permission from the publishers.

For permission to photocopy or use material electronically from this work, please access www.copyright.com (<http://www.copyright.com/>) or contact the Copyright Clearance Center, Inc. (CCC), 222 Rosewood Drive, Danvers, MA 01923, 978-750-8400. CCC is a not-for-profit organization that provides licenses and registration for a variety of users. For organizations that have been granted a photocopy license by the CCC, a separate system of payment has been arranged.

Trademark Notice: Product or corporate names may be trademarks or registered trademarks, and are used only for identification and explanation without intent to infringe.

Library of Congress Cataloging-in-Publication Data

Names: Richards, Keith L., author.
Title: Design engineer's sourcebook / Keith L. Richards.
Description: Boca Raton : Taylor & Francis, CRC Press, 2018. | Includes index.
Identifiers: LCCN 2017021302 | ISBN 9781498763417 (hardback) | ISBN 9781315367514 (ebook)
Subjects: LCSH: Mechanical engineering--Handbooks, manuals, etc. | Machine design--Handbooks, manuals, etc. | Mechanical movements--Handbooks, manuals, etc.
Classification: LCC TJ153 .R483 2018 | DDC 620/.0042--dc23
LC record available at <https://lccn.loc.gov/2017021302>

Visit the Taylor & Francis Web site at
<http://www.taylorandfrancis.com>

and the CRC Press Web site at
<http://www.crcpress.com>

Printed and bound in the United States of America by
Edwards Brothers Malloy on sustainably sourced paper

Design Engineer's Sourcebook

Author

Keith L. Richards is a retired mechanical design engineer who has worked in the industry for more than 55 years. Initially, he served an engineering apprenticeship with BSA Tools that manufactured a wide range of machine tools including the Acme Gridley, a multi-spindle automatic lathe built under licence, and the BSA single spindle automatic lathes; these were used in Britain and widely exported around the world.

On leaving the BSA, for a number of years he served as a freelance engineering designer in a wide range of industries that also included aluminum rolling mill design, Industrial fork lift trucks, and the Hutton tension leg platform, an offshore oil production platform. His responsibility on this project covered the mooring system components of the platform, and he was answerable to the customer (Conoco) and Lloyds inspectorate for all the engineering aspects. In later years, Keith was more involved in the aerospace industry working on projects covering aircraft undercarriages and environmental control systems for military and commercial aircraft, and also worked on the A380 wing box and trailing edge panels.

Contents

Author.....	xxxv
-------------	------

Section I Reference

1 Mathematics.....	3
1.1 Trigonometry	3
1.1.1 Right-Angled Triangle.....	3
1.1.2 Oblique-Angled Triangles	4
1.1.3 Trigonometric Relations.....	4
1.2 Hyperbolic Functions	5
1.2.1 Inverse Hyperbolic Functions.....	5
1.3 Solution of the Quadratic Equation.....	6
1.4 Solution of Simultaneous Equations (Two Unknowns).....	6
1.5 Laws of Exponents	6
1.6 Expansions	7
1.7 Real Root of the Equation $f(x)=0$ Using the Newton–Raphson Method	7
1.8 Series	8
1.9 Logarithms.....	8
1.10 Differential Calculus	9
1.11 Integral Calculus	12
1.11.1 Integration Is the Inverse of Differentiation	12
1.11.2 Indefinite Integrals	12
1.11.3 Determination of an Area.....	14
1.11.4 Approximate Integration	15
1.12 Laplace Transforms.....	16
1.12.1 First Derivative.....	16
1.12.2 Second Derivative	17
1.12.3 Higher Derivatives.....	18
1.13 Parallel Axis Theorem	18
1.13.1 Calculation of the Moment of Inertia Using the Parallel Axis Theorem.....	18
1.14 Complex Numbers	20
1.14.1 Introduction.....	20
1.14.2 Argand Diagram.....	21
1.14.3 Manipulation of Complex Numbers	22
1.14.3.1 Addition and Subtraction.....	22
1.14.3.2 Multiplication.....	22
1.14.3.3 Division.....	23
1.14.4 Polar Form of a Complex Number	23
1.14.5 Exponential Form of a Complex Number	25
1.15 Determinates	26
1.15.1 Introduction.....	26
1.15.2 Description.....	26

1.15.3 Determinant Order	27
1.15.4 Properties of the Determinant	28
1.15.5 Minors and Cofactors	28
1.16 Matrices	28
1.16.1 Introduction	28
1.16.2 Definitions.....	29
1.16.2.1 Square Matrix	29
1.16.2.2 Row Matrix.....	29
1.16.2.3 Column Matrix	29
1.16.2.4 Diagonal Matrix	30
1.16.2.5 Unit Matrix	30
1.16.2.6 Symmetric Matrix	30
1.16.2.7 Skew Symmetric Matrix—That Is, Anti-Symmetric ($a_{ij} = -a_{ji}$).....	30
1.16.2.8 Null Matrix.....	30
1.16.3 Matrix Algebra	30
1.16.3.1 Additions of Matrices	30
1.16.3.2 Multiplication of Matrices.....	31
1.16.3.3 Transposition of a Matrix.....	31
1.16.3.4 Adjoint of a Matrix	31
1.16.3.5 Inverse of a Square Matrix.....	31
1.16.3.6 Transformation from Cylindrical Coordinates to Cartesian Coordinates	32
2 Introduction to Numerical Methods.....	33
2.1 Introduction	33
2.2 Numerical Methods for Integration	33
2.2.1 Manual Method.....	34
2.2.2 Mid-Ordinate Rule	34
2.2.3 Trapezoidal Rule	37
2.2.4 Simpson's Rule	39
2.3 Evaluation of Errors	40
2.4 Round-Off and Truncation Errors.....	40
2.4.1 Round-Off Errors	41
2.4.2 Truncation Errors.....	41
2.5 Errors Arising from Differentiation	43
2.6 Integration Errors.....	43
2.7 Series	44
2.8 Newton–Raphson Method.....	44
2.8.1 Demonstration of the Method.....	45
2.9 Iterative Methods for Solving Linear Equations	47
2.9.1 Gauss Elimination Method	47
2.9.2 Jacobi Iterative Method	47
2.9.3 Gauss–Seidel Method	49
2.10 Non-Linear Equations	53
2.10.1 Newton's Method.....	53
3 Probability	57
3.1 Introduction	57
3.2 Numerical Value of Probability	57

3.3	Calculation of Probability	57
3.3.1	Proportion of Cases Favorable in an Exhaustive Set	58
3.3.2	Addition of Probabilities.....	59
3.4	Permutations and Combinations	60
3.4.1	Permutations.....	60
3.4.2	Combinations	61
3.4.3	Compound Probability and Multiplication of Probabilities.....	64
3.4.3.1	Compound Events and Dependence	64
3.5	Binomial, Poisson, and Multinomial Laws of Probability	65
3.5.1	Series of Trials	65
3.5.2	Binomial Distribution	66
3.5.3	The Poisson Distribution	68
3.5.4	The Multinomial Law of Probability	69
4	Statistics.....	71
4.1	Introduction	71
4.1.1	Collection of Data	71
4.1.2	Tabulation of Data.....	71
4.1.2.1	Sample Values	72
4.1.2.2	Raw Data	72
4.1.2.3	Bands.....	72
4.1.2.4	Mean.....	73
4.1.2.5	Median	74
4.1.2.6	Mode.....	74
4.1.2.7	Ogive and Quartiles.....	74
4.2	Standard Deviation.....	76
4.2.1	Dispersion	76
4.2.2	Range	76
4.2.3	Variance.....	76
4.2.3.1	Variance of a Population	76
4.2.3.2	Variance of a Sample.....	77
4.2.4	Standard Deviation.....	77
4.3	Fitting Functions to Experimental Data	79
5	Properties of Sections and Figures	85
5.1	Centroid C_x, C_y, C_z	85
5.2	Moment of Inertia/Second Moment of Area.....	85
5.3	Polar Moment of Inertia of a Plane Area	85
6	Properties of Engineering Materials	91
6.1	Introduction	91
6.2	General Physical Properties.....	91
6.2.1	Density	91
6.2.2	Availability/Manufacturability	91
6.2.3	Cost	92
6.2.4	Appearance	92
6.3	Mechanical Properties.....	92
6.3.1	Strength	92
6.3.2	Elastic Limit	92

6.3.3	Proportional Limit	93
6.3.4	Yield Strength.....	93
6.3.5	Ultimate Tensile Strength.....	93
6.3.6	True Fracture Strength.....	93
6.3.7	Ductility	93
6.3.8	Toughness	93
6.3.9	Fatigue Ratio.....	94
6.3.10	Loss Coefficient	94
6.4	Thermal Properties	94
6.4.1	Thermal Conductivity	94
6.4.2	Thermal Diffusivity.....	95
6.4.3	Specific Heat	95
6.4.4	Melting Point	95
6.4.5	Glass Transition Temperature	95
6.4.6	Thermal Coefficient of Expansion.....	95
6.4.7	Thermal Shock Resistance.....	95
6.4.8	Creep Resistance	95
6.5	Materials: Ferrous Metals	97
6.5.1	Cast Iron.....	97
6.5.2	Carbon Steel.....	97
6.5.3	Alloy Steel.....	98
6.5.4	Stainless Steel	98
6.5.5	Tool Steels.....	99
6.6	Materials: Nonferrous Metals	100
6.6.1	Aluminum	100
6.6.1.1	Some Common Uses	100
6.6.1.2	Properties	101
6.6.2	Copper	101
6.6.3	Nickel.....	101
6.6.4	Titanium	101
6.6.5	Zinc	102
6.6.5.1	Uses	102

Section II Mechanics

7	Statics	107
7.1	Force, Mass and Moments	107
7.1.1	System of Units.....	108
7.1.2	Free-Body Diagrams.....	108
7.1.3	Forces and Moments.....	108
7.1.3.1	Force	108
7.1.3.2	Moments	109
7.1.3.3	Couples	110
7.1.3.4	Rigid-Body Equilibrium.....	110
7.2	Structures	111
7.2.1	Pin Joint	112
7.2.1.1	Struts and Ties	112
7.2.1.2	Bow's Notation.....	112

7.2.2	Solving Forces in Pin-Jointed Frames	115
7.2.3	Method of Joints	116
7.2.4	Graphical Methods as Applied to a 2-Dimensional Framework	117
7.2.5	Method of Sections as Applied to a Plane Framework	118
7.3	Vectors and Vector Analysis.....	121
7.3.1	Vector Addition	121
7.3.2	Vector Subtraction.....	121
7.3.3	Resolving a Vector into Components.....	121
7.3.4	Analytical Determination of the Components of the Vector.....	122
7.3.5	Resultant of a Number of Coplanar Vectors (More than Two Vectors)	123
7.3.6	Analytical Solution to Figure 7.22.....	124
7.3.7	Product of Vectors.....	124
7.3.7.1	Multiplication of a Vector 'P' by a Scalar 'K'	124
7.3.7.2	Scalar Product of Two Vectors	124
7.3.8	Vector (or Cross) Product	125
8	Dynamics	127
8.1	Kinematics.....	127
8.2	Nomenclature	127
8.3	Newton's Laws of Motion (Constant Acceleration).....	127
8.3.1	Linear Motion Equations	128
8.3.2	Angular Motion Equations.....	128
8.4	Rectilinear Motions	128
8.4.1	Uniform Linear Motion.....	129
8.4.2	Non-Uniform Linear Motion.....	129
8.4.3	Variable Velocity	129
8.4.4	Variable Acceleration.....	130
8.5	Circular Motion.....	131
8.5.1	Motion on a Circular Path	131
8.5.2	Rolling Wheel.....	131
8.6	Absolute and Relative Motion.....	132
8.7	Rotating Unit Vector	132
8.8	Vector of Point in a Rotating Reference Frame	133
8.9	Velocity of a Point in a Moving Reference Frame	134
8.10	Acceleration of a Particle.....	134
8.11	Kinematics of Rigid Bodies in One Plane.....	135
8.12	Instantaneous Centre of Rotation.....	136
8.13	Kinematics of Rigid Bodies in Three Dimensions	137
8.14	Theorems.....	137
8.15	Translation Motion.....	138
8.16	Rotation about a Fixed Axis	138
8.17	Rotation about a Fixed Point	139
8.18	General Motion.....	140
9	Mechanical Vibrations	143
9.1	Introduction	143
9.2	Single Degree of Freedom: Free Vibrations.....	144
9.2.1	Free Natural Vibrations	144

9.2.2	Simple Harmonic Motion	144
9.2.2.1	Angular Frequency, Frequency and Periodic Time	147
9.2.2.2	Equations for SHM.....	147
9.2.2.3	Free Natural Vibrations of a Single-Degree-of-Freedom System	149
9.2.2.4	Elementary Parts of a Vibrating System	151
9.2.2.5	Linear Elastic Oscillations	152
9.2.2.6	Transverse Vibrations	155
9.2.2.7	Energy Methods (Rayleigh)	157
9.2.2.8	Kinetic Energy	158
9.3	Damped Vibrations.....	161
9.3.1	Viscous Damping.....	162
9.3.2	Coulomb Damping	167
9.3.3	Inertial Damping	168
9.3.4	Internal Damping	168
9.4	Single Degree of Freedom: Forced Vibrations	169
9.4.1	Forced Vibrations.....	171
9.4.1.1	Disturbing Force Acting on Mass	171
9.4.1.2	Phasor Representation.....	172
9.5	Natural Frequency of Beams and Shafts	173
9.5.1	Degrees of Freedom.....	173
9.5.2	Beams Subject to Transverse Vibrations.....	174
9.5.3	Simply Supported Beam Subject to Transverse Vibration	174
9.5.4	Torsional Frequency of a Cantilevered Shaft Carrying a Mass at the Free End.....	175
9.5.5	Torsional Frequency of a Shaft Carrying Two Masses.....	176
9.5.6	Torsionally Equivalent Shafts	176
9.5.7	Torsional Frequency of a Geared Shaft Carrying Two Masses.....	180
9.5.8	Torsional Frequency of a Shaft Carrying Three Masses	185
9.6	Forced Vibrations	186
9.6.1	Overview.....	186
9.6.2	External Forcing	187
9.6.3	Frequency Response Diagrams	189
9.6.4	Harmonic Movement of the Support	193
9.6.5	Magnification Factor.....	194
9.6.6	Transmissibility.....	197
9.6.7	Using Forced Vibration Response to Measure the Properties of a Structure.....	198
10	Control Systems	203
10.1	Introduction to Control Systems Modelling	203
10.1.1	Introduction	203
10.1.1.1	Basics of Control Theory	203
10.1.1.2	Open Loop Control System	204
10.1.1.3	Closed Loop Control System	205
10.1.1.4	Control System Definitions.....	205
10.1.1.5	Feedback Characteristics.....	206
10.1.1.6	Control Models	206
10.1.1.7	Block Diagrams and Transfer Functions	206

10.1.2	Engineering System Models.....	207
10.1.2.1	Similarities of Elements between Systems	208
10.1.2.2	Laplace Transforms.....	209
10.1.2.3	Transfer Functions	209
10.1.2.4	Linear Mechanical Systems	209
10.1.2.5	Rotary Mechanical Systems.....	216
10.1.2.6	Thermal Systems	221
10.1.2.7	Hydraulic System	226
10.1.2.8	Electrical System Models	234
10.1.2.9	Closed Loop System Transfer Function with a Unity Feedback.....	238
10.1.3	Block Diagram and Transfer Function Manipulations.....	240
10.1.3.1	Open Loop Control System	241
10.1.3.2	Closed Loop Control System.....	241
10.1.3.3	Summing Junctions	241
10.1.3.4	Closed Loop System Transfer Functions	243
10.1.3.5	Velocity Feedback.....	244
10.1.3.6	Disturbance.....	246
10.1.3.7	Proportional and Differential Control	248
10.1.3.8	Simplifying Complex Systems	250
10.2	Analysis of Control Systems.....	252
10.2.1	Introduction	252
10.2.1.1	System Response	252
10.2.2	On/Off Control.....	252
10.2.3	Response of Continuous Control Systems.....	254
10.2.3.1	Standard Models	255
10.2.4	Standard Inputs	255
10.2.4.1	Impulse.....	255
10.2.4.2	Step Change	255
10.2.4.3	Ramp or Velocity Change	255
10.2.4.4	Parabolic or Acceleration Change.....	256
10.2.4.5	Sinusoidal Change	256
10.2.4.6	Exponential Change	256
10.2.5	Linear System.....	257
10.2.6	Linear Time-Invariant Systems	257
10.2.7	Laplace Transforms.....	257
10.2.8	The Standard First-Order System	260
10.2.8.1	Response to an Impulse and Step Input.....	260
10.2.9	First-Order Response Graph to a Step Input.....	260
10.2.9.1	First-Order Time Constant.....	261
10.2.10	Response of a Standard First-Order System to a Ramp Input.....	261
10.2.11	Response of a Standard First-Order System to a Sinusoidal Input....	262
10.2.12	Gain of a First-Order System	263
10.2.13	The Use of Partial Fractions to Solve Responses	265
10.2.13.1	Unit Step Input	265
10.2.13.2	Unit Ramp	266
10.2.14	Standard Second-Order System	268
10.2.14.1	Forms of the Standard Transfer Functions.....	268
10.2.14.2	Time Constant Form	268

10.2.14.3	Natural Frequency Form.....	269
10.2.14.4	Polynomial Form.....	269
10.2.14.5	σ and ω_r Form	270
10.2.14.6	Poles	270
10.2.14.7	Response to a Step Input.....	271
10.2.14.8	Amplitude Reduction Factor	273
10.2.14.9	Ramp Input	274
10.2.14.10	Sinusoidal Input	275
10.2.14.11	DC Gain of Second-Order Systems	276
10.2.15	The s-Plane, Poles, and Zeros of the Second-Order System.....	278
10.2.16	Sinusoidal Response	280
10.2.16.1	Integrator	281
10.2.16.2	Differentiator	282
10.2.16.3	Exponential Delay	282
10.2.17	The Standard First-Order Transfer Function	283
10.2.18	The Standard Second-Order Transfer Function	285
10.2.19	Stability Analysis	287
10.2.19.1	Introduction	287
10.2.19.2	Definition.....	287
10.2.19.3	Stability of a Linear Control System.....	288
10.2.19.4	Analysis of Circuit Stability	288
10.2.19.5	Nyquist Diagrams.....	289
10.2.20	Bode Plots	290
10.2.21	Gain and Phase Margins Using the Bode Plot.....	298
11	Physics.....	299
11.1	Heat	299
11.1.1	Temperature	299
11.1.1.1	Temperature Scales	300
11.1.1.2	Kelvin Scale.....	300
11.1.1.3	Effects of Temperature	301
11.1.1.4	Newton's Law of Cooling.....	303
11.1.2	Heat Capacity	305
11.1.3	Heat Transfer.....	305
11.1.3.1	Conduction.....	306
11.1.3.2	Convection	307
11.1.3.3	Radiation	307
11.1.4	Calorimetry	308
11.2	Light	310
11.2.1	Fundamentals	310
11.2.2	Production of Light.....	310
11.2.3	Velocity	310
11.2.4	Other Characteristics	310
11.2.5	Polarization	311
11.2.6	Classification of Polarization	312
11.2.6.1	Linear Polarization.....	312
11.2.6.2	Circular Polarization	312
11.2.6.3	Elliptical Polarization	312
11.2.7	Optics	313