

# PRINCIPLES OF NEURODYNAMICS

PERCEPTRONS AND THE THEORY
OF
BRAIN MECHANISMS

By FRANK ROSENBLATT



SPARTAN BOOKS

6411 CHILLUM PLACE N.W. . WASHINGTON, D.C.

# Library of Congress Card Number 62-12882

Copyright © 1962 by Spartan Books

Reproduction in whole or in part is permitted for any purpose of the United States Government.

Printed in the United States of America

#### PREFACE

It is only after much hesitation that the writer has reconciled himself to the addition of the term "neurodynamics" to the list of such recent linguistic artifacts as "cybernetics", "bionics", "autonomics", "biomimesis", "synnoetics", "intelectronics", and "robotics". It is hoped that by selecting a term which more clearly delimits our realm of interest and indicates its relationship to traditional academic disciplines, the underlying motivation of the perceptron program may be more successfully communicated. The term "perceptron", originally intended as a generic name for a variety of theoretical nerve nets, has an unfortunate tendency to suggest a specific piece of hardware, and it is only with difficulty that its well-meaning popularizers can be persuaded to suppress their natural urge to capitalize the initial "P". On being asked, "How is Perceptron performing today?" I am often tempted to respond, "Very well, thank you, and how are Neutron and Electron behaving?"

That the aims and methods of perceptron research are in need of clarification is apparent from the extent of the controversy within the scientific community since 1957, concerning the value of the perceptron concept. There seem to have been at least three main reasons for negative reactions to the program. First, was the admitted lack of mathematical rigor in preliminary reports. Second, was the handling of the first public announcement of the program in 1958 by the popular press, which fell to the task with all of the exuberance and sense of discretion of a pack of happy bloodhounds. Such headlines as "Frankenstein Monster Designed by Navy Robot That Thinks" (Tulsa, Oklahoma Times) were hardly designed to inspire scientific confidence. Third, and perhaps most significant, there has been a failure to comprehend the difference in motivation between the perceptron program and the various engineering projects concerned with automatic pattern recognition, "artificial intelligence", and advanced computers. For this writer, the perceptron program is not primarily concerned with the inven-

tion of devices for "artificial intelligence", but rather with investigating the physical structures and neurodynamic principles which underlie "natural intelligence". A perceptron is first and foremost a brain model, not an invention for pattern recognition. As a brain model, its utility is in enabling us to determine the physical conditions for the emergence of various psychological properties. It is by no means a "complete" model, and we are fully aware of the simplifications which have been made from biological systems; but it is, at least, an analyzable model. The results of this approach have already been substantial; a number of fundamental principles have been established, which are presented in this report, and these principles may be freely applied, wherever they prove useful, by inventors of pattern recognition machines and artificial intelligence systems.

The purpose of this report is to set forth the principles, motivation, and accomplishments of perceptron theory in their entirety, and to provide a self-sufficient text for those who are interested in a serious study of neurodynamics. The writer is convinced that this is as definitive a treatment as can reasonably be accomplished in a volume of managable size. Since this volume attempts to present a consistent theoretical position, however, the student would be well advised to round out his reading with several of the alternative approaches referenced in Part I. Within the last year, a number of comprehensive reviews of the literature have appeared, which provide convenient jumping-off points for such a study.\*

The work reported here has been performed jointly at the Cornell
Aeronautical Laboratory in Buffalo and at Cornell University in Ithaca. Both
programs have been under the support of the Information Systems Branch of the
Office of Naval Research -- the Buffalo program since July, 1957, and the Ithaca

<sup>\*</sup>See, for example, Minsky's article, "Steps Toward Artificial Intelligence", Proc. I.R.E., 49, January, 1961, for an entertaining statement of the views of the loyal opposition, which includes an excellent bibliography.

program since September, 1959. A number of other agencies have contributed to particular aspects of the program. The Rome Air Development Center has assisted in the development of the Mark I perceptron, and we are indebted to the Atomic Energy Commission for making the facilities of the NYU computing center available to us.

A great many individuals have participated in this work. R. D. Joseph and H. D. Block, in particular, have contributed ideas, suggestions, and criticisms to an extent which should entitle them to co-authorship of several chapters of this volume. I am especially indebted to both of them for their heroic performance in proofreading the mathematical exposition presented here, a task which has occupied many weeks of their time, and which has saved me from committing many a mathematical felony. Carl Kesler, Trevor Barker, David Feign, and Louise Hay have rendered invaluable assistance in programming the various digital computers employed on the project, while the engineering work on the Mark I was carried out primarily by Charles Wightman and Francis Martin at C.A.L. The experimental program with the Mark I was carried out by John Hay. In addition to all of those who have contributed directly to the research activities, the writer is indebted to Professors Mark Kac, Barkley Rosser, and other members of the Cornell faculty for their administrative support and encouragement, and to Alexander Stieber, W. S. Holmes, and the administrative staffs of the Cornell Aeronautical Laboratory and the Office of Naval Research whose confidence and support have carried the program successfully through its infancy.

> Frank Rosenblatt 15 March 1961

#### ERRATA

```
Page 9, line 10: Change Kohler to Köhler
```

Page 111, footnote (line 4): Change; to,

Page 121, line 12: Change "remaining" to "following"

Page 124, line 14: Change  $b_i X^\#$  to  $b_i (X^\#)$ Page 125, line 18: Change  $b_i X^\#$  to  $b_i (X^\#)$ Page 126, line 4: Change  $b_i X^\#$  to  $b_i (X^\#)$ Page 127, line 7: Change  $b_i X^\#$  to  $b_i (X^\#)$ 

Page 139, fourth label under "Typical A-units" should read (Probability  $Q_j - Q_{i,j}$ ) instead of (Probability  $Q_j - Q_i$ ).

Page 142, Figure 10c: Change R = 1.0 to R = .10

Page 147, Equation 6.10: Include  $\mathcal{E}_{ijk}$  in the argument of  $\mathcal{P}_{x}$ .

Page 149, footnote (line 4); Change "displayed to "displaced"

Page 155, line 8: Change  $\alpha_i^*$  to  $\alpha_i^*$ 

Page 159, first two equations: Change  $e_{ir}^{\star}$  to  $c_{ir}^{\star}$ 

Page 160, line 5: Change first word to "close"

Page 165, heading of first table: Correct spelling of "excitatory"

Page 166, line 14: Change page reference from 75 to 102

Page 326, line 1: continuous

Page 356, line 8: Change first symbol from  $M_i^{(t)}$  to  $M^{(i)}(t)$ 

Page 356, line 19: Change  $(t_0)$  to (0)

Page 362, line 11: fifth word should be "region"

Page 391, line 19: Insert the sentence: "Signal transmission times are again taken to be instantaneous."

Page 391, line 22: Change t+1 to t+ $\tau$ 

Page 395, label of last matrix, change < to >

Page 399: In label of last matrix, change 302 to 303

Page 443: In subheading of table, change x = 2 to x = 3

Page 622: Change name in eleventh entry to "Chiu"

#### TABLE OF CONTENTS

				Page Number
PR	EFAC	E		v
		PA	RT I - DEVELOPMENT OF BASIC CONCEPT	rs
1.	INTR	ODUCT	TION	3
2.	HIST	ORICAI	REVIEW OF ALTERNATIVE APPROACHES	9
	2.1		aches to the Brain Model Problem	9
	2.2	Monoty	ypic Models	11
	2.3	Genoty	rpic Models	19
	2.4	Positio	on of the Present Theory	27
3.	PHY	29		
	3.1	Establ	ished Fundamentals	30
		3 1 1	Neuron Doctrine and Nerve Impulses	30
			Topological Organization of the Network	35
			Localization of Function	40
			Innate Computational Functions	43
			Phenomena of Learning and Forgetting	45
			Field Phenomena in Perception	48
			Choice-Mechanisms in Perception and	10
			Behavior	50
		3.1.8	Complex Behavioral Sequences	51
	3.2	Curren	nt Issues	52
		3.2.1	Elementary Memory Mechanisms	53
			Memory Localization	58
			Isomorphism and the Representation of	
			Structured Information	60
		3.2.4	Adaptive Processes in Perception	61
			Influence of Motivation on Memory	63
			The Nature of Awareness and Cognitive	
		0, -, 0	Systems	65
	3.3	Experi	imental Tests of Performance	67
		3.3.1	Discrimination Experiments	67
			Generalization Experiments	69
			Figure Detection Experiments	70
			Quantitative Judgement Experiments	71

			Page Number
	3.3	Experimental Tests of Performance (cont'd)	
		3.3.5 Sequence Recognition Experiments	72
		3.3.6 Relation Recognition Experiments	73
		3 3 7 Program-Learning Experiments	74
		3.3.8 Selective Recall Experiments	75
		3.3.9 Other Types of Experiments 3.3.10 Application of Experimental Designs	75
		to Perceptrons	76
4	BASI	C DEFINITIONS AND CONCEPTS	79
	4 1	Signals and Signal Transmission Networks	79
	4.2	Elementary Units, Signals, and States in a	
		Perceptron	80
	4.3	Definition and Classification of Perceptrons	83
		Stimuli and Environments	87
	4.5	Response Functions and Solutions	87
	4 6	Reinforcement Systems	88
	4 7	Experimental Systems	92
	PA	RT II - THREE-LAYER SERIES-COUPLED PERCEP	TRONS
5	THE	EXISTENCE AND ATTAINABILITY OF SOLUTIONS	TNT
5		MENTARY PERCEPTRONS	97
	5 1	Description of Elementary &-Perceptrons	97
	5 2	The Existence of Universal Perceptrons	99
		The G-matrix of an Elementary &-Perceptron	101
		Conditions for the Existence of Solutions	103
	5.5	The Principal Convergence Theorem	109
	5.6	Additional Convergence Theorems	117
6	O-F	UNCTIONS AND BIAS RATIOS IN ELEMENTARY	
		CEPTRONS	128
	6.1	Definitions and Notation	128
	6 2	Models to be Analyzed	129
		6.2.1 Binomial Models	129
		6.2 2 Poisson Models	131
		6.2.3 Gaussian Models	132
	6.3	Analysis of Q;	133
	6 4	Analysis of Q;;	138
	6.5	Analysis of Q;	146
	6.6	Bias Ratios of A-units	148

			Page Number
7.		FORMANCE OF ELEMENTARY ∞-PERCEPTRONS SYCHOLOGICAL EXPERIMENTS	153
	7.1	Discrimination Experiments with S-controlled Reinforcement	153
		7.1.1 Notation and Symbols	154
		7.1.2 Fixed Sequence Experiments: Analysis	155
		7.1.3 Fixed Sequence Experiments: Examples	162
		7.1.4 Random Sequence Experiments: Analysis	166
		7.1.5 Random Sequence Experiments: Examples	169
	7.2	Discrimination Experiments with Error Correction	ı
		Procedures	172
		7.2.1 Experiments with Binomial Models 7.2.2 Experiments with Constrained Sensory	173
		Connections	179
	7.3	Discrimination Experiments with R-controlled	
		Reinforcement	183
	7.4	Detection Experiments	185
		7.4.1 Detection in Noisy Environments	186
		7.4.2 Detection in Organized Environments	189
	7.5	Generalization Experiments	190
	7.6	Summary of Capabilities of Elementary &-Perceptrons	191
	7.7	Functionally Equivalent Systems	193
8.	PER	FORMANCE OF ELEMENTARY 7-PERCEPTRONS	
٠.		SYCHOLOGICAL EXPERIMENTS	195
	8.1	Discrimination Experiments with S-controlled	
		Reinforcement	196
		8.1.1 Fixed Sequence Experiments: Analysis	196
		8.1.2 Fixed Sequence Experiments: Examples	200
		8.1.3 Random Sequence Experiments: Analysis	202
		8.1.4 Random Sequence Experiments: Examples	203
	8.2	Discrimination Experiments with Error-Corrective	e
		Reinforcement	211
	8.3	Discrimination Experiments with R-controlled	
		Reinforcement	213
	8.4	Detection Experiments	216
	8.5	Generalization and Other Capabilities	219

			Pag	e Number
9.	ELEN	MENTAR	RY PERCEPTRONS WITH LIMITED VALUES	221
	9.1	Analysi	is of Systems with Bounded Values	221
			Terminal Value Distribution in a Bounded	222
			Terminal Value Distribution in Bounded	227
			S-controlled Experiments Performance of Bounded 7-systems in	228
			S-controlled Experiments	232
	9.2	Analys	is of Systems with Decaying Values	233
	9.3	Experi	ments with Decaying Value Perceptrons	235
		9.3.2	S-controlled Discrimination Experiments Error-correction Experiments R-controlled Experiments	235 235 239
10.	SIMP		CEPTRONS WITH NON-SIMPLE A AND R-	245
	10.1	Comple	etely Linear Perceptrons	246
	10.2	Percep	trons with Continuous R-units	248
	10.3	Percep	trons with Non-linear Transmission Functions	254
	10.4	Optimu	m Transmission Functions	261
11.	PERC	CEPTRO	ONS WITH DISTRIBUTED TRANSMISSION TIMES	265
	11.1	Binomi	al Models with Discrete Spectrum of $ au_{i,j}$	265
	11.2	Poisso	n Models with Discrete Spectrum of $ au_{i,j}$	268
	11.3	Models	with Normal Distribution of Ti,	271
12.	PERC	CEPTRO	ONS WITH MULTIPLE R-UNITS	273
	12.1	Perfor Percep	mance Analysis for Multiple R-unit strons	273
	12.2	Coding Percep	and Code-Optimization in Multiple Response otrons	279
	12.3	Experi	ments with Multiple Response Systems	284
13.		EE-LAY NECTIO	ER SYSTEMS WITH VARIABLE S-A NS	287
	13.1	Assign	ed Error, and the Local Information Rule	287
	13.2	Necess	sity of Non-deterministic Correction	289

			Page Number
13,		EE-LAYER SYSTEMS WITH VARIABLE S-A NECTIONS (cont'd)	
	13.3	Back-Propagating Error Correction Procedures	292
	13.4	Simulation Experiments	298
14.		MARY OF THREE-LAYER SERIES-COUPLED EMS: CAPABILITIES AND DEFICIENCIES	303
	PART	III - MULTI-LAYER AND CROSS-COUPLED PERC	EPTRONS
15.		II-LAYER PERCEPTRONS WITH FIXED PRE-	313
	15.1	Multi-layer Binomial and Poisson Models	316
	15.2	The Concept of Similarity-Generalization	320
		15.2.1 Similarity Classes	321
		15.2.2 Measurement of Similarity, Objective and Subjective	324
	15.3	Four-Layer Systems with Intrinsic Similarity Generalization	326
		15.3.1 Perceptron Organization 15.3.2 Analysis 15.3.3 Examples	326 329 338
	15.4	Laws of Similarity-Generalization in Perceptrons	342
16.		R-LAYER PERCEPTRONS WITH ADAPTIVE FERMINAL NETWORKS	345
	16.1	Description of the Model	346
	16.2	General Analysis	348
		16.2.1 Development of the Steady-State Equation 16.2.2 A Numerical Example	348 360
	16.3	Organization of Dichotomies	364
	16.4	Organization of Multiple Classes	370
	16.5	Similarity Generalization	375
	16.6	Analysis of Value-Conserving Models	385
		16.6.1 Analysis of <i>Y</i> -systems 16.6.2 Analysis of <i>Γ</i> -systems	386 388
	16.7	Functionally Equivalent Models	389

		<u>P</u>	age Number
17.	OPE	N-LOOP CROSS-COUPLED SYSTEMS	391
	17.1	Similarity-Generalizing Systems: An Analog of the Four-Layer System	391
	17.2	Comparison of Four-Layer and Open-Loop Cross-Coupled Models	393
	17.3	Reduction of Size Requirements for Universal Perceptrons	401
18.	Q-FU	NCTIONS FOR CROSS-COUPLED PERCEPTRONS	403
	18.1	Stimulus Sequences: Notation	404
	18.2	$Q_l$ Functions and Stability	407
	18.3	$Q_{ij}$ Functions	413
19.		PTIVE PROCESSES IN CLOSED-LOOP CROSS- PLED PERCEPTRONS.	421
	19.1	Postulated Organization and Dynamics	422
	19.2	The Phase Space of the A-units	423
	19.3	The Assumption of Finite Sequences	425
	19.4	General Analysis: The Time-Dependent Equation	427
	19.5	Steady State Solutions	435
	19.6	Analysis of Finite-Sequence Environments	441
	19.7	Analysis of Continuous Periodic Environments	446
	19.8	Analysis of Continuous Aperiodic Environments	451
	19.9	Cross-Coupled Perceptrons with Value-Conservation	453
		19.9.1 Analysis of $\Gamma$ -systems 19.9.2 Analysis of $\Gamma$ -systems	453 456
	19.10	Similarity Generalization Experiments	457
	19.11	Comparison of Cross-Coupled and Multi-Layer Systems	462
20.	PERC	CEPTRONS WITH CROSS-COUPLED S AND R-SYSTEM	AS 465
	20.1	Cross-coupled S-units	465
	20.2	Cross-coupled R-units	466

# PART IV - BACK-COUPLED PERCEPTRONS AND PROBLEMS FOR FUTURE STUDY

21.		K-COUPLED PERCEPTRONS AND SELECTIVE ENTION	471
	21.1	Three-Layer Systems with Fixed R-A Connections	472
		21.1.1 Single Modality Input Systems 21.1.2 Dual Modality Input Systems	472 481
	21.2	Three-Layer Systems with Variable R-A Connections	485
		21.2.1 Fixed Threshold Systems 21.2.2 Servo-Controlled Threshold Systems	485 489
	21.3	Linguistic Concept Association in a Four-Layer Perceptron	493
22.	PRO	GRAM-LEARNING PERCEPTRONS	499
	22.1	Learning Fixed Response Sequences	500
	22.2	Conditional Response Sequences	502
	22.3	Programs Requiring Data Storage	504
	22.4	Attention-Scanning and Perception of Complex Objects	506
	22.5	Recognition of Abstract Relations	508
23.	SENS	ORY ANALYZING MECHANISMS	511
	23.1	Visual Analyzing Mechanisms	512
		23.1.1 Local Property Detectors 23.1.2 Heirarchical Retinal Field Organizations 23.1.3 Sequential Observation Programs 23.1.4 Sampling of Sensory Parameters 23.1.5 "Mixed Strategies" and the Design of General Purpose Systems	512 522 530 532
	23.2	Audio-Analyzing Mechanisms	537
		23. 2. 1 Fourier Analysis and Parameter Sampling 23. 2. 2 A Phoneme-Analyzing Perceptron 23. 2. 3 Melodic Bias in a Cross-Coupled	537 538
		Audio-Perceptron	546
24	PER	CEPTION OF FIGURAL UNITY	549

			Page Number
25.	VARI	ABLE-STRUCTURE PERCEPTRONS	557
	25.1	Structural Modification of S-A Networks	557
	25.2	Systems with Make-Break Mechanisms for Synaptic Junctions	560
26.	BIOL	OGICAL APPLICATIONS OF PERCEPTRON THEOR	Y 563
	26.1	Biological Methods for the Achievement of Complex Structures	563
	26.2	Basic Types of Memory Processes	565
	26.3	Physical Requirements for Biological Memory Mechanisms	567
	26.4	Mechanisms of Motivation	571
27.	CON	CLUSIONS AND FUTURE DIRECTIONS	573
	27.1	Psychological Properties in Neurodynamic Systems	575
	27.2	Strategy and Methodology for Future Study	577
	27.3	Construction of Physical Models and Engineering Applications	581
	27.4	Concluding Remarks	584
		APPENDICES	
API	PENDI	X A - NOTATION AND STANDARD SYMBOLS	589
		otational Conventions tandard Symbols	589 590
API	PENDI	X B - LIST OF THEOREMS AND COROLLARIES	595
API	PENDI	X C - BASIC EQUATIONS	603
AP	PENDI	X D - STANDARD DIAGNOSTIC EXPERIMENTS	607
RE	FERE	NCES	609
DIS	TRIBI	ITION LIST	617

### PART I

# DEVELOPMENT OF BASIC CONCEPTS