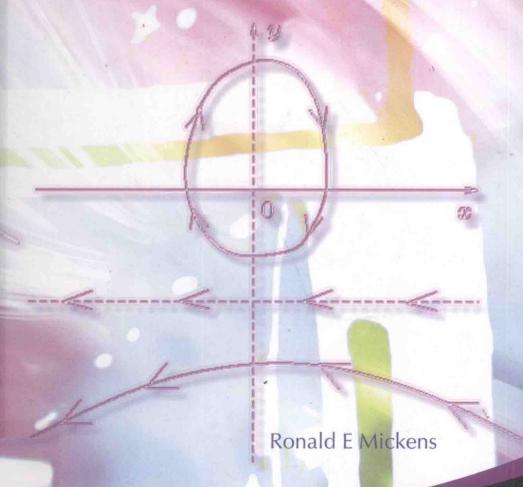
Truly onlinear Oscillations

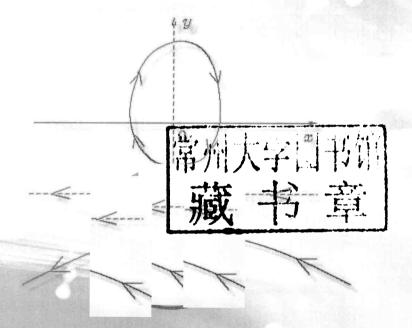
Harmonic Balance, Parameter Expansions, Iteration, and Averaging Methods



World Scientific

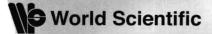
Truly / onlinear Oscillations

Harmonic Balance, Parameter Expansions, Iteration, and Averaging Methods



Ronald E Mickens

Clark Atlanta University, USA



Published by

World Scientific Publishing Co. Pte. Ltd. 5 Toh Tuck Link, Singapore 596224

USA office: 27 Warren Street, Suite 401-402, Hackensack, NJ 07601 UK office: 57 Shelton Street, Covent Garden, London WC2H 9HE

Library of Congress Cataloging-in-Publication Data

Mickens, Ronald E., 1943-

Truly nonlinear oscillations: harmonic balance, parameter expansions, iteration, and averaging methods / by Ronald E. Mickens.

p. cm.

Includes bibliographical references and index.

ISBN-13: 978-981-4291-65-1 (hardcover : alk. paper) ISBN-10: 981-4291-65-X (hardcover : alk. paper)

1. Approximation theory. 2. Nonlinear oscillations. I. Title.

QA221.M53 2010 511'.4--dc22

2009038794

British Library Cataloguing-in-Publication Data

A catalogue record for this book is available from the British Library.

Copyright © 2010 by World Scientific Publishing Co. Pte. Ltd.

All rights reserved. This book, or parts thereof, may not be reproduced in any form or by any means, electronic or mechanical, including photocopying, recording or any information storage and retrieval system now known or to be invented, without written permission from the Publisher.

For photocopying of material in this volume, please pay a copying fee through the Copyright Clearance Center, Inc., 222 Rosewood Drive, Danvers, MA 01923, USA. In this case permission to photocopy is not required from the publisher.

Preface

This small volume introduces several important methods for calculating approximations to the periodic solutions of "truly nonlinear" (TNL) oscillator differential equations. This class of equations take the form

$$\ddot{x} + g(x) = \epsilon F(x, \dot{x}),$$

where g(x) has no linear approximation at x = 0. During the past several decades a broad range of calculational procedures for solving such differential equations have been created by an internationally based group of researchers. These techniques appear under headings such as

- averaging
- combined and linearization
- harmonic balance
- homotopy perturbation
- iteration
- parameter expansion
- variational iteration methods.

Further, these methodologies have not only been applied to TNL oscillators, but also to strongly nonlinear oscillations where a parameter may take on large values. Most of these techniques have undergone Darwinian type evolution and, as a consequence, a large number of papers are published each year on specializations of a particular method. While we have been thorough in our personal examination of the research literature, only those papers having an immediate connection to the topic under discussion are cited because of the magnitude of existing publications and because an interested user of this volume can easily locate the relevant materials from various websites.

We have written this book for the individual who wishes to learn, understand, and apply available techniques for analyzing and solving problems involving TNL oscillations. It is assumed that the reader of this volume has a background preparation that includes knowledge of perturbation methods for the standard oscillatory systems modeled by the equation

$$\ddot{x} + x = \epsilon F(x, \dot{x}).$$

In particular, this includes an understanding of concepts such as secular terms, limit-cycles, uniformly-valid approximations, and the elements of Fourier series.

The basic style and presentation of the material in this book is heuristic rather than rigorous. The references at the end of each chapter, along with an examination of relevant websites, will allow the reader to fully comprehend what is currently known about a particular technique. However, the reader should also realize that the creation and development of most of the methods discussed in this book do not derive from rigorous mathematical derivations. This task is a future project for those who have the interests and necessary background to carry out these procedures. However, these efforts are clearly not relevant for our present needs.

The book consists of seven chapters and several appendices. Chapter 1 offers an overview of the book. In particular, it presents a definition of TNL equations, introduces the concept of odd-parity systems, and calculates the exact solutions to four TNL oscillatory systems.

Chapter 2 provides a brief discussion of several procedures for a priori determining whether a given TNL differential equation has periodic and/or oscillatory solutions. The next four chapters present introductions to most of the significant procedures for calculating analytical approximations to the solutions of TNL differential equations. These chapters discuss, respectively, harmonic balance, parameter expansion, iteration, and averaging methods. Each chapter gives not only the basic methodology for each technique, but also provides a range of worked examples illustrating their use.

The last chapter considers six TNL oscillator equations and compares results obtained by all the methods that are applicable to each. It ends with general comments on TNL oscillators and provides a short listing of unresolved research problems.

We also include a number of appendices covering topics relevant to understanding the general issues covered in this book. The topics discussed range from certain mathematical relations to basic results on linear secondorder differential equations having constant coefficients. Brief presentations Preface ix

are given on Fourier series, the Lindstedt-Poincaré perturbation method, and the standard first-order method of averaging. A final appendix, "Discrete Models of Two TNL Oscillators," illustrates the complexities that may arise when one attempts to construct discretizations to calculate numerical solutions.

I thank my many colleagues around the world for the interest in my work, their generalization of these results and their own original "creations" on the subject of TNL oscillations. As always, I am truly grateful to Ms. Annette Rohrs for her technical services in seeing that my handwritten pages were transformed into the present format. Both she and my wife, Maria Mickens, provided valuable editorial assistance and the needed encouragement to successfully complete this project. Finally, I wish to acknowledge Dr. Shirley Williams-Kirksey, Dean of the School of Arts and Sciences, for providing Professional Development Funds to assist in the completion of this project. Without this support the writing effort would not have been done on time.

Ronald E. Mickens Atlanta, GA August 2009

Contents

Preface	vii
List of Figures	xix
List of Tables	xxi
1. Background and General Comments	1
1.1 Truly Nonlinear Functions	1
1.2 Truly Nonlinear Oscillators	2
1.3 General Remarks	3
1.4 Scaling and Dimensionless Form of Differential Equations	5
1.4.1 Linear Damped Oscillator	5
1.4.2 Nonlinear Oscillator	6
$1.4.3 \ddot{x} + ax^p = 0 \dots \dots \dots \dots \dots$	7
1.4.4 $\ddot{x} + ax + bx^{1/3} = 0 \dots \dots \dots$	8
1.5 Exactly Solvable TNL Oscillators	9
1.5.1 Antisymmetric, Constant Force Oscillator	10
1.5.2 Particle-in-a-Box	11
1.5.3 Restricted Duffing Equation	12
1.5.4 Quadratic Oscillator	14
1.6 Overview of TNL Oscillator Methods	14
1.6.1 Harmonic Balance	16
1.6.2 Parameter Expansion	16
1.6.3 Averaging Methods	17
1.6.4 Iteration Techniques	18
1.7 Discussion	18
Problems	20

	Refe	rences		21
2.	Esta	blishing	Periodicity 2	23
	2.1	Phase-	-Space	23
		2.1.1		24
		2.1.2		24
		2.1.3		25
		2.1.4		25
		2.1.5		26
		2.1.6		26
		2.1.7		26
	2.2	Applic		27
		2.2.1		27
		2.2.2	Several TNL Oscillator Equations	
	2.3	Dissipa	ative Systems: Energy Methods	
		2.3.1	Damped Linear Oscillator	
		2.3.2	Damped TNL Oscillator	
		2.3.3	Mixed-Damped TNL Oscillator	
	2.4	Resum	ne	
	Prob			
3.	Harn	nonic Ba	alance 4	3
	3.1	Direct	Harmonic Balance: Methodology 4	1
	3.2		d Examples	
	0.2	3.2.1	$\ddot{x} + x^3 = 0 \qquad \qquad$	
		3.2.2	$\ddot{x} + x^{-1} = 0 \qquad \qquad$	
		3.2.3	$\ddot{x} + x^2 \operatorname{sgn}(x) = 0 \dots \dots$	
		3.2.4	$\ddot{x} + x^{1/3} = 0 \dots \qquad 5$	
		3.2.5	$\ddot{x} + x^{-1/3} = 0 \dots \qquad 5$	
	3.3		all Approximations	
	0.0	3.3.1	Fourier Expansion	
		3.3.2	Properties of a_k	
		3.3.3	Calculation of \ddot{x}	
	3.4		d Examples	
	0.1	3.4.1	$\ddot{x} + x^3 = 0 \dots \dots \dots \dots \dots \dots \dots \dots \dots $	
		3.4.2	$\ddot{x} + x^2 \operatorname{sgn}(x) = 0 \dots \dots$	
		3.4.3	$\ddot{x} + x^{-1} = 0 \tag{6}$	

Contents	xiii

	3.5	Third-Order Equations	67
		3.5.1 Castor Model	68
		3.5.2 TNL Castor Models	69
	3.6	Resume	70
		3.6.1 Advantages	70
		3.6.2 Disadvantages	70
	Probl	lems	71
	Refer	rences	72
4.	Parar	meter Expansions	75
	4.1	Introduction	75
	4.2	Worked Examples	76
		4.2.1 $\ddot{x} + x^3 = 0$	76
		4.2.2 $\ddot{x} + x^{-1} = 0$	78
		4.2.3 $\ddot{x} + x^3/(1+x^2) = 0 \dots \dots \dots \dots$	80
		4.2.4 $\ddot{x} + x^{1/3} = 0$	81
		4.2.5 $\ddot{x} + x^3 = \epsilon(1 - x^2)\dot{x}$	84
		4.2.6 $\ddot{x} + \text{sgn}(x) = 0$	85
	4.3	Discussion	86
		4.3.1 Advantages	87
		4.3.2 Difficulties	87
	Probl	lems	87
		rences	88
5.	Iterat	tion Methods	89
	5.1	General Methodology	89
	0.1	5.1.1 Direct Iteration	89
		5.1.2 Extended Iteration	91
	5.2	Worked Examples: Direct Iteration	92
		$5.2.1 \dot{x} + x^3 = 0 \dots \dots \dots \dots \dots$	92
		$5.2.2 \ddot{x} + x^3/(1+x^2) = 0 \dots \dots \dots \dots$	97
			100
			103
			105
			108
			110
	5.3		112
	**************************************		113

		5.3.2 $\ddot{x} + x^{-1} = 0$	15
	5.4		17
	0.2		18
			19
	Prob	~	$\frac{1}{20}$
			21
6.	Aver	aging Methods	23
	6.1	Elementary TNL Averaging Methods	24
			24
			26
	6.2		29
			29
			31
			32
			33
			34
		6.2.6 $\ddot{x} + x = -2\epsilon(\dot{x})^{1/3}$	35
		6.2.7 General Comments	37
	6.3	Cveticanin's Averaging Method	38
		6.3.1 Exact Period	39
		6.3.2 Averaging Method	40
		6.3.3 Summary	42
	6.4	*	42
			42
			44
		6.4.3 $\ddot{x} + x x ^{\alpha - 1} = \epsilon(1 - x^2)\dot{x}$	45
	6.5		47
	6.6	Comments	49
	Prob.	lems	
	Refer	rences	52
7.	Comp	parative Analysis 15	55
	7.1	Purpose	55
	7.2	$\ddot{x} + x^3 = 0 \dots \dots$	56
		7.2.1 Harmonic Balance	56
		7.2.2 Parameter Expansion	58
			58

Contents xv

			159
	7.3	$\ddot{x} + x^{1/3} = 0 \dots \dots$	160
		7.3.1 Harmonic Balance	160
		7.3.2 Parameter Expansion	161
		7.3.3 Iteration	162
		7.3.4 Comment	162
	7.4	$\ddot{x} + x^3 = -2\epsilon \dot{x} \dots \dots \dots \dots \dots \dots \dots \dots$	163
		7.4.1 Mickens-Oyedeji	163
		7.4.2 Combined-Linearization-Averaging	165
		7.4.3 Cveticanin's Method	166
			167
	7.5	$\ddot{x} + x^{1/3} = -2\epsilon \dot{x} \dots \dots \dots \dots \dots$	167
		7.5.1 Combined-Linearization-Averaging	167
		7.5.2 Cveticanin's Method	168
		7.5.3 Discussion	170
	7.6	$\ddot{x} + x^3 = \epsilon(1 - x^2)\dot{x} \dots \dots \dots \dots$	170
			170
			171
			172
	7.7	$\ddot{x} + x^{1/3} = \epsilon(1 - x^2)\dot{x} \dots \dots \dots \dots$	175
	7.8		175
		7.8.1 General Comments	176
			177
	7.9		179
	Refere		181
App	pendix	A Mathematical Relations	183
	A.1	Trigonometric Relations	183
		A.1.1 Exponential Definitions of Trigonometric Functions	183
		A.1.2 Functions of Sums of Angles	183
		A.1.3 Powers of Trigonometric Functions	183
		A.1.4 Other Trigonometric Relations	184
		A.1.5 Derivatives and Integrals of Trigonometric	
		Functions	185
	A.2	Factors and Expansions	186
	A.3	Quadratic Equations	187
	A.4		187
	A.5	Differentiation of a Definite Integral with Respect to a Pa-	
			188

A.6	Eigenvalues of a 2×2 Matrix	188
Refe	rences	189
Appendi	x B Gamma and Beta Functions	191
B.1	Gamma Function	191
B.2	The Beta Function	191
B.3	Two Useful Integrals	192
Appendi	x C Fourier Series	193
C.1	Definition of Fourier Series	193
C.2	Convergence of Fourier Series	194
	C.2.1 Examples	194
	C.2.2 Convergence Theorem	194
C.3	Bounds on Fourier Coefficients	195
C.4	Expansion of $F(a\cos x, -a\sin x)$ in a Fourier Series	195
C.5	Fourier Series for $(\cos \theta)^{\alpha}$ and $(\sin \theta)^{\alpha}$	196
Refe	rences	198
	x D Basic Theorems of the Theory of Second-Order	
Di	fferential Equations	199
D.1	Introduction	199
D.2	Existence and Uniqueness of the Solution	200
D.3	Dependence of the Solution on Initial Conditions	200
D.4	Dependence of the Solution on a Parameter	201
Refe	rences	202
Appendi	x E Linear Second-Order Differential Equations	203
E.1	Basic Existence Theorem	203
E.2	Homogeneous Linear Differential Equations	203
12.2	E.2.1 Linear Combination	204
	E.2.2 Linear Dependent and Linear Independent	204
	Functions	204
	E.2.3 Theorems on Linear Second-Order Homogeneous	204
	Differential Equations	204
E.3	Inhomogeneous Linear Differential Equations	204 205
11.0	E.3.1 Principle of Superposition	206
	E.3.2 Solutions of Linear Inhomogeneous Differential	200
	Equations of Linear inhomogeneous Differential	207

Contents xvii

E.4	Linear Second-Order Homogeneous Differential Equations	
	with Constant Coefficients	207
E.5	Linear Second-Order Inhomogeneous Differential	
	Equations with Constant Coefficients	208
E.6	Secular Terms	210
Refere	ences	211
Appendix	F Lindstedt-Poincaré Perturbation Method	213
Refere	ences	216
Appendix	G A Standard Averaging Method	217
Refere	ences	220
Appendix	H Discrete Models of Two TNL Oscillators	221
H.1	NSFD Rules	221
	Discrete Energy Function	222
	Cube-Root Equation	223
H.4	Cube-Root/van der Pol Equation	225
Refere	nces	226
Bibliograph	hy	227
Index		237

List of Figures

onic os- he solid	
	29
d curves	30
0. (b)	
	36
	38
	38
note the $x(0) = \dots$	58
	113
$\epsilon(\dot{x})^{1/3}$.	137
re cubic	
	164
	165
= 0.01,	168
	he solid the sign

7.5.2 This graph is the same as that in Figure 7.5.1, except that the	
interval in time is twice as long	169
7.6.1 Numerical solution of Eq. (7.6.1) for $x(0) = 4$, $y(0) = 0$, and	
$\epsilon = 0.1.$	173
7.6.2 Numerical solution of Eq. (7.6.2) for $x(0) = 0.1$, $y(0) = 0$, and	
$\epsilon=0.1.$	174

List of Tables

3.2.1 Values for $A^{1/3}\Omega(A)$	57
7.4.1 Comparison of the amplitude and effective angular frequencies for the linearly damped, pure cubic, Duffing oscillator	167

Chapter 1

Background and General Comments

This chapter introduces the basic, but fundamental concepts relating to the class of oscillators we call "truly nonlinear." The two phrases "truly nonlinear oscillators" and "truly nonlinear differential equations" are used interchangeable. In Sections 1.1 and 1.2, respectively, we define truly nonlinear (TNL) functions and TNL oscillators. Section 1.3 presents general comments regarding time reversal invariant systems and odd parity oscillators. Section 1.4 discusses the important topic of the elimination of dimensional quantities in the physical nonlinear differential equations through the use of scaling parameters. The existence of and exact solutions to four TNL oscillators are given in Section 1.5; this is followed by a brief overview of four methods that can be used to construct analytic approximations to the periodic solutions for TNL oscillator differential equations. We conclude the chapter with a set of possible criteria that may be used to judge the value of a calculational method for generating approximate solutions.

1.1 Truly Nonlinear Functions

A TNL function is defined with respect to its properties in a neighborhood at a given point. For our purposes, we select x = 0. Thus, for a function f(x), we make the following definition:

Definition 1.1. f(x) is a TNL function, at x = 0, if f(x) has no linear approximation in any neighborhood of x = 0.

The following are several explicit examples of TNL functions

$$f_1(x) = x^3$$
, $f_2(x) = x^{1/3}$, $f_3(x) = x + x^{1/3}$. (1.1.1)