CHAOTIC DYNAMICS

From the One-Dimensional Endomorphism to the Two-Dimensional Diffeomorphism

Christian Mira

Groupe d'Etude des Systèmes Non Linéaires et Applications INSA Toulouse France





World Scientific Publishing Co. Pte. Ltd. P.O. Box 128, Farrer Road, Singapore 9128

U.S.A. office: World Scientific Publishing Co., Inc. 687 Hartwell Street, Teaneck NJ 07666, USA

Library of Congress Cataloging-in-Publication data is available.

CHAOTIC DYNAMICS

Copyright © 1987 by World Scientific Publishing Co Pte Ltd.

All rights reserved. This book, or parts thereof, may not be reproduced in any form or by any means, electronic or mechanical, including photocopying, recording or any information storage and retrieval system now known or to be invented, without written permission from the Publisher.

ISBN 9971-50-324-7

Printed in Singapore by Fong and Sons Printers Pte. Ltd.

PREFACE

The subject matter concerns the study of complex motions of dynamical systems, via the basic mathematical tool of maps (equivalent denomination recurrences; a non-invertible map being an endomorphism, an invertible and differentiable one being a diffeomorphism). More precisely, the book treats the properties of a class of determinist mathematical models, the solutions of which have not the periodical regularity. Nowadays, depending on the context, such solutions are called "chaotic". Since few years, chaotic dynamics has become a favour choice for the most part of disciplines dealing with evolution phenomena. It results a considerable increase of the number of publications.

Due to its sudden and "explosive" growth, the subject matter has been developed independently of fundamental results obtained before. Then many present results are rediscoveries, or variants of older ones.

From this point of view the book will appear non-conventional, because its basic references are not those of the literature now considered as classical. Some readers will no doubt find occasions to feel irritated by it. More particularly, the assertion that so popular present notions as those of "invariant coordinates", "kneading invariant", and others, are variant of Myrberg's results will appear disappointing for some. Nevertheless one of the purposes of this publication is to give to the reader an information about generally unknown works of Hadamard, Lattès, Cigala, Myrberg, Neimark, Leonov, Pulkin, ..., and thus to restore certain anteriorities. However, it is worth of note that this choice does by no means constitute a negative judgment of the works of the literature now called classical. Generally written according to the present standards of the "abstract theory of dynamical systems", they are excellent and necessary from the point of view of formal exposition and rigour. With these criterions, such works conserve wholly their own merits, and must be considered as productions of quality.

The debate which might result from the choices of this book would not be a new one. So, in his paper, "George David Birkhoff and his mathematical work" (Bull. Amer. Math. Soc., May 1946, vol. 52, n° 5, part 1, pp. 357-391), Morse wrote:

"Birkhoff was uncompromising in his appraisal of mathematics, by the test of originality and relevance. For him the systematic organization or exposition of a mathematical theory was always secondary in importance to its discovery. I recall his remarks on a mathematical treatise that had come to his attention and eventually had a wide circulation but which he did not regard as original. Birkhoff said: "I read this book through in half hour"... Some of the current mathematical theories were regarded by Birkhoff as no more than relatively obvious elaborations of concrete exemples".

Besides before Birkhoff, the famous mathematician Halphen is also known to have often complained that non-essential generalizations are overcrowding the publication media. In connection with this, it is well known that the majority of scientists were not led to their discoveries by a process of deduction from general postulates or general principles, but rather by a thorought examination of properly chosen particular cases. The generalizations have come later, because it is far easier to generalize an established result than to discover a new line of argument |G23|.

The book may also appear non-conventional from another point of view, which incidentally is a consequence of the first one. Indeed, another possible reason of irritation for certain abstractly inclined readers might be related to the terminology adopted from the original works and the absence of the previously mentioned ars-pro-artis generalizations so popular in contemporary mathematics. The resulting formulation of problems may therefore appear primitive, sometimes even simplistic. The style may appear less formal and rigorous than that of contemporary papers about the abstract theory of dynamical systems. The answer to this eventual remark consits in stating precisely that the book does not pretend to be a mathematical treatise on dynamical systems (it is published in a physics collection), because it is not presented in a sufficiently elaborate and rigorous form. Its objective is far more modest and consists of:

- -(a)- giving among the basic tools of dynamical systems theory, a large part of the most efficient ones for solving practical problems (cf. such problems for example in |G| 35 |G| 18 |N| 5 |C| 1.
- -(b)- understanding dominating internal mechanisms of evolution processes, and thus preserving a phenomenological transparency through the simplest possible concrete examples (in the sense of the above mentioned Birkhoff's citation), from which perhaps "standard" mathematical theories might be elaborated. Indeed, it can be considered that the field of "concrete dynamic systems" is constituted by two sets of results. The first one is related to the study of problems directly suggested by practice (Physics, Engineering,...). The second one concerns the study of equations, not directly tied with practice, but having the lowest dimension, and the simplest structure, which permit to isolate in the purest form a "mathematical phenomenon", by eliminating "parasitic effects" of a more complicated structure. The bringing to light of the phenomenon of Myrberg's period doubling cascades, and their accumulations,

from the very simple discrete dynamic system $x_{n+1} = x_n^2 - \lambda$ (x being a real variable, λ a real parameter, $n = 0, 1, 2, \ldots$ is of such a type, by reason of its many practical implications. The Smale's horseshoe is also of this type. Consequently, the approach which is adopted is a geometric one, based on an important number of figures.

-(c)- stimulating some ways of research from the choices of examples.

Is is worth of note that the choice of this less formal style has again the advantage of optimizing the interdisciplinary communication, even if it has to appear old-fashioned to abstractly inclined readers.

Beyond as systematic as possible a study of critical cases in the Ljapunov'sense, and of the crossing through the corresponding bifurcations, it is attempted to realize the mentioned objective by showing that two basic fractal bifurcations structures play a fundamental role in the understanding of the dominating internal mechanisms in a wide class of chaotic behaviours. They were called:

- "box-within-a-box" (or "embedded boxes" in |G 14|) bifurcations structure (structure de bifurcations boites-emboitées in French | G 32 M 25, 1975), which corresponds to an ordering of the Myrberg'spectra (often called in the contemporary literature Feigenbaum's cascades of bifurcations by period doubling).
- "boxes in files" bifurcations structure (structure de bifurcation boites en files' | M 27 |, 1978) which corresponds to an ordering of the Farey's sequences of fractions in their lowest terms, and which was elaborated from an adaptation of the Leonov's results |L 14 | about piecewise linear maps bifurcations structure.

From the knowledge of these structures, it resulted the elaboration of a particular symbolism associated with their fractal properties, and the introduction of new notions such as :

- . fuzzy, or chaotic, basin boundary (frontière floue | M 23 |, 1975)
- . average value cycle (cycle en valeur moyenne" | M 22 |, 1976) known now
- under the denomination phenomenon of intermittency . average value cyclic chaotic segment (segment stochastique cyclique en valeur moyenne" M 22, 1976) related to what it is now called attractor in crisis.
- . adjoint cycles, and self adjoint cycle | K 3 | F 7 (1985) which extend the possibilities of the symbolic dynamics, and which permits an understanding of the complex communications between sheets of a foliated box-within-a-box bifurcation structure |F 7 ||F 8 ||F 9|.
- . the notions related to various non-classical global bifurcations, a part of them characterizing the transition order z chaos.

A non negligible part of the book constitutes a synopsis of slowly accumulated results obtained by the research group of Toulouse which works about non linear dynamical systems since 1962. The existence of this group would not be possible without my meeting I. GUMOWSKI in 1958. From this personal event resulted my "initiation" into the famous (but in this time rather little known in western countries) works of the Andronov's school | B 14|. Since that time, a long friendly collaboration has permited a continuous and fruitfull action in this field, and many common publications using Andronov ideas. I. Gumowski is gratefully acknowledged for his invaluable contribution to the researches of the Toulouse group, which thus has profited of his interdisciplinary scientific knowledges of exceptional extent. All the researchers who worked, and who presently are working in this group, are also acknowledged. A particular mention is made to H. Kawakami, who efficiency collaborated at this task as a visiting Professor in 1984-1985. His presence gave a new and important impulsion to the studies related to the two-dimensional diffeomorphism, when he introduced the above mentioned fruitful notion of "adjoint cycles" and "self adjoint cycle".

Since 1978, R. Thom has accepted to present some papers of the group in "Comptes Rendus de l'Académie des Sciences de Paris". He is warmly thanked for his interest to the corresponding work, and for some fruitfull discussions which resulted.

Voluntarily certain subjects are not treated (renormalization, fractal dimension, applications to practical dynamical problems, ...). For a usefull complementary information on them, and others developed in this book, among the numerous available publications, it is suggested to consult:

- * The Neimark's book \mid N 5 \mid (1972) devoted to the method of point mappings and their applications to the theory of automatic control and the theory of dynamical systems. Scientist of the Andronov's school, Neimark has brought one of the most important contributions to this question.
- * The Guckenheimer and Holmes book \mid G 18 \mid (1983) dealing with non linear oscillations, dynamical systems and bifurcations, which is one of the most interesting publications recently published.
- * The Gumowski and Mira's book |G| 35| (1980) about chaotic dynamics, based on the point mappings method, with applications to engineering problems. The book |G| 36| (1980) of the same authors completes the theoretical aspects of |G| 35|.
- * The book "Chaos" by Hao Bai-Lin (World Scientific Singapore, 1984), which is a selection of the classical literature on chaos with 41 papers among the most known.
- * The Holmes and Whitley's paper \mid H 10 \mid (1984) which constitutes the most complete study on homoclinic tangency in two-dimensional diffeomorphisms. The original study of \mid H11 \mid (1985) by Holmes and Williams.
- * The series of papers by Grebogi, Mc Donald, Kostelich, Ott, and Yorke |G| = |G| = |G| 10, |M| = |G| 11, |M| = |G| 11, |M| = |G| 12, |M| = |G| 12, |M| = |G| 13, |M| = |G| 13, |M| = |G| 14, |M| = |G| 15, |M| = |G| 15, |M| = |G| 16, |M| = |G| 17, |M| = |G| 18, |M| = |G| 18, |M| = |G| 17, |M| = |G| 18, |M| = |G| 18,

chaotic transients.

- * The book "Circuits non linéaires" by M. Hasler and J. Neirynck (Presses Polytechniques Romandes, 1985) which gives examples of electrical circuits with chaotic behaviours.
- * A recentsystematic study of chaotic dynamics in an electrical circuit can also be found in the paper "The double scroll" by L.O. Chua, T. Matsumoto and M. Komuro, I.E.E.E. Trans. on Circ. and Syst., vol CAS 32, n° 8 (1985), 798-813. About such studies, it is worth of note the important contribution of Hayashi and Kawakami since 1972 (cf. some references in | K 2 | and | M 48 |).
- * The very recent book "Difference equations and their applications" by A.N. Sharkovsky, Yu. L. Maistrenko, E. Yu. Romanenko (Kiev Naukova Dumka, 1986). Here, new results of the authors, concerning methods of qualitative study of different classes of difference equations, and differential-difference equations, are laid.

٥٥

Not having a usual practice of english, the quality of the english of this book is certainly affected. The reader may excuse this fact.

A part of the research of Chapter 6 was executed under contract DRET $n^{\circ}\,$ 85-1303 (French Ministry of Defense).

The most part of the figures were drawn by G. Roussel, and a part of the text was typed by Mrs C. Grima. These contributions are gratefully acknowledged.

Toulouse, April 1987

Christian MIRA

CONTENTS

CHAPTER 1: DYNAMIC SYSTEMS AND RECURRENCES. GENERALITIES. 1.1. Continuous dynamic systems and discrete dynamic systems. 1.2. Birkhoff classification of dynamic motions. Impredictibility of chaotic motions. 3.3. Some considerations about recurrences. 1.4. Considerations about stability. Some definitions. 1.5. The Poincaré's method of surface of section. 1.6. Diffeomorphism and endomorphism. The Hadamard's theorem. The two classes of endomorphisms. 1.7. Imbedding of an endomorphism into a diffeomorphism with a higher dimension. 1.8. The Valiron's results. 1.9. Consequences of the Valiron's results. 1.10. Autonomous recurrences and the Schröder's equation. 1.10.1. Generalities. 1.10.2. Basin boundary and the Schröder equation. 1.10.3. One-dimensional recurrences and chaotic behaviour. Generalization of the Chebyshev's polynomials. 1.10.4. Generalization to m-dimensional recurrences m> 1. 1.11. The problem of the fractional iterates. 22. Autonomous linear case. 23. Autonomous non linear case. The singularities. 23. Autonomous non linear case. Stability of fixed point and cycles. 23. 1. Recurrence defined by a smooth function. 23. 2. Autonomous non linear case. Local bifurcations. 24. Autonomous non linear case. Local bifurcations. 24. Autonomous non linear case. Local bifurcations. 25. 4. Autonomous non linear case. Local bifurcations. 26. 4. Autonomous non linear case. Local bifurcations. 27. Autonomous non linear case. Local bifurcations.	Preface	vii
1.1. Continuous dynamic systems and discrete dynamic systems. 1.2. Birkhoff classification of dynamic motions. Impredictibility of chaotic motions. 1.3. Some considerations about recurrences. 1.4. Considerations about stability. Some definitions. 1.5. The Poincaré's method of surface of section. 1.6. Diffeomorphism and endomorphism. The Hadamard's theorem. The two classes of endomorphisms. 1.7. Imbedding of an endomorphism into a diffeomorphism with a higher dimension. 1.8. The Valiron's results. 1.9. Consequences of the Valiron's results. 1.10.1. Generalities. 1.10.1. Generalities. 1.10.1. Generalities. 1.10.2. Basin boundary and the Schröder's equation. 1.10.3. One-dimensional recurrences and chaotic behaviour. Generalization of the Chebyshev's polynomials. 1.10.4. Generalization to m-dimensional recurrences m > 1. 1.11. The problem of the fractional iterates. CHAPTER 2: SOME PROPERTIES OF ONE-DIMENSIONAL RECURRENCES (maps). Introduction. 2.1. Autonomous linear case. 2.2. Autonomous non linear case. The singularities. 2.3. Autonomous non linear case. Stability of fixed point and cycles. 2.3.1. Recurrence defined by a smooth function. 2.3.2. The function defining the recurrence is not a smooth one. 2.4.1. Recurrence defined by a smooth function. 2.4.2. Recurrence defined by a smooth function. 2.4.1. Recurrence defined by a smooth function. 2.4.2. Recurrence defined by a smooth function.	CHAPTER 1 : DYNAMIC SYSTEMS AND RECURRENCES. GENE	RALITIES.
systems. 1.2. Birkhoff classification of dynamic motions. Impredictibility of chaotic motions. 1.3. Some considerations about recurrences. 1.4. Considerations about stability. Some definitions. 1.5. The Poincard's method of surface of section. 1.6. Diffeomorphism and endomorphism. The Hadamard's theorem. The two classes of endomorphisms. 1.7. Imbedding of an endomorphism into a diffeomorphism with a higher dimension. 1.8. The Valiron's results. 1.9. Consequences of the Valiron's results. 1.10. Autonomous recurrences and the Schröder's equation. 1.10.1. Generalities. 1.10.2. Basin boundary and the Schröder equation. 1.10.3. One-dimensional recurrences and chaotic behaviour. Generalization of the Chebyshev's polynomials. 1.10.4. Generalization to m-dimensional recurrences m > 1. 1.11. The problem of the fractional iterates. CHAPTER 2: SOME PROPERTIES OF ONE-DIMENSIONAL RECURRENCES (maps). Introduction. 2.1. Autonomous linear case. 2.2. Autonomous non linear case. The singularities. 2.3. Autonomous non linear case. Stability of fixed point and cycles. 2.3.1. Recurrence defined by a smooth function. 2.3.2. The function defining the recurrence is not a smooth one. 2.4.1. Recurrence defined by a smooth function. 2.4.2. Recurrence defined by a smooth function. 2.4.1. Recurrence defined by a smooth function. 2.4.2. Recurrence defined by a smooth function.		
dictibility of chaotic motions. Impredictibility of chaotic motions. 1.3. Some considerations about recurrences. 1.4. Considerations about stability. Some definitions. 1.5. The Poincaré's method of surface of section. 1.6. Diffeomorphism and endomorphism. The Hadamard's theorem. The two classes of endomorphisms. 1.7. Imbedding of an endomorphism into a diffeomorphism with a higher dimension. 1.8. The Valiron's results. 1.9. Consequences of the Valiron's results. 1.10. Autonomous recurrences and the Schröder's equation. 1.10.1. Generalities. 1.10.2. Basin boundary and the Schröder equation. 1.10.3. One-dimensional recurrences and chaotic behaviour. Generalization of the Chebyshev's polynomials. 1.10.4. Generalization to m-dimensional recurrences m > 1. 1.11. The problem of the fractional iterates. 22. Autonomous linear case. 23. Autonomous linear case. 24. Autonomous non linear case. Stability of fixed point and cycles. 25. Autonomous non linear case. Stability of fixed point and cycles. 26. Autonomous non linear case. Local bifurcations. 27. Autonomous non linear case. Local bifurcations. 28. Autonomous non linear case. Local bifurcations. 29. Autonomous non linear case. Local bifurcations. 20. Autonomous non linear case. Local bifurcations. 20. Autonomous non linear case. Local bifurcations. 21. Autonomous non linear case. Local bifurcations.		
dictibility of chaotic motions. 1.3. Some considerations about recurrences. 1.4. Considerations about stability. Some definitions. 1.5. The Poincaré's method of surface of section. 1.6. Diffeomorphism and endomorphism. The Hadamard's theorem. The two classes of endomorphisms. 1.7. Imbedding of an endomorphism into a diffeomorphism with a higher dimension. 1.8. The Valiron's results. 1.9. Consequences of the Valiron's results. 1.10.1. Generalities. 1.10.2. Basin boundary and the Schröder equation. 1.10.3. One-dimensional recurrences and chaotic behaviour. Generalization of the Chebyshev's polynomials. 1.10.4. Generalization to m-dimensional recurrences m > 1. 1.11. The problem of the fractional iterates. CHAPTER 2: SOME PROPERTIES OF ONE-DIMENSIONAL RECURRENCES (maps). Introduction. 2.1. Autonomous linear case. 2.2. Autonomous non linear case. The singularities. 2.3. Autonomous non linear case. Stability of fixed point and cycles. 2.3.1. Recurrence defined by a smooth function. 2.3.2. The function defining the recurrence is not a smooth one. 2.4.1. Recurrence defined by a smooth function. 2.4.2. Recurrence defined by a smooth function. 2.4.2. Recurrence defined by a smooth function. 2.4.2. Recurrence defined by a smooth function.		Impre-
1.4. Considerations about stability. Some definitions. 1.5. The Poincaré's method of surface of section. 1.6. Diffeomorphism and endomorphism. The Hadamard's theorem. The two classes of endomorphisms. 1.7. Imbedding of an endomorphism into a diffeomorphism with a higher dimension. 1.8. The Valiron's results. 1.9. Consequences of the Valiron's results. 1.10.1. Generalities. 1.10.2. Basin boundary and the Schröder equation. 1.10.3. One-dimensional recurrences and chaotic behaviour. Generalization of the Chebyshev's polynomials. 1.10.4. Generalization to m-dimensional recurrences m > 1. 1.11. The problem of the fractional iterates. CHAPTER 2: SOME PROPERTIES OF ONE-DIMENSIONAL RECURRENCES (maps). Introduction. 2.1. Autonomous linear case. 2.2. Autonomous non linear case. Stability of fixed point and cycles. 2.3. Recurrence defined by a smooth function. 2.3.2. The function defining the recurrence is not a smooth one. 2.4.1. Recurrence defined by a smooth function. 2.4.2. Recurrence defined by a continuous but not	dictibility of chaotic motions.	
1.5. The Poincaré's method of surface of section. 1.6. Diffeomorphism and endomorphism. The Hadamard's theorem. The two classes of endomorphisms. 1.7. Imbedding of an endomorphism into a diffeomorphism with a higher dimension. 1.8. The Valiron's results. 1.9. Consequences of the Valiron's results. 1.10.1. Generalities. 1.10.2. Basin boundary and the Schröder equation. 1.10.3. One-dimensional recurrences and chaotic behaviour. Generalization of the Chebyshev's polynomials. 1.10.4. Generalization to m-dimensional recurrences m > 1. 1.11. The problem of the fractional iterates. 29 1.11. The problem of the fractional iterates. 31 CHAPTER 2: SOME PROPERTIES OF ONE-DIMENSIONAL RECURRENCES (maps). Introduction. 2.1. Autonomous linear case. 2.2. Autonomous non linear case. Stability of fixed point and cycles. 2.3. Recurrence defined by a smooth function. 2.3.2. The function defining the recurrence is not a smooth one. 2.4.1. Recurrence defined by a smooth function. 2.4.2. Recurrence defined by a smooth function. 2.4.1. Recurrence defined by a smooth function. 2.4.2. Recurrence defined by a smooth function.	The state of the s	6
1.6. Diffeomorphism and endomorphism. The Hadamard's theorem. The two classes of endomorphisms. 1.7. Imbedding of an endomorphism into a diffeomorphism with a higher dimension. 1.8. The Valiron's results. 1.9. Consequences of the Valiron's results. 1.10.1. Generalities. 1.10.2. Basin boundary and the Schröder's equation. 1.10.3. One-dimensional recurrences and chaotic behaviour. Generalization of the Chebyshev's polynomials. 1.10.4. Generalization to m-dimensional recurrences m > 1. 1.11. The problem of the fractional iterates. 29. 1.11. The problem of the fractional iterates. 31. CHAPTER 2: SOME PROPERTIES OF ONE-DIMENSIONAL RECURRENCES (maps). Introduction. 2.1. Autonomous linear case. 2.2. Autonomous non linear case. Stability of fixed point and cycles. 2.3.1. Recurrence defined by a smooth function. 2.3.2. The function defining the recurrence is not a smooth one. 2.4.1. Recurrence defined by a smooth function. 2.4.2. Recurrence defined by a smooth function. 2.4.1. Recurrence defined by a smooth function. 2.4.2. Recurrence defined by a smooth function.	1.4. Considerations about stability. Some defini	
theorem. The two classes of endomorphisms. 1.7. Imbedding of an endomorphism into a diffeomorphism with a higher dimension. 1.8. The Valiron's results. 1.9. Consequences of the Valiron's results. 1.10.1. Generalities. 1.10.2. Basin boundary and the Schröder equation. 1.10.3. One-dimensional recurrences and chaotic behaviour. Generalization of the Chebyshev's polynomials. 1.10.4. Generalization to m-dimensional recurrences m > 1. 1.11. The problem of the fractional iterates. 21. Autonomous linear case. 22. Autonomous non linear case. The singularities. 23. Autonomous non linear case. Stability of fixed point and cycles. 23. The function defining the recurrence is not a smooth one. 24. Autonomous non linear case. Local bifurcations. 25. Autonomous non linear case. Local bifurcations. 26. Autonomous non linear case. Local bifurcations. 27. Autonomous non linear case. Local bifurcations. 28. Autonomous non linear case. Local bifurcations. 29. Autonomous non linear case. Local bifurcations. 20. Autonomous non linear case. Local bifurcations. 20. Autonomous non linear case. Local bifurcations. 21. Autonomous non linear case. Local bifurcations. 22. Autonomous non linear case. Local bifurcations. 23. Autonomous non linear case. Local bifurcations.		
1.7. Imbedding of an endomorphism into a diffeomorphism with a higher dimension. 1.8. The Valiron's results. 1.9. Consequences of the Valiron's results. 1.10. Autonomous recurrences and the Schröder's equation. 1.10.1. Generalities. 1.10.2. Basin boundary and the Schröder equation. 1.10.3. One-dimensional recurrences and chaotic behaviour. Generalization of the Chebyshev's polynomials. 1.10.4. Generalization to m-dimensional recurrences m > 1. 1.11. The problem of the fractional iterates. 29 1.11. The problem of the fractional iterates. 31 CHAPTER 2: SOME PROPERTIES OF ONE-DIMENSIONAL RECURRENCES (maps). Introduction. 33 2.1. Autonomous linear case. 34 2.2. Autonomous non linear case. The singularities. 36 2.3. Autonomous non linear case. Stability of fixed point and cycles. 2.3.1. Recurrence defined by a smooth function. 2.3.2. The function defining the recurrence is not a smooth one. 2.4.1. Recurrence defined by a smooth function. 2.4.2. Recurrence defined by a smooth function. 2.4.1. Recurrence defined by a smooth function. 34 2.4.1. Recurrence defined by a smooth function. 35 2.4.1. Recurrence defined by a smooth function. 36 37 38 39 30 30 31 31 32 32 34 35 36 36 37 38 39 30 30 30 31 31 32 33 34 35 36 36 37 38 38 39 30 30 30 31 31 32 32 34 35 36 36 37 38 38 39 30 30 31 31 32 33 34 34 35 36 36 37 38 38 39 30 30 30 31 31 32 32 34 34 35 36 36 37 38 38 39 30 30 31 31 32 32 34 34 35 36 36 37 37 38 38 39 30 30 31 31 32 32 34 34 35 36 37 37 38 38 39 30 30 31 31 32 33 34 34 35 36 37 37 38 38 39 30 30 31 31 32 33 34 34 34 34 34 34 34 34	The fide and	
with a higher dimension. 1.8. The Valiron's results. 1.9. Consequences of the Valiron's results. 1.10. Autonomous recurrences and the Schröder's equation. 1.10.1. Generalities. 1.10.2. Basin boundary and the Schröder equation. 1.10.3. One-dimensional recurrences and chaotic behaviour. Generalization of the Chebyshev's polynomials. 1.10.4. Generalization to m-dimensional recurrences m > 1. 1.11. The problem of the fractional iterates. CHAPTER 2: SOME PROPERTIES OF ONE-DIMENSIONAL RECURRENCES (maps). Introduction. 2.1. Autonomous linear case. 2.2. Autonomous non linear case. The singularities. 2.3. Autonomous non linear case. Stability of fixed point and cycles. 2.3.1. Recurrence defined by a smooth function. 2.3.2. The function defining the recurrence is not a smooth one. 2.4.1. Recurrence defined by a smooth function. 2.4.2. Recurrence defined by a smooth function. 2.4.1. Recurrence defined by a smooth function. 2.4.1. Recurrence defined by a smooth function. 2.4.1. Recurrence defined by a smooth function. 2.4.2. Recurrence defined by a smooth function. 2.4.1. Recurrence defined by a smooth function. 2.4.2. Recurrence defined by a continuous but not	1.7. Imbedding of an endomorphism into a diffeomo	rnhism
1.8. The Valiron's results. 1.9. Consequences of the Valiron's results. 20 1.10. Autonomous recurrences and the Schröder's equation. 21 21.10.1. Generalities. 21.10.2. Basin boundary and the Schröder equation. 22 23.10.3. One-dimensional recurrences and chaotic behaviour. Generalization of the Chebyshev's polynomials. 24 25 26 27 28 29 29 20 20 20 21 20 21 21 21 22 22 23 24 25 26 26 27 28 29 20 20 20 21 21 21 21 21 21 21 21 21 21 21 22 23 24 25 26 27 28 28 29 29 20 20 20 20 20 20 20 20 20 20 20 20 20	with a higher dimension.	
1.10. Autonomous recurrences and the Schröder's equation. 1.10.1. Generalities. 1.10.2. Basin boundary and the Schröder equation. 1.10.3. One-dimensional recurrences and chaotic behaviour. Generalization of the Chebyshev's polynomials. 1.10.4. Generalization to m-dimensional recurrences m > 1. 1.11. The problem of the fractional iterates. 29 1.11. The problem of the fractional iterates. 31 CHAPTER 2: SOME PROPERTIES OF ONE-DIMENSIONAL RECURRENCES (maps). Introduction. 2.1. Autonomous linear case. 2.2. Autonomous non linear case. The singularities. 2.3. Autonomous non linear case. Stability of fixed point and cycles. 2.3.1. Recurrence defined by a smooth function. 2.3.2. The function defining the recurrence is not a smooth one. 2.4.1. Recurrence defined by a smooth function. 2.4.1. Recurrence defined by a smooth function. 2.4.1. Recurrence defined by a smooth function. 2.4.2. Recurrence defined by a smooth function.		= -
1.10.1. Generalities. 1.10.2. Basin boundary and the Schröder equation. 1.10.3. One-dimensional recurrences and chaotic behaviour. Generalization of the Chebyshev's polynomials. 1.10.4. Generalization to m-dimensional recurrences m > 1. 1.11. The problem of the fractional iterates. 29 1.11. The problem of the fractional iterates. 31 CHAPTER 2: SOME PROPERTIES OF ONE-DIMENSIONAL RECURRENCES (maps). Introduction. 2.1. Autonomous linear case. 2.2. Autonomous non linear case. The singularities. 2.3. Autonomous non linear case. Stability of fixed point and cycles. 2.3.1. Recurrence defined by a smooth function. 2.3.2. The function defining the recurrence is not a smooth one. 2.4.1. Recurrence defined by a smooth function. 2.4.1. Recurrence defined by a smooth function. 2.4.1. Recurrence defined by a smooth function. 2.4.2. Recurrence defined by a smooth function.	1.9. Consequences of the Valiron's results.	20
1.10.2. Basin boundary and the Schröder equation. 1.10.3. One-dimensional recurrences and chaotic behaviour. Generalization of the Chebyshev's polynomials. 1.10.4. Generalization to m-dimensional recurrences m > 1. 29 1.11. The problem of the fractional iterates. 1.10.4. Some PROPERTIES OF ONE-DIMENSIONAL RECURRENCES (maps). Introduction. 2.1. Autonomous linear case. 2.2. Autonomous non linear case. The singularities. 2.3. Autonomous non linear case. Stability of fixed point and cycles. 2.3.1. Recurrence defined by a smooth function. 2.3.2. The function defining the recurrence is not a smooth one. 2.4.1. Recurrence defined by a smooth function. 2.4.2. Recurrence defined by a smooth function. 2.4.1. Recurrence defined by a smooth function. 2.4.2. Recurrence defined by a smooth function.	1.10. Autonomous recurrences and the Schröder's eq	uation. 21
1.10.3. One-dimensional recurrences and chaotic behaviour. Generalization of the Chebyshev's polynomials. 1.10.4. Generalization to m-dimensional recurrences m > 1. 29 1.11. The problem of the fractional iterates. CHAPTER 2: SOME PROPERTIES OF ONE-DIMENSIONAL RECURRENCES (maps). Introduction. 2.1. Autonomous linear case. 2.2. Autonomous non linear case. The singularities. 2.3. Autonomous non linear case. Stability of fixed point and cycles. 2.3.1. Recurrence defined by a smooth function. 2.3.2. The function defining the recurrence is not a smooth one. 2.4.1. Recurrence defined by a smooth function. 2.4.1. Recurrence defined by a smooth function. 2.4.2. Recurrence defined by a smooth function. 2.4.1. Recurrence defined by a smooth function. 2.4.2. Recurrence defined by a smooth function.	1.10.1. Generalities.	21
1.10.3. One-dimensional recurrences and chaotic behaviour. Generalization of the Chebyshev's polynomials. 1.10.4. Generalization to m-dimensional recurrences m > 1. 29 1.11. The problem of the fractional iterates. CHAPTER 2: SOME PROPERTIES OF ONE-DIMENSIONAL RECURRENCES (maps). Introduction. 2.1. Autonomous linear case. 2.2. Autonomous non linear case. The singularities. 2.3. Autonomous non linear case. Stability of fixed point and cycles. 2.3.1. Recurrence defined by a smooth function. 2.3.2. The function defining the recurrence is not a smooth one. 2.4.1. Recurrence defined by a smooth function. 2.4.1. Recurrence defined by a smooth function. 2.4.2. Recurrence defined by a smooth function. 2.4.1. Recurrence defined by a smooth function. 2.4.2. Recurrence defined by a smooth function.	1.10.2. Basin boundary and the Schröder eq	uation. 22
polynomials. 1.10.4. Generalization to m-dimensional recurrences m > 1. 29 1.11. The problem of the fractional iterates. CHAPTER 2 : SOME PROPERTIES OF ONE-DIMENSIONAL RECURRENCES (maps). Introduction. 2.1. Autonomous linear case. 2.2. Autonomous non linear case. The singularities. 2.3. Autonomous non linear case. Stability of fixed point and cycles. 2.3.1. Recurrence defined by a smooth function. 2.3.2. The function defining the recurrence is not a smooth one. 2.4. Autonomous non linear case. Local bifurcations. 2.4. Recurrence defined by a smooth function.		
1.10.4. Generalization to m-dimensional recurrences m > 1. 29 1.11. The problem of the fractional iterates. CHAPTER 2: SOME PROPERTIES OF ONE-DIMENSIONAL RECURRENCES (maps). Introduction. 2.1. Autonomous linear case. 2.2. Autonomous non linear case. The singularities. 2.3. Autonomous non linear case. Stability of fixed point and cycles. 2.3.1. Recurrence defined by a smooth function. 2.3.2. The function defining the recurrence is not a smooth one. 45 2.4.1. Recurrence defined by a smooth function. 2.4.2. Recurrence defined by a smooth function. 48 2.4.1. Recurrence defined by a smooth function. 2.4.2. Recurrence defined by a continuous but not		
1.11. The problem of the fractional iterates. CHAPTER 2 : SOME PROPERTIES OF ONE-DIMENSIONAL RECURRENCES (maps). Introduction. 2.1. Autonomous linear case. 2.2. Autonomous non linear case. The singularities. 2.3. Autonomous non linear case. Stability of fixed point and cycles. 2.3.1. Recurrence defined by a smooth function. 2.3.2. The function defining the recurrence is not a smooth one. 2.4. Autonomous non linear case. Local bifurcations. 47 2.4.1. Recurrence defined by a smooth function. 2.4.2. Recurrence defined by a continuous but not		
1.11. The problem of the fractional iterates. CHAPTER 2: SOME PROPERTIES OF ONE-DIMENSIONAL RECURRENCES (maps). Introduction. 2.1. Autonomous linear case. 2.2. Autonomous non linear case. The singularities. 2.3. Autonomous non linear case. Stability of fixed point and cycles. 2.3.1. Recurrence defined by a smooth function. 2.3.2. The function defining the recurrence is not a smooth one. 2.4. Autonomous non linear case. Local bifurcations. 2.4.1. Recurrence defined by a smooth function. 2.4.2. Recurrence defined by a smooth function. 2.4.2. Recurrence defined by a smooth function. 2.4.2. Recurrence defined by a continuous but not		
CHAPTER 2 : SOME PROPERTIES OF ONE-DIMENSIONAL RECURRENCES (maps). Introduction. 2.1. Autonomous linear case. 2.2. Autonomous non linear case. The singularities. 2.3. Autonomous non linear case. Stability of fixed point and cycles. 40. 2.3.1. Recurrence defined by a smooth function. 2.3.2. The function defining the recurrence is not a smooth one. 45. 2.4.1. Recurrence defined by a smooth function. 2.4.2. Recurrence defined by a smooth function. 48.		
(maps). Introduction. 2.1. Autonomous linear case. 2.2. Autonomous non linear case. The singularities. 2.3. Autonomous non linear case. Stability of fixed point and cycles. 40 2.3.1. Recurrence defined by a smooth function. 2.3.2. The function defining the recurrence is not a smooth one. 45 2.4.1. Recurrence defined by a smooth function. 2.4.2. Recurrence defined by a smooth function. 48	1.11. The problem of the fractional iterates.	31
(maps). Introduction. 2.1. Autonomous linear case. 2.2. Autonomous non linear case. The singularities. 2.3. Autonomous non linear case. Stability of fixed point and cycles. 40 2.3.1. Recurrence defined by a smooth function. 2.3.2. The function defining the recurrence is not a smooth one. 45 2.4.1. Recurrence defined by a smooth function. 2.4.2. Recurrence defined by a smooth function. 48		
(maps). Introduction. 2.1. Autonomous linear case. 2.2. Autonomous non linear case. The singularities. 2.3. Autonomous non linear case. Stability of fixed point and cycles. 40 2.3.1. Recurrence defined by a smooth function. 2.3.2. The function defining the recurrence is not a smooth one. 45 2.4.1. Recurrence defined by a smooth function. 2.4.2. Recurrence defined by a smooth function. 48	CHAPTER 2 · SOME PROPERTIES OF ONE-DIMENSIONAL PRO	IIDDENCES
Introduction. 2.1. Autonomous linear case. 2.2. Autonomous non linear case. The singularities. 2.3. Autonomous non linear case. Stability of fixed point and cycles. 40. 2.3.1. Recurrence defined by a smooth function. 2.3.2. The function defining the recurrence is not a smooth one. 45. 2.4.1. Recurrence defined by a smooth function. 2.4.2. Recurrence defined by a smooth function. 48.		DRAENCES
2.1. Autonomous linear case. 2.2. Autonomous non linear case. The singularities. 2.3. Autonomous non linear case. Stability of fixed point and cycles. 2.3.1. Recurrence defined by a smooth function. 2.3.2. The function defining the recurrence is not a smooth one. 2.4. Autonomous non linear case. Local bifurcations. 2.4.1. Recurrence defined by a smooth function. 2.4.2. Recurrence defined by a continuous but not	- '	2.2
2.2. Autonomous non linear case. The singularities. 2.3. Autonomous non linear case. Stability of fixed point and cycles. 2.3.1. Recurrence defined by a smooth function. 2.3.2. The function defining the recurrence is not a smooth one. 2.4. Autonomous non linear case. Local bifurcations. 2.4.1. Recurrence defined by a smooth function. 2.4.2. Recurrence defined by a continuous but not		
2.3. Autonomous non linear case. Stability of fixed point and cycles. 2.3.1. Recurrence defined by a smooth function. 2.3.2. The function defining the recurrence is not a smooth one. 45 2.4. Autonomous non linear case. Local bifurcations. 2.4.1. Recurrence defined by a smooth function. 2.4.2. Recurrence defined by a continuous but not		
and cycles. 2.3.1. Recurrence defined by a smooth function. 2.3.2. The function defining the recurrence is not a smooth one. 45 2.4. Autonomous non linear case. Local bifurcations. 2.4.1. Recurrence defined by a smooth function. 2.4.2. Recurrence defined by a continuous but not		
2.3.2. The function defining the recurrence is not a smooth one. 45 2.4. Autonomous non linear case. Local bifurcations. 2.4.1. Recurrence defined by a smooth function. 2.4.2. Recurrence defined by a continuous but not		_
2.3.2. The function defining the recurrence is not a smooth one. 45 2.4. Autonomous non linear case. Local bifurcations. 2.4.1. Recurrence defined by a smooth function. 2.4.2. Recurrence defined by a continuous but not	2 3 l Pacurrence defined by a smooth fun	ction 40
not a smooth one. 2.4. Autonomous non linear case. Local bifurcations. 47 2.4.1. Recurrence defined by a smooth function. 2.4.2. Recurrence defined by a continuous but not		
2.4. Autonomous non linear case. Local bifurcations. 47 2.4.1. Recurrence defined by a smooth function. 2.4.2. Recurrence defined by a continuous but not		
2.4.1. Recurrence defined by a smooth function. 48 2.4.2. Recurrence defined by a continuous but not	2 / Autonomous non linear coss. I cosl hifuresti	
2.4.2. Recurrence defined by a continuous but not		

2.5.	Bifurcat	ions of piecewise continuous recurrences.	56
	2.5.1.		
	2.5.2.	Piecewise continuous recurrences.	56 62
2.6. 2.7.	rropert1	es of invertible one-dimensional recurrences. es of non-invertible one-dímensional	62
	recurren		63
	2.7.1.		63
	2.7.2.	Fatou's theorems about critical points. Construction of T^r from the map T .	64
	2.7.4.	Cycles of one-dimensional endomorphisms.	65
	2.7.5.	Absorbing segment.	68 69
2.8.	Domain of	attraction (Basin) of an attractive fixed	0)
	point. S	Some global bifurcations.	70
	2.8.1.		70
		of two points.	70
	2.8.2.		70
		number of disjointed parts with only one	
		accumulation point. First example of global bifurcation.	
	2.8.3.	Complex basin of the first type. Second	71
		example of global bifurcation. Chaotic	
	2.8.4.	transient.	74
	2.0.4.	Complex basin of second type. Chaotic (or fuzzy) basin boundary. Third example of a	
		global bifurcation.	77
	2.8.5.	Some remarks.	78
2.9.		e map of the circle onto itself.	80
	2.9.1.	Diffeomorphism of the circle.	80
	2.9.2. 2.9.3.	Generalizations.	84
	2.7.3.	Boxes in files bifurcations structure and Farey sequences.	
	2.9.4.	Boxes in files bifurcations structure and	85
		the phenomenon of phase intermittency.	85
CHAPT	ER 3 : MYRI REC	BERG'S RESULTS ON THE ONE-DIMENSIONAL QUADRATIC URRENCES. THEIR CONSEQUENCES.	
3.1.	Introduct	ion.	87
3.2.	Some gene	ral properties.	90
	3.2.1.	First set of Myrberg's results.	90
	3.2.2.	Number of all the possible cycles of order k.	93
	3.2.3.	Number of the bifurcations giving rise to the	
	3.2.4.	cycles of order k. Properties related to $\lambda = \lambda_1^*$.	94
	3.2.5.		97
	٠. ٢. ٠ ٠ ٠	Properties related to $\lambda > \lambda_1^*$.	102

3.3.	The Myrbe	erg's results.	103
	3.3.1.	The Myrberg's characterization of a cycle	
		point.	103
	3.3.2.	The Myrberg's rotation sequence.	105
	3.3.3.	The Myrberg's ordering law. Consequences.	106
	3.3.4.	The Myrberg's ordering law and its relation	
		to the notion of invariant coordinate and	
		kneading invariant.	109
	3.3.5.	Fundamental bifurcations and Myrberg's	
	-	singular parameter values of the first type.	110
	3.3.6.		
		the first type.	113
	3.3.7.		
		first numbering of the cycles of the same	
		order. Non-embedded representation.	113
	3.3.8.	Myrberg singular parameter values of the	113
	3.3.0.	second type.	114
	3.3.9.	Myrberg's singular parameter values of the	114
	3.3.3.		116
		third type.	110
3.4.	Convergen	ce of rotation sequences toward a singular	
	value.	•	119
	3.4.1.	Convergence toward a singular value of the	
		first type.	119
	3.4.2.	Convergence toward a singular value of the	
		second type.	120
	3.4.3.	Convergence toward a singular value of the	
		third type.	124
	3.4.4.	Remark.	126
3.5.	The Alcor	ithms giving the set of all the ordered cycles	
J.J.	of order		126
	or order	κ,	120
	3.5.1.	Notations and definitions.	126
	3.5.2.	First algorithm.	127
		Second algorithm.	127
		-	
3.6.	Adjoint,	and self adjoint, binary words of the cycles	120
	of unimod	al one dimensional endomorphisms. Symmetry.	130
3.7.	The compl	ete non-embedded representation of a cycle.	131
CHAPT		BOX-WITHIN-A-BOX BIFURCATIONS STRUCTURE	
	AND	ITS CONSEQUENCES.	
4.1.	Introduct	ion	133
4.2.		rization of a cycle by a decimal rotation	
4.2.		•	135
	sequence.		
	4.2.1.	Definition of the decimal rotation sequence.	135
	4.2.2.	Deduction of the binary sequence from the	
		decimal one.	135
	4.2.3.	Deduction of the decimal rotation sequence	
		from the binary one.	136

	4.2.4. 4.2.5.	Necessary and sufficient condition for a permutation of the k first integers to be a decimal rotation sequence of a map defined by a function having a single extremum. The subset of the rotation sequences directly related to the Poincaré's rotation numbers.	136 138
4.3.	Decomposa	able and indecomposable rotation sequences $[u]$.	142
	4.3.1. 4.3.2.	Definition and examples.	142
	4.3.3.	representation. Composition of indecomposable rotation	144
		sequences.	146
4.4.	The box-w structure	vithin-a-box bifurcations structure (fractal	149
	4.4.1.	Simple (or non-embedded) boxes of the	
		structure.	149
	4.4.2.	Embedded boxes of first kind.	151
	4.4.3. 4.4.4.	Embedded boxes of second kind. Accumulation points of the boxes	153
		$(f(x, \lambda) \equiv x^2 - \lambda).$	156
4.5.	Resulting	properties on the x-axis.	161
	4.5.1.	The parameter value λ is not singular in	
	4.5.2.	the sense of Myrberg. The parameter value λ is singular of the	161
	4.5.3.	the transfer that we are strikely of the	162
	4.5.4.	second type. The parameter value λ is singular of the	162
		third type. Phenomenon of intermittency.	164
4.6.	Invariant	measures associated with singular parameters	
. 7	values or	the second type.	166
4.7. 4.8.	Toporogic:	al entropy. ralizations.	174
4.0.	some gene.		176
	4.8.1.	Recurrence defined by a function with only	
	402	one extremum.	176
	4.8.2.	Recurrence defined by a function with two extrema.	
			178
4.9.	Recurrence function	e defined by a continuous piecewise linear with only one extremum.	179
CHAPTI	er 5 ; som	E PROPERTIES OF TWO-DIMENSIONAL RECURRENCES	
5.1.	Introducti	ion.	184
5.2.	Autonomous	s linear case.	188
	5.2.1.	General solution.	188
	5.2.2.	Invariant curves when the multipliers are real and different.	190
			200

xvi

	5.2.3. Invariant curves when the multipliers are	
	complex.	191
	5.2.4. Case of two real multipliers with equal	
	moduli. 5.2.5. Degenerate singular points.	194 194
5,3.		
5.4.	Autonomous non linear case. Homoclinic and hetero-	195
	clinic points.	201
5.5.	Critical case $ S_1 = 1$, $ S_2 \neq 1$.	202
	5.5.1. Particular case. The map has a whole	
	curve made up of fixed points, or of	
	points of order two cycles.	202
	5.5.2. General case.	203
5.6.	Bifurcations by passing through the multiplier	
	$S_1 = \pm 1$.	207
	5.6.1. Passing through the particular critical	
	case of § 5.5.1.	207
	5.6.2. General case with one multiplier $S_1 = +1$. 5.6.3. General case with one multiplier $S_1 = -1$.	211
	<u> </u>	214
5.7.	Critical case with multipliers $S_{1,2} = \exp(\pm j \phi)$, $j = \sqrt{-1}$.	015
5.8.	The non-exceptional case. The exceptional case with $\phi = 2k\pi/q$, $q = odd$ integer.	215 220
3.0.		
	5.8.1. First situation. 5.8.2. Second situation.	220 221
5 0		
3.9.	The exceptional case with $\phi \approx 2k\pi/q$, $q = \text{even integer}$.	224
	5.9.1. First situation.	225
	5.9.2. Second situation.	229
5.10.	Critical cases with multipliers $S = \exp(-j \phi)$,	
5 11	ϕ = 0, or π . Bifurcation by crossing through the critical case	231
J. II.	$S = \exp(\frac{1}{2}j \phi)$.	234
	5.11.1. Crossing through a non-exceptional case. 5.11.2. Crossing through an exceptional case.	234 239
r 10		
3.12.	Critical case with two multipliers $S_1 = S_2 = +1$ when the linear approximation matrix is not reducible to	
	a diagonal form.	239
5.13.	Bifurcation by crossing the critical case of the	
	§ 5.12.	245
	5.13.1. Crossing through critical cases with real	
	principal invariant curves.	247
	5.13.2. Crossing through critical cases without	0.00
	real principal invariant curves.	250
5.14.	Birth of invariant closed curves from a linear	
	conservative case perturbed by small non linear	251
	DIRRIDALIVE LETTE.	2.11

5.15.	Birth of	invariant closed curves in some other cases bifurcations.	255
5.16.	First exa	mple of the bifurcations of the two precedent	255
	paragraph	S.	258
3,1/,	chaotic b	ample. Global bifurcations in presence of ehaviour.	266
СНАРТ	ER 6 : TWO BOX	-DIMENSIONAL DIFFEOMORPHISMS AND THE FOLIATED -WITHIN-A-BOX BIFURCATIONS STRUCTURE.	
	Introduct		280
6.2.	Behaviour	of the diffeomorphism for small values of $ b $.	286
	6.2.1.	Degenerate ω -invariant curves of T_b for	
	622	$b = 0$, and invariant curves for $b \neq 0$.	286
	6.2.3.	Consequence: "oscillating" basins. α -invariant curves of the map T_b , for small	289
		values of b .	291
	6.2.4.	Complex basins : chaotic transients, fuzzy	
		(or chaotic) basins boundary.	296
6.3.	Behaviour case.	of the diffeomorphism in the conservative	
			298
	6.3.1.	Quadratic case $b = -1$. Properties of the phase plane.	200
	6.3.2.	Quadratic case $b = -1$. Local bifurcations.	298 304
	6.3.3.	Non quadratic case $b = -1$.	309
	6.3.4.	Behaviour for $b = +1$.	310
6.4.		of the diffeomorphism in the almost	
6.5.	Conservat:		311
0.5.	parameter	case. First set of properties of the plane.	313
6.6.	-	horseshoe and the two-dimensional quadratic	313
	diffeomor	phism. Representation of the cycles.	317
		The Smale horseshoe.	317
	6.6.2.	Representation of the cycles. Symmetry.	319
6.7.	*	case. Box-within-a-box foliated bifurcation	
	structure	•	326
		Origin of the foliation.	326
	6.7.2.	Homoclinic and heteroclinic situations. Morse-Smale area.	334
			334
6.8.		s of formation of cycles represented in the phase plane.	341
6.9.		ties of the fractal foliated bifurcations	241
	structure		
	structure	•	349
	6.9.1.	Generalities.	349
	6.9.2.	The cross-road area.	351

6.9.3. The saddle area. 6.9.4. The spring area. Local and global aspects.	358 361
6.10. Contracted representation of the parameters plane. Consequence.6.11. Symbolic dynamics of communications in the fractal foliated bifurcations structure. Connections chain.	373 375
 6.11.1. Notions of connections chain and communications cell. 6.11.2. Connections chain and communications cell of simple situations. 6.11.3. Connections chain and communications cell of more complex situations. 6.11.4. Organization of connections chain belonging 	375 378 388
to a same list E _k (b < 0). 6.12. Bifurcations structure of two-dimensional cubic diffeomorphism. 6.12.1. Generalities.	391 395 395
6.12.2. Description of the chains of bifurcations (6.41).	397
Appendix A - Poincaré's indexes B3 .	407
Appendix B - Equivalence between the canonical form of a two-dimensional recurrence and the reduced Cigala form.	411
Appendix C - Critical case with two pairs of complex multipliers in a four-dimensional non-linear recurrence.	413
Appendix D - Particular case of a two-dimensional recurrence with real variables reduced to a one-dimensional recurrence with complex variable.	421
Appendix E - The problem of structural stability in the chaotic dynamic situations.	424
References	427
Index	445

Chapter 1

DYNAMIC SYSTEMS AND RECURRENCES. GENERALITIES

1.1. CONTINUOUS DYNAMIC SYSTEMS AND DISCRETE DYNAMIC SYSTEMS

The content of this monograph concerns evolution processes, or equivalently dynamic systems. Till now, a generally accepted, and unambiguous, definition of this notion seems not yet exist. In a concrete context, that of the experimental physics, for example, a "dynamic system" is a limited configuration of objects, or again a more or less subjective description of this configuration in a verbal, or mathematical, form. Because it is impossible to study a limited configuration when it is imbedded into the whole universe, it is necessary to separate, or isolate, this configuration via an appropriate artifice consisting at the final step in choosing a certain number of relevant variables, and parameters. This indispensable process of separation leads to what is called a constraint of separation, which can have different forms according to the considered limited configuration, the desidered mathematical formulation, and the nature of the sought solution. In an abstract context, it is supposed that the constraint of separation is known, and the expression "dynamic system" simply designates the equation of the motion |G 33|.

A first possible formulation of motion equations is that ordinary differential equations with real variables, the time t being the independent variable, in one of the two explicit forms:

(1.1)
$$dx_i/dt = f_i(x_1, x_2, ..., x_n), i = 1, 2, ..., m, x_i(t_0) = x_{i_0}$$

(1.2) $dx_i/dt = f_i(x_1, x_2, ..., x_n, t), i = 1,2,...,m, x_i(t_0) = x_{i_0}$

The first one is called a m-dimensional autonomous equation and the second one a m-dimensional non-autonomous equation. When the existence and uniqueness conditions are satisfied for the initial condition $x_i(t_0)$, the solution is a continuous function of t, and corresponds to what is called a phase trajectory, or a motion, in the phase space of coordinates x_1, \ldots, x_m . The equations (1.1), (1.2) also can be represented in a vectorial form $X^{\bullet} = F(X)$, $X^{\bullet} = F(X)$, $X^{\bullet} = dX/dt$.

A second possible formulation is that of recurrences, or equivalently point-mappings, maps, iterations (these forms are indifferently used in this book), for which the time t is no longer a continuous independent variable but a sequence of integers, $n = 0, 1, 2, \ldots$ (discrete time), in one of the two explicit vectorial forms:

(1.3)
$$X_{n+1} = F(X_n)$$
, or $X_{n+1} = T(X_n)$, $X(n=0) = X_0$

(1.4)
$$X_{n+1} = F(X_n, n)$$
, or $X_{n+1} = T_n X_n, X(n=0) = X_0$

X being a real vector with components $(x_1, ..., x_p)$, F a single valued vectorial, function of X. In (1.3) (autonomous equation), T is the p-dimensional point-mapping which gives the point \mathbf{X}_{n+1} from the point X_n, and which is independant of n. In (1.4), (non autonomous equation), the point-mapping depends on n. When existence and uniqueness conditions are satisfied for the initial condition X_0 , the solution $X_n = X(n, X_0)$ is a sequence of points (iterated sequence, or orbit, or discrete phase trajectory) in the p-dimensional discrete phase plane. The recurrences (1.3), (1.4) can be directly the mathematical models of a class of dynamic systems which are by nature of the discrete type, i.e. the available information about their states is only obtained in a sampled form. However, the autonomous recurrence (1.3) plays a fundamental role, when it is associated with an autonomous differential equation (1.1), the dimension p of (1.3) being not higher than (m-1), or with (1.2) when the f_i are periodical functions of t with a fixed period. In this case (1.3) is the result of the application of the Poincaré's method of section. The reduction of the effective dimension of the differential equation, which is so obtained, makes easier its

study. Details about this method will be considered in an other paragraph. It should be stressed that the inverse process, consisting in the construction of a differential equation from a recurrence (1.3), is generally not possible. The functional space of recurrences is thus much richer than that of differential equations, and this richness induces some far-reaching theoretical and practical properties | G 35 | | G 36 |.

1.2. BIRKHOFF CLASSIFICATION OF DYNAMIC MOTIONS. IMPREDICTIBILITY OF CHAOTIC MOTIONS

In his book "Dynamical Systems" | B 9 | Birkhoff wrote: "the final aim of the theory of dynamical systems must be directed towards the qualitative determination of all possible types of motions and the interrelations of these motions". Going towards this purpose, by using ideas developed by Poincaré, as a first step Birkhoff proposed en 1927 a classification of dynamic motions, which has been refined by Andronov in 1933 with the diagram of fig. 1.1. In this diagram, starting from the lower part up to the top, an increase of the structural complexity of motions manifests itself as a gradual transition from orderly to chaotic (erratic, or stochastic) motions.

It is recalled that steady states of *quasi periodic* type correspond to oscillations containing a finite number M of mutually incommensurable frequencies. Steady states of almost periodic type correspond to oscillations containing infinitely many mutually incommensurable frequencies $(M \to \infty)$. Let us denote by $X(t, X_0)$ a dynamical system defined in some metric space R, the trajectory of which passes through the point X_0 .

The motion X(t, X_0) is called recurrent, if for any $\varepsilon>0$ there can be found a $\tau(\varepsilon)>0$ such that any arc of the phase trajectory of time length τ approximates the entire trajectory with a precision to within ε . In other words, whatever may be the numbers t_1 , t_2 , there can be found a number t_3 such that $t_2 < t_3 < t_2 + \tau$, and $\rho[X(t_1, X_0), X(t_3, X_0)] < \varepsilon$, where $\rho(\alpha, \beta)$ is the distance between α and $\beta \mid N \delta \mid$.