# Roger Mansuy **Marc Yor**

**Random Times** and Enlargements of Filtrations in a Brownian Setting

$$\mathcal{F}_t^{\sigma(X)} = \mathcal{F}_t \vee \sigma(X)$$
$$\mathcal{F}_t^{\Lambda} = \mathcal{F}_t \vee \sigma(\Lambda \wedge t)$$



# Random Times and Enlargements of Filtrations in a Brownian Setting



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Dedicated to the memory of J.L. Doob (1910 - 2004) and P.-A. Meyer (1934 - 2003)



In the neighborhood of the second author's family home...

### **Preface**

These notes represent accurately the contents of the six lectures we gave in the Statistics Department of Columbia University, between the 10th and the 25th of November 2004.

The audience was a mix of faculty, most of whom were fine "connoisseurs" of stochastic calculus, excursion theory, and so on, and graduate students who were basically acquainted with Brownian motion.

Our aim in teaching this course was two-fold:

- on one hand, to give the audience some familiarity with the theory and main examples of enlargements of filtrations, either of the initial or the progressive kinds;
- on the other hand, to update the relevant Chapters<sup>1</sup> of Part II [Yor97b] of the Zürich volumes, precisely, those which were devoted to martingale and filtration problems, i.e. **Chapters** 12 to 17 in Part II.

Each lecture was followed by an exercises session. Here is the detailed organization of these lecture notes:

- as a set of **Preliminaries**, the basic operations of stochastic calculus and of the (Strasbourg) general theory of processes are recalled; no doubt that this is too sketchy, only a first aid tool kit is being presented, and the reader will want to read much more, e.g. [Del72] and the last volume, by Dellacherie, Maisonneuve and Meyer, of Probabilités et Potentiel [DMM92];
- in Chapter 1, the transformation of martingales in a "small" filtration into semimartingales in a bigger filtration is being studied; an important number of, by now, classical examples, drawn more or less from Jeulin's monograph [Jeu80] or Jeulin-Yor [JY85], are presented, and then collected in an appendix at the end of the chapter: this appendix consists in two

<sup>&</sup>lt;sup>1</sup> An updated, revisited version of **Chapters** 1 to 11, corresponding to Part I [Yor92a], is being published in the Springer Universitext collection under the title Aspects of Brownian motion [MY05a].

tables, the first one for progressive enlargements, the second one for initial enlargements; we tried to gather there some most important examples, which often come up in the discussion of various Brownian path decompositions and their applications. This presentation is close to the effort made in the *Récapitulatif* in [JY85] pp. 305-313;

- in **Chapter** 2, we examine what remains of a number of classical results in martingale theory when, instead of dealing with a stopping time, one works up to a general random time;
- the main topic of **Chapter** 3 consists in the comparison of  $\mathbb{E}[X|\mathcal{F}_{\gamma}]$  and  $X_{\gamma} := \mathbb{E}[X|\mathcal{F}_{t}]_{|t=\gamma}$  where, for the simplicity of our exposition,  $\gamma$  is the last zero before 1 of an underlying Brownian motion, and X is a generic integrable random variable. Note how easily one may be confusing the two quantities, which indeed are identical when  $\gamma$  is replaced by a stopping time. Moreover, in our set-up with  $\gamma$ , one of these quantities is equal to 0 if and only if the other one is, and this remark leads naturally to the description of all martingales which vanish on the (random) set of the Brownian zeroes;
- Chapter 4 discusses the predictable and chaotic representation properties (abbreviated respectively as PRP and CRP) for a given martingale with respect to a filtration. Although the CRP is rarer than the PRP, a much better understanding of the CRP, and many examples, have been obtained since the unexpected discovery by Émery [Éme89] that Azéma's martingale enjoys the CRP. In particular, we introduce in this chapter the Dunkl martingales, which also enjoy the CRP.
- the two next **Chapters** 5 and 6 are devoted to questions of filtrations. They are tightly knit with the preceding chapters, e.g. in **Chapter** 5, Azéma's martingale plays a central role, and in **Chapter** 6, ends of predictable sets are being discussed in the framework of the Brownian filtration. In more details, the deep roots of **Chapter** 5 are to be found in excursion theory where, traditionally, a level, e.g. level 0, is being singled out from the start, and excursions away from this level are studied. It was then natural to consider how quantities and concepts related to a given level based excursion theory vary with that level. Two different suggestions for this kind of study were made, the first one by D. Williams, with following studies by J. Walsh and C. Rogers, the second one by J. Azéma, which provoked answers from Y. Hu. Both set-ups are being examined in **Chapter** 5.

Chapter 6 develops our present understanding of the Brownian filtration, or rather, of some fundamental properties which are necessary for a given filtration to be generated by a Brownian motion. The results are due mainly to B. Tsirel'son, and collaborators, between 1996 and 2000 (roughly). In particular, it was established during this period that:

- the filtration of a N-legged Brownian spider  $(N \ge 3)$  is not strongly Brownian.

- there exist probability measures Q equivalent to Wiener measure, such that under Q, the natural filtration of the coordinate process is not strongly Brownian.

Tsirel'son original "hands on" method of attack of these questions later developed into the search of "invariants of filtration", e.g. the notions of standard filtration, cosy filtration,..., which were studied by M. Emery and co-workers, and Tsirel'son himself, and which we briefly present at the end of **Chapter** 6.

• Each chapter ends with some exercises, which complement the content of that chapter. A standard feature of these exercises, as well as the style of their solutions, is an illustration of general "principles", which we present in the framework of explicit examples. The solutions-presented in **Chapter** 7 – are succinctly written, but should contain sufficient details for the reader. As much as possible, the arguments in the proposed solutions are closely connected with the material found in the corresponding chapters. We also took the opportunity to include some open questions, sometimes in the form of exercises, which are then indicated with the symbol \mathbf{H}.

We are both very grateful for the warm hospitality we received during our stay in Columbia University as well as the strong motivation of the audience during the sessions. Thanks to everyone involved, and special thanks to Peter Bank and Joannis Karatzas.

Paris, November 3, 2005 Roger Mansuy Marc Yor

# Contents

-1	Notation and Convention
0	Preliminaries       3         0.1 Doob's Maximal Identity       3         0.2 Balayage Formula       4         0.3 Predictable Compensators       6         0.4 $\sigma$ -fields Associated with a Random Time $\Lambda$ 6         0.5 Integration by Parts Formulae       7         0.6 $H^1$ and BMO Spaces       7         0.7 Exercises       8
1	Enlargements of Filtrations       1.7         1.1       Some General Problems of Enlargements       1.7         1.2       Progressive Enlargement       1.7         1.2.1       Decomposition Formula       1.7         1.2.2       Pitman's Theorem on 2S-B and Some Generalizations via Some Progressive Enlargement of Filtration       1.7         1.3       Initial Enlargement       1.8         1.4       Further References       2.5         1.5       Exercises       2.5
A	Appendix: Some Enlargements Formulae37Tables $1\alpha$ and $1\beta$ : Progressive Enlargements32Tables $2\alpha$ and $2\beta$ : Initial Enlargements34Comments on the Tables36
2	Stopping and Non-stopping Times       4         2.1       Stopping Times and Doob's Optional Theorem       4         2.1.1       The Knight-Maisonneuve Characterization       4         of Stopping Times       4         2.1.2       D. Williams' Example of a Pseudo-stopping Time       4

		2.1.3 A Characterization of Pseudo-stopping Times	43
	2.2	How Badly are the BDG Inequalities Affected	
		by a General Random Time?	44
		2.2.1 A Global Approach (Common to all $\Lambda$ 's)	45
		2.2.2 An "Individual" Approach (Depending on $\Lambda$ )	46
	2.3	Local Time Estimates	47
	2.4	Further References	49
	2.5	Exercises	49
3		the Martingales which Vanish on the Set	
		Brownian Zeroes	53
	3.1	Some Quantities Associated with $\gamma$	53
		3.1.1 Azéma Supermartingale	
		and the Predictable Compensator Associated with $\gamma$	54
		3.1.2 Path Decomposition Relative to $\gamma$	55
		3.1.3 Brownian Meander	55
	3.2	Some Examples of Martingales which Vanish	
		on $\mathcal{Z} = \{t; B_t = 0\}$	57
	3.3	Some Brownian Martingales with a Given Local Time,	
		or Supremum Process	59
	3.4	A Remarkable Coincidence between $\mathbb{E}[X \mathcal{F}_{\gamma}]$ and $X_{\gamma}$	60
	3.5	Resolution of Some Conditional Equations	62
	3.6	Understanding how $\mathbb{E}[X \mathcal{F}_{\gamma}]$ and $X_{\gamma}$ Differ	64
	3.7	Exercises	66
4	PR	P and CRP for Some Remarkable Martingales	71
	4.1	Definition and First Example	71
	4.2	PRP and Extremal Martingale Distributions	74
	4.3	CRP: An Attempt Towards a General Discussion	75
		4.3.1 An Attempt to Understand the CRP in Terms	
		of a Generalized Moments Problem	76
		4.3.2 Some Sufficient Conditions for the CRP	77
		4.3.3 The Case of the Azéma Martingale	79
	4.4	Exercises	83
5	Unv	veiling the Brownian Path (or history) as the Level Rises	87
	5.1	Above and Under a Given Level	88
		5.1.1 First Computations in Williams' Framework	88
		5.1.2 First Computations in Azéma-Hu's Framework	90
	5.2	Rogers-Walsh Theorem about Williams' Filtration	93
		5.2.1 Some Space Martingales which are Constant	
		up to a Fixed Level	93
		5.2.2 A Dense Family of Continuous Martingales	94
	5.3	A Discussion Relative to $(\mathcal{E}^a_{\mathbb{A}}, a \in \mathbb{R})$	95
		5.3.1 Hu's Result about $(\mathcal{E}^a, a \in \mathbb{R})$ -Martingales	95

		Contents XIII			
		5.3.2 Some Markov Processes with Respect to $(\mathcal{E}_{\mathbb{A}}^a, a \in \mathbb{R}) \dots 97$			
	5.4	Some Subfiltrations of the Brownian Filtration			
	5.5	Exercises			
6	We	ak and Strong Brownian Filtrations			
	6.1	Definitions			
	6.2	Examples of Weak Brownian Filtrations			
		6.2.1 Change of Probability			
		6.2.2 Change of Time			
		6.2.3 Walsh's Brownian Motion and Spider Martingales 109			
	6.3	Invariants of a Filtration			
	6.4	Further References			
	6.5	Exercises			
7	Ske	tches of Solutions for the Exercises			
References					
Index					

## **Notation and Convention**

Here is a short list of current notation and convention used in the different chapters.

- We shall always assume that the underlying probability space  $(\Omega, \mathcal{F}, P)$  is separable.
- Let  $\mathcal{A}(\subset \mathcal{F})$  be a  $\sigma$ -field, X an  $\mathcal{A}$ -measurable random variable and Y a random variable independent of  $\mathcal{A}$ . Then, for any Borel function f, the conditional expectation  $\mathbb{E}\left[f(X,Y)|\mathcal{A}\right]$  shall be denoted as  $\hat{\mathbb{E}}\left[f(X,\hat{Y})\right]$ . In other words, the expectation concerns the hat-variables with all others remaining frozen.
- We sometimes make the abuse of notation:  $X \in \mathcal{A}$ , meaning that the random variable X is  $\mathcal{A}$ -measurable.
- The symbol  $\gamma_t$  (resp.  $\delta_t$ ) will only be used to denote the last (resp. the first) zero of a certain process, usually Brownian motion, before (resp. after) the time t. We often abbreviate  $\gamma_1$  and  $\delta_1$  by  $\gamma$  and  $\delta$ .
- In general, to a process N, we associate  $\overline{N}$ , its one sided supremum process; namely, for  $t \geq 0$ ,  $\overline{N}_t := \sup_{s \leq t} N_s$ . However, for Brownian motion  $(B_t; t \geq 0)$ , we keep the usual notation  $(S_t; t \geq 0)$  for its one-sided supremum.
- In this book, studies of the law of a process  $(X_t; t \geq 0)$  often begin with: "For any bounded functional F,  $\mathbb{E}[F(X_s; s \leq t)] \dots$ ". By this sentence, we mean that F is a measurable functional on  $\mathcal{C}([0,t],\mathbb{R})$  if X is assumed to be continuous, on  $\mathcal{D}([0,t],\mathbb{R})$  otherwise.
- $\mathcal{F}^{\sigma(X)}$  will denote the initial enlargement of the filtration  $(\mathcal{F}_t; t \geq 0)$  with the random variable X, that is the filtration defined by

$$\mathcal{F}_{t}^{\sigma(X)} := \bigcap_{\varepsilon > 0} \left( \mathcal{F}_{t+\varepsilon} \vee \sigma(X) \right), \qquad t \ge 0$$

We shall sometimes use the terminology: X-initial enlargement of  $(\mathcal{F}_t; t \geq 0)$ .

• For  $\Lambda: \Omega \to [0, \infty]$ , a random time, we denote by  $\mathcal{F}^{\Lambda}$  the smallest filtration which contains  $(\mathcal{F}_t; t \geq 0)$ , and makes  $\Lambda$  a stopping time, i.e.

$$\mathcal{F}_t^{\Lambda} := \bigcap_{\varepsilon > 0} \left( \mathcal{F}_{t+\varepsilon} \vee \sigma(\Lambda \wedge (t+\varepsilon)) \right), \qquad t \ge 0$$

We shall sometimes use the terminology:  $\Lambda$ -progressive enlargement of  $(\mathcal{F}_t; t \geq 0)$ .

- All martingales considered in this volume are assumed to be càdlàg (i.e. right-continuous and left-limited); in a number of cases, they are even assumed to be continuous, but this will always be specified.
- $\mathbf{e}$  (resp.  $\mathcal{N}$ ) will often denote a standard exponentially distributed variable (resp. a standard normal variable).
- The symbol  $\hookrightarrow$  (resp.  $\not\hookrightarrow$ ) denotes immersion (resp. non-immersion) between two filtrations  $(\mathcal{F}_t; t \geq 0)$  and  $(\mathcal{G}_t; t \geq 0)$  such that  $\mathcal{F}_t \subseteq \mathcal{G}_t$  for every  $t; (\mathcal{F}_t; t \geq 0)$  is said to be immersed in  $(\mathcal{G}_t; t \geq 0)$  if all  $(\mathcal{F}_t; t \geq 0)$ -martingales are  $(\mathcal{G}_t; t \geq 0)$ -martingales. This notion will be studied in Chapter 5, but we already note that the more general situation when some (perhaps all...)  $(\mathcal{F}_t; t \geq 0)$ -martingales are  $(\mathcal{G}_t; t \geq 0)$ -semimartingales will be a recurrent subject of study in these lecture notes.

#### **Preliminaries**

Throughout these preliminaries, we are working with an underlying filtered probability space  $(\Omega, \mathcal{F}, (\mathcal{F}_t; t \geq 0), \mathbb{P})$ . We insist that most of the notions introduced below are relative to this filtered probability space.

#### 0.1 Doob's Maximal Identity

The following lemmas are variants of Doob's optional stopping theorem.

**Lemma 0.1** Let N be a  $\mathbb{R}_+$ -valued continuous local martingale with  $N_0 = 1$ , and  $N_t \xrightarrow[t\to\infty]{} 0$ .

Denote  $\overline{N}_t = \sup_{s \le t} N_s$  and  $\overline{N}^t = \sup_{s > t} N_s$ .

Then  $\overline{N}_{\infty} \stackrel{(law)}{=} 1/U$  where U denotes a uniformly distributed variable. More generally, for every finite stopping time T such that  $N_T > 0$  a.s.,  $N_T/\overline{N}^T$  is a uniform variable independent of  $\mathcal{F}_T$ .

#### Proof

- Define, for a > 1,  $T_a = \inf\{t \ge 0, N_t = a\}$ .  $1 = \mathbb{E}[N_0] = \mathbb{E}[N_{T_a}] = aP(\overline{N}_{\infty} \ge a) (= aP(T_a < \infty))$   $P(\overline{N}_{\infty} \ge a) = \frac{1}{a} \text{ i.e. } P\left(1/\overline{N}_{\infty} \le \frac{1}{a}\right) = \frac{1}{a}$
- For any finite stopping time T such that  $N_T > 0$  a.s., consider the local martingale constructed from N by shifting time from T, namely  $(N_{u+T}/N_T; u \ge 0)$ . We can apply the first step of this proof to this local martingale whose supremum is  $\overline{N}^T/N_T$ . The result follows easily.

The next lemma completes, in some sense, Lemma 0.1.  $(N_t; t \geq 0)$  is now replaced by a general continuous semi-martingale  $(X_t; t \geq 0)$ , which is not necessarily positive.

R. Mansuy and M. Yor: Random Times and Enlargements of Filtrations in a Brownian Setting, Lect. Notes Math. 1873, 3-9 (2006) © Springer-Verlag Berlin Heidelberg 2006 **Lemma 0.2** Let  $h : \mathbb{R} \to \mathbb{R}$  be a locally integrable function and set  $H(x) = \int_0^x dy h(y)$ .

Then  $H(\overline{X}_t) - h(\overline{X}_t)(\overline{X}_t - X_t) = \int_0^t h(\overline{X}_s) dX_s$ ; hence, if  $(X_t; t \ge 0)$  is a local martingale, so is  $(H(\overline{X}_t) - h(\overline{X}_t)(\overline{X}_t - X_t), t \ge 0)$ .

#### Proof

This result is easily obtained when h is regular thanks to Itô formula, and the essential fact that  $d\overline{X}_t$  is carried by  $\{t; \overline{X}_t = X_t\}$ . The general result follows from a monotone class argument.

**Comment 0.1** For  $h(x) = 1_{x \le a}$  and  $(X_t; t \ge 0)$  a continuous local martingale, Lemma 0.2 yields that

$$(a1_{\overline{X}_t > a} + X_t 1_{\overline{X}_t < a}; \ t \ge 0)$$

is a local martingale, from which the result of Lemma 0.1 follows.

**Example 0.1** (Doob's inequality in  $L^p$  for positive submartingales)

We consider  $(\Sigma_t; t \geq 0)$  a positive continuous submartingale.

Taking  $F(x) = x^p$  with p > 1, Lemma 0.2 implies that  $\overline{\Sigma}_t^p - p\overline{\Sigma}_t^{p-1}(\overline{\Sigma}_t - \Sigma_t)$  is a local submartingale.

Up to a localization argument, we obtain

$$\begin{split} \mathbb{E}\left[\overline{\Sigma}_{t}^{p}\right] &\leq \frac{p}{p-1}\mathbb{E}\left[\overline{\Sigma}_{t}^{p-1}\varSigma_{t}\right] \\ &\leq \frac{p}{p-1}\mathbb{E}\left[\overline{\Sigma}_{t}^{p}\right]^{(p-1)/p}\mathbb{E}\left[\varSigma_{t}^{p}\right]^{1/p} \end{aligned} \qquad (H\ddot{o}lder) \end{split}$$

Thus

$$\|\overline{\Sigma}_t\|_p \le \frac{p}{p-1} \|\Sigma_t\|_p$$

### 0.2 Balayage Formula

The result of Lemma 0.2 may be understood in a more general framework. Let  $(k_u; u \ge 0)$  be a locally bounded, predictable process,  $(Y_u; u \ge 0)$  a continuous semi-martingale starting at 0.

Denote by  $\gamma_t$  and  $\delta_t$  respectively the last zero of Y before t and the first zero of Y after t, namely:

$$\gamma_t = \sup\{u \le t; \ Y_u = 0\}$$
  
$$\delta_t = \inf\{u \ge t; \ Y_u = 0\}$$

Then

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