Fundamentals of Electric Circuits

电路基础

Charles K. Alexander Matthew N. O. Sadiku







entals of

ELECTRIC CIRCUITS

CHARLES K. ALEXANDER

School of Electrical Engineering and Computer Science

Ohio University

MATTHEW N. O. SADIKU

Department of Electrical and Computer Engineering

Temple University

(京)新登字 158 号

Fundamentals of Electric Circuits

Charles K. Alexander, Matthew N.O. Sadiku

Copyright © 2000 by The McGraw-Hill Companies, Inc.

Original English Language Edition Published by The McGraw-Hill Companies, Inc.

All Rights Reserved.

For sale in Mainland China only.

本书影印版由 McGraw-Hill 出版公司授权清华大学出版社在中国境内(不包括香港、澳门特别行政区和台湾地区)独家出版、发行。

未经出版者书面许可,不得以任何方式复制或抄袭本书的任何部分。

本书封面贴有清华大学出版社激光防伪标签,无标签者不得销售。

北京市版权局著作权合同登记号:01-2000-3526

书 名: 电路基础

Fundamentals of Electric Circuits

作 者: Charles K. Alexander, Matthew N.O. Sadiku

出版者: 清华大学出版社(北京清华大学学研大厦,邮编 100084) http:// www. tup. tsinghua. edu. cn

印刷者:北京市清华园胶印厂

发行者: 新华书店总店北京发行所

开 本: 787×960 1/16 印张:59.75

版 次: 2000年12月第1版 2002年6月第2次印刷

书 号: ISBN 7-900630-98-8

印 数:3001~5000

定 价:88.00元

Contents

D. C.	17 No. 1 No. 1 April 200
Preface v	3.7 Nodal Versus Mesh Analysis 99
Acknowledgments vi	3.8 Circuit Analysis with <i>PSpice</i> 100
A Note to the Student ix	†3.9 Applications: DC Transistor Circuits 102
	3.10 Summary 107 Review Ouestions 107
PART I DC CIRCUITS I	Review Questions 107 Problems 109
Chapter 1 Basic Concepts 3	Comprehensive Problems 117
1.1 Introduction 4	Chapter 4 Circuit Theorems 119
1.2 Systems of Units 4	4.1 Introduction 120
1.3 Charge and Current 6	4.2 Linearity Property 120
1.4 Voltage 9	4.3 Superposition 122
1.5 Power and Energy 10 1.6 Circuit Elements 13	4.4 Source Transformation 127
	4.5 Thevenin's Theorem 131
The state of the s	4.6 Norton's Theorem 137
1.7.1 TV Picture Tube 1.7.2 Electricity Bills	†4.7 Derivations of Thevenin's and Norton's
STATE STATE STATE OF BUTCHER	Theorems 140
†1.8 Problem Solving 18	4.8 Maximum Power Transfer 142
1.9 Summary 21	4.9 Verifying Circuit Theorems
Review Questions 22 Problems 23	with PSpice 144
Comprehensive Problems 25	† 4.10 Applications 147
	4.10.1 Source Modeling
Chapter 2 Basic Laws 27	4.10.2 Resistance Measurement
2.1 Introduction 28	4.11 Summary 153
2.2 Ohm's Laws 28	Review Questions 153
†2.3 Nodes, Branches, and Loops 33	Problems 154 Comprehensive Problems 162
2.4 Kirchhoff's Laws 35	Comprehensive Problems 102
2.5 Series Resistors and Voltage Division 41	Chapter 5 Operational Amplifiers 165
2.6 Parallel Resistors and Current Division 42	5.1 Introduction 166
†2.7 Wye-Delta Transformations 50	5.2 Operational Amplifiers 166
† 2.8 Applications 54	5.3 Ideal Op Amp 170
2.8.1 Lighting Systems	5.4 Inverting Amplifier 171
2.8.2 Design of DC Meters	5.5 Noninverting Amplifier 174
2.9 Summary 60	5.6 Summing Amplifier 176
Review Questions 61	5.7 Difference Amplifier 177
Problems 63 Comprehensive Problems 72	5.8 Cascaded Op Amp Circuits 181
Completionsive Problems /2	5.9 Op Amp Circuit Analysis
Chapter 3 Methods of Analysis 75	with PSpice 183
	† 5.10 Applications 185
,,,	5.10.1 Digital-to Analog Converter
accept to the second of the se	5.10.1 Digital-to Attailog Converter 5.10.2 Instrumentation Amplifiers
3.3 Nodal Analysis with Voltage Sources 82 3.4 Mesh Analysis 87	5.11 Summary 188
3.5 Mesh Analysis with Current Sources 92	Review Questions 190
†3.6 Nodal and Mesh Analyses by Inspection 95	Problems 191
110dai and Mesh Analyses by Hispection 93	Comprehensive Problems 200

Ch	apter 6 Capacitors and Inductors 201	8.12 Summary 340
March Control		Review Questions 340
6.1	Introduction 202	Problems 341
6.2	Capacitors 202	Comprehensive Problems 350
6.3	Series and Parallel Capacitors 208	1 = 1
6.4	Inductors 211	PART 2 AC CIRCUITS 351
6.5	Series and Parallel Inductors 216	Chapter 9 Sinusoids and Phasors 353
†6.6	Applications 219	
	6.6.1 Integrator	9.1 Introduction 354
	6.6.2 Differentiator	9.2 Sinusoids 355
	6.6.3 Analog Computer	9.3 Phasors 359
6.7	Summary 225	9.4 Phasor Relationships for Circuit
Review Que		Elements 367
Problems	227	9.5 Impedance and Admittance 369
Comprehens	ive Problems 235	9.6 Kirchhoff's Laws in the Frequency
Ch	7 Cian Onder Ciantes 227	Domain 372
Entertain the second	apter 7 First-Order Circuits 237	9.7 Impedance Combinations .373
7.1	Introduction 238	† 9.8 Applications 379
7.2	The Source-free <i>RC</i> Circuit 238	9.8.1 Phase-Shifters
7.3	The Source-free RL Circuit 243	9.8.2 AC Bridges
7.4	Singularity Functions 249	9.9 Summary 384
7.5	Step Response of an RC Circuit 257	Review Questions 385
7.6	Step Response of an RL Circuit 263	Problems 385
† 7.7	First-order Op Amp Circuits 268	Comprehensive Problems 392
7.8	Transient Analysis with PSpice 273	
† 7.9	Applications 276	Chapter 10 Sinusoidal Steady-State Analysis 393
	7.9.1 Delay Circuits	10.1 Introduction 394
	7.9.2 Photoflash Unit 7.9.3 Relay Circuits	10.2 Nodal Analysis 394
	7.9.3 Relay Circuits 7.9.4 Automobile Ignition Circuit	10.3 Mesh Analysis 397
7 10		10.4 Superposition Theorem 400
		10.5 Source Transformation 404
Review Que: Problems	284	10.6 Thevenin and Norton Equivalent
Comprehens	ive Problems 293	Circuits 406
		10.7 Op Amp AC Circuits 411
Ch	apter 8 Second-Order Circuits 295	10.8 AC Analysis Using PSpice 413
8.1	Introduction 296	†10.9 Applications 416
8.2	Finding Initial and Final Values 296	The state of the s
8.3		10.9.1 Capacitance Multiplier 10.9.2 Oscillators
8.4	The Source-Free Series <i>RLC</i> Circuit 301	
	The Source-Free Parallel <i>RLC</i> Circuit 308	10.10 Summary 420
8.5	Step Response of a Series <i>RLC</i>	Review Questions 421 Problems 422
0.7	Circuit 314	170001110 422
8.6	Step Response of a Parallel RLC	Chapter II AC Power Analysis 433
	Circuit 319	
8.7	General Second-Order Circuits 322	II.I Introduction 434
8.8	Second-Order Op Amp Circuits 327	11.2 Instantaneous and Average Power 434
8.9	PSpice Analysis of RLC Circuits 330	11.3 Maximum Average Power Transfer 440
	Duality 332	II.4 Effective or RMS Value 443
†8.11	Applications 336	11.5 Apparent Power and Power Factor 447
	8.11.1 Automobile Ignition System	II.6 Complex Power 449
	8.11.2 Smoothing Circuits	†11.7 Conservation of AC Power 453

11.8	Power Factor Correction 457	14.4 Bode Plots 589	
†11.9	Applications 459	14.5 Series Resonance 600	
	11.9.1 Power Measurement	14.6 Parallel Resonance 605	
	11.9.2 Electricity Consumption Cost	14.7 Passive Filters 608	
11.10	Summary 464	14.7.1 Lowpass Filter	
Review Quest		14.7.2 Highpass Filter	
	466	14.7.3 Bandpass Filter	
Comprehensiv	ve Problems 474	14.7.4 Bandstop Filter	
Cha	pter 12 Three-Phase Circuits 477	14.8 Active Filters 613	
		14.8.1 First-Order Lowpass Filter	
12.1	Introduction 478	14.8.2 First-Order Highpass Filter	
12.2	Balanced Three-Phase Voltages 479	14.8.3 Bandpass Filter 14.8.4 Bandreject (or Notch) Filte	r
12.3	Balanced Wye-Wye Connection 482	The state of the s	7.0
12.4	Balanced Wye-Delta Connection 486	† 14.9 Scaling 619	
12.5	Balanced Delta-Delta Connection 488	14.9.1 Magnitude Scaling	
12.6	Balanced Delta-Wye Connection 490	14.9.2 Frequency Scaling 14.9.3 Magnitude and Frequency	Scaling
12.7	Power in a Balanced System 494		Jeaning
†12.8	Unbalanced Three-Phase Systems 500	14.10 Frequency Response Using	
12.9	PSpice for Three-Phase Circuits 504	PSpice 622	
†12.10	Applications 508	† 14.11 Applications 626	
	12.10.1 Three-Phase Power Measurement	14.11.1 Radio Receiver	
	12.10.2 Residential Wiring	14.11.2 Touch-Tone Telephone 14.11.3 Crossover Network	
12.11	Summary 516	Land of the second of	
Review Quest			
Problems Comprehensiv	518 ve Problems 525	Review Questions 633 Problems 633	
Comprehensiv	TOBICITS 323	Comprehensive Problems 640	
Cha	pter 13 Magnetically Coupled Circuits 527		
13.1	Introduction 528		
13.2	Mutual Inductance 528	PART 3 ADVANCED CIRCUIT ANALYSIS 643	
13.3	Energy in a Coupled Circuit 535	Chapter 15 The Laplace Transform 645	
13.4	Linear Transformers 539	15.1 Introduction 646	
13.5	Ideal Transformers 545	15.2 Definition of the Laplace	
13.6	Ideal Autotransformers 552	Transform 646	
†13.7	Three-Phase Transformers 556	15.3 Properties of the Laplace	
13.8	PSpice Analysis of Magnetically Coupled	Transform 649	
5,500	Circuits 559	15.4 The Inverse Laplace Transform	659
†13.9	Applications 563		00)
		15.4.1 Simple Poles 15.4.2 Repeated Poles	
	13.9.1 Transformer as an Isolation Device 13.9.2 Transformer as a Matching Device	15.4.3 Complex Poles	
	13.9.3 Power Distribution	15.5 Application to Circuits 666	
13.10	Summary 569	15.6 Transfer Functions 672	
Review Quest		15.7 The Convolution Integral 677	
Problems	571	†15.8 Application to Integrodifferential	
Comprehensiv	ve Problems 582		
C	14 F D 502	Equations 685	
	pter 14 Frequency Response 583	† 15.9 Applications 687	
14.1	Introduction 584	15.9.1 Network Stability	
14.2	Transfer Function 584	15.9.2 Network Synthesis	
†14.3	The Decibel Scale 588	15.10 Summary 694	

Transforms

Applications

17.7.1

17.7.2

†17.7

784

785

Amplitude Modulation Sampling

Review Questi Problems Comprehensiv	696	17.8 Summary 789 Review Questions 790 Problems 790
Chap	ter 16 The Fourier Series 707	Comprehensive Problems 794
16.1	Introduction 708	Chapter 18 Two-Port Networks 795
16.2	Trigonometric Fourier Series 708	18.1 Introduction 796
16.3	Symmetry Considerations 717	18.2 Impedance Parameters 796
	16.3.1 Even Symmetry	18.3 Admittance Parameters 801
	16.3.2 Odd Symmetry	18.4 Hybrid Parameters 804
	16.3.3 Half-Wave Symmetry	18.5 Transmission Parameters 809
16.4	Circuit Applicatons 727	†18.6 Relationships between Parameters 814
16.5	Average Power and RMS Values 730	18.7 Interconnection of Networks 817
16.6	Exponential Fourier Series 734	18.8 Computing Two-Port Parameters Using
16.7	Fourier Analysis with <i>PSpice</i> 740	PSpice 823
	16.7.1 Discrete Fourier Transform	†18.9 Applications 826
	16.7.2 Fast Fourier Transform	18.9.1 Transistor Circuits
†16.8	Applications 746	18.9.2 Ladder Network Synthesis
	16.8.1 Spectrum Analyzers 16.8.2 Filters	18.10 Summary 833 Review Ouestions 834
1/ 0		Problems 835
16.9	Summary 749	Comprehensive Problems 844
Review Questi Problems Comprehensiv	751	Appendix A Solution of Simultaneous Equations Using Cramer's Rule 845
Chap	ter 17 Fourier Transform 759	Appendix B Complex Numbers 851
17.1	Introduction 760	Appendix C Mathematical Formulas 859
17.2	Definition of the Fourier Transform 760	Appendix D PSpice for Windows 865
17.3	Properties of the Fourier Transform 766	
17.4	Circuit Applications 779	Appendix E Answers to Odd-Numbered Problems 893
17.5	Parseval's Theorem 782	Selected Bibliography 929
17.6	Comparing the Fourier and Laplace	Indian occ

Index

933

DC CIRCUITS

1	
Chapter 1	Basic Concepts
Chapter 2	Basic Laws
Chapter 3	Methods of Analysis
Chapter 4	Circuit Theorems
Chapter 5	Operational Amplifier
Chapter 6	Capacitors and Inductors
Chapter 7	First-Order Circuits
Chapter 8	Second-Order Circuits

CHAPTER

BASIC CONCEPTS

It is engineering that changes the world.

-Isaac Asimov

Historical Profiles

Alessandro Antonio Volta (1745–1827), an Italian physicist, invented the electric battery—which provided the first continuous flow of electricity—and the capacitor.

Born into a noble family in Como, Italy, Volta was performing electrical experiments at age 18. His invention of the battery in 1796 revolutionized the use of electricity. The publication of his work in 1800 marked the beginning of electric circuit theory. Volta received many honors during his lifetime. The unit of voltage or potential difference, the volt, was named in his honor.



Andre-Marie Ampere (1775–1836), a French mathematician and physicist, laid the foundation of electrodynamics. He defined the electric current and developed a way to measure it in the 1820s.

Born in Lyons, France, Ampere at age 12 mastered Latin in a few weeks, as he was intensely interested in mathematics and many of the best mathematical works were in Latin. He was a brilliant scientist and a prolific writer. He formulated the laws of electromagnetics. He invented the electromagnet and the ammeter. The unit of electric current, the ampere, was named after him.

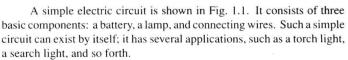


I.I INTRODUCTION

Electric circuit theory and electromagnetic theory are the two fundamental theories upon which all branches of electrical engineering are built. Many branches of electrical engineering, such as power, electric machines, control, electronics, communications, and instrumentation, are based on electric circuit theory. Therefore, the basic electric circuit theory course is the most important course for an electrical engineering student, and always an excellent starting point for a beginning student in electrical engineering education. Circuit theory is also valuable to students specializing in other branches of the physical sciences because circuits are a good model for the study of energy systems in general, and because of the applied mathematics, physics, and topology involved.

In electrical engineering, we are often interested in communicating or transferring energy from one point to another. To do this requires an interconnection of electrical devices. Such interconnection is referred to as an *electric circuit*, and each component of the circuit is known as an *element*.

An electric circuit is an interconnection of electrical elements.



A complicated real circuit is displayed in Fig. 1.2, representing the schematic diagram for a radio receiver. Although it seems complicated, this circuit can be analyzed using the techniques we cover in this book. Our goal in this text is to learn various analytical techniques and computer software applications for describing the behavior of a circuit like this.

Electric circuits are used in numerous electrical systems to accomplish different tasks. Our objective in this book is not the study of various uses and applications of circuits. Rather our major concern is the analysis of the circuits. By the analysis of a circuit, we mean a study of the behavior of the circuit: How does it respond to a given input? How do the interconnected elements and devices in the circuit interact?

We commence our study by defining some basic concepts. These concepts include charge, current, voltage, circuit elements, power, and energy. Before defining these concepts, we must first establish a system of units that we will use throughout the text.

1.2 SYSTEMS OF UNITS

As electrical engineers, we deal with measurable quantities. Our measurement, however, must be communicated in a standard language that virtually all professionals can understand, irrespective of the country where the measurement is conducted. Such an international measurement language is the International System of Units (SI), adopted by the General Conference on Weights and Measures in 1960. In this system,

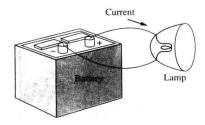


Figure I.I A simple electric circuit.

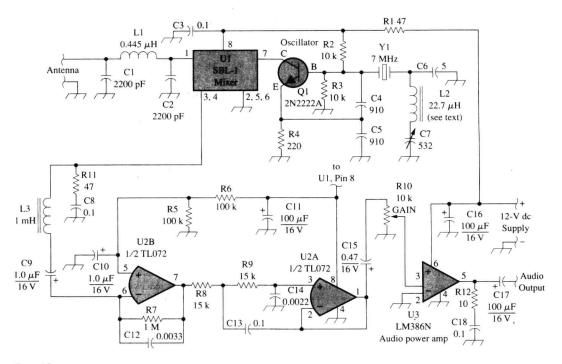


Figure 1.2 Electric circuit of a radio receiver. (Reproduced with permission from QST, August 1995, p. 23.)

there are six principal units from which the units of all other physical quantities can be derived. Table 1.1 shows the six units, their symbols, and the physical quantities they represent. The SI units are used throughout this text.

One great advantage of the SI unit is that it uses prefixes based on the power of 10 to relate larger and smaller units to the basic unit. Table 1.2 shows the SI prefixes and their symbols. For example, the following are expressions of the same distance in meters (m):

600,000,000 mm	600,000 m	600 km
000,000,000 11111	000,000 111	OOO KIII

TABLE I.I The six basic SI units.		
Quantity	Basic unit	Symbol
Length	meter	m
Mass	kilogram	kg
Time	second	S
Electric current	ampere	A
Thermodynamic temperature	kelvin	K
Luminous intensity	candela	cd

TABLE 1.2	The SI prefixes.		
Multiplier	Prefix	Symbol	
1018	exa	Е	
1015	peta	P	
1012	tera	T	
10^{9}	giga	G	
10^{6}	mega	M	
10^{3}	kilo	k	
10^{2}	hecto	h	
10	deka	da	
10^{-1}	deci	d	
10^{-2}	centi	c	
10^{-3}	milli	m	
10^{-6}	micro	μ	
10^{-9}	nano	n	
10^{-12}	pico	p	
10^{-15}	femto	f	
10^{-18}	atto	a	

1.3 CHARGE AND CURRENT

The concept of electric charge is the underlying principle for explaining all electrical phenomena. Also, the most basic quantity in an electric circuit is the *electric charge*. We all experience the effect of electric charge when we try to remove our wool sweater and have it stick to our body or walk across a carpet and receive a shock.

Charge is an electrical property of the atomic particles of which matter consists, measured in coulombs (C).

We know from elementary physics that all matter is made of fundamental building blocks known as atoms and that each atom consists of electrons, protons, and neutrons. We also know that the charge e on an electron is negative and equal in magnitude to 1.602×10^{-19} C, while a proton carries a positive charge of the same magnitude as the electron. The presence of equal numbers of protons and electrons leaves an atom neutrally charged.

The following points should be noted about electric charge:

- 1. The coulomb is a large unit for charges. In 1 C of charge, there are $1/(1.602 \times 10^{-19}) = 6.24 \times 10^{18}$ electrons. Thus realistic or laboratory values of charges are on the order of pC, nC, or μ C.¹
- 2. According to experimental observations, the only charges that occur in nature are integral multiples of the electronic charge $e = -1.602 \times 10^{-19} \text{ C}$.
- The law of conservation of charge states that charge can neither be created nor destroyed, only transferred. Thus the algebraic sum of the electric charges in a system does not change.

We now consider the flow of electric charges. A unique feature of electric charge or electricity is the fact that it is mobile; that is, it can be transferred from one place to another, where it can be converted to another form of energy.

When a conducting wire (consisting of several atoms) is connected to a battery (a source of electromotive force), the charges are compelled to move; positive charges move in one direction while negative charges move in the opposite direction. This motion of charges creates electric current. It is conventional to take the current flow as the movement of positive charges, that is, opposite to the flow of negative charges, as Fig. 1.3 illustrates. This convention was introduced by Benjamin Franklin (1706–1790), the American scientist and inventor. Although we now know that current in metallic conductors is due to negatively charged electrons, we will follow the universally accepted convention that current is the net flow of positive charges. Thus,

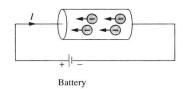


Figure 1.3 Electric current due to flow of electronic charge in a conductor.

A convention is a standard way of describing something so that others in the profession can understand what we mean. We will be using IEEE conventions throughout this book.

¹However, a large power supply capacitor can store up to 0.5 C of charge.

Electric current is the time rate of change of charge, measured in amperes (A).

Mathematically, the relationship between current i, charge q, and time t is

$$i = \frac{dq}{dt} \tag{1.1}$$

where current is measured in amperes (A), and

1 ampere = 1 coulomb/second

The charge transferred between time t_0 and t is obtained by integrating both sides of Eq. (1.1). We obtain

$$q = \int_{t_0}^t i \, dt \tag{1.2}$$

The way we define current as i in Eq. (1.1) suggests that current need not be a constant-valued function. As many of the examples and problems in this chapter and subsequent chapters suggest, there can be several types of current; that is, charge can vary with time in several ways that may be represented by different kinds of mathematical functions.

If the current does not change with time, but remains constant, we call it a *direct current* (dc).

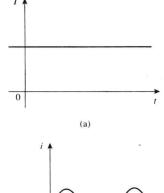
A direct current (dc) is a current that remains constant with time.

By convention the symbol *I* is used to represent such a constant current. A time-varying current is represented by the symbol *i*. A common form of time-varying current is the sinusoidal current or *alternating current* (ac).

An alternating current (ac) is a current that varies sinusoidally with time.

Such current is used in your household, to run the air conditioner, refrigerator, washing machine, and other electric appliances. Figure 1.4 shows direct current and alternating current; these are the two most common types of current. We will consider other types later in the book.

Once we define current as the movement of charge, we expect current to have an associated direction of flow. As mentioned earlier, the direction of current flow is conventionally taken as the direction of positive charge movement. Based on this convention, a current of 5 A may be represented positively or negatively as shown in Fig. 1.5. In other words, a negative current of -5 A flowing in one direction as shown in Fig. 1.5(b) is the same as a current of +5 A flowing in the opposite direction.



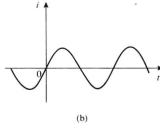


Figure 1.4 Two common types of current: (a) direct current (dc), (b) alternating current (ac).



Figure 1.5 Conventional current flow:
(a) positive current flow, (b) negative current flow.

EXAMPLE I.

How much charge is represented by 4,600 electrons?

Solution:

Each electron has -1.602×10^{-19} C. Hence 4,600 electrons will have -1.602×10^{-19} C/electron \times 4,600 electrons $= -7.369 \times 10^{-16}$ C

PRACTICE PROBLEM I.

Calculate the amount of charge represented by two million protons.

Answer: $+3.204 \times 10^{-13}$ C.

EXAMPLE | . 2

The total charge entering a terminal is given by $q = 5t \sin 4\pi t$ mC. Calculate the current at t = 0.5 s.

Solution:

$$i = \frac{dq}{dt} = \frac{d}{dt}(5t \sin 4\pi t) \text{ mC/s} = (5 \sin 4\pi t + 20\pi t \cos 4\pi t) \text{ mA}$$

At $t = 0.5$,

$$i = 5 \sin 2\pi + 10\pi \cos 2\pi = 0 + 10\pi = 31.42 \text{ mA}$$

PRACTICE PROBLEM 1.2

If in Example 1.2, $q = (10 - 10e^{-2t})$ mC, find the current at t = 0.5 s.

Answer: 7.36 mA.

EXAMPLE 1.3

Determine the total charge entering a terminal between t = 1 s and t = 2 s if the current passing the terminal is $i = (3t^2 - t)$ A.

Solution:

$$q = \int_{t=1}^{2} i \, dt = \int_{1}^{2} (3t^{2} - t) \, dt$$
$$= \left(t^{3} - \frac{t^{2}}{2} \right) \Big|_{1}^{2} = (8 - 2) - \left(1 - \frac{1}{2} \right) = 5.5 \, \text{C}$$

PRACTICE PROBLEM 1.3

The current flowing through an element is

$$i = \begin{cases} 2 \text{ A}, & 0 < t < 1 \\ 2t^2 \text{ A}, & t > 1 \end{cases}$$

Calculate the charge entering the element from t = 0 to t = 2 s.

Answer: 6.667 C.

1.4 VOLTAGE

As explained briefly in the previous section, to move the electron in a conductor in a particular direction requires some work or energy transfer. This work is performed by an external electromotive force (emf), typically represented by the battery in Fig. 1.3. This emf is also known as *voltage* or *potential difference*. The voltage v_{ab} between two points a and b in an electric circuit is the energy (or work) needed to move a unit charge from a to b; mathematically,

$$v_{ab} = \frac{dw}{dq} \tag{1.3}$$

where w is energy in joules (J) and q is charge in coulombs (C). The voltage v_{ab} or simply v is measured in volts (V), named in honor of the Italian physicist Alessandro Antonio Volta (1745–1827), who invented the first voltaic battery. From Eq. (1.3), it is evident that

1 volt = 1 joule/coulomb = 1 newton meter/coulomb

Thus,

Voltage (or potential difference) is the energy required to move a unit charge through an element, measured in volts (V).

Figure 1.6 shows the voltage across an element (represented by a rectangular block) connected to points a and b. The plus (+) and minus (-) signs are used to define reference direction or voltage polarity. The v_{ab} can be interpreted in two ways: (1) point a is at a potential of v_{ab} volts higher than point b, or (2) the potential at point a with respect to point b is v_{ab} . It follows logically that in general

$$v_{ab} = -v_{ba} \tag{1.4}$$

For example, in Fig. 1.7, we have two representations of the same voltage. In Fig. 1.7(a), point a is +9 V above point b; in Fig. 1.7(b), point b is -9 V above point a. We may say that in Fig. 1.7(a), there is a 9-V voltage drop from a to b or equivalently a 9-V voltage rise from b to a. In other words, a voltage drop from a to b is equivalent to a voltage rise from b to a.

Current and voltage are the two basic variables in electric circuits. The common term signal is used for an electric quantity such as a current or a voltage (or even electromagnetic wave) when it is used for conveying information. Engineers prefer to call such variables signals rather than mathematical functions of time because of their importance in communications and other disciplines. Like electric current, a constant voltage is called a dc voltage and is represented by V, whereas a sinusoidally time-varying voltage is called an ac voltage and is represented by v. A dc voltage is commonly produced by a battery; ac voltage is produced by an electric generator.



Figure 1.6 Polarity of voltage v_{ab} .

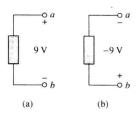


Figure 1.7 Two equivalent representations of the same voltage v_{ab} : (a) point a is 9 V above point b, (b) point b is -9 V above point a.

Keep in mind that electric current is always through an element and that electric voltage is always across the element or between two points.

1.5 POWER AND ENERGY

Although current and voltage are the two basic variables in an electric circuit, they are not sufficient by themselves. For practical purposes, we need to know how much *power* an electric device can handle. We all know from experience that a 100-watt bulb gives more light than a 60-watt bulb. We also know that when we pay our bills to the electric utility companies, we are paying for the electric *energy* consumed over a certain period of time. Thus power and energy calculations are important in circuit analysis.

To relate power and energy to voltage and current, we recall from physics that:

Power is the time rate of expending or absorbing energy, measured in watts (W).

We write this relationship as

$$p = \frac{dw}{dt} \tag{1.5}$$

where p is power in watts (W), w is energy in joules (J), and t is time in seconds (s). From Eqs. (1.1), (1.3), and (1.5), it follows that

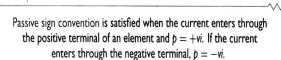
$$p = \frac{dw}{dt} = \frac{dw}{dq} \cdot \frac{dq}{dt} = vi \tag{1.6}$$

or

$$p = vi \tag{1.7}$$

The power p in Eq. (1.7) is a time-varying quantity and is called the *instantaneous power*. Thus, the power absorbed or supplied by an element is the product of the voltage across the element and the current through it. If the power has a + sign, power is being delivered to or absorbed by the element. If, on the other hand, the power has a - sign, power is being supplied by the element. But how do we know when the power has a negative or a positive sign?

Current direction and voltage polarity play a major role in determining the sign of power. It is therefore important that we pay attention to the relationship between current i and voltage v in Fig. 1.8(a). The voltage polarity and current direction must conform with those shown in Fig. 1.8(a) in order for the power to have a positive sign. This is known as the passive sign convention. By the passive sign convention, current enters through the positive polarity of the voltage. In this case, p = +vi or vi > 0 implies that the element is absorbing power. However, if p = -vi or vi < 0, as in Fig. 1.8(b), the element is releasing or supplying power.



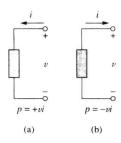


Figure 1.8 Reference polarities for power using the passive sign convention: (a) absorbing power, (b) supplying power.