## Lecture Notes in Artificial Intelligence

Subseries of Lecture Notes in Computer Science

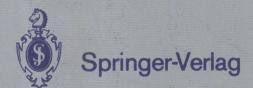
Edited by J. Siekmann

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Rolf T. Nossum (Ed.)

# Advanced Topics in Artificial Intelligence

2nd Advanced Course, ACAI '87 Oslo, Norway, July/August 1987



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### Advanced Topics in Artificial Intelligence

2nd Advanced Course, ACAI '87 Oslo, Norway, July 28 – August 7, 1987



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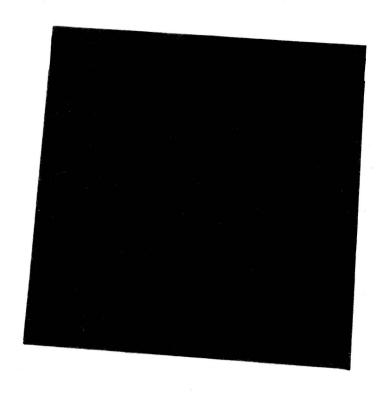
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#### **Editorial**

Artificial Intelligence has become a major discipline under the roof of Computer Science. This is also reflected by a growing number of titles devoted to this fast developing field to be published in our Lecture Notes in Computer Science. To make these volumes immediately visible we have decided to distinguish them by a special cover as Lecture Notes in Artificial Intelligence, constituting a subseries of the Lecture Notes in Computer Science. This subseries is edited by an Editorial Board of experts from all areas of Al, chaired by Jörg Siekmann, who are looking forward to consider further Al monographs and proceedings of high scientific quality for publication.

We hope that the constitution of this subseries will be well accepted by the audience of the Lecture Notes in Computer Science, and we feel confident that the subseries will be recognized as an outstanding opportunity for publication by authors and editors of the Al community.

Editors and publisher

#### PREFACE

Artificial Intelligence being a rapidly developing scientific field, there continually exists a need for rapidly disseminating its latest advances to students and practitioners.

Conferences and conference proceedings are a relatively rapid communication channel, but often the quality of the material presented in them is variable, and the style of presentation quite demanding.

The biennial Advanced Courses in Artifical Intelligence, organized under the auspices of ECCAI, the European Coordinating Committee for Artificial Intelligence, provide a forum for communicating the latest results of the field. World-class AI scientists are invited to lecture, and are asked to provide written accounts of their lectures for publication. The present volume draws on the material presented at the second Advanced Course, which was held in Oslo, Norway, in July 1987.

In contrast to the first Advanced Course, reported as Springer Lecture Notes in Computer Science vol. 232, which covered the foundations of AI extensively, the second Advanced Course emphasized in-depth treatment of a selection of special topics in AI. Inevitably, the course also contained reports on advances in some of the same areas as were covered in the first course.

Philippe Jorrand's chapter gives a unified view of computational mechanisms based on syntactic manipulation of algebraic terms. Dis- and anti-unification are introduced, and their significance explained by way of examples. Term rewriting systems, functional programming systems, and logic programming systems arise as instances of a common computational foundation.

The chapter by Wolfgang Bibel contains new material on enhancements of matrix-based automated deduction, and tells of recent research on how it extends to non-standard logics. A case is made that matrix-based deduction is particularly amenable to this kind of extension.

In the chapter on Qualitative Reasoning, Tony Cohn surveys the state of the art of this important and rapidly developing field as it appears in the summer of 1987.

The chapter on Knowledge Acquisition, by Bob Wielinga and his coworkers, focuses on a major bottleneck in the practical deployment of AI in the form of Expert Systems. It contains a comprehensive overview of elicitation techniques in use today, and stresses those that result in formal specification of knowledge bases.

Alan Biermann's chapter on Learning Systems presents a unified framework for classifying such systems. The reader may wish to refer to his chapter in vol. 232 of the Springer Lecture Notes in Computer Science for background material.

Sam Steel gives an up-to-date and in-depth treatment of the essential Topics in Planning, in the chapter so named.

The chapter on Natural Language Systems by Jens Erik Fenstad gives insight into the situational semantics approach. The reader will appreciate the relationship with other branches of AI, for instance, with AI planning, and the plan-based theory of action, both of which, like situational semantics, appear to owe much to a logical framework laid in the 60s by McCarthy.

Springer-Verlag deserve a special word of acknowledgement for recognizing the value of the material contained in this volume, and offering their very efficient publishing services. This adds to the feeling of satisfaction that comes from organizing an event like the Advanced Course in Artificial Intelligence.

Rolf Nossum, Oslo.

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# FUNDAMENTAL MECHANISMS FOR ARTIFICIAL INTELLIGENCE PROGRAMMING LANGUAGES

- AN INTRODUCTION -

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2

L INTRODUCTION

Artificial intelligence is not computer science. But computers are essential tools for research in artificial intelligence. Computers are the kind of machinery which is best fitted for mechanizing the various models for perception, reasoning, learning and control of action which are relevant to

artificial intelligence.

Most artificial intelligence programs are quite complex objects and mastering the complexity of

their design is a major research objective which lies at the intersection of computer science and

artificial intelligence. Progress in that domain relies both on experience and on theory.

The material presented in this chapter is an introduction to the fundamental mechanisms of artificial

intelligence languages and architectures. These mechanisms and the objects they involve are most

of the time presented quite formally. The use of appropriate formalisms is indeed the price to pay for mastering complexity: without it, the relevant and useful properties cannot be clearly isolated

nor properly used.

II. TERMS AND BASIC OPERATIONS ON TERMS

The notion of term for representing data objects, programs, computations and proofs constitutes

the most primitive layer for the notions presented in this chapter. On top of it, all other

mechanisms will be constructed. The material in this section is mostly drawn from [Huet 85].

II.1. Strings, trees and terms

II.1.1. Strings

Strings are well known objects. Let  $\Sigma$  be a countable set of objects called symbols:  $\Sigma$  is the

alphabet with which strings will be constructed. A string u of length n on  $\Sigma$  is a function from

 $\{0,...,n-1\}$  into  $\Sigma: \Sigma^n$  is the set of all strings of length n on  $\Sigma$ . Let  $u_i$  denote the value of u(i-1):

 $u_i \in \Sigma$ .

Some classical notations for well understood notions:

-  $\Sigma^* = \bigcup_{u \in \mathbb{N}} \Sigma^n$  is the set of all strings

-  $\Lambda$  denotes the null string :  $\Lambda \in \Sigma^0$ 

- 'a' denotes  $u \in \Sigma^{I}$ , when  $u_{I} = a$ , for  $a \in \Sigma$
- $u^{\Lambda}v$  denotes the concatenation of u and v
- 'abc' = 'a'^'b'^'c', where  $a, b, c \in \Sigma$
- $u.a = u^{\prime}a'$ , where  $u \in \Sigma^*$ ,  $a \in \Sigma$ .
- $-u \le v$  (u "is a prefix of" v) iff  $\exists w$  such that  $v = u^w$

#### II.1.2. Trees

A tree has a structure and has pieces of information attached to its nodes and leaves. The structure of a tree will be represented by a set of strings on positive integers, called "positions", which enumerate in a "logical" way the nodes and leaves. Such a set of positions is called a tree domain.

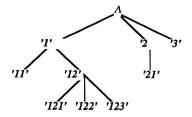
The information attached to nodes and leaves will be symbols from some alphabet  $\Sigma$ .

Thus, given  $N_{+}$ , the set of positive integers,  $N_{+}^{*}$  is the set of all positions. Given a position u = w.m and a position v = w.n, if m < n, u is said to be "left of"  $v : u <_{L} v$ . Then, a tree domain D is a subset of  $N_{+}^{*}$  which is closed under both the prefix and the "left of" orderings:

$$-u \in D \land v < u \implies v \in D$$

$$-u \in D \land v <_L u \implies v \in D$$

Clearly,  $\Lambda$  belongs to every non empty tree domain and is the position of the root of trees. For example, the set of positions  $\{\Lambda, '1', '11', '12', '121', '122', '123', '2', '21', '3'\}$  is a tree domain which represents the following structure:



Finally, attaching information (i.e. symbols in  $\Sigma$ ) to the nodes and leaves is done by defining a tree M as a function from its domain D into  $\Sigma$ . M is then called a  $\Sigma$ -tree :  $M \in D \to \Sigma$ . Given an arbitrary  $\Sigma$ -tree M, its domain is referred to by D(M).

#### II.1.3. Operations on trees

Let M be a  $\Sigma$ -tree and u be a position in its domain D(M). Two basic operations are defined on such trees: access to the subtree rooted at position u in M and grafting of a new subtree at position u in M.

The subtree rooted at position u in M is denoted by M/u. It is of course also a  $\Sigma$ -tree:

$$(M/u)(v) = M(u^{\lambda}v)$$

Given a  $\Sigma$ -tree N, the tree obtained by grafting N at position u in M is denoted by  $M[u \leftarrow N]$ . This tree is the same as M, except that the subtree which was rooted at position u in M is replaced by N in  $M[u \leftarrow N]$ . This tree is also a  $\Sigma$ -tree:

$$v \in D(M) \land \neg (u \le v) \implies M[u \leftarrow N] = M(v)$$
  
 $w \in D(N) \land v = u^{\wedge}w \implies M[u \leftarrow N](v) = N(w)$ 

#### II.1.4. Terms

Let M be a  $\Sigma$ -tree. The top-width of M is  $||M|| = \max\{n \mid 'n' \in D(M)\}$ , i.e. the number of subtrees directly descending under the root of M. On alphabet  $\Sigma$ , a function  $\alpha$  into the integers N, called arity function, is defined:  $\alpha \in \Sigma \to N$ . An alphabet with an arity function is called a graded alphabet. A  $\Sigma$ -term is then a  $\Sigma$ -tree on a graded alphabet  $\Sigma$ , such that the number of subtrees directly descending from every node is equal to the arity of the symbol of  $\Sigma$  attached to that node:

M is a 
$$\Sigma$$
-term  $\iff \forall u \in D(M) /|M/u|/ = \alpha(M(u))$ 

The set of all  $\Sigma$ -terms is denoted by  $T(\Sigma)$ . The usual parenthesized syntax for terms is defined as follows: given  $F \in \Sigma$ , with  $\alpha(F) = n$ , and  $M_1, ..., M_n \in T(\Sigma)$ , then  $F(M_1, ..., M_n) \in T(\Sigma)$ .

#### II.2. Variables and substitutions

#### II.2.1. Terms with variables

Let V be a countable set of objects called variables, disjoint from  $\Sigma: V \cap \Sigma = \emptyset$ , and such that the arity of all variables is  $0: \forall x \in V$ ,  $\alpha(x) = 0$ . Variables of V can be attached to positions of terms, as is already the case for symbols of  $\Sigma$ . Since their arity is 0, they will always appear on leaves of terms. The set of terms with variables is denoted by  $T(\Sigma, V)$  and is equal to  $T(\Sigma \cup V)$ .

Let M be a term on  $\Sigma$  and  $V: M \in T(\Sigma, V)$ . The set of distinct variables which occur in M is:

$$V(M) = \{x \in V \mid \exists u \in D(M), M(u) = x\}$$

The number of distinct variables in M is denoted by v(M) = V(M)/.

#### II.2.2. Substitutions

As is usual in the description of computations, the purpose of variables is to be replaced by values. Here, the considered values are terms: terms can be substituted for variables in  $M \in T(\Sigma, V)$ . Thus, some of the leaves of M to which variables are attached will be replaced by terms. Technically, this is achieved by grafting these terms at the corresponding leaf positions in M.

The elementary form of a substitution  $\sigma$  is a function from the set V of variables into the set  $T(\Sigma,V)$  of terms,  $\sigma \in V \to T(\Sigma,V)$ , and is the identity almost everywhere. The domain of a substitution  $\sigma$  is the set of variables where  $\sigma$  is not the identity:

$$D(\sigma) = \{x \in V \mid \sigma(x) \neq x\}$$

In practice, substitutions are not simply applied to variables, but are applied to terms: for performing a substitution  $\sigma$  on the leaves of terms of the form  $F(M_1, ..., M_n)$ ,  $\sigma$  is extended to a morphism over the set of terms  $T(\Sigma, V)$ :

$$\sigma(F(M_1, ..., M_n)) = F(\sigma(M_1), ..., \sigma(M_n))$$

If there are several occurrences of variable x, they will all be replaced by the same term o(x).

#### II.3. The domain of terms

#### II.3.1. Ordering among terms in $T(\Sigma, V)$

11. \$ 2.1. 2.11.

Let M and N be two terms in  $T(\Sigma, V)$ . M is said to be "less instanciated" than N iff N can be obtained from M by substituting terms for some of the variables in M:

$$M \le N \iff \exists \sigma, N = \sigma(M)$$

This relation is also read "N is an instance of M".

For example, with M = F(G(x,a),y) and N = F(G(H(b),a),y),  $M \le N$  since  $N = \sigma(M)$  with

 $\sigma(x)=H(b)$ . If N=F(G(u,a),v), it would still be the case that  $M \le N$ . But, in this situation, N has exactly the same structure as M and differs from M only by a consistent renaming of its variables. As a consequence, with the inverse substitution, it would also be the case that  $N \le M$ . The relation defined above is thus a quasi ordering, since its is not anti reflexive: both  $M \le N$  and  $N \le M$  can hold, while M and N are different terms. Such bijective substitutions (i.e. consistent renamings of variables) are called permutations. Two terms are said to be isomorphic if one of them can be obtained from the other by a permutation:

$$\forall M, N \in T(\Sigma, V), M \equiv N \iff M = \sigma(N) \text{ for some permutation } \sigma$$
  
$$\iff M \leq N \land N \leq M$$

#### II.3.2. Properties of the ordering in $T(\Sigma, V)$

The strict ordering ">", defined as

$$M > N \iff N \le M \land \neg (M \le N)$$

is a well founded ordering. This is easy to see, using the size |M| of finite terms:

$$|M| = |F(M_1, ..., M_n)| = 1 + \sum_{i=1..n} |M_i|$$

Then, with  $\mu(M) = |M| - \nu(M)$ :

$$M > N \implies \mu(M) > \mu(N)$$

Thus, there is no infinite descending chain  $M_1 > M_2 > ...$ 

#### II.3.3. Terms form a complete lattice

Given two terms M and N in  $T(\Sigma, V)$ , it is always possible to find a term  $M \cap N$  which is the most instanciated term such that both  $M \cap N \leq M$  and  $M \cap N \leq N$  hold. The term  $M \cap N$  is then a greatest lower bound (g.l.b.) of M and N. This term is unique, up to the isomorphism  $\equiv$ .

For example, given M = F(G(x,a),H(b)) and N = F(G(y,c),d), the term  $M \cap N$  would be isomorphic to F(G(u,v),w). A general definition of this operation " $\cap$ " in  $T(\Sigma,V)$  is as follows:

$$F(M_1, ..., M_n) \cap F(N_1, ..., N_n) = F(M_1 \cap N_1, ..., M_n \cap N_n)$$
  
 $M \cap N = \phi(M, N)$  in all other cases

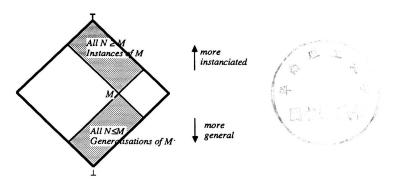
where  $\phi$  is an arbitrary bijection which maps pairs of terms into variables:

$$\phi: T(\Sigma, V) \times T(\Sigma, V) \to V$$

For distinct  $\phi$ , this definition of  $M \cap V$  produces isomorphic results. The term  $M \cap V$  is a g.l.b. of M and N under the ordering  $\leq$ . For identifying all isomorphic terms to a single object, the quotient of  $T(\Sigma, V)$  by  $\equiv$  is considered:

$$T(\Sigma, V) = T(\Sigma, V) / \equiv$$

and this domain is completed by a top **T** (i.e. an element greater than all other elements). The domain  $\mathcal{T}(\Sigma,V)$  is a complete lattice. It is easy to verify that the bottom of  $\mathcal{T}(\Sigma,V)$  is  $\bot = V$ , the set of variables. Pictorially,  $\mathcal{T}(\Sigma,V)$  can be represented as follows:



A term  $\sigma(M)$  such that  $V(\sigma(M)) = \emptyset$  is called a ground instance of M.