

S. Albeverio
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M. Talagrand

Lectures on Probability Theory and Statistics

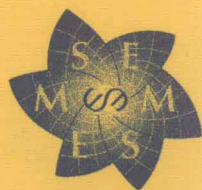
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INTRODUCTION

This volume contains lectures given at the Saint-Flour Summer School of Probability Theory during the period August 17th - September 3d, 2000. This school was Summer School 2000 of the European Mathematical Society.

We thank the authors for all the hard work they accomplished. Their lectures are a work of reference in their domain.

The School brought together 90 participants, 39 of whom gave a lecture concerning their research work.

At the end of this volume you will find the list of participants and their papers.

Thanks. We thank the European Math Society, the European Commission DG12, Blaise Pascal University, the CNRS, the UNESCO, the city of Saint-Flour, the department of Cantal, the Region of Auvergne for their helps and sponsoring.

Finally, to facilitate research concerning previous schools we give here the number of the volume of "Lecture Notes" where they can be found:

Lecture Notes in Mathematics

1971 : n° 307 – 1973 : n° 390 – 1974 : n° 480 – 1975 : n° 539 –
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1986 : n° 50

Table of Contents

Part I Sergio Albeverio: Theory of Dirichlet forms and applications	
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0	Introduction	4
1	Functional analytic background: semigroups, generators, resolvents	7
2	Closed symmetric coercive forms associated with C_0 -contraction semigroups	18
3	Contraction properties of forms, positivity preserving and submarkovian semigroups.....	33
4	Potential Theory and Markov Processes associated with Dirichlet Forms	43
5	Diffusions and stochastic differential equations associated with classical Dirichlet forms	51
6	Applications	64
	References	75
	Index	103

Part II Walter Schachermayer: Introduction to the Mathematics of Financial Markets	
--	--

1	Introduction: Bachelier's Thesis from 1900	111
2	Models of Financial Markets on Finite Probability Spaces	127
3	The Binomial Model, Bachelier's Model and the Black-Scholes Model	140

4 The No-Arbitrage Theory for General Processes 153

5 Some Applications of the Fundamental Theorem of Asset Pricing 173

References 177

Part III Michel Talagrand: Mean field models for spin glasses: a first course

1 Introduction 185

2 What this is all about: the REM 188

3 The Sherrington-Kirkpatrick model at high temperature .. 201

4 The p -spin interaction model 213

5 External field and the replica-symmetric solution 221

6 Exponential inequalities 240

7 Central limit theorems and the Almeida-Thouless line 253

8 Emergence and separation of the lumps in the p -spin interaction model 269

Bibliography 284

Part I

**Sergio Albeverio: Theory of Dirichlet forms
and applications**

Table of Contents

0	Introduction	4
1	Functional analytic background: semigroups, generators, resolvents	7
1.1	Semigroups, Generators	7
1.2	The case of a Hilbert space	13
1.3	Examples	15
2	Closed symmetric coercive forms associated with C_0-contraction semigroups	18
2.1	Sesquilinear forms and associated operators	18
2.2	The relation between closed positive symmetric forms and C_0 -contraction semigroups and resolvents	24
3	Contraction properties of forms, positivity preserving and submarkovian semigroups	33
3.1	Positivity preserving semigroups and contraction properties of forms- Beurling-Deny formula.	33
3.2	Beurling-Deny criterium for submarkovian contraction semigroups	35
3.3	Dirichlet forms	36
3.4	Examples of Dirichlet forms	37
3.5	Beurling-Deny structure theorem for Dirichlet forms	41
3.6	A remark on the theory of non symmetric Dirichlet forms	42
4	Potential Theory and Markov Processes associated with Dirichlet Forms	43
4.1	Motivations	43
4.2	Basic notions of potential theory for Dirichlet forms	44
4.3	Quasi-regular Dirichlet forms	46
4.4	Association of “nice processes” with quasi-regular Dirichlet forms	46
4.5	Stochastic analysis related to Dirichlet forms	50
5	Diffusions and stochastic differential equations associated with classical Dirichlet forms	51
5.1	Diffusions associated with classical Dirichlet forms	51
5.2	Stochastic differential equations satisfied by diffusions associated with classical Dirichlet forms	55
5.3	The general problem of stochastic dynamics	57

5.4	Large time asymptotics of processes associated with Dirichlet forms	59
5.5	Relations of large time asymptotics with space quasi-invariance and ergodicity of measures	60
6	Applications	64
6.1	The stochastic quantization equation and the quantum fields .	64
6.2	Diffusions on configuration spaces and classical statistical mechanics	68
6.3	Other applications	70
6.4	Other problems, applications and topics connected with Dirichlet forms	71

Summary. The theory of Dirichlet forms, Markov semigroups and associated processes on finite and infinite dimensional spaces is reviewed in an unified way. Applications are given including stochastic (partial) differential equations, stochastic dynamics of lattice or continuous classical and quantum systems, quantum fields and the geometry of loop spaces.

0 Introduction

The theory of Dirichlet forms is situated in a vast interdisciplinary area which includes analysis, probability theory and geometry.

Historically its roots are in the interplay between ideas of analysis (calculus of variations, boundary value problems, potential theory) and probability theory (Brownian motion, stochastic processes, martingale theory).

First, let us shortly mention the connection between the “phenomenon” of Brownian motion, and the probability and analysis which goes with it. As well known the phenomenon of Brownian motion has been described by a botanist, R. Brown (1827), as well as by a statistician, in connection with astronomical observations, T.N. Thiele (1870), by an economist, L. Bachelier (1900), (cf. [455]), and by physicists, A. Einstein (1905) and M. Smoluchowski (1906), before N. Wiener gave a precise mathematical framework for its description (1921-1923), inventing the prototype of interesting probability measures on infinite dimensional spaces (Wiener measure). See, e.g., [394] for the fascinating history of the discovery of Brownian motion (see also [241], [16] for subsequent developments).

This went parallel to the development of infinite dimensional analysis (calculus of variation, differential calculus in infinite dimensions, functional analysis, Lebesgue, Fréchet, Gâteaux, P. Lévy...) and of potential theory.

Although some intimate connections between the heat equation and Brownian motion were already implicit in the work of Bachelier, Einstein and Smoluchowski, it was only in the 30's (Kolmogorov, Schrödinger) and the 40's that the strong connection between analytic problems of potential theory and fine properties of Brownian motion (and more generally stochastic processes) became clear, by the work of Kakutani. The connection between analysis and probability (involving the use of Wiener measure to solve certain analytic problems) as further developed in the late 40's and the 50's, together with the application of methods of semigroup theory in the study of partial differential equations (Cameron, Doob, Dynkin, Feller, Hille, Hunt, Martin, ...).

The theory of stochastic differential equations has its origins already in work by P. Langevin (1911), N. Bernstein (30's), I. Gikhman and K. Ito (in the 40's), but further great developments were achieved in connection with the above mentioned advances in analysis, on one hand, and martingale theory, on the other hand.

By this the well known relations between Markov semigroups, their generators and Markov processes were developed, see, e.g. [162], [160], [207], [208], [209], [276], [463].

This theory is largely concerned with processes with “relatively nice characteristics” and with “finite dimensional state space” E (in fact locally compact state spaces are usually assumed). From many areas, however, there is a demand of extending the theory in two directions:

- 1) “more general characteristics”, e.g. allowing for singular terms in the generators
- 2) infinite dimensional (and nonlinear) state spaces.

As far as 1) is concerned let us mention the needs of handling Schrödinger operators and associated processes in the case of non smooth potentials, see [70].

As far as 2) is concerned let us mention the theory of partial differential equations with stochastic terms (e.g. “noises”), see, e.g. [201], [28], [37], [38], [129], [127] the description of processes arising in quantum field theory (work by Friedrichs, Gelfand, Gross, Minlos, Nelson, Segal...) or in statistical mechanics, see, e.g. [16], [15], [344], [242]. Other areas which require infinite dimensional processes are the study of variational problems (e.g. Dirichlet problem in infinite dimensions) [278], the study of certain infinite dimensional stochastic equations of biology, e.g. [474], the representation theory of infinite dimensional groups, e.g. [68], the study of loop groups, e.g. [30], [12], the study of the development of interest rates in mathematical finance, e.g. [416], [337], [502].

The theory of Dirichlet forms is an appropriate tool for these extensions. In fact it is central for it to work with reference measures μ which are neither necessarily “flat” nor smooth and in replacing the Markov semigroups on continuous functions of the “classical theory” by Markov semigroups on

$L^2(\mu)$ -spaces (thus making extensive use of “Hilbert space methods” [211]). The theory of Dirichlet forms was first developed by Feller in the 1-dimensional case, then extended to the locally compact case with symmetric generators by Beurling and Deny (1958-1959), Silverstein (1974), Ancona (1976), Fukushima (1971-1980) and others (see, e.g., [244], [258]). (Extensions to non symmetric generators were given by J. Elliott, S. Carrillo-Menendez (1975), Y. Lejan (1977-1982), a.a., see, e.g. [367]).

The case of infinite dimensional state spaces has been investigated by S. Albeverio and R. Høegh-Krohn (1975-1977), who were stimulated by previous analytic work by L. Gross (1974) and used the framework of rigged Hilbert spaces (along similar lines is also the work of P. Paclet (1978)). These studies were successively considerably extended by Yu. Kondratiev (1982-1987), S. Kusuoka (1984), E. Dynkin (1982), S. Albeverio and M. Röckner (1989-1991), N. Bouleau and F. Hirsch (1986-1991), see [39], [147], [278], [367], [230], [172], [465], [234], [235], [236], [237], [238], [239], [256].

An important tool to unify the finite and infinite dimensional theory was provided by a theory developed in 1991, by S. Albeverio, Z.M. Ma and M. Röckner, by which the analytic property of quasi regularity for Dirichlet forms has been shown in “maximal generality” to be equivalent with nice properties of the corresponding processes.

The main aim of these lectures is to present some of the basic tools to understand the theory of Dirichlet forms, including the forefront of the present research. Some parts of the theory are developed in more details, some are only sketched, but we made an effort to provide suitable references for further study.

The references should also be understood as suggestions in the latter sense, in particular, with a few exceptions, whenever a review paper or book is available we would quote it rather than an original reference. We apologize for this “distortion”, which corresponds to an attempt of keeping the reference list into some reasonable bounds - we hope however the references we give will also help the interested reader to reconstruct historical developments.

For the same reason, all references of the form “see [X]” should be understood as “see [X] and references therein”.

1 Functional analytic background: semigroups, generators, resolvents

1.1 Semigroups, Generators

The natural setting used in these lectures is the one of normed linear spaces B over the closed algebraic field $\mathbb{K} = \mathbb{R}$ or \mathbb{C} . Some of the results are however depending on the additional structure of completeness, therefore we shall assume most of the time that B is a Banach space.

We are interested in describing operators like the Laplacian Δ and the associated semigroup (heat semigroup), and vast generalizations of them.

Let $L \equiv (L, D(L))$ be a linear operator on a normed space B over \mathbb{K} , defined on a linear subset $D(L)$ of B , the definition domain of L .

We say that two such operators $L_i, i = 1, 2$ are equal if $D(L_1) = D(L_2)$ and $L_1 u = L_2 u, \forall u \in D(L_1)$.

L is said to be bounded if $\exists C \geq 0$ s.t. $\|Lu\| \leq C\|u\|, \forall u \in D(L) = B$.

We then have, setting $\|L\| \equiv \sup_{u \in B, \|u\| \leq 1} \|Lu\| \in [0, +\infty]$

$$L \text{ bounded} \Leftrightarrow \|L\| < +\infty.$$

L is said to be continuous at 0 ($\in D(L)!$) if $u_n \rightarrow 0, u_n \in D(L)$ implies $Lu_n \rightarrow 0, n \rightarrow \infty$.

L is said to be continuous if $u_n \rightarrow u, u_n \in D(L)$ implies

$u \in D(L)$ and $Lu_n \rightarrow Lu, n \rightarrow \infty$.

One easily shows

$$L \text{ bounded} \Leftrightarrow L \text{ continuous at } 0 \Leftrightarrow L \text{ continuous.}$$

We define $L = \alpha_1 L_1 + \alpha_2 L_2, \alpha_i \in \mathbb{K}, i = 1, 2$, by

$$D(L) = D(L_1) \cap D(L_2), Lu = \alpha_1 L_1 u + \alpha_2 L_2 u, \forall u \in D(L).$$

Moreover we define for L_1, L_2

$$L_1 L_2 u \equiv L_1(L_2 u), \forall u \in D(L_1 L_2) \equiv L_1 D(L_2) \equiv \{u \in B | L_2 u \in D(L_1)\}$$

Definition 1. A linear bounded operator A on a normed linear space B is a contraction if $\|A\| \leq 1$. A family $T = (T_t)_{t \geq 0}$ of linear bounded operators on B is said to be a strongly continuous semigroup or C_0 -semigroup if

- i) $T_0 = 1$ (the identity on B)
- ii) $\lim_{t \downarrow 0} T_t u = u, \forall u \in B$ (strong continuity)
- iii) $(T_t)_{t \geq 0}$ is a semigroup i.e.
 $T_t T_s = T_s T_t = T_{s+t}, \forall t, s > 0$.
 $(T_t)_{t \geq 0}$ is said to be a C_0 -semigroup of contractions or a C_0 -contraction semigroup if, in addition,
 iv) T_t is a contraction for all $t \geq 0$.

Exercise 1. Show that i),ii),iv) imply that $t \rightarrow T_t u$ is continuous, for all $t \geq 0, \forall u \in B$.

Definition 2. Let $T \equiv (T_t)_{t \geq 0}$ be a C_0 -contraction semigroup on B . The linear operator L is said to be generator of T if:

$$\begin{aligned} i) \quad D(L) &\equiv \left\{ u \in B \mid \lim_{t \downarrow 0} \frac{1}{t} (T_t u - u) \text{ exists in } B \right\} \\ ii) \quad Lu &= \lim_{t \downarrow 0} \frac{1}{t} (T_t u - u) \quad \forall u \in D(L) \end{aligned}$$

Exercise 2. Show that the “strong derivative” $\frac{d}{dt} T_t u \equiv \lim_{h \downarrow 0} \frac{(T_{t+h} - T_t)u}{h}$ exists in B , for all $u \in D(L)$ and $\frac{d}{dt} T_t u = L T_t u = T_t L u \quad \forall t \geq 0, \forall u \in D(L)$. In particular $Lu = \frac{d}{dt} T_t u|_{t=0}, \forall u \in D(L)$.

It is easy to convince oneself that even simple operators like the Laplacian Δ are not bounded, e.g. in $B = L^2(\mathbb{R}^d)$. For this reason it is useful to introduce the concept of a closed operator.

Definition 3. A linear operator L in B is called closed if $u_n \in D(L)$, $u_n \rightarrow u$ as $n \rightarrow \infty$, Lu_n convergent as $n \rightarrow \infty$, in B , imply that $u \in D(L)$, and $Lu_n \rightarrow Lu$.

Exercise 3. Show that L closed $\Leftrightarrow G(L)$ closed in $B \times B$, where $G(L) \equiv \{ \{u, Lu\}, u \in D(L) \}$ is the graph of L .

Proposition 1. Let $T = (T_t)_{t \geq 0}$ be a C_0 -contraction semigroup on a Banach space B , with generator L . Then $T_t u = u + \int_0^t T_s L u ds, u \in D(L)$ where the integral on the r.h.s is to be understood in the natural sense of strong integrals on Banach spaces (Bochner integral¹).

Proof. This follows immediately from Exercise 2, via integration. \square

Proposition 2. The generator L of a C_0 -contraction semigroup $T = (T_t)_{t \geq 0}$ on a Banach space is a closed operator.

Proof. This easily follows from Proposition 1, the strong continuity (Exercise 1), the fact that for $u_n \rightarrow u$, Lu_n convergent to v , $\|T_s Lu_n\| \leq \|Lu_n\| \leq C$, for some $C \geq 0$, independent of n , as Lu_n converges, and dominated convergence. \square

Proposition 3. The generator L of a C_0 -contraction semigroup $T = (T_t)_{t \geq 0}$ on a Banach space is densely defined.

¹ See, e.g. [506], p.132

Proof. One easily shows that for any $u \in B$, with $v_t \equiv \int_0^t T_s u ds$:

$$\frac{1}{r} [v_{t+r} - v_t] = \frac{1}{r} [T_r v_t - v_t] \rightarrow T_t u - u, \text{ as } r \downarrow 0$$

hence $v_t \in D(L)$.

On the other hand

$\frac{v_t}{t} \rightarrow u, t \downarrow 0$, yielding an approximation of an arbitrary $u \in B$ by elements $\frac{v_t}{t}$ in $D(L)$. \square

Corollary 1. *If $T = (T_t)_{t \geq 0}, S = (S_t)_{t \geq 0}$ are two C_0 -contraction semigroups on a Banach space with the same generator L , then $T_t = S_t \quad \forall t \geq 0$.*

Proof. From Exercise 2 we have easily $\frac{d}{ds} T_{t-s} S_s u = 0, \forall 0 \leq s \leq t, \forall u \in D(L)$ from which $T_t u = S_t u \forall u \in D(L)$ follows, hence $T_t = S_t$, these being bounded and $D(L)$ being dense. \square

The above corollary implies that the usual notation $T_t = e^{tL}, t \geq 0$ for the semigroup with generator L is justified.

The question when a given densely defined linear operator L is the generator of a C_0 -contraction semigroup is answered by the theory of Hille-Yosida. For this we recall some basic definitions.

If L is a linear injection (1-1 map), then L^{-1} is defined on $D(L^{-1}) = LD(L)$, by $L^{-1}u = v, u \in D(L^{-1})$, with v s.t. $Lv = u$.

For a linear operator L the resolvent set is defined by:

$\rho(L) \equiv \{\alpha \in \mathbb{K} \mid \alpha - L : D(L) \rightarrow B \text{ is an injection onto } B \text{ i.e. } D((\alpha - L)^{-1}) = B. \text{ Moreover } (\alpha - L)^{-1} \text{ is bounded.}\}$

Exercise 4. Show that if $\rho(L) \neq \emptyset$ then $\rho(L)$ is closed (use that $(\alpha - L)^{-1}$ for $\alpha \in \rho(L)$ is bounded).

The spectrum $\sigma(L)$ of L is by definition the complement in \mathbb{K} of $\rho(L)$. For $\alpha \in \rho(L), G_\alpha \equiv (\alpha - L)^{-1}$ (which exists as a bounded operator on B) is called the resolvent of L at α .

$(G_\alpha)_{\alpha \in \rho(L)}$ is called the resolvent family associated to L .

Exercise 5. Show that $(G_\alpha)_{\alpha \in \rho(L)}$ satisfies the resolvent identity $G_\alpha - G_\beta = (\beta - \alpha)G_\alpha G_\beta = (\beta - \alpha)G_\beta G_\alpha, \forall \alpha, \beta \in \rho(L)$.

Proposition 4. *Let L be the generator of a C_0 -contraction semigroup on a Banach space. Then $(0, \infty) \subset \rho(L)$ and for any*

$$\operatorname{Re} \alpha > 0 : (\alpha - L)^{-1} u = G_\alpha u = \int_0^{+\infty} e^{-\alpha t} T_t u dt$$

(where the integral is in Bochner's sense) and $\|G_\alpha\| \leq \frac{1}{\operatorname{Re} \alpha}$.

Proof. Set $R_\alpha \equiv \int_0^{+\infty} e^{-\alpha t} T_t dt$.

It is easily seen that $(\alpha - L)R_\alpha u = u, \forall u \in B, \operatorname{Re} \alpha > 0$. Since L is closed for all $u \in D(L) : LR_\alpha u = R_\alpha Lu$, from which one deduces that $\alpha - L$ is injective for $\operatorname{Re} \alpha > 0$ (in particular for $\alpha > 0$) and $R_\alpha = G_\alpha$. The bound in Proposition 4 then follows from the definition of R_α . \square

Remark 1. G_α is the Laplace transform of T_t (in the sense given by Proposition 4).

Theorem 1. (Hille-Yosida, for C_0 -contraction semigroups):

Let L be a linear operator in a Banach space B . The following are equivalent:

- i) L is the generator of a C_0 -contraction semigroup $T = (T_t)_{t \geq 0}$ on B .
- ii) L is densely defined and
 - $\alpha) (0, \infty) \subset \rho(L)$
 - $\beta) \|\alpha(\alpha - L)^{-1}\| \leq 1 \quad \forall \alpha > 0$

Corollary 2. If ii) is fulfilled then L is closed and uniquely determined.

Proof. ii) implies i) by Theorem 1 and hence that L is closed by Proposition 2. The rest follows from Corollary 1. \square

Proof. (of Theorem 1)

i) \Rightarrow ii): From i) we have L closed, densely defined (Propositions 2,3). That $(0, \infty) \subset \rho(L)$ and ii) holds follows from Proposition 4.

ii) \Rightarrow i): For details we refer to, e.g.[413]. In the proof the following Proposition is useful.

Proposition 5. Let L satisfy the conditions ii) of Theorem 1. Set $G_\alpha = (\alpha - L)^{-1}, \alpha > 0$. Then

- i) $\alpha G_\alpha u \rightarrow u$ in B , as $\alpha \rightarrow +\infty$
- ii) Define $L^{(\alpha)} \equiv -\alpha + \alpha^2 G_\alpha, \alpha > 0$ ("Yosida approximation of L "). Then $L^{(\alpha)}$ is bounded, $D(L^{(\alpha)}) = B, L^{(\alpha)}u \rightarrow Lu, \alpha \uparrow +\infty, u \in D(L)$, and $e^{tL^{(\alpha)}}u$ converges as $\alpha \uparrow +\infty$ for all $u \in D(L)$ to $\tilde{T}_t u$, where \tilde{T}_t is a C_0 -contraction semigroup, with generator L . Moreover \tilde{T}_t coincides with the semigroup T_t generated by L mentioned in i).

Proof. For $u \in D(L)$ we have

$$\begin{aligned}
 \|\alpha G_\alpha u - u\| &= \|\alpha(\alpha - L)^{-1}u - (\alpha - L)(\alpha - L)^{-1}u\| \\
 &= \|L(\alpha - L)^{-1}u\| \\
 &= \|(\alpha - L)^{-1}Lu\| \\
 &\leq \frac{1}{\alpha} \|Lu\| \rightarrow 0, \alpha \uparrow +\infty
 \end{aligned}$$

(where we used Proposition 4). But αG_α is a contraction by Proposition 4 and $D(L)$ is dense by assumption, hence $\alpha G_\alpha u \rightarrow u$ as $\alpha \uparrow +\infty$, for all $u \in B$.

From this it is easy to see that $\alpha G_\alpha Lu \rightarrow Lu, u \in D(L)$, as $\alpha \uparrow +\infty$, and thus $L^{(\alpha)}u = -\alpha u + \alpha^2 G_\alpha u = \alpha G_\alpha Lu \rightarrow Lu$ as $\alpha \uparrow +\infty$.

The rest follows by realizing that

$$e^{tL^{(\alpha)}}u = \sum_{n=0}^{\infty} \frac{t^n}{n!} L^{(\alpha)^n}u = e^{\alpha t} e^{-\alpha^2 G_\alpha u}$$

Remark 2. Another useful “approximation formula” for T_t in terms of the resolvent is the following one:

$$T_t u = \lim_{n \rightarrow \infty} \left(\frac{n}{t} \right)^n (G_{\frac{n}{t}} u)^n, \forall u \in B$$

(see, e.g., [413], p. 33).

Remark 3. In the formulation of Hille-Yosida’s theorem i) can be replaced by a statement involving the generator of a C_0 -contraction resolvent family according to the following definition.

Definition 4. A C_0 -contraction resolvent family is a family $(G_\alpha)_{\alpha>0}$ such that

$$\alpha G_\alpha u \rightarrow u, \alpha \uparrow +\infty, \|\alpha G_\alpha\| \leq 1, \alpha > 0$$

and the resolvent identity in Exercise 5 holds.

Hille-Yosida’s theorem holds then with i) replaced by:

i’) L is the generator of a C_0 -contraction resolvent family $(G_\alpha)_{\alpha>0}$ in the sense that $G_\alpha = (\alpha - L)^{-1}$ on B . There is a one-to-one correspondence between C_0 -contraction semigroups $(T_t)_{t \geq 0}$ and C_0 -contraction resolvent families $(G_\alpha)_{\alpha>0}$ given by the Laplace-transform formula in Proposition 4 (and Remark 1) resp. Proposition 5 or Remark 2 after Proposition 5.

Hille-Yosida’s characterization of generators L involves the resolvent G_α . A pure characterization of L , under some “direct restrictions” on L is given by the Lumer-Phillips theorem, for which we need a definition.

Definition 5. The duality set $F(u)$ for any element u in a Banach space B is defined by

$$F(u) \equiv \{u^* \in B^* | \langle u^*, u \rangle = \|u\|^2 = \|u^*\|^2\},$$

where B^* is the dual of B (the space of continuous linear functionals on B) and \langle, \rangle is the dualization between B and B^* .

An operator L is *dissipative* on B if for any $u \in D(L)$ there exists some $u^* \in F(u)$ such that $\operatorname{Re} \langle u^*, Lu \rangle \leq 0$.

($-L$ is then said to be accretive).