## **Rotating Electric Machinery and Transformer Technology**

Donald V. Richardson

# **Rotating Electric Machinery** and Transformer Technology

Donald V. Richardson, MME, PE

Electrical Engineering Technology Waterbury State Technical College

Consulting Engineer

Reston Publishing Company, Inc. A Prentice-Hall Company Reston, Virginia

#### Library of Congress Cataloging in Publication Data

Richardson, Donald V
Rotating electric machinery and transformer technology.

Bibliography: p. 601 Includes index. 1. Electric machinery. I. Title. TK2181.R48 621.31'042 77-531 ISBN 0-87909-732-9

© 1978 by Reston Publishing Company, Inc. A Prentice-Hall Company Reston, Virginia 22090

All rights reserved. No part of this book may be reproduced in any way, or by any means, without permission in writing from the publisher.

10 9 8 7 6 5 4 3

Printed in the United States of America

### **Preface**

The last generation since World War II has seen two major forces develop in engineering education. On one hand, the traditional four-year engineering courses have become more generalized and analytical and, at the same time, less equipment oriented. This results in competent practicing engineering graduates who cannot comfortably work with actual apparatus although they are trained in the design analysis of equipment to be developed. On the other hand, technically oriented new courses of study have appeared around the country in the community colleges, technical colleges, and private two-year institutions. These courses of study are designed to turn out the student who can both analyze and work with actual apparatus.

Many excellent texts exist that cater to the needs of the new type of four-year college student as far as the engineering study of transient conditions in rotating electric machinery. However, prior to this book, few really suitable texts have been available that cater to the needs of the two-year technical college student or to the four-year bachelor of engineering technology student. No other electrical machinery text has yet appeared in System International units. Therefore, this text and its accompanying synchronized laboratory text, Laboratory Operations for Rotating Electric Machinery, are specifically prepared to enable the technical college student and the practicing engineer to recognize, understand, analyze, specify, connect, control, and satisfactorily apply the various existing types of electric motors and generators.

In the current and still worsening energy crisis, there is a new emphasis on the efficiency of all machine processes. For this reason, strong emphasis is placed upon the production and measurement of horsepower or its watt equivalent and the isolation of the accompanying losses. The intended result is that the reader who is trained by these methods will be competent and comfortable with the requirements to analyze or test the power required by a specific machine. The reader will also be able to determine the accompanying losses and specify the

most effective machine for the job. He or she will be competent to connect the motor, generator, or transformer with its correct controls and safety devices. Finally, he or she will be able to test the installation with a wide variety of methods in order to realistically use the facilities on hand in a specific laboratory or industrial situation.

To educate a student in these directly applicable methods so that he or she may be qualified to fit into an early employment situation requires that the text subjects be assembled in a sequence that appears at first to be obsolete as far as electrical machinery texts are concerned. In reality, the older four-year texts were the way they were because the then-student, who is now an experienced practitioner, was required to work with real-world equipment. The older texts were almost all concerned with steady-state conditions. New unified treatment texts are now primarily concerned with transient conditions that are met in automatic control systems. The transient-condition studies are vital in new control system design, but their analysis requires mathematics that are beyond the skills acquired in a two-year college. This text is specifically aimed at filling the gap that has been left by a whole generation that has neglected or ignored the requirements to define, install, test, and control steady-state power equipment. The requirement to apply motor and generator equipment is greater than ever and will continue to grow in importance as the use of motor-driven equipment increases.

This text uses *both* English and unified System International (SI) units so that the inevitable transition can be approached with confidence.

The unit conversion tables are designed to take advantage of the higher data accuracy obtainable with modern digital instrumentation. Five significant figures are provided in all situations.

Pocket calculators that have significant scientific computation capability have proliferated to such an extent that the slide rule has become obsolete. As a result, the inclusion of trigonometric and logarithmic tables is no longer required. All examples and problems herein can still be solved by use of a slide rule, but the tabular and conversion data are such that full advantage can be taken of the scientific pocket calculator.

As the basis of electrical machine understanding progresses, experiments that illuminate and clarify the principles under discussion are referred to as they are presented in the synchronized laboratory text. This enables a school with almost any degree of electric machinery laboratory equipment to actually have its students perform the most relevant possible experiments.

The experimental methods and computational procedures described enable the practicing engineer and maintenance technician to perform useful development work without specialized apparatus, such as dynamometers. Efficiency calculations can be readily performed on machine tools, conveyors, and other installed and working equipment.

It is not proposed that the students in any one school perform all the course study or the related experiments since more than an academic year's work is included. Rather, the material to be covered should be related to the experiments that use the highest level of equipment available and that most nearly fill the portion of the academic year to be used. The solutions manual offers suggested material to include or delete to match available time.

It has been the author's experience that the student or practicing engineer who is experienced in this material is well prepared either to go on to a four-year engineering degree or to take a responsible position in industry. He is able to make use of motors, generators, and transformers on a confident basis and without needing the help of some intermediary to make the needed installations.

In the preparation of any textbook certain major areas of aid and decision stand out. I wish to acknowledge the help and confidence of Mr. Weldon Rackley, editor, Mr. Lawrence Benincasa, regional editor, and Ms. Linda Weigle, production editor, all of Reston Publishing Company. Professor Joseph Aidala of Queensboro Community College has given very significant advice.

The decisions used in the handling of System International metric units or SI came from the give and take of the System International Metric Unit Conference for Authors, Editors, and Publishers. This was held at Rensselaer Polytechnic Institute under the auspices of the American Society for Engineering Education.

On a more personal basis, the freely given permission to use the laboratory and other facilities at the Waterbury State Technical College was offered by President Kenneth W. Fogg, Dean of Instruction John J. Nowicki and his successor Dean Kenneth E. DeRego, and the Department Head for Electrical Technology, Professor Edward P. Kearney.

The manuscript has been edited, proofread, and typed by my wife, Betty, whose partnership in time and effort has fully matched my own. My father, John W. Richardson, who is a retired mechanical engineer, has also proofread the entire manuscript and checked all worked example solutions.

Donald V. Richardson

## **Rotating Electric Machinery** and Transformer Technology

## **Contents**

	PREFACE	XV
CHAPTER 1	INTRODUCTION  1-1 Change of Major Use to Alternating Current, 1; 1-2 Early Use of Motors, 4; 1-3 Electric Power Distribution to Homes, 7; 1-4 Electric Motors Not Widely Understood, 9; 1-5 Prerequisite Requirements, 9; 1-6 Efficient Use of Energy, 9; 1-7 System International Metric Units, 10; 1-8 The Future of Electric Machines, 12	1
CHAPTER 2	ELECTROMECHANICAL ENERGY CONVERSION 2-1 Electricity in the Middle, 14; 2-2 Scarcity of Useful Energy-Conversion Devices, 15; 2-3 Faraday's Basic Discovery, 16; 2-4 Related Fundamental Laws, 16; 2-5 Faraday's Law of Induction, 17; 2-6 Neumann's Formulation, 18; 2-7 Fleming's Relationships, 24; 2-8 Lenz's Law, 25; 2-9 Direct-Current Generator and Motor Mechanical Construction, 25; 2-10 Practical Generator Voltage Development, 31; 2-11 Biot- Savart Force Relationship, 37; 2-12 Left-Hand Rule of Motor Action, 40; 2-13 Other Related Laws, 41; 2-14 Unit Conversions, 43; Questions, 46; Problems, 47	14
CHAPTER 3	ACTUAL MACHINE CONSTRUCTION, DC DYNAMOS 3-1 Mechanical Construction, 49; 3-1-1 Main Frame, 49; 3-1-2 Field Poles, 51; 3-1-3 Armature Structure, 53; 3-1-4 Armature Winding Coils, 53; 3-1-5 Commutator, 53; 3-1-6 Brushes, 54; 3-1-7 Armature Shaft Bearings, 55; 3-1-8 End Bell Structure, 55; 3-1-9 Brush Rigging, 55; 3-1-10 Field Coils, 55; 3-1-11 Commutating Fields, 56;	49

3-1-12 Compensating Windings, **56**; 3-2 Armature Windings, **57**; 3-2-1 Winding Types, **57**; 3-2-2 Lap Windings, **58**; 3-2-3 Wave Windings, **59**; 3-2-4 Frog-Leg Windings and Equalizer Connections, **59**; 3-2-5 Multielement and Multiplex Coils, **60**; 3-3 Commutator and Related Elements, **62**; 3-3-1 Brush Spacing, **62**; 3-3-2 Brush Neutral Position, **62**; 3-4 Armature Reaction, **63**; 3-4-1 Correcting Armature Reaction Effect, **63**; 3-5 Armature Reactance, **66**; 3-5-1 Brush Short-Circuiting Effect, **67**; 3-5-2 Opposing Effects of Design Features, **67**; 3-5-3 Desired Improvements, **69**; 3-6 Magnetic Circuit, **71**; 3-6-1 Simplified Magnetic Circuit Analysis, **72**; 3-6-2 Magnetic Circuit Design Observations, **76**; *Questions*, **80**; *Problems*, **81** 

84

110

#### CHAPTER 4 DIRECT-CURRENT GENERATOR CHARACTERISTICS

4-1 Separately Excited Generator, 85; 4-1-1 Generator Magnetization Curve, 87; 4-2 Basic Generator Types, 87; 4-3 Shunt Generator Buildup and Polarity, 88; 4-3-1 Field Excitation Line, 89; 4-3-2 Generator Build Down, 89; 4-3-3 Residual Magnetic Field and Field Flashing, 91; 4-3-4 Generator Polarity, 91; 4-4 Shunt Generator External Characteristics, 91; 4-4-1 Internal Voltage Loss in a Shunt Generator, 92; 4-4-2 Internal and Related External Characteristics, 94; 4-4-3 Generator Regulation, 96; 4-5 Series Generator, 97; 4-5-1 Series Generator Buildup and Polarity, 97; 4-5-2 Series Generator Characteristics and Adjustment, 97; 4-5-3 Series Generator Polarity and Build Down, 99: 4-6 Series Generator External Characteristics, 99; 4-6-1 Series Generator Internal Voltage Loss, 100; 4-7 Compound Generator Operation, 101; 4-7-1 Cumulative Compound Operation, 101; 4-7-2 Differential Compound Operation, 102; 4-8 Compound Generator Characteristics, 104; 4-9 Compound Generator Adjustments, 105; Questions, 107; Problems, 108

#### CHAPTER 5 PARALLELING OF DIRECT-CURRENT GENERATORS

5-1 Modern Uses of Paralleling, 111; 5-2 Parallel dc Generator Requirements, 111; 5-3 Parallel Shunt Generators: Identical Units, 113; 5-4 Parallel Shunt Generators: Different Units, 115; 5-5 Parallel Cumulative Compound Generators: Identical Units, 116; 5-5-1 Equalizer Bus Connection, 117; 5-6 Parallel Cumulative Compound Generators: Different Ratings, 119; 5-6-1 Transposed Equalizer Connections, 119; Questions, 121; Problems, 122

#### CHAPTER 6 THE DIRECT-CURRENT MOTOR

6-1 Meaning of Power, 124; 6-1-1 Force, 124; 6-1-2 Work, 125; 6-1-3 Power, 125; 6-2 Relation of Torque and Power. 126: 6-2-1 Development of Torque, 128; 6-3 Measurement of Torque, 130; 6-3-1 Prony Brake, 130; 6-3-2 Two-Scale Prony Brake, 132; 6-3-3 Dynamometer, 133; 6-4 Back Electromotive Force in a Motor, 136: 6-4-1 Armature Power Developed, 137; 6-4-2 Equilibrium Motor Speed, 139; 6-5 Shunt Motor, 140; 6-5-1 Shunt Motor Speed Characteristics, 140; 6-5-2 Shunt Motor Torque Characteristics, 140; 6-5-3 Speed Regulation. 142; 6-5-4 Standard Power Ratings, 142; 6-5-5 Permanent Magnet Field Motors, 144; 6-6 Series Motor, 144; 6-6-1 Series Motor Speed Characteristics, 145; 6-6-2 Series Motor Torque Characteristics, 145; 6-6-3 Series Versus Shunt Motor Usage, 151; 6-7 Compound Motor, 151; 6-7-1 Compound Motor Speed Characteristics, 152; 6-7-2 Compound Motor Torque Characteristics, 153; 6-8 Comparison of Direct-Current Motor Characteristics, 154; 6-9 Direct-Current Motor Starting Problems, 155; 6-9-1 Dc Starting Switch, 156; 6-10 Direct-Current Motor Reversing, 160; 6-10-1 Direct-Current Motor Reversing Circuit Connections, 161; 6-11 Force, Torque, and Speed Unit Conversions, 161; Questions, 164; Problems, 165

#### CHAPTER 7 EFFICIENCY OF DIRECT-CURRENT MACHINERY

7-1 Basic Efficiency Relationships, 169: 7-1-1 Convenient Data Sources, 170; 7-2 Types of Losses in Direct-Current Machines. 170; 7-2-1 Rotational Losses, 171; 7-2-2 Winding Resistance Losses, 172; 7-2-3 Shunt Field Loss, 173; 7-3 Relationships Between Losses, 174: 7-4 Isolation and Determination of Losses, 181; 7-4-1 Self-Powered Rotational Loss Tests, 181; 7-4-2 Separately Powered Rotational Loss. 184: 7-4-3 Mechanical Brush Drag, 184; 7-4-4 Hysteresis and Eddy Current Losses, 186; 7-4-5 Winding Resistances, 187; 7-4-6 Resistance from Wire Characteristics. **187**: 7-4-7 Temperature Effect on Resistance, 196: 7-5 Armature Circuit Resistance, 200; 7-5-1 Ohmmeter or Ohm's Law Method, 200; 7-5-2 Voltmeter-Ammeter Methods, 201; 7-5-3 Resistance Calculation, 201; 7-5-4 Forgue's Method. 202; 7-6 Calibrating a dc motor or Generator, 205; Questions, 213; Problems, 215

#### CHAPTER 8 DIRECT-CURRENT MOTOR CONTROL AND OPERATION

8-1 Motor Load Characteristic List, 217; 8-1-1 Power Supply,

123

167

217

217; 8-1-2 Starting Requirement Considerations, 217; 8-1-3 Stopping Requirement Considerations, 218; 8-1-4 Reversing Requirement Considerations, 218; 8-1-5 Normal Running Requirement Considerations, 219; 8-1-6 Speed Control Requirement Considerations, 219: 8-1-7 Safety and Environmental Requirement Considerations, 219; 8-2 Components and Related Diagram Symbols, 220; 8-2-1 Primary Control Devices, 221; 8-2-2 Pilot Control Devices, 229; 8-3 Manual Direct-Current Motor Starters, 235; 8-3-1 Two-Point Starter, 235; 8-3-2 Three-Point Starter, 235: 8-3-3 Four-Point Starter, 235; 8-3-4 Drum Rotary Switch Starter, 238; 8-4 Automatic Direct-Current Motor Starters, 241; 8-4-1 Definite Time Acceleration dc Starters, 242; 8-4-2 Current Limit Acceleration Starters, 246; 8-5 Reversing Control of Direct-Current Motors, 249; 8-5-1 Manual Reverse Control. 249; 8-5-2 Pushbutton Control with Reverse, 250; 8-6 Plugging Reverse Control, 254; 8-6-1 Typical Plugging Reverse Controller, 255; 8-7 Retardation and Stopping, 258; 8-7-1 Dynamic Braking, 259; 8-7-2 Regenerative Braking, 260; 8-7-3 Electric Brakes, 261; 8-8 Jogging, 262; 8-9 Direct-Current Motor Speed Control, 264; 8-9-1 Basic Causes and Limits of Speed, 265; 8-9-2 Specific Speed Relationships, 266; 8-9-3 Mechanisms Used in Speed Control, 270; Questions, 271; Problems, 272

## CHAPTER 9 DIRECT-CURRENT MOTOR AND GENERATOR SELECTION

274

9-1 Shaft Power, 274; 9-2 Characteristics of Driven Load, 275; 9-3 Speed Rating, 275; 9-4 Frame Size, 276; 9-5 Speed Classification, 284; 9-6 Effect of Duty Cycle, 284; 9-7 Ambient Temperature Effects, 286; 9-8 Allowable Temperature Rise, 287; 9-9 Voltage and Current Ratings, 289; 9-10 Machine Enclosure Types, 289; 9-11 Maintenance and Accessibility, 292; Questions, 292; Problems, 293

#### **CHAPTER 10 ALTERNATING-CURRENT DYNAMOS**

295

10-1 Physical Construction of Alternating-Current Machines, 295; 10-1-1 Fixed Armature or Stator, 296; 10-1-2 Rotating Field Structure, 297; 10-2 Alternator Windings, 298; 10-2-1 Chording of Windings, 298; 10-2-2 Coil Group Connections, 300; 10-2-3 Winding Distribution, 301; 10-3 Synchronous Alternator, 301; Questions, 306; Problems, 306

<b>CHAPTER 11</b>	THE SYNCHRONOUS ALTERNATOR	308
	11-1 Voltage Relations, 308; 11-1-1 Basic Voltage Generation	
	Formula, 308; 11-2 Winding Pitch, 310; 11-3 Winding	
	Distribution, 310; 11-4 Complete Pole-Phase Group Voltage	
	Relations, 314; Questions, 315; Problems, 316	
CHAPTER 12	SYNCHRONOUS ALTERNATOR REGULATION	317
	12-1 Representative Alternator Performance, 318;	
	12-2 Alternator Percentage Regulation, 320; 12-3 Unity	
	Power Factor Regulation, 322; 12-4 Lagging Power Factor	
	Regulation, 324; 12-5 Leading Power Factor Loads, 324; 12-6 Load Power Factor Relations Summarized, 325;	
	12-0 Load Fower Factor Relations Summarized, 325, 12-7 Winding Resistance, 326; 12-8 Synchronous Impedance,	
	327; Questions, 332, Problems, 333	
CHAPTER 13	PARALLELING OF SYNCHRONOUS ALTERNATORS	335
	13-1 Parallel Voltage Requirements, 337; 13-1-1 Matching	
	Voltages and Transformers, 337; 13-1-2 Opposing Versus Same	
	Voltages, 337; 13-2 Phase Sequence Considerations, 338; 13-2-1 Out-of-Phase Sequence Problem Magnitude, 338;	
	13-2-2 Incorrect Phase Sequence Forces, <b>339</b> ; 13-3 In-Phase	
	Requirements for Paralleling, 340; 13-4 Identical Frequency	
	Requirement, 341; 13-4-1 Allowable Frequency Differences,	
	341; 13-5 Prime-Mover Torque Speed Relation, 342;	
	13-5-1 Unmatching Torque Speed Relations, 343;	
	13-6 Alternator Synchronizing Procedures, 343; 13-6-1 Voltage	
	Matching, 343; 13-6-2 Phase Sequence Matching, 344;	
	13-6-3 Dark Lamp Phase Sequence Indication, <b>344</b> ; 13-6-4 Bright Lamp Phase Sequence Indication, <b>344</b> ;	
	13-6-5 Two Bright, One Dark Phase Sequence Indication, 344;	
	13-6-6 Alternative Phase Sequence Indication Methods, <b>344</b> ;	
	13-7 In-Phase Determination, 346; 13-7-1 Dark Lamp	
	In-Phase Indication, 346; 13-7-2 Bright Lamp In-Phase	
	Indication, 346; 13-7-3 Two Bright, One Dark In-Phase	
	Indication, 347; 13-8 Frequency Synchronization, 348;	
	13-9 Synchroscope Synchronization, 348; Questions, 349	
CHAPTER 14	IDEAL AND PRACTICAL TRANSFORMERS	350
	14-1 Ideal Transformer, 353; 14-1-1 Transformation Ratio	550
	Relations, 356; 14-1-2 General Transformer Equation, 360;	
	14-2 Practical Transformer Conditions, 364; Questions, 368;	

Problems, 369

**CHAPTER 15 TRANSFORMER EQUIVALENT CIRCUITS** 

	15-3-2 Lagging Power Factor Voltage Relations, 378; 15-3-3 Leading Power Factor Voltage Relations, 378; 15-4 Transformer Voltage Regulation by Phasor Relations, 379; 15-5 Transformer Voltage Regulation by Short-Circuit Test, 382; 15-6 Open-Circuit Test for Magnetic Losses, 385; 15-7 Transformer Efficiency, 387; Questions, 391, Problems, 391	
CHAPTER 16	SPECIFIC TRANSFORMER TYPES	394
	16-1 Transformers With Multiple Windings, 394; 16-1-1 Coil Identification Tests, 395; 16-1-2 Polarity and Voltage Tests, 396; 16-2 Autotransformer, 398; 16-2-1 Autotransformer Power Division, 401; 16-3 Instrument Transformers, 403; 16-3-1 Potential Transformers, 403; 16-3-2 Current Transformers, 404; Questions, 405; Problems, 405	
CHAPTER 17	TRANSFORMER CONNECTIONS	407
	17-1 Parallel Transformer Connections, 407; 17-1-1 Unmatching Parallel Transformers, 408; 17-1-2 Matching Parallel Transformers, 408; 17-2 Three-Phase Transformer Circuits, 410; 17-2-1 Three-Phase Y-Y Connections, 411; 17-2-2 Three-Phase Δ-Δ Connections, 413; 17-2-3 Three-Phase Y-Δ Connections, 413; 17-2-4 Three-Phase Δ-Y Connections, 413; 17-2-5 Three-Phase Open Delta or V-V, 418; 17-2-6 Three-Phase Scott Tee or T-T, 420; 17-2-7 Three-Phase to Two-Phase Scott Tee, 422; 17-3 Three-Phase Transformer Paralleling, 424; 17-4 Multiple-Phase Transformation, 424; Questions, 424; Problems, 425	
CHAPTER 18	THE POLYPHASE INDUCTION MOTOR	427
	18-1 Induction Motor Action, 427; 18-1-1 Rotating Magnetic Field from Polyphase Fixed Stator Coils, 428; 18-1-2 Induction Motor Rotor Torque Development, 432; 18-2 Induction Motor Performance Parameters, 434; 18-2-1 No-Load Test or Rotational-Loss Test, 435; 18-2-2 Blocked Rotor Test, 435; 18-2-3 Stator Resistance Test, 438; 18-2-4 Induction Motor Load Test, 438; 18-2-5 Motor Parameters Summarized, 438; 18-3 Induction Motor Performance, 439; 18-3-1 Rotor Current	×

15-1 Reflected Impedance, 371; 15-2 Simplified Equivalent Circuits, 373; 15-3 Secondary Voltage Phasor Relations, 376;

15-3-1 Unity Power Factor Voltage Relations, 378;

371

and Power, 439; 18-3-2 Induction Motor Torque, 444; 18-3-3 Maximum Torque Developed, 445; 18-3-4 Starting Torque Relations, 449; Questions, 451; Problems, 451

#### CHAPTER 19 POLYPHASE INDUCTION MOTOR CHARACTERISTICS

454

19-1 Motor Classes of the National Electrical Manufacturers Association, 454; 19-1-1 NEMA Class Motor Characteristics, 456; 19-2 Wound-Rotor Motor Characteristics, 457; 19-3 Induction Motor Speed Control, 460; 19-3-1 Motor Speed Change by Frequency Change, 461; 19-3-2 Motor Speed Change by Pole Change, 462; 19-3-3 Motor Speed Change by Voltage Change, 463; 19-3-4 Motor Speed Change by Rotor Resistance, 463; 19-4 Induction Motor Efficiency, 463; 19-4-1 Efficiency from No-Load and Blocked-Rotor Tests, 464; 19-4-2 Efficiency from the AIEE Load Slip Method, 466; Questions, 468; Problems, 469

#### CHAPTER 20 THE SYNCHRONOUS MOTOR

470

20-1 Similarity to Synchronous Alternators, 471; 20-1-1 Synchronous Motor Action, 471; 20-2 Synchronous Motor Starting, 472; 20-3 Synchronous Motor Power Factor Control, 474; 20-4 Synchronous Motor V Curve, 476; 20-5 Synchronous Motor Power Factor Correction, 477; 20-6 Synchronous Capacitor, 481; 20-7 Synchronous Dynamo Efficiency, 481; 20-8 Synchronous Motor Characteristic Curves, 485; Questions, 486, Problems, 487

#### CHAPTER 21 THE SINGLE-PHASE INDUCTION MOTOR

488

21-1 Single-Phase Induction Motor Starting, 489; 21-1-1 No Torque at Standstill with Single Phase, 491; 21-1-2 Double Revolving Field Theory, 491; 21-1-3 Rotor Cross Field Theory, 492; 21-2 Resistance Split-Phase Starting, 494; 21-2-1 Starting Switch Problems, 496; 21-2-2 Reversing Resistance Split-Phase Motors, 498; 21-3 Capacitor-Start Induction Motors, 498; 21-3-1 Capacitor Requirements, 499; 21-3-2 Starting Switch Problems, 500; 21-4 Capacitor-Start Capacitor-Run Motors, 501; 21-4-1 Autotransformer and Capacitor Circuits, 503; 21-5 Permanent-Split Capacitor Motor, 503; 21-6 Single-Phase Induction Motor Load Characteristics, 506; 21-6-1 Resistance Split-Phase Motors, 506; 21-6-2 Capacitor-Start Motors, 508; 21-6-3 Capacitor-Start Capacitor-Run Motors, 509; 21-7 Single-Phase Induction Motor Efficiency, 509;

21-7-1 No-Load or Rotational-Loss Tests, **509**; 21-7-2 Blocked-Rotor Test, **510**; 21-7-3 Stator Resistance Test, **510**; 21-7-4 Efficiency from the AIEE Method, **510**; Questions, **510**; Problems, **511** 

## CHAPTER 22 SHADED-POLE, SYNCHRONOUS, UNIVERSAL, AND OTHER SINGLE-PHASE AC MOTORS

513

22-1 Shaded-Pole Induction Motors, **514**; 22-1-1 Shaded-Pole Motor Reversing, **517**; 22-2 Reluctance-Start Induction Motors, **518**; 22-3 Single-Phase Synchronous Motors, **520**; 22-3-1 Reluctance Motors, **520**; 22-3-2 Hysteresis Motors, **522**; 22-3-3 Subsynchronous Motors, **523**; 22-4 Polyphase Synchronous Induction Motors, **523**; 22-5 Induction-Type Motor Efficiencies, **524**; 22-5-1 Nonsynchronous Motors, **524**; 22-6 Universal Motor Characteristics, **528**; 22-6-2 Universal Motor Efficiency, **529**; 22-7 Single-Phase Motor Application, **529**; *Questions*, **532**; *Problems*, **533** 

## CHAPTER 23 ALTERNATING-CURRENT MOTOR CONTROL AND OPERATION

535

23-1 Alternating-Current Motor Load Characteristic List, 535: 23-1-1 Power Supply, 535; 23-1-2 Starting Requirement Considerations, 536; 23-1-3 Stopping Requirement Considerations, 536; 23-1-4 Reversing Requirement Considerations, 536; 23-1-5 Normal Running Requirement Considerations, 536; 23-1-6 Speed Control Requirement Considerations, 536; 23-1-7 Safety and Environmental Requirement Considerations, 536; 23-2 Components and Related Design Symbols, 536; 23-2-1 Line Voltage Transformers, 536; 23-2-2 Pilot Control Circuit Transformers, 536; 23-3 Nonreversing Full-Voltage Motor Starter, 537; 23-4 Reversing Full-Voltage Motor Starters, 540: 23-4-1 Drum Rotary Switch Controls, 540; 23-4-2 Three-Phase Integral Horsepower Controls, 540; 23-5 Reduced-Voltage Three-Phase Motor Controls, 543; 23-5-1 Specific Starting Circuits, 544; 23-5-2 Other Reduced-Current Starting Circuits. 546; 23-5-3 Wound-Rotor Induction Motor Starting, 546: 23-6 Reversing Reduced-Current Controls, 548: 23-7 Plugging Reverse of Alternating-Current Motors, 548; 23-8 Retarding and Stopping Alternating-Current Motors, 549; 23-9 Alternating-Current Motor Jogging Controls, 550; 23-10 AlternatingCurrent Motor Speed Control, **550**; 23-10-1 Consequent Pole Speed Controls, **551**; 23-10-2 Two-Winding Speed Controls, **551**; 23-10-3 Two Speed with Reverse Controls, **551**; Questions, **556** 

CHAPTER 24	ALTERNATING-CURRENT MOTOR SELECTION	557
	24-1 Shaft Power, 558; 24-2 Characteristics of the Driven	
	Load, <b>558</b> ; 24-3 Speed Rating, <b>558</b> ; 24-4 Frame Size, <b>559</b> ;	
	24-5 Speed Classification, <b>561</b> ; 24-6 Effect of Duty Cycle, <b>563</b> ; 24-7 Ambient Temperature Effects, <b>564</b> ; 24-8 Allowable	
	Temperature Rise, <b>564</b> ; 24-9 Voltage and Current Ratings,	
	564; 24-9-1 Alternating Current Voltage-Level Ratings, 564;	
	24-9-2 Alternating Current Frequency, 566;	
	24-9-3 Alternating Current Motor Current Levels, <b>566</b> ;	
	24-9-4 Motor Protective Devices, <b>571</b> ; 24-9-5 Motor Power Factor, <b>572</b> ; 24-10 Machine Enclosure Types, <b>575</b> ;	
	24-11 Maintenance and Accessibility, <b>575</b> ; 24-12 Efficiency,	
	575; 24-13 Radio and Television Inteference, 575; Questions,	
	<b>576</b> ; Problems, <b>577</b>	
CHAPTER 25	SPECIAL USES OF SYNCHRONOUS	
	AND INDUCTION MACHINES	579
	25-1 Frequency Converter Set, <b>579</b> ; 25-2 Induction Frequency Converter, <b>579</b> ; 25-3 Induction Phase Converter, Single- to Three-Phase, <b>580</b> ; 25-4 Induction Phase Converter, Single- to Two- to Three-Phase, <b>585</b> ; 25-5 Induction Regulator, <b>585</b> ; 25-6 Linear Motion Devices, <b>586</b> ; <i>Questions</i> , <b>587</b>	
APPENDIX A	UNIT CONVERSIONS	588
APPENDIX B	LIST OF SYMBOLS	591
APPENDIX C	GREEK SYMBOLS	596
APPENDIX D	CONSTANTS AND COEFFICIENTS USED IN TEXT	598
APPENDIX E	INDUCTION MOTOR LOCKED ROTOR INDICATING	
	CODE LETTERS	600
	BIBLIOGRAPHY	601
	INDEX	603

## Introduction

Some major electrical developments that took place nearly a century ago started a chain of interlocking developments that have permanently changed our lives. Thomas Alva Edison experimentally developed a useful electric light. He immediately foresaw that widespread and effective use of his light would require a practical source and distribution of large amounts of electric power. His development work on steam-engine-driven direct-current (dc) generators enabled the commercial expansion of electric lighting. Figure 1-1 shows a very early dc generator.

Overlapping the early use of electric lighting was the development by Sprague and others of practical dc motors and motor speed controls. This enabled the building of what would now be called urban electric railroad systems. These early trolley cars enabled mass commuting to work and business toward the end of the last century. An early trolley car using dc motors is shown in Fig. 1-2.

#### 1-1 CHANGE OF MAJOR USE TO ALTERNATING CURRENT

The widespread distribution of direct-current electric power has virtually disappeared. The single-unit street-surface electric rail car, as distinguished from the multiple-unit subway car, is about gone. Alternating-current electric distribution became nearly universal by the second half of the twentieth century.

The advantage of alternating current over direct current in power distribution is based on the ease of changing the ac voltage level. High-voltage power lines carry their energy with a correspondingly lower current. From the very basic Ohm's law, the voltage drop in a resistance is related to the current and the resistance. Since the resistance of a power line, or any conductor, is related to its cross-sectional area, a larger-sized wire will have less resistance. On the other hand, a long-distance line will cost a prohibitive amount if it is made of a large cross section. A modern high-voltage ac distribution line is shown in Fig. 1-3.