

Volume nine

Symposium on reconstructive hand surgery

Editors

J. William Littler
Lester M. Cramer
James W. Smith



*Educational Foundation of the American Society
of Plastic and Reconstructive Surgeons*

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Symposium on
reconstructive hand surgery

Editors

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Symposium on
reconstructive hand surgery

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Preface

In November of 1972, following months of careful preparation by Dr. James Smith and Dr. Lester Cramer, on behalf of the Educational Foundation of the American Society of Plastic and Reconstructive Surgeons, over five hundred physicians and allied personnel gathered at Rockefeller University in New York City for a three-day symposium on care of the disabled hand. The attendance attested to a growing awareness for those patients of all ages and from all walks of life who suffer from disabilities of the hand. This volume contains the essence of that meeting. Many subjects were of necessity excluded from the symposium in order to concentrate on more fundamental and technical aspects of special problems.

Our contributors present a provocative array of subject matter extending from basic principles of

hand surgery to sophisticated procedures made possible by microsurgical techniques. This more recent refinement has great value and is essential in selected cases complicated by vascular and nerve involvement, for it allows a more meticulous coaptation of these critical structures, as demonstrated by Millesi's excellent work. Nonetheless, such technique is but an adjunct to the hand surgeon's ingenuity, for it is only through a carefully planned and skillfully executed primary or secondary surgical and rehabilitative program that the motivated hand patient will be restored to the greatest useful functional potential within the shortest period of time. It is to this end that the following material is devoted.

J. William Littler

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Part I

Basic architecture and functional anatomy

Chapter 1

Hand structure and function

J. William Littler, M.D.

Man's hand gives to his spirit the power for universal domination and "... it presents the last and best proof in the order of that principle of adaptation which evinces design."

Charles Bell, 1833

This chapter concerns the basic architectural and functional aspects of the human hand, a primitive yet perfected prehensile pentadactyl structure modified little since the Primate's origin eons ago. Despite its primordial condition, inherent structural and mathematical principles allow for great adaptability and, through the brain, ingenuity.

A semicircular row of four carpal bones forms the base of the hand. The ancient Arch of Tiberius (Fig. 1-1) might easily have had for its original design this transverse skeletal arrangement. The simple architectural principle of the segmented cuneiform arch is demonstrated in Fig. 1-2 with the capitate (os magnum) as the keystone, flanked radialward by the lesser and greater multangular (trapezoid and trapezium) bones and ulnarward by the hamate. Sturdy ligaments unite these wedge-shaped bones, and the arch is further strengthened by the broad volar retinacular ligament that forms the "floor" of the vaulted carpal tunnel, preventing prolapse of the digital flexor tendons during wrist flexion. Two central metacarpals (II and III) are bound firmly to the lesser multangular and capitate bones and constitute with the carpal arch the *fixed skeletal hand unit*.

Viewed laterally, this fixed unit exhibits a special longitudinal carpometacarpal arch or curve roughly simulating a common cycloid, one often favored in bridge construction (Fig. 1-3). The unit is stabilized at the radiocarpal joint by powerful extensor-flexor muscle tendon systems responsible for wrist stability in the basic acts of digital flexion and extension,



Fig. 1-1. It is possible that man's skeletal remnants revealed to him the basic principles of architecture. The crude Arch of Tiberius in the Roman Forum could have had for its original design the semicircular carpal arch of the hand, so perfectly demonstrated in the simple but elegant segmented cuneiform (Roman) arch.

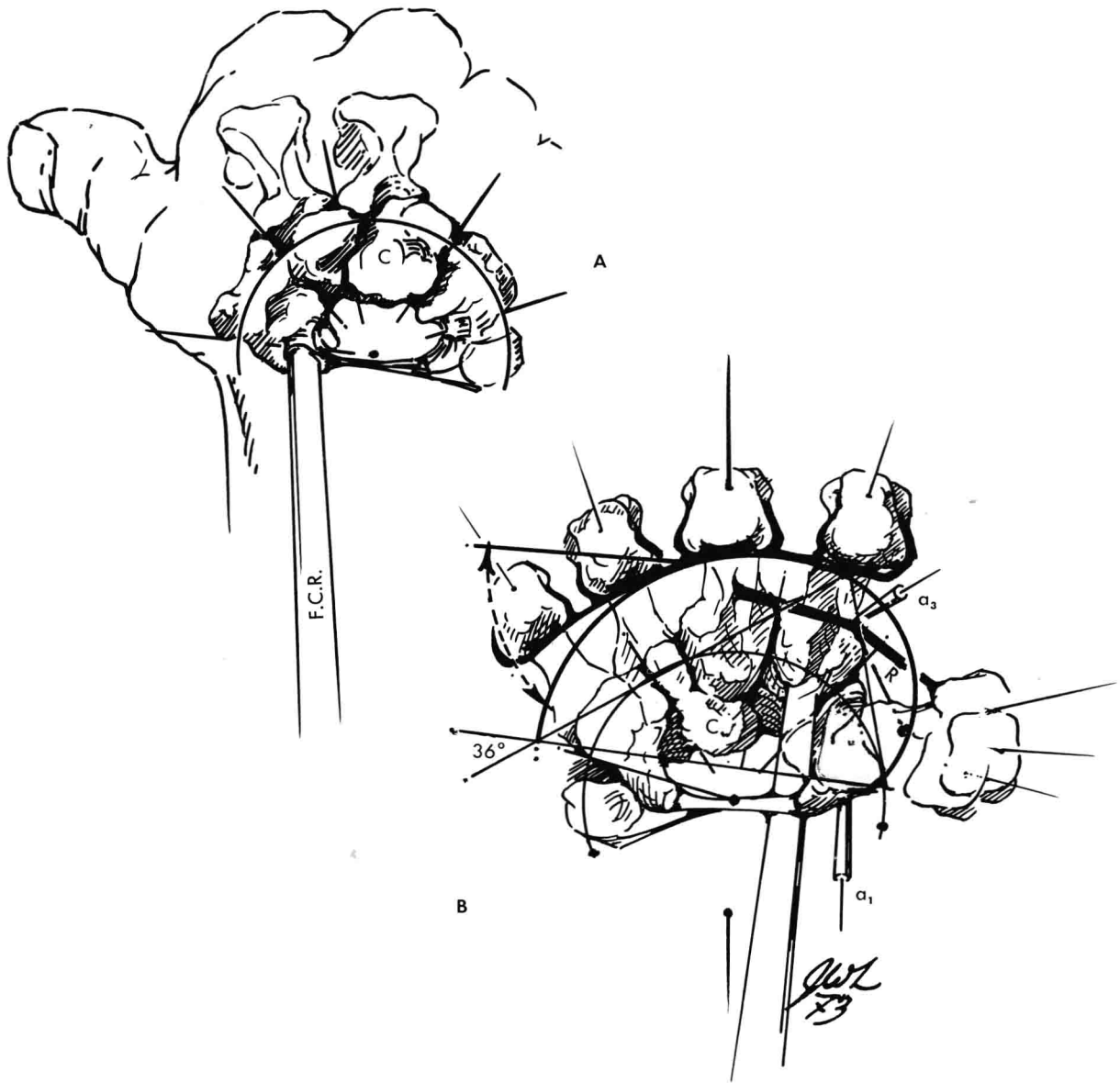


Fig. 1-2. **A**, Second and third metacarpals and semicircular carpal arch constitute the fixed unit of the hand. **B**, Lateral metacarpals (I, IV, and V) have a variable range of movement determined by their basal carpal articulations and their tether to the central metacarpals (II and III): the first (I) through the powerful flexor-adductor intrinsic musculature; the fourth and fifth (IV and V) through the intervolar plate ligaments.* These lateral mobile metacarpals, empowered by extrinsic and intrinsic muscles, are rotated externally and internally and provide the versatile transverse arch (equiangular curve) so essential for grasp adaptability. **C**, Capitate (os magnum)—“keystone” of arch. For definition of *R*, *a₁*, and *a₃* see Fig. 1-3.

*Absence of intervolar plate ligament affords freedom to thumb metacarpal (I).

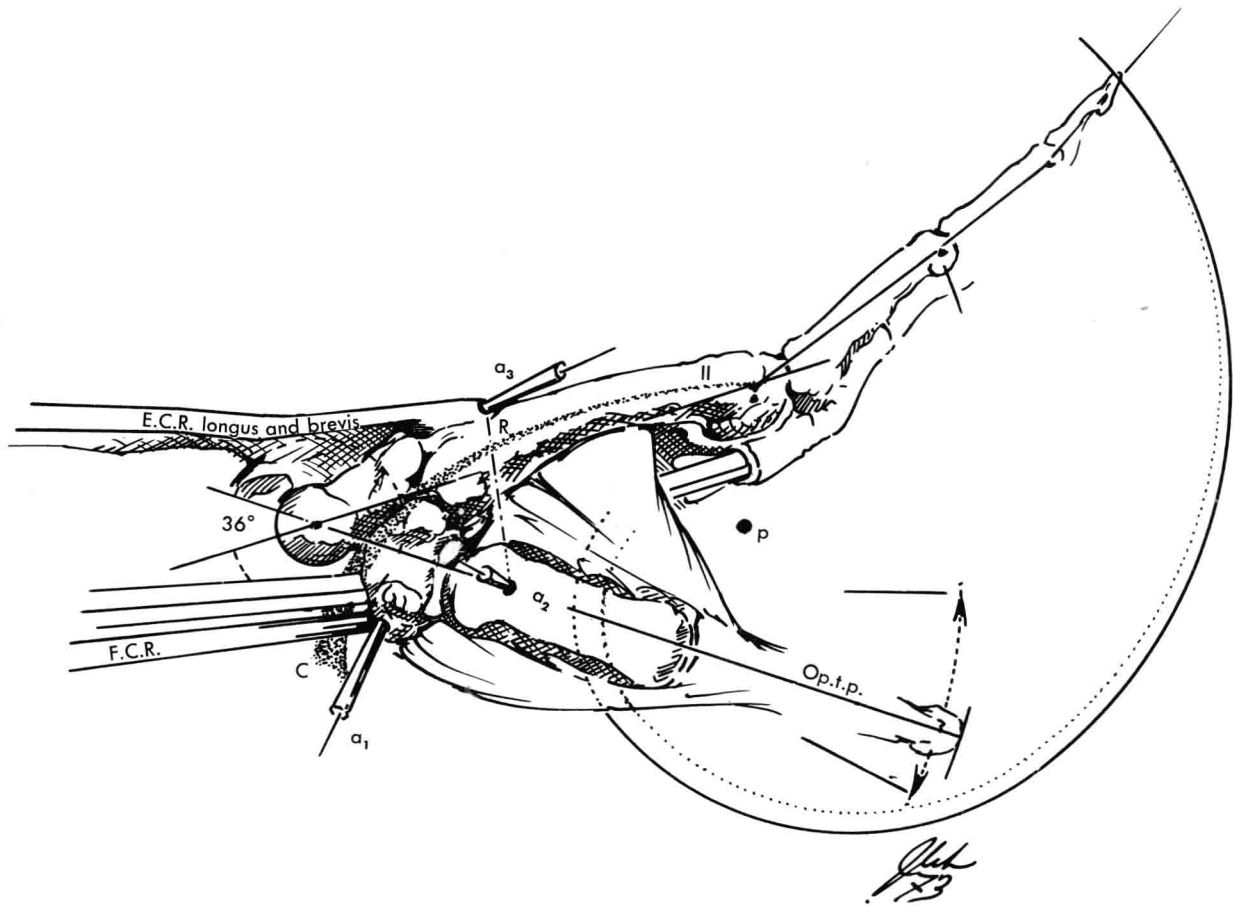


Fig. 1-3. Fixed carpometacarpal longitudinal arch exhibits a special curve not unlike the common cycloid, *C* (stippled); a sturdy base (controlled at radiocarpal axis* by powerful wrist extensor and flexor muscles) is thus afforded the mobile metacarpal and phalangeal components.† In optimum functional position, *Op.t.p.*, thumb metacarpal projects from carpal base (trapezium) at intermetacarpal angle of 36 degrees (and in 20 degrees of radiopalmar abduction). The axes of thumb metacarpal movement are a_1 , flexion-adduction, extension-abduction, and circumduction; a_2 , palmar plane adduction-abduction; and a_3 , locus and variable radius (R) of circumduction.

*The center of wrist movement is through head of os magnum (capitate).

†In the sagittal plane the normal fingertip from full extension to full flexion traces an equi-angular curve with its polar axis at p .

with which they are reciprocally synergistic. Of the three wrist extensors, the extensor carpi radialis brevis, inserted into the base of the central metacarpal, has the greatest mechanical advantage on the radiocarpal axis and is therefore most important in stabilizing the wrist for power grasp.

Despite their primary role, these important wrist extensor muscles are often rendered involuntarily ineffective even by relatively minor hand injury and/or immobilization.* It is imperative, therefore, that they promptly be returned to strong active independent use through concerted volitional effort. At times the wrist must be immobilized in extension by a plaster gauntlet and effort directed toward regaining active digital interphalangeal flexion power; the synergism existing between the extrinsic digital flexor and the wrist extensor systems will then restore action for the latter automatically.†

A particular angular relationship exists between the articular surface of the greater multangular and the fixed second metacarpal that allows the mobile first metacarpal to have an optimum functional intermetacarpal projection angle of approximately 36 degrees with 20 degrees of radiopalmar abduction. It is in this projection (fist position) that a fusion of the basal thumb joint is mandatory for optimum function in the event of traumatic joint disruption, painful osteoarthritis, or an uncompensated intrinsic muscle paralysis (Fig. 1-4).

Mobile lateral metacarpals (I, IV, and V) and all phalanges provide for the complex adaptable transverse and longitudinal arches that constitute the compound curves of the hand. The lateral metacarpals are tethered to the central metacarpal (III); the first, controlled by powerful adductor musculature, has far greater mobility than the fourth and fifth, which are restrained by the intervolar plate ligaments, allowing a limited extension-flexion rotation arc through the action of the extensor carpi ulnaris and hypothenar muscles. These lateral metacarpals create the *adaptable transverse metacarpal arch* (Fig. 1-2, B).

The adaptable transverse and longitudinal arches of the hand are developed by the mobile lateral metacarpals and the phalanges as they flex and extend around the *fixed skeletal unit*. From full extension-abduction to full flexion-adduction the phalanges of the fingers empowered by the extrin-

sic and intrinsic muscle systems encircle a "polar axis" in their sweep through an equiangular pathway* to encompass progressively smaller diameters (Fig. 1-5).

This particular function is based on an inherent numerical series that gives a clue to the order of things in nature and the arts. The interarticular (axial) lengths found in the hand follow closely the well-known mathematical sequence attributed to

*A plane curve that cuts all its radii vectores at the same angle.



Fig. 1-4. With basal thumb joint fused in optimum position, a flexion-adduction and extension-abduction cardinal plane of movement provided by metacarpophalangeal and interphalangeal joints maintains a strong, functional relationship with fingers.

*The patient will often use digital extensors for wrist extension in lieu of the normal wrist extensors.

†Movements, not muscles, are represented in the cerebral cortex.⁶

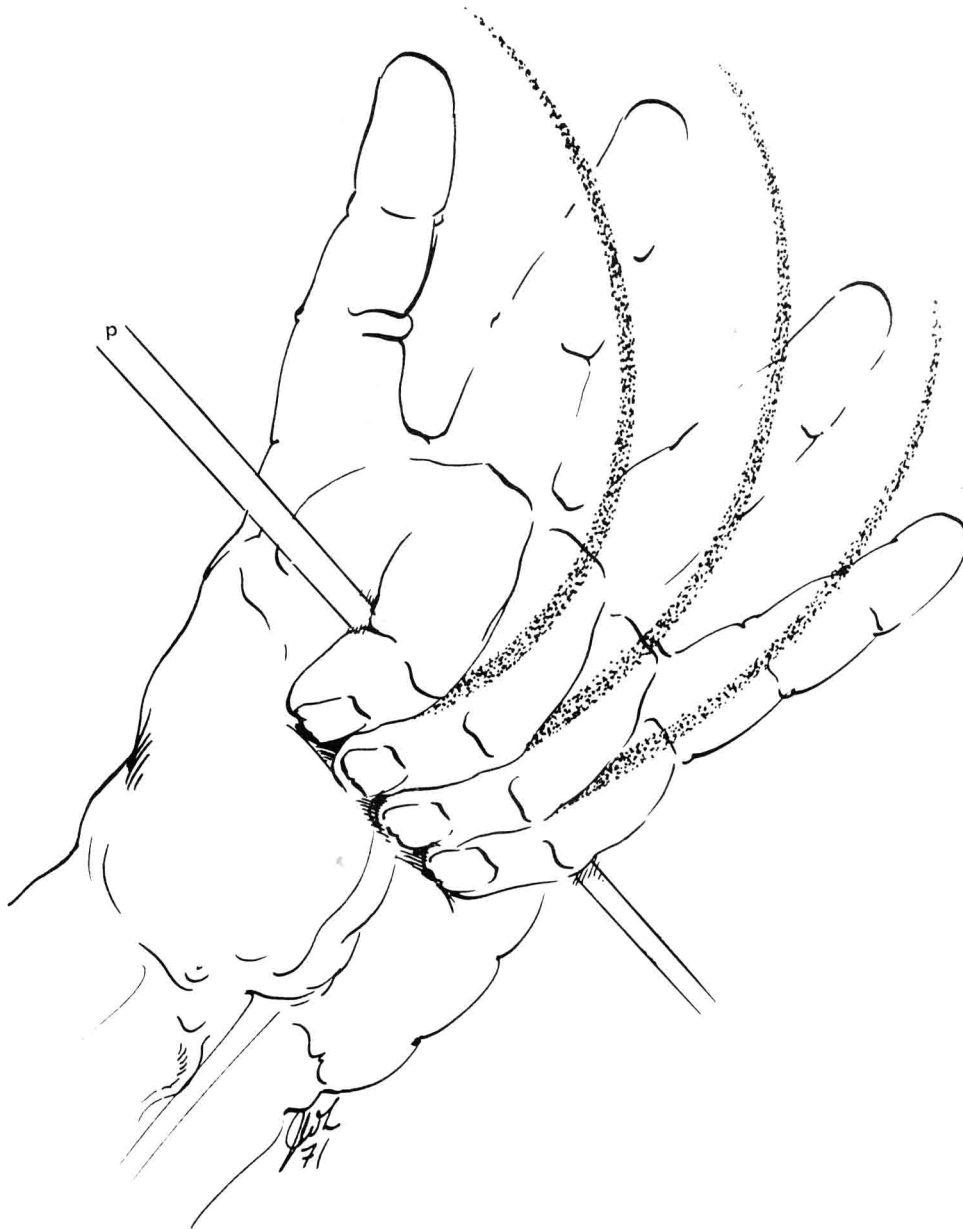


Fig. 1-5. From full extension-abduction to full flexion-adduction the fingers execute an equiangular sagittal pathway (curve) encompassing objects of grasp perfectly. A powerful, four-jaw "chucklike" grip results. *p*, Polar axis of curve.⁵

Leonardo da Pisa (known as Fibonacci, circa 1202).^{*} A break in the curve is inevitable with the joint imbalance created by an intrinsic muscle paralysis (claw deformity) or a loss of superficial flexor tendon function.

The terminal phalanx of man's thumb is a de-

^{*}The one to the other of the numerical series 0, 0.1, 1.2, 3, 5, 8, 13 . . . has a ratio of 1:1.618.

velopmental exception in length and pulp volume over that expected by the series. It is for the most part the only major deviation from the primitive pattern, having, unlike the anthropoids, a powerful long flexor tendon (Fig. 1-6). When diametric to the fingers, the normal independent thumb equals them in power and provides for firm grasp and pinch.

Text continued on p. 10.