



“十二五”普通高等教育本科国家级规划教材

# Theory of Machines and Mechanisms

(Bilingual) second edition

## 机械原理

(英汉双语)  
第2版

张颖 张春林 主编



配套教师课件



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“十二五”普通高等教育本科国家级

# Theory of Machines and Mechanisms

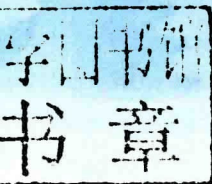
(Bilingual Edition)

## Second Edition

# 机械原理

(英汉双语)

第2版



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本书是按照高等工科教育逐步与国际教育接轨的要求编写的机械原理课程英汉双语教材。在满足国内教学基本要求的基础上,体现了我国机械原理课程教学的现状和特色,吸取了国外同类教材的特点。全书内容从机构分析、机构设计、机构系统设计到机械动力学,遵循以设计为主线,加强对基本概念、基本理论、基本方法的理解,以理论与工程实践相结合为指导思想,对传统机械原理的内容进行了整合,结合现代科学技术的发展,增加了新内容,删减了过于陈旧的内容。

全书共有13章。第1章介绍机械的基本概念;第2~4章主要介绍机构的结构分析、运动分析和力分析;第5~9章主要介绍常用机构的设计;第10章介绍空间机构和机器人机构;第11章介绍机构系统的设计;第12和13章主要介绍机械系统的运转及速度波动的调节,机械的平衡。创新设计的思想融于各章内容中。

本书的英文内容,在反映中文内容的前提下,采用典型的科技英语表现方式和通俗易懂的词汇,简便易读。同时在附录中增加了英语常用符号与公式读法,供广大读者参考。

本书可作为高等工科大学机械类专业的机械原理教材,特别适合作为英汉双语教材,也可以作为机械工程人员的参考用书。

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## Preface to the Second Edition

This book has been written for mechanical engineering students who are beginning to study the theory of machines and mechanisms or professional English.

Since the book was published in 2012, some universities take it as Chinese textbook of theory of machines and mechanisms for undergraduates, some universities take it as English textbook of theory of machines and mechanisms for undergraduates, some universities take it as bilingual education textbook of theory of machines and mechanisms, some universities take it as foreign students textbook of theory of machines and mechanisms, and some universities take it as international class students textbook of theory of machines and mechanisms. Such students will have acquired a set of mechanical engineering knowledge and the ability to use English language to express themselves in spoken and written forms.

This edition has been influenced by changes in engineering education, suggestions by colleagues and users, and the author's checkup.

The major revisionary works for publishing this new edition are as follows.

Effort has been made to remove all sorts of errors and misprints as far as possible.

We adopt a simple mathematical manner for easy comprehension by students in Chapter 5, but there are not any examples to describe the new methods. So many examples have been added in Chapter 5.

Geneva wheel with 6 slots will be more helpful to understand the action ratio, so we use a Geneva wheel with 6 slots instead of Geneva wheel with 4 slots.

Some of examples have been added in Chapter 13 too.

Two-dimensional codes are added in this edition to describe the mechanisms animated figures.

I acknowledge the efforts of professor He Cencheng of Beijing University of Technology for revisionary and compiled works for this edition.

Zhao Jiaheng of Beijing Institute of Technology compiled some examples.

Finally, I make an affectionate acknowledge to my PhD doctors team for their support.

I am grateful to all readers who pointed out errors and mistakes of the previous edition and gave valuable suggestions.

Zhang Chunlin

## 第2版前言

本教材是为机械工程专业的大学生学习机械原理课程或专业英语编写的。

本教材于2012年出版后，一些学校选其作为本科生机械原理课程的中文教材，教学时讲授中文，英语内容作为参考；一些学校选其作为机械原理课程的英文教材，教学时讲授英文，中文内容作为参考；一些开设双语教学的学校，选其作为本科生的英汉双语教学机械原理课程教材，教学时有时用英文讲授，有时用中文讲授，中、英文内容可用来对比和参考。一些学校选其作为外国留学生的机械原理课程教材，也有一些学校选其作为国际班的机械原理课程教材。本教材不但使学生获得机械原理的基本知识，还可以提高学生英语的口语和写作能力。

经过几年的使用，根据作者自查和用户意见反馈，对其进行了修改、补充和完善，如在平面连杆机构的综合内容中，引入了新方法，但缺少例题佐证。所以，本次修改增加了相应例题；在说明槽轮机构的运动特性时，采用了六槽槽轮代替四槽槽轮，这样就容易理解主动销轮和从动槽轮的转角关系，更容易理解槽轮机构的运动系数。在机械平衡设计一章中也增加了例题。

本次修订还更正了一些文字错误和语法错误，并引入了二维码技术，读者只要用手机扫描插图旁的二维码，就可以观看相应机构的动画，增强了本教材的可读性。

北京工业大学的何岑成老师参与了本次修订工作和英语教材的编审工作，北京理工大学的赵嘉珩为本教材增编了例题。

感谢我的博士生团队为本书的修订所做的工作。

由于编者水平有限，书中难免存在错误和疏漏之处，欢迎广大读者批评指正。

张春林

# Preface to the First Edition

Along with the rapid development of science and technology, the higher education will speed up internationalization. So it is necessary to compile a compatible textbook which not only has Chinese feature, but also makes for globalization. This is a new object that the teaching reform of China's higher education is faced with. On the one hand, the direct adoption of the foreign classical textbooks does not suit the actual state of our teaching in Chinese universities; on the other hand, the Chinese language textbooks cannot be brought in line with the international practice. Therefore, we will compile a bilingual textbook on "theory of machines and mechanisms" with the support of China Machine Press.

This book is based on the basic teaching requirement of the "theory of machines and mechanisms" issued by the Ministry of Education. The basic concepts, basic principles and basic skills are reinforced, and we take the content of synthesis or design as a main clue to cultivate consciousness and capability of innovation for mechanical engineering. We hope that this book can include the features inheriting from the traditional textbooks, and can be in line with some foreign textbooks.

## 1. Descriptions about "theory of machines and mechanisms" in the Chinese book

1) This book is compiled with analysis of mechanisms, design of mechanisms, design of mechanism systems and dynamics of mechanisms.

2) It highlights the analytical methods, such as kinematic analysis of mechanisms, force analysis of mechanisms, synthesis of mechanisms, cam mechanisms and balancing design, etc., and de-emphasizes graphical methods.

3) Some of the traditional contents of "theory of machines and mechanisms" are modified, integrated and expanded in this book.

The concepts of mechanism and machine are defined in Chapter 1, and they are up-to-date ideas. Composition principle of mechanisms is expanded to creative design of mechanisms. A new method which is used to determine the self-locking of a mechanism has been brought up, in which we will use the total reaction force acting on the friction cone or friction circle to determine self-locking phenomenon of a mechanism instead of use of efficiency. The concept is clear and the method is simple and practical. It highlights design as the main clue. By using the less complicated geometry algebra method instead of traditional coordinate transformation method in the analytical design of four-bar mechanism and cam mechanism, we can simplify mathematical design methods easily. This textbook also provides readers with creative design of mechanisms and design of mechanism systems to implement the overall content from simple to complicated; the contents of modified gears, helical gears, bevel gears, worm gears and intermittent mechanisms are simplified; the kinetostatic analysis of mechanism and force analysis including friction and self-locking are merged into a force analysis of mechanisms.

4) This textbook attempts to be different from the traditional versions by adopting color rendered figures and three-dimensional figures illustrations, which are clear and easy to read.

5) The exercises are divided into four parts: reading, comprehension, practice, and self-test. Furthermore, there are some analog test papers. These problems can help students to understand the



basic concepts and to prepare them to cope with real engineering problems in practice.

6) As a bilingual textbook, a lot of described contents are simplified to reduce its length. It shortens traditional Chinese text to keep concise and compact to highlight consistent context and accurate terminology.

2. Descriptions about “theory of machines and mechanisms” in the English book

1) The main purpose of the bilingual textbook is to help students study the contents of “theory of machines and mechanisms”, rather than only English.

2) The English version is not the strict translation of the Chinese version, but their contents are coincident basically.

3) All the figures, tables and formulas between the Chinese version and English version correspond with each other; they have a good comparability.

4) The professional and conventional vocabularies are adopted from foreign textbooks; so the book has a good credibility.

5) Basic English grammar of science and technology makes reading easy.

6) The reading and comprehension which include the basic concepts are adopted from foreign textbooks.

7) Some concepts between the Chinese version and English version are a little different, such as redundant degree of freedom and local degree of freedom, redundant constraint and virtual constraint. This will benefit students to some extent.

The authors of the Chinese version are as follows.

Professor Zhang Chunlin (Chapters 1, 2 and 3), Zhao Ziqiang (Chapters 4, 5 and 6), Li Zhixiang (Chapters 7 and 8), Ma Chao (Chapters 9, 10, 11, 12 and 13).

Zhang Ying of Beijing University of Technology compiled and translated Chapters 1, 2, 3, 4, 5, 6, 7, 8, 9. Wang Zeyang compiled and translated Chapters 10 and 11. Feng Xinxin compiled and translated Chapters 12 and 13. Zhang Ying thoroughly compiled and edited the English Version and Professor Zhang Chunlin compiled and edited the entire bilingual text.

#### Acknowledgments

The authors would like to express their thanks for the cooperation of all those individuals who generously made this item available.

Sincere thanks also go to Professor Ge Wenjie of Northwestern Polytechnical University, who provided a part of 3D graphics. Some of the graphics are adopted from the other authors. We would like to express our thanks to them.

Finally, we would like to make an affectionate acknowledgment to China Machine Press for the support and we acknowledge the efforts of editorial staff for bringing out the new bilingual version in an excellent format.

It is hard to avoid errors and mistakes in the first edition, because the knowledge of English of authors is limited; the authors invite criticisms and suggestions from all readers for further improvement of the book, so that the errors can be corrected in future versions.

Zhang Chunlin  
Ever Bright Garden, Beijing

## 第1版前言

随着科学技术的飞速发展和教育逐渐走向世界,编写具有中国特色、又逐步与发达国家接轨的教材,是中国高等学校教学改革所面临的新课题。直接引入国外教材的方法不适合国内的教学现状,单纯的中文教材不能满足逐步与国际接轨的需要。因此,在机械工业出版社的支持下,作者开始尝试编写中英文双语机械原理教材。

本教材的指导思想是在教育部颁布的教学基本要求基础上,加强基本理论、基本方法和基本技能的培养;以设计为主线,突出创新意识和创新设计能力的培养;既反映中国同类教材的内容与特色,又逐步与国外同类教材接轨。

### 1. 关于本教材中文部分的编写说明

1) 本教材按照机构分析、机构设计、机构系统设计和机构动力学设计的体系编写。

2) 教材内容中淡化图解法、强化解析法,如机构运动分析、力分析、连杆机构综合、凸轮机构设计、平衡设计等,淡化了图解法,突出了解析法。

3) 本教材对传统机械原理课程内容进行了修改、整合与拓展。在绪论中重新定义了机构与机器的基本概念,使其更具有时代特点;把机构组成原理拓展到机构创新设计;放弃传统的利用效率判断机构自锁的方法,改为利用总反力作用在摩擦锥或摩擦圆之内来判断机构的自锁现象,概念清晰,方法实用,把摩擦与自锁机构设计相结合,强化了设计主线;在连杆机构和凸轮机构的解析法设计中,放弃了传统的坐标变换法,采用了简单的几何代数法,简化了数学运算过程。

本教材还增加了创新设计、机构系统设计的内容,完善了从简单机构设计到复杂机构系统设计的整体内容;同时简化了齿轮机构中的变位齿轮、斜齿轮、锥齿轮、蜗杆机构以及其他常用机构的内容。把机构动态静力分析、摩擦与自锁、考虑摩擦的力分析等内容整合为机构的力分析。

4) 为了突出教材的新颖性,学习了国外同类教材的插图风格,重新绘制了平面彩色渲染图和一些三维图形,代替了传统的黑白线条图形,层次分明,有益于对教材内容的理解。

5) 改革了配套习题的体系与内容。本教材的配套习题集内容分为阅读、理解、设计和自测四个组成部分,习题集最后辅以部分模拟试卷,形成一套完整的课后训练系统。在加强基本理论、基本概念的基础上,采用与工程实践相结合的题目,突出了理论与实践相结合的训练目的,使学生逐步学习解决工程设计中的问题。

6) 由于本书为双语教材,为了不增加篇幅,简化了传统中文教材的叙述内容,使论述更加简练。

### 2. 关于本教材英文部分的说明

1) 编写英汉双语教材,其目的是通过英文内容的学习,掌握机械原理的基本知识,为本专业领域内进行国际交流奠定基础。



2) 英文内容没有采取严格的汉语翻译内容, 而是强调基本内容的一致性和英文词汇的准确性。

3) 教材体系和内容与对应的中文教材相一致, 如图、表、公式都有严格的对应, 具有可比性。

4) 编写中尽量采用国外同类教材中的常用标准专业词汇, 具有可信性。

5) 尽量采用常用的词汇和简单的初级科技语法, 容易理解, 具有可读性。

6) 本书配套习题集中的阅读与理解部分, 以基本概念与基本理论为主, 参考大量原版教材及文献。

7) 该书中, 有些中英文的概念存在差别, 有益于中外教材内容的接轨。如该书第2章中, 中文教材中的局部自由度、虚约束, 在英文教材中为多余自由度、多余约束。保留这些差别是有益的。

参加本书中文编写的教师有: 张春林(第1章, 第2章, 第3章), 赵自强(第4章, 第5章, 第6章), 李志香(第7章, 第8章), 马超(第9章, 第10章, 第11章, 第12章, 第13章)。

参加英文编写的教师有: 张颖(第1章, 第2章, 第3章, 第4章, 第5章, 第6章, 第7章, 第8章, 第9章), 王泽洋(第10章, 第11章), 冯欣欣(第12章, 第13章)。

本书英文部分由北京工业大学的张颖负责统稿。全书由张春林负责统稿。另外, 在编写过程中, 西北工业大学的葛文杰教授提供了部分3D图形, 还有一些老师提供了部分图形, 编者表示感谢。

由于编者水平有限, 书中难免存在错误和疏漏之处, 特别是英文部分难免存在中国式的英文表述, 敬请广大读者批评指正。

张春林

于北京光大花园

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# Chapter 1

## Introduction

# 第1章

## 绪 论

## 1.1 General Information

A variety of machineries, such as textile machinery, printing machinery, food machinery, transportation machinery, mining machinery, construction machinery, engineering machinery, agricultural machinery, forestry machinery, packaging machinery, metallurgical machinery, fluid machinery, service machinery, weapons, robots and so on, have played an important role in nowadays economic development and national defense. They have promoted the development of human society. How to improve old pattern of machinery and design new machinery are essential tasks in the field of mechanical engineering.

### 1. The Concept of Machinery

Along with the progress of human society, the concept of machinery is developed and improved gradually. Human beings began to use stone tools from the primitive society at first, such as stone axes and stone knives. With the development of technology, our ancestor invented some simple wooden tools, such as lever, windlass, human power waterwheel, animal power waterwheel and so on. On the basis of these simple tools, some complicated devices were invented, such as water-powered roller and windmills. In the 18th century, after the British industrial revolution, human invented steam engine, internal combustion engine and electromotor, therefore the foundation of modern mechanical industry was established. After the computer was invented, the automatic control technology, information technology, and the transducer technology were used in machinery, which made the machines realize automation and intelligent. New technology and equipments, such as robots, numerical control machines, high-speed vehicles and aircrafts, heavy machinery, micro machinery and so on, have promoted the human society's prosperity and progress.

In different period, the definition of machinery is different, as well. In general, machinery is a device which can realize the mechanical movement. For example, screwdrivers, hammers, pliers, scissors are machinery and tanks, planes, cars, ships, robots, and other senior complicated equipment are also machinery. However, in modern society, people used to define the simplest machinery with no power as tools, such as lever, pliers, scissors, wheelbarrow, and so on.

In mechanical engineering, when talking about specific machinery, it is called a machine.

(1) Mechanism A mechanism is a device, which produces specific mechanical motions. Thus, the function of a mechanism is to transmit and modify a motion. We often use a drawing with some simple lines and symbols to describe the mechanism, and it is called kinematical diagram.

(2) Machine A machine is a device which produces specific mechanical motions, and it can transmit or modify mechanical energy, materials and information. A machine may be a mechanism or a combination of mechanisms capable of transmitting or modifying motion and mechanical energy.

For instance, vehicles, tanks, missiles, planes, ships and so on are all machines. But the television is not a machine, because it has nothing to do with mechanical movement.

Fig. 1-1a shows an internal combustion engine which transforms thermal energy into mechanical energy. The sliding motion of piston 1 will be transformed to the series rotation of crank shaft 3 by coupler 2. This kind of mechanism is called a linkage.



## 1.1 机械总论

各种各样的机械,如纺织机械、印刷机械、食品机械、交通运输机械、矿山机械、建筑机械、工程机械、农业机械、林业机械、包装机械、冶金机械、流体机械、服务机械、兵器与机器人等,在经济建设和国防建设领域中发挥了巨大作用,促进了人类社会的发展。改造原有机械、设计新机械是机械工程领域中的重要任务。了解机械、设计机械是机械工程专业教学中的重要内容。

### 1. 机械的概念

机械的概念是伴随人类社会的不断进步逐渐发展与完善的。从早期原始社会人类使用的诸如石斧、石刀等最简单的石制工具,到杠杆、辘轳、人力脚踏水车、兽力汲水车等简单木制工具,发展到较复杂的水力驱动的水碾和风力驱动的风车等都是简单机械。18世纪英国工业革命后,人类发明的蒸汽机、内燃机、电动机等复杂的机械,奠定了现代机械的基础。计算机发明后,自动控制技术、信息技术、传感技术融入机械中,机械实现了自动化和智能化。机器人、数控机床、高速运载工具,重型机械、微型机械等大量先进机械加速了人类社会的繁荣和进步,机械进入机电结合的新时代。

不同历史时期,人们对机械的定义也有所不同。从广义角度讲,凡是能实现机械运动的装置都是机械。例如:螺钉旋具、锤子、钳子、剪子等简单工具是机械,汽车、坦克、飞机、舰船、各类加工机床、机械手、机器人、复印机、打印机等高级复杂装备也是机械。无论其结构和材料如何,只要是实现机械运动的装置,就称之为机械。在现代社会中,人们常把最简单的、没有动力源的简单机械称为工具或器械,如杠杆、钳子、剪子、手推车等最简单的机械常称为工具。

工程中,谈到具体的机械时,常使用机器这个名词,泛指时则用机械来统称。

(1) 机构 机器的重要特征是执行机械运动,工程上把机器中执行机械运动的装置称为机构。为研究方便,常用简单的符号和线条表示机构的组成情况和运动情况,并称之为机构运动简图。

(2) 机器 机器是执行机械运动的装置,用来变换或传递能量、物料或信息。机器的重要特征是执行机械运动,同时完成能量的转换,或物料、信息的传递。汽车、坦克、导弹、飞机、轮船、车床、起重机、织布机、印刷机、包装机等大量具有不同外形、不同性能和用途的装置都是具体的机器。电视机不是机器,因其功能与机械运动无关。

图1-1a所示的四冲程内燃机,是一个把热能转换为机械能的机器。该内燃机中,活塞1做往复移动并通过连杆2推动曲轴3连续旋转。这种把活塞移动转化为曲轴连续转动的装置称为连杆机构。

凸轮7转动,驱动推杆8往复移动,该机构称为凸轮机构。再通过杠杆9,驱动气门10的开启,控制进、排气阀的运动,保证缸体11按顺序吸进燃气和排出废气。四冲程内燃机中,活塞往复移动四次,曲轴转动两周,进气阀和排气阀各启闭一次,所以凸轮转速为曲轴转速的一半。也就是说,在曲轴和凸轮轴之间要设置减速齿轮4、5、6,该机构称为齿轮机构。齿轮机构实现了高速转动到低速转动的运动变换。

综上所述,机构是组成机器的主体。为表明机器的组成和运动情况,常用机构运动简图来表示。

Cam 7 and follower 8 are called cam mechanism. The opening and closing of valve 10 can be controlled by lever 9. This can ensure that cylinder 11 takes in the gas and exhales the waste gas. In a four-stroke engine, it takes four strokes of the piston to complete one cycle. That is to say, the circle is completed in two revolutions of the crank shaft, and the valves work at a time. Therefore, the engine requires a gear mechanism to reduce the speed of the crankshaft, such as gears 4, 5, 6.

There are four strokes in the engine. They are intake stroke, compression stroke, power stroke and exhaust stroke, but only one power stroke works, so the speed of the crank shaft fluctuates cyclically. A flywheel must be mounted on the crank shaft.

Fig. 1-1b shows the skeleton diagram of the four-stroke engine. The design can be simplified by use of skeleton diagram.

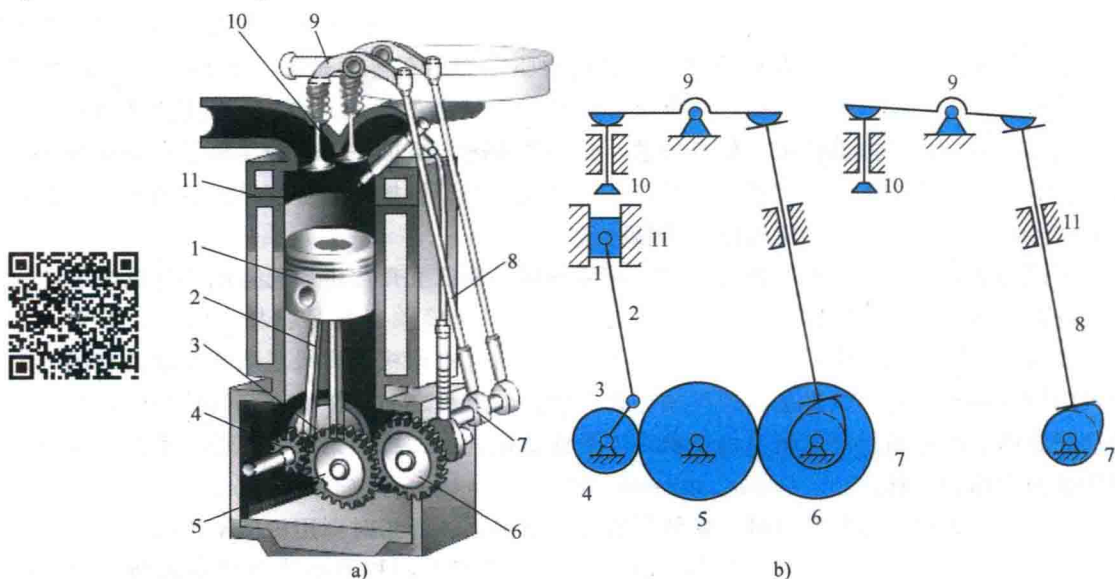


Fig. 1-1 Internal combustion engine and scheme(内燃机及其机构简图)

1—piston(活塞) 2—coupler(连杆) 3—crank shaft(曲轴) 4,5,6—speed reducing gear(减速齿轮) 7—cam(凸轮)  
8—follower(推杆) 9—lever(杠杆) 10—valve(气门) 11—frame(缸体)

Although there are various types of machines, the mechanisms consisting of machines are finite. Therefore, the theory of mechanism is very important to design machines.

(3) Machinery In the viewpoint of kinematics, mechanism and machine have no difference, so mechanisms and machines are generally called machinery in mechanical engineering. There is no energy transforming and modifying in a mechanism, for example, mechanical watch is a mechanism but not a machine, because it can not transform energy.

## 2. Composition of Machines

A machine consists of prime power, transmission system and working system. A modern machine also contains a control system. Fig. 1-2 shows the block diagram of composition of a machine.

Fig. 1-3b shows a diagram of an automatic gate. Fig. 1-3a shows the composition of the driver. The prime power is electromotor 3 which has a high speed. But gate 2 needs a low speed to work, so we have to install gear mechanisms and chain mechanisms to modify the speed of gate 2. The reducer 4 and chain driver 5 are transmission system. Gate 2 consisting of the parallel linkages is called working system. The control system and sense system are not illustrated in the gate.



图 1-1b 所示为该内燃机的机构简图。为表达清楚,另一套凸轮机构单独画出。使用机构简图对内燃机进行分析和设计时,简化了设计工作。由于缸体中进气、压缩、燃烧、排气交替进行,导致曲轴运动速度不均匀,所以在曲轴的另一端还要安装调速飞轮。上述各机构协调动作,才能满足内燃机的工作要求。

机器的种类很多,其功能、形状、结构、尺寸等也各不相同,但组成不同机器的机构种类却是有限的,仅有十余种。因此,要研究用有限的机构组成的无限的机器,就必须掌握机构的种类、工作原理及设计方法。

(3) 机械 机构与机器都是实现机械运动的装置,所以从运动学的观点看,两者是一样的;不同的是,机构没有能量的转换和信息的传递。例如:机械表是机构而不是机器,因为弹簧能量没有转换为机械能输出,其作用仅为克服各运动件的摩擦阻力。

从机械运动的观点看问题,机构与机器没有本质区别,工程中将机构与机器统称为机械。

## 2. 机器的组成

根据机器的定义,机器中要有动力源,称为原动机;机器中还要有机械运动的传递装置或机械运动形态的变换装置,常将它们称为机械传动系统和工作执行系统,统称为机械运动系统;现代机器还有控制系统。图 1-2 所示为常见机器组成示意图。

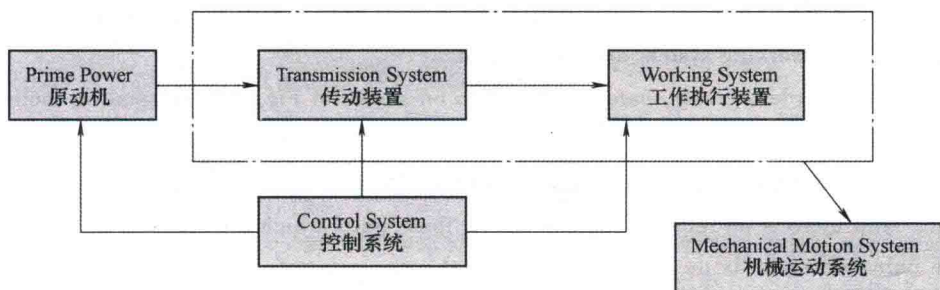


Fig. 1-2 Composition of common machine (常见机器组成示意图)

图 1-3 所示为电动大门示意图,其驱动器 1 的内部组成如图 1-3a 所示。原动机为电动机 3,其转速很高,而大门 2 的开启速度较低,所以要经过齿轮传动机构组成的减速器 4 和链传动机构 5 把电动机 3 的转速降下来,图示的减速器和链传动机构就是速度变换机构。由许多平行四边形机构和滚轮组成的大门 2 称为工作执行机构。

工程中应用的机械运动系统大都具有减速机构。但也有一些现代机器没有减速机构,直接用可控电动机驱动工作执行机构。