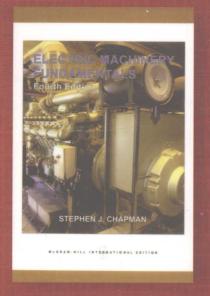


清华版双语教学用书



电机原理及驱动

电机学基础(第4版)

Electric Machinery Fundamentals

(Fourth Edition)

Stephen J. Chapman 原著 满永奎 编译



清华大学出版社

清华版双语教学用书

电机原理及驱动

- 电机学基础 (第4版)

Electric Machinery Fundamentals

(Fourth Edition)

Stephen J. Chapman 原著 满永奎 编译

清华大学出版社 北京 Stephen J. Chapman

Electric Machinery Fundamentals (4th Edition)

EISBN: 0-07-115155-9

Copyright © 2005 by The McGraw-Hill Companies, Inc.

Original language published by The McGraw-Hill Companies, Inc. All rights reserved. No part of this publication may be reproduced or distributed by any means, or stored in a database or retrieval system, without the prior written permission of the publisher.

Bilingual abridged edition is published and distributed exclusively by Tsinghua University Press under the authorization by McGraw-Hill Education (Asia) Co., within the territory of the People's Republic of China only (excluding Hong Kong, Macao SAR and Taiwan). Unauthorized export of this edition is a violation of the Copyright Act. Violation of this Law is subject to Civil and Criminal Penalties. 本书双语缩编版由美国麦格劳·希尔教育出版(亚洲)公司授权清华大学出版社在中华人民共和国境内(不包括中国香港、澳门特别行政区和中国台湾地区)独家出版发行。未经许可之出口视为违反著作权法,将受法律之制裁。未经出版者预先书面许可,不得以任何方式复制或抄袭本书的任何部分。

北京市版权局著作权合同登记号 图字: 01-2008-2461

本书封面贴有 McGraw-Hill 公司防伪标签,无标签者不得销售。版权所有,侵权必究。侵权举报电话: 010-62782989 13701121933

图书在版编目(CIP)数据

电机原理及驱动——电机学基础:第4版/(美)查普曼(Stephen J. Chapman)原著; 满永奎编译.—北京:清华大学出版社,2008.7

书名原文: Electric Machinery Fundamentals(4th Edition)

(清华版双语教学用书)

ISBN 978-7-302-17730-2

I. 电··· Ⅱ. ①查··· ②满··· Ⅲ. 电机学 - 双语教学 - 教材 Ⅳ. TM3 中国版本图书馆 CIP 数据核字(2008)第 074598 号

责任编辑:王敏稚

责任校对:白 蕾

责任印制:李红英

出版发行:清华大学出版社 地 址:北京清华大学学研大厦 A 座

http://www.tup.com.cn

邮 编:100084

社 总 机: 010-62770175 邮 购: 010-62786544

投稿与读者服务: 010-62776969,c-service@tup. tsinghua. edu. cn 质 量 反 馈: 010-62772015,zhiliang@tup. tsinghua. edu. cn

印刷者:北京四季青印刷厂

装 订 者: 三河市新茂装订有限公司

经 销:全国新华书店

开 本: 152×228 印 张: 37 字 数: 657 千字

版 次:2008年7月第1版 印 次:2008年7月第1次印刷

印 数:1~2200

定 价: 59.00元

本书如存在文字不清、漏印、缺页、倒页、脱页等印装质量问题,请与清华大学出版社出版部联系调换。联系电话:(010)62770177转3103 产品编号:026476-01

ABOUT THE AUTHOR

Stephen J. Chapman received a B.S. in Electrical Engineering from Louisiana State University (1975) and an M.S.E. in Electrical Engineering from the University of Central Florida (1979), and pursued further graduate studies at Rice University.

From 1975 to 1980, he served as an officer in the U.S. Navy, assigned to teach electrical engineering at the U.S. Naval Nuclear Power School in Orlando, Florida. From 1980 to 1982, he was affiliated with the University of Houston, where he ran the power systems program in the College of Technology.

From 1982 to 1988 and from 1991 to 1995, he served as a member of the technical staff of the Massachusetts Institute of Technology's Lincoln Laboratory, both at the main facility in Lexington, Massachusetts, and at the field site on Kwajalein Atoll in the Republic of the Marshall Islands. While there, he did research in radar signal processing systems. He ultimately became the leader of four large operational range instrumentation radars at the Kwajalein field site (TRADEX, ALTAIR, ALCOR, and MMW).

From 1988 to 1991, Mr. Chapman was a research engineer in Shell Development Company in Houston, Texas, where he did seismic signal processing research. He was also affiliated with the University of Houston, where he continued to teach on a part-time basis.

Mr. Chapman is currently manager of systems modeling and operational analysis for BAE SYSTEMS Australia, in Melbourne.

Mr. Chapman is a senior member of the Institute of Electrical and Electronic Engineers (and several of its component societies). He is also a member of the Association for Computing Machinery and the Institution of Engineers (Australia).

编译者序

改革开放以来,我国的经济进入了快速发展期,很快融入了世界经济发展的大潮。随着我国加入 WTO,日益国际化的经济对我国专业人员的国际化水平提出了更高的要求。较高的国际化水平的一个突出的方面是专业人员的专业英文的交流能力有待极大提高。

因为客观市场对此有迫切需求,国家教委也将双语教学列为高等学校教育质量 评估中的一项重要指标。

作为本书的编译者,我在多年与英国大学的合作研究和与外国公司的合作中,深刻认识到,专业英文的直接交流会极大地帮助我们发挥自身的潜能,增加在世界舞台上的竞争能力。而另一方面,在东北大学的多年教学中和在面试研究生和博士生的口语时,我也发现目前国内学生的专业英文能力比之他们的口语能力差距较大。因此我坚信:坚持双语教学,对于提高我国专业技术人员的直接交流能力,适应我国快速的经济发展需要,必将会起到积极的推动作用。

本书是基于由 Stephen J. Chapman 编写, McGraw- Hill 出版社出版的 Electric Machinery Fundamentals 一书的第 4 版(2005)改编。原著凝聚了作者在美国佛罗里达海军核动力学院和休斯敦大学的多年教学经验,作者在著书时掌握的主要原则是使其尽可能地通俗易懂,便于自学,这是本书的最大特点。此外,书中的内容最大限度地跟踪最新技术的发展,因此,原著自 1985 年第 1 版出版以来,已经成为世界上的畅销教材。

随着现代电力电子技术和交流控制技术的发展,交流电机在更多的领域不断取代直流电机的应用,而原著的第4版也正是为了适应新技术的发展,先阐述交流部分内容,开创了以交流内容作为重点的先河,有别于一般的传统教材。

本书保留了原著第4版的大部分章节。其中删除了原书中的第3章"功率电子学"部分,因为在我国,大部分学校另设这门课程。在原著中,关于同步电机有两章,同步发电机和同步电动机(原书的第5章和第6章),而我们在教授这门课程时,往往没有很多课时用在同步电机上,因此将原著的两章合并为一章(作为本书的第4章)。

为了便于读者理解,编译者增加了"词汇"和"导读"部分。在"词汇"部分,侧重点是专业词汇,给出了相对应的汉语术语。尽管穿插在书中各节列出了一些词汇,但是,为了读者查阅方便,在最后附录中,还按字母顺序列出了总的英汉对照词汇表。

为了使读者减少对中文的依赖性,编译者在"导读"部分,使用汉语注释的侧重点是理解上的难点,而不是本章节的重点;而本章节的重点内容,读者可以阅读原文中的"Summary",还可以由教师在讲课中予以指导。

参加本书编译工作的还有边春元,李爱萍,杨东升等,在此,向他们表示谢意。 在本教材的编译过程中,得到了清华大学出版社的鼎力支持,在此,表示诚挚的 感谢。

本教材可以作为高等学校电气工程和自动化专业本科学生的专业基础课双语 教材,也可以作为电气工程和自动化领域工程技术人员的技术参考书。

> 东北大学 满永奎 2008年6月

In the years since the first edition of *Electric Machinery Fundamentals* was published, there has been rapid advance in the development of larger and more sophisticated solid-state motor drive packages. The first edition of this book stated that dc motors were the method of choice for demanding variable-speed applications. That statement is no longer true today. Now, the system of choice for speed control applications is most often an ac induction motor with a solid-state motor drive. DC motors have been largely relegated to special-purpose applications where a dc power source is readily available, such as in automotive electrical systems.

The third edition of the book was extensively restructured to reflect these changes. The material on ac motors and generators is now covered in Chapters 4 through 7, before the material on dc machines. In addition, the dc machinery coverage was reduced compared to earlier editions. The fourth edition continues with this same basic structure.

Chapter 1 provides an introduction to basic machinery concepts, and concludes by applying those concepts to a linear dc machine, which is the simplest possible example of a machine. Chapter 2 covers transformers, and Chapter 3 is an introduction to solid-state power electronic circuits. The material in Chapter 3 is optional, but it supports ac and dc motor control discussions in Chapters 7, 9, and 10.

After Chapter 3, an instructor may choose to teach either dc or ac machinery first. Chapters 4 through 9 cover ac machinery, and Chapters 8 and 9 cover dc machinery. These chapter sequences have been made completely independent of each other, so that instructors can cover the material in the order that best suits their needs. For example, a one-semester course with a primary concentration in ac machinery might consist of parts of Chapters 1 to 7, with any remaining time devoted to dc machinery. A one-semester course with a primary concentration in dc machinery might consist of parts of Chapters 1, 3, 8, and 9, with any remain-

编译者注:由于本书对原书章节做了一些删节与合并,因此本前言中的章节号与书中内容有一些不同。参见"编译者序"。为了便于读者更好地理解本前言内容,现将原书各章标题列出:Chapter 1 Introduction to Machinery Principles; Chapter 2 Transformers; Chapter 3 Introduction to Power Electronics; Chapter 4 AC Machinery Fundamentals; Chapter 5 Synchronous Generators; Chapter 6 Synchronous Motors; Chapter 7 Induction Motors; Chapter 8 DC Machinery Fundamentals; Chapter 9 DC Motors and Generators; Chapter 10 Single-Phase and Special-Purpose Motors。

ing time devoted to ac machinery. Chapter 10 is devoted to single-phase and special-purpose motors, such as universal motors, stepper motors, brushless dc motors, and shaded-pole motors.

The homework problems and the ends of chapters have been revised and corrected, and more than 70 percent of the problems are either new or modified since the last edition.

In recent years, there have been major changes in the methods used to teach machinery to electrical engineering and electrical technology students. Excellent analytical tools such as MATLAB have become widely available in university engineering curricula. These tools make very complex calculations simple to perform, and allow students to explore the behavior of problems interactively. This edition of *Electric Machinery Fundamentals* makes selected use of MATLAB to enhance a student's learning experience where appropriate. For example, students use MATLAB in Chapter 7 to calculate the torque—speed characteristics of induction motors and to explore the properties of double-cage induction motors.

This text does not teach MATLAB; it assumes that the student is familiar with it through previous work. Also, the book does *not* depend on a student having MATLAB MATLAB provides an enhancement to the learning experience if it is available, but if it is not, the examples involving MATLAB can simply be skipped, and the remainder of the text still makes sense.

Supplemental materials supporting the book are available from the book's website, at www.mhhe.com/engcs/electrical/chapman. The materials available at that address include MATLAB source code, pointers to sites of interest to machinery students, a list of errata in the text, some supplemental topics that are not covered in the main text, and supplemental MATLAB tools.

This book would never have been possible without the help of dozens of people over the past 18 years. I am not able to acknowledge them all here, but I would especially like to thank Charles P. LeMone, Teruo Nakawaga, and Tadeo Mose of Toshiba International Corporation for their invaluable help with the solid-state machinery control material in Chapter 3. I would also like to thank Jeffrey Kostecki, Jim Wright, and others at Marathon Electric Company for supplying measured data from some of the real generators that the company builds. Their material has enhanced this revision.

Finally, I would like to thank my wife Rosa and our children Avi, David, Rachel, Aaron, Sarah, Naomi, Shira, and Devorah for their forbearance during the revision process. I couldn't imagine a better incentive to write!

Stephen J. Chapman Melbourne, Victoria, Australia

BRIEF CONTENTS

Chapter	1	Introduction to Machinery Principles	1
Chapter	2	Transformers	49
Chapter	3	AC Machinery Fundamentals	126
Chapter	4	Synchronous Generators and Motors	166
Chapter	5	Induction Motors	227
Chapter	6	DC Machinery Fundamentals	322
Chapter	7	DC Motors and Generators	380
Chapter	8	Single-Phase and Special-Purpose Motors	470
Appendix	A	Three-Phase Circuits	510
Appendix	В	Coil Pitch and Distributed Windings	536
Appendix	C	Salient-Pole Theory of Synchronous Machines	556
Appendix	D	Tables of Constants and Conversion Factors	566

TABLE OF CONTENTS

Chapter 1	Introduction to Machinery Principles	
1.1	Electrical Machines, Transformers, and Daily Life	1
1.2	Rotational Motion, Newton's Law, and Power Relationships	2
	Angular Position θ / Angular Velocity ω / Angular Acceleration α / Torque τ / Newton's Law of Rotation / Work W / Power P	
1.3	The Magnetic Field	8
	Production of a Magnetic Field / Magnetic Circuits / Magnetic Behavior of Ferromagnetic Materials / Energy Losses in a Ferromagnetic Core	
1.4	Faraday's Law—Induced Voltage from a Time-Changing	
	Magnetic Field	29
1.5	Production of Induced Force on a Wire	32
1.6	Induced Voltage on a Conductor Moving in a Magnetic Field	34
1.7	Real, Reactive, and Apparent Power in AC Circuits	36
	Alternative Forms of the Power Equations / Complex Power / The Relationships between Impedance Angle, Current Angle, and Power / The Power Triangle	
1.8	Summary Transfer of the Samuel Control of th	42
	Questions	43
	Problems	44
	References	48
Chapter 2	Transformers	49
2.1	Why Transformers Are Important to Modern Life	50
2.2	Types and Construction of Transformers	51

2.3	The Ideal Transformer	53
	Power in an Ideal Transformer / Impedance Transformation through a Transformer / Analysis of Circuits Containing Ideal Transformers	
2.4	Theory of Operation of Real Single-Phase Transformers	61
	The Voltage Ratio across a Transformer / The Magnetization Current in a Real Transformer / The Current Ratio on a Transformer and the Dot Convention	
2.5	The Equivalent Circuit of a Transformer	71
	The Exact Equivalent Circuit of a Real Transformer / Approximate Equivalent Circuits of a Transformer / Determining the Values of Components in the Transformer Model	
2.6	The Per-Unit System of Measurements	81
2.7	Transformer Voltage Regulation and Efficiency	87
	The Transformer Phasor Diagram / Transformer Efficiency	
2.8	Transformer Taps and Voltage Regulation	94
2.9	The Autotransformer	95
	Voltage and Current Relationships in an Autotransformer / The Apparent Power Rating Advantage of Autotransformers / The Internal Impedance of an Autotransformer	
2.10	Three-Phase Transformers	103
2.11	Three-Phase Transformer Connections / The Per-Unit System for Three-Phase Transformers Transformer Ratings and Related Problems The Voltage and Frequency Ratings of a Transformer /	113
to the	The Apparent Power Rating of a Transformer / The Problem of Current Inrush / The Transformer Nameplate	
2.12	Instrument Transformers	118
2.13	Summary	120
	Questions	120
	Problems	121
	References	125
Chapter 3	AC Machinery Fundamentals	126
3.1	A Simple Loop in a Uniform Magnetic Field	127
	The Voltage Induced in a Simple Rotating Loop / The Torque Induced in a Current-Carrying Loop	
3.2	The Rotating Magnetic Field	135
	Proof of the Rotating Magnetic Field Concept / The Relationship between Electrical Frequency and the Speed	

	of Magnetic Field Rotation / Reversing the Direction of Magnetic Field Rotation	
3.3	Magnetomotive Force and Flux Distribution on AC Machines	142
3.4	Induced Voltage in AC Machines	146
	The Induced Voltage in a Coil on a Two-Pole Stator / The Induced Voltage in a Three-Phase Set of Coils / The RMS Voltage in a Three-Phase Stator	
3.5	Induced Torque in an AC Machine	152
3.6	Winding Insulation in an AC Machine	156
3.7	AC Machine Power Flows and Losses	158
	The Losses in AC Machines / The Power-Flow Diagram	
3.8	Voltage Regulation and Speed Regulation	161
3.9	Summary	162
	Questions	164
	Problems	164
	References	165
Chapter 4	Synchronous Generators and Motors	166
4.1	Synchronous Generator Construction	166
4.2	The Speed of Rotation of a Synchronous Generator	172
4.3	The Internal Generated Voltage of a Synchronous Generator	173
4.4	The Equivalent Circuit of a Synchronous Generator	174
4.5	The Phasor Diagram of a Synchronous Generator	180
4.6	Power and Torque in Synchronous Generators	181
4.7	Measuring Synchronous Generator Model Parameters	184
	The Short-Circuit Ratio	
4.8	Basic Principles of Motor Operation	190
	The Equivalent Circuit of a Synchronous Motor / The Synchronous Motor from a Magnetic Field Perspective	
4.9	Steady-State Synchronous Motor Operation	194
***	The Synchronous Motor Torque–Speed Characteristic Curve /	
	The Effect of Load Changes on a Synchronous Motor / The Effect of Field Current Changes on a Synchronous Motor / The Synchronous Motor and Power-Factor Correction / The Synchronous Capacitor or Synchronous Condenser	
4.10	Starting Synchronous Motors	209
	Motor Starting by Reduced Electrical Frequency / Motor	
	Starting with an External Prime Mover / Motor Starting by Using Amortisseur Windings / The Effect of Amortisseur Windings on Motor Stability	
4.11	Synchronous Generators and Synchronous Motors	217
4.12	Synchronous Motor Ratings	218

4.13	Summary	219
	Questions	220
	Problems	221
	References	226
Chapter 5	Induction Motors	227
5.1	Induction Motor Construction	227
5.2	Basic Induction Motor Concepts	231
	The Development of Induced Torque in an Induction Motor / The Concept of Rotor Slip / The Electrical Frequency on the Rotor	
5.3	The Equivalent Circuit of an Induction Motor	236
	The Transformer Model of an Induction Motor / The Rotor Circuit Model / The Final Equivalent Circuit	
5.4	Power and Torque in Induction Motors	242
	Losses and the Power-Flow Diagram / Power and Torque in an Induction Motor / Separating the Rotor Copper Losses and the Power Converted in an Induction Motor's Equivalent Circuit	
5.5	Induction Motor Torque-Speed Characteristics	249
	Induced Torque from a Physical Standpoint / The Derivation of the Induction Motor Induced-Torque Equation / Comments on the Induction Motor Torque–Speed Curve / Maximum (Pullout) Torque in an Induction Motor	
5.6	Variations in Induction Motor Torque-Speed Characteristics	264
	Control of Motor Characteristics by Cage Rotor Design / Deep-Bar and Double-Cage Rotor Designs / Induction Motor Design Classes	
5.7	Trends in Induction Motor Design	274
5.8	Starting Induction Motors	279
	Induction Motor Starting Circuits	
5.9	Speed Control of Induction Motors	285
	Induction Motor Speed Control by Pole Changing / Speed Control by Changing the Line Frequency / Speed Control by Changing the Line Voltage / Speed Control by Changing the Rotor Resistance	
5.10	Solid-State Induction Motor Drives	294
	Frequency (Speed) Adjustment / A Choice of Voltage and Frequency Patterns / Independently Adjustable Acceleration and Deceleration Ramps / Motor Protection	
5.11	Determining Circuit Model Parameters	302
	T /	

	The No-Load Test / The DC Test for Stator Resistance / The Locked-Rotor Test	
5.12	The Induction Generator	311
5.12	The Induction Generator Operating Alone / Induction Generator Applications	311
5.13	Induction Motor Ratings	315
5.14	Summary	317
	Questions	318
	Problems	319
	References	321
Chapter 6	DC Machinery Fundamentals	322
6.1	A Simple Rotating Loop between Curved Pole Faces	322
	The Voltage Induced in a Rotating Loop / Getting DC	
	Voltage out of the Rotating Loop / The Induced Torque in	
	the Rotating Loop	
6.2	Commutation in a Simple Four-Loop DC Machine	334
6.3	Commutation and Armature Construction in Real	339
	DC Machines	339
	The Rotor Coils / Connections to the Commutator Segments / The Lap Winding / The Wave Winding / The	
	Frog-Leg Winding	
6.4	Problems with Commutation in Real Machines	351
0.4	Armature Reaction / L di/dt Voltages / Solutions to the	551
	Problems with Commutation	
6.5	The Internal Generated Voltage and Induced Torque	
0.0	Equations of Real DC Machines	364
6.6	The Construction of DC Machines	368
	Pole and Frame Construction / Rotor or Armature	
	Construction / Commutator and Brushes / Winding	
	Insulation	
6.7	Power Flow and Losses in DC Machines	374
	The Losses in DC Machines / The Power-Flow Diagram	
6.8	Summary	377
	Questions	378
	Problems	378
	References	378
Chapter 7	DC Motors and Generators	380
7.1	Introduction to DC Motors	380
7.1	The Equivalent Circuit of a DC Motor	383

7.3	The Magnetization Curve of a DC Machine	385
7.4	Separately Excited and Shunt DC Motors	386
	The Terminal Characteristic of a Shunt DC Motor /	
	Nonlinear Analysis of a Shunt DC Motor / Speed Control	
	of Shunt DC Motors / The Effect of an Open Field Circuit	
7.5	The Permanent-Magnet DC Motor	405
7.6	The Series DC Motor	408
	Induced Torque in a Series DC Motor / The Terminal	
	Characteristic of a Series DC Motor / Speed Control of	
	Series DC Motors	
7.7	The Compounded DC Motor	413
	The Torque-Speed Characteristic of a Cumulatively	
	Compounded DC Motor / The Torque-Speed	
	Characteristic of a Differentially Compounded DC Motor /	
	The Nonlinear Analysis of Compounded DC Motors /	
	Speed Control in the Cumulatively Compounded DC Motor	
7.8	DC Motor Starters	418
	DC Motor Problems on Starting / DC Motor Starting	
	Circuits	
7.9	The Ward-Leonard System and Solid-State Speed Controllers	427
	Protection Circuit Section / Start/Stop Circuit Section /	
	High-Power Electronics Section / Low-Power Electronics	
	Section	
7.10	DC Motor Efficiency Calculations	437
7.11	Introduction to DC Generators	440
7.12	The Separately Excited Generator	442
	The Terminal Characteristic of a Separately Excited DC	
	Generator / Control of Terminal Voltage / Nonlinear	
	Analysis of a Separately Excited DC Generator	
7.13	The Shunt DC Generator	448
	Voltage Buildup in a Shunt Generator / The Terminal	
	Characteristic of a Shunt DC Generator / Voltage Control	
	for a Shunt DC Generator / The Analysis of Shunt DC	
_	Generators	
7.14	The Series DC Generator	454
	The Terminal Characteristic of a Series Generator	
7.15	The Cumulatively Compounded DC Generator	457
	The Terminal Characteristic of a Cumulatively	
	Compounded DC Generator / Voltage Control of	
	Cumulatively Compounded DC Generators / Analysis of	
	Cumulatively Compounded DC Generators	

7.16	Summary		462
	Questions		463
	Problems		464
	References		469
	anisa Lisasidida	. G. Coil Pitch and Dr.	Abgrouds.
Chapter 8	Single-Phase and	Special-Purpose Moto	ors 470
8.1	The Universal Motor		471
	Applications of Univers Universal Motors	al Motors / Speed Control of	
8.2		Phase Induction Motors Field Theory of Single-Phase	474
		e Cross-Field Theory of Single-	
8.3	Starting Single-Phase In	nduction Motors	483
	Permanent Split-Capac	Capacitor-Start Motors / itor and Capacitor-Start, / Shaded-Pole Motors / Phase Induction Motors	
8.4	Speed Control of Single	e-Phase Induction Motors	493
8.5	Other Types of Motors		495
		lysteresis Motors / hless DC Motors	
8.6	Summary		507
	Questions		508
	Problems		509
	References		509
Appendix A	Three-Phase Cir	cuits	510
A.1	Generation of Three-Ph	ase Voltages and Currents	510
A.2	Voltages and Currents is	n a Three-Phase Circuit	514
	O .	in the Wye (Y) Connection / in the Delta (Δ) Connection	
A.3	Power Relationships in	Three-Phase Circuits	519
	1	uations Involving Phase Quantit uations Involving Line Quantitie	
A.4	Analysis of Balanced T		522
A 5			520

A.6	Using the Power Triangle	529
	Questions	532
	Problems	533
	References	535
Appendix B	Coil Pitch and Distributed Windings	536
B.1	The Effect of Coil Pitch on AC Machines	536
	The Pitch of a Coil / The Induced Voltage of a Fractional- Pitch Coil / Harmonic Problems and Fractional-Pitch Windings	
B.2	Distributed Windings in AC Machines	545
	The Breadth or Distribution Factor / The Generated Voltage Including Distribution Effects / Tooth or Slot Harmonics	
В.3	Summary	553
	Questions	554
	Problems	554
	References	555
Appendix C	Salient-Pole Theory of Synchronous	
	Machines	556
C.1	Development of the Equivalent Circuit of	
	a Salient-Pole Synchronous Generator	557
C.2	Torque and Power Equations of Salient-Pole Machine	563
	Problems	564
Appendix D	Tables of Constants and Conversion Factors	566

CHAPTER 1

INTRODUCTION TO MACHINERY PRINCIPLES

1.1 ELECTRICAL MACHINES, TRANSFORMERS, AND DAILY LIFE

An **electrical machine** is a device that can convert either mechanical energy to electrical energy or electrical energy to mechanical energy. When such a device is used to convert mechanical energy to electrical energy, it is called a *generator*. When it converts electrical energy to mechanical energy, it is called a *motor*. Since any given electrical machine can convert power in either direction, any machine can be used as either a generator or a motor. Almost all practical motors and generators convert energy from one form to another through the action of a magnetic field, and only machines using magnetic fields to perform such conversions are considered in this book.

The *transformer* is an electrical device that is closely related to electrical machines. It converts ac electrical energy at one voltage level to ac electrical energy at another voltage level. Since transformers operate on the same principles as generators and motors, depending on the action of a magnetic field to accomplish the change in voltage level, they are usually studied together with generators and motors.

These three types of electric devices are ubiquitous in modern daily life. Electric motors in the home run refrigerators, freezers, vacuum cleaners, blenders, air conditioners, fans, and many similar appliances. In the workplace, motors provide the motive power for almost all tools. Of course, generators are necessary to supply the power used by all these motors.

Why are electric motors and generators so common? The answer is very